

AQ-F210

Feeder protection device



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Disclaimer

Please read these instructions carefully before using the equipment or taking any other actions with respect to the equipment. Only trained and qualified persons are allowed to perform installation, operation, service or maintenance of the equipment. Such qualified persons have the responsibility to take all appropriate measures, including e.g. use of authentication, encryption, anti-virus programs, safe switching programs etc. necessary to ensure a safe and secure environment and usability of the equipment. The warranty granted to the equipment remains in force only provided that the instructions contained in this document have been strictly complied with.

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1 Document information

1.1 Version 2 revision notes

Table. 1.1 - 1. Version 2 revision notes

| | |
|----------|--|
| Revision | 2.00 |
| Date | 6.6.2019 |
| Changes | <ul style="list-style-type: none"> - New more consistent look. - Improved descriptions generally in many chapters. - Improved readability of a lot of drawings and images. - Updated protection functions included in every manual. - Every protection relay type now has connection drawing, application example drawing with function block diagram and application example with wiring. - Added General-menu description. |
| Revision | 2.01 |
| Date | 6.11.2019 |
| Changes | <ul style="list-style-type: none"> - Added description for LED test and button test. - Complete rewrite of every chapter. - Improvements to many drawings and formula images. - Order codes revised. - Added double ST 100 Mbps Ethernet communication module and Double RJ45 10/100 Mbps Ethernet communication module descriptions |
| Revision | 2.02 |
| Date | 7.7.2020 |
| Changes | - A number of image descriptions improved. |
| Revision | 2.03 |
| Date | 27.8.2020 |

| | |
|----------|---|
| Changes | <ul style="list-style-type: none"> - Terminology consistency improved (e.g. binary inputs are now always called digital inputs). - Tech data modified to be more informative about what type of measurement inputs are used (phase currents/voltages, residual currents/voltages), what component of that measurement is available (RMS, TRMS, peak-to-peak) and possible calculated measurement values (powers, impedances, angles etc.). - Tech data updated: non-directional overcurrent - Tech data updated: non-directional earthfault - Tech data updated: current unbalance - Improvements to many drawings and formula images. - Improved and updated device user interface display images. - AQ-F210 Functions included list Added: Indicator objects, programmable control switches, mA output control and measurement recorder. - Added 6th harmonic to harmonic overcurrent protection function. - Changed disturbance recorder maximum digital channel amount from 32 to 95. - Added residual current coarse and fine measurement data to disturbance recorder description. - HSO1 and HSO2 connection swapped in arc protection card (was way wrong before). - Updated IO1 and IO2 rated current range. - Added inches to Dimensions and installation chapter. - Added raising frames, wall mounting bracket, combiflex frame to order code. - Added logical input and logical output function descriptions. - Additions to Abbreviations chapter. - Added button test description to Local panel structure chapter. - Added Fault register view to Basic configuration chapter. - Added parameter descriptions to General menu Device user interface chapter. - Protection device user interface chapter almost completely rewritten and restructured. - Added new parameter descriptions to Monitoring menu device user interface chapter. - Added note to Configuring user levels and passwords chapter that user level with a password automatically locks itself after 30 minutes of inactivity. - Added more "Tripped stage" indications and fault types to Measurement value recorder function. - Updated: Digital input activation and release threshold setting ranges and added drop-off delay setting. - Added sample rate to voltage and current measurement tech data. |
| Revision | 2.04 |
| Date | 8.6.2021 |
| Changes | <ul style="list-style-type: none"> - Increased the consistency in terminology - Various image upgrades - Visual update to the order codes |
| Revision | 2.05 |
| Date | 22.6.2021 |
| Changes | <ul style="list-style-type: none"> - Fixed phase current measurement continuous thermal withstand from 30A to 20A. - Fixed lots of timing errors written to registers table. "Prefault" is -200 ms from Start event, "Pretrigger" is -20 ms from trip (or start if fault doesn't progress to trip), "Fault" is start (or trip if fault doesn't progress to trip). - Added event history technical data |
| Revision | 2.06 |
| Date | 21.6.2022 |

| | |
|----------|---|
| Changes | <ul style="list-style-type: none"> - Improved descriptions generally in many chapters. - Improved readability of a lot of drawings and images. - Order codes have been revised. - Fixed bias calculation formula for restricted earth fault function. Was correctly in the code, just written wrong in the manual. - Added new trip detections and fault types to measurement value recorder. - Added user description parameter descriptions for digital inputs, digital outputs, logical inputs, logical outputs and GOOSE inputs. - Arc point sensor HSO1 and HSO2 position fixed. - Added spare part codes and compatibilities to option cards. |
| Revision | 2.07 |
| Date | 7.7.2022 |
| Changes | |
| Revision | 2.08 |
| Date | 8.9.2022 |
| Changes | <ul style="list-style-type: none"> - Added stage forcing parameter to function descriptions. - Fixes to "Real time signals to comm" description. - Added "Ethernet port" parameter description to IEC61850, IEC104 and Modbus TCP descriptions. - Removed "Measurement update interval" settings from Modbus description. No longer in use. - Renamed "System integration" chapter to "Communication" and restructured the chapters to be closer to how they are in the menus. - Added "Event logger" chapter. |
| Revision | 2.09 |
| Date | 14.3.2023 |
| Changes | <ul style="list-style-type: none"> - Updated the Arcteq logo on the cover page and refined the manual's visual look. - Added the "Safety information" chapter and changed the notes throughout the document accordingly. - Changed the "IED user interface" chapter's title to "Device user interface" and replaced all 'IED' terms with 'device' or 'unit'. - Updated the rated values for the change-over CPU digital outputs in "Technical data". - Added the maximum and minimum allowed tracking frequencies to the settings table of the "Frequency tracking and scaling" chapter (under "Measurements"). |
| Revision | 2.10 |
| Date | 19.6.2023 |
| Changes | - Updated order codes. |
| Revision | 2.11 |
| Date | 29.11.2023 |
| Changes | <ul style="list-style-type: none"> - Added the 5 ms update time in the measurement chapters. - Added spring lock cage options for connectors. See the "Ordering information" chapter. - Updated the contact address for technical support in the "Contact and reference information" chapter. |
| Revision | 2.12 |

| | |
|---------|--|
| Date | January 2024 |
| Changes | <ul style="list-style-type: none"> - Added "I2 meas / I2 set" and other read-only parameters to "I2> function". - Added Chinese and Kazakh languages as language options in "General menu". |

1.2 Version 1 revision notes

Table. 1.2 - 2. Version 1 revision notes

| | |
|----------|--|
| Revision | 1.00 |
| Date | 8.4.2013 |
| Changes | <ul style="list-style-type: none"> • The first revision for AQ-F210. |
| Revision | 1.01 |
| Date | 22.11.2013 |
| Changes | <ul style="list-style-type: none"> • Application example for ARON input connection added to Chapter 8. • Application example for trip circuit supervision added. • Added the arc protection module description. • Added the arc protection description and technical data. |
| Revision | 1.02 |
| Date | 20.1.2015 |
| Changes | <ul style="list-style-type: none"> • Added RTD & mA input modules, the double LC 100Mb Ethernet card module and the Serial RS-232 & serial fiber module hardware descriptions. • Added the system integration text for the SPA protocol. • Order code updated. |
| Revision | 1.03 |
| Date | 23.10.2015 |
| Changes | <ul style="list-style-type: none"> • CPU card digital input setup added. • Connection example revised. |
| Revision | 1.04 |
| Date | 30.5.2015 |
| Changes | <ul style="list-style-type: none"> • Added the PCB and Terminal options to the order code. |
| Revision | 1.05 |
| Date | 30.8.2016 |
| Changes | <ul style="list-style-type: none"> • Added the password set-up guide (previously only in the AQtivate 200 user guide). |
| Revision | 1.06 |
| Date | 9.2.2017 |

| | |
|----------|---|
| Changes | <ul style="list-style-type: none"> Added Programmable Control Switch and Indicator Object descriptions. Order code updated. |
| Revision | 1.07 |
| Date | 12.12.2017 |
| Changes | <ul style="list-style-type: none"> Measurement value recorder description. ZCT connection added to the current measurement description. Ring-lug CT card option description added. Order code revised. Non-standard inverse time delay curves added. Internal harmonic blocking parameter to the I> and I0> functions. RTD & mA card description improved. |
| Revision | 1.08 |
| Date | 14.8.2018 |
| Changes | <ul style="list-style-type: none"> Added the mA output option card description and updated the order code. |
| Revision | 1.09 |
| Date | 18.1.2018 |
| Changes | <ul style="list-style-type: none"> HMI display technical data added. |

1.3 Safety information

This document contains important instructions that should be saved for future use. Read the document carefully before installing, operating, servicing, or maintaining this equipment. Please read and follow all the instructions carefully to prevent accidents, injury and damage to property.

Additionally, this document contains four (4) types of special messages to call the reader's attention to useful information as follows:



NOTICE!

"Notice" messages indicate relevant factors and conditions to the the concept discussed in the text, as well as to other relevant advice.



CAUTION!

"Caution" messages indicate a potentially hazardous situation which, if not avoided, **could** result in minor or moderate personal injury, in equipment/property damage, or software corruption.



WARNING!

"Warning" messages indicate a potentially hazardous situation which, if not avoided, **could** result in death or serious personal injury as well as serious damage to equipment/property.



DANGER!

"Danger" messages indicate an imminently hazardous situation which, if not avoided, **will** result in death or serious personal injury.

These symbols are added throughout the document to ensure all users' personal safety and to avoid unintentional damage to the equipment or connected devices.

Please note that although these warnings relate to direct damage to personnel and/or equipment, it should be understood that operating damaged equipment may also lead to further, indirect damage to personnel and/or equipment. Therefore, we expect any user to fully comply with these special messages.

1.4 Abbreviations

AI – Analog input

AR – Auto-recloser

ASDU – Application service data unit

AVR – Automatic voltage regulator

BCD – Binary-coded decimal

CB – Circuit breaker

CBFP – Circuit breaker failure protection

CLPU – Cold load pick-up

CPU – Central processing unit

CT – Current transformer

CTM – Current transformer module

CTS – Current transformer supervision

DG – Distributed generation

DHCP – Dynamic Host Configuration Protocol

DI – Digital input

DO – Digital output

DOL – Direct-on-line

DR – Disturbance recorder

DT – Definite time

FF – Fundamental frequency

FFT – Fast Fourier transform

FTP – File Transfer Protocol

GI – General interrogation

HMI – Human-machine interface

HR – Holding register

HV – High voltage

HW – Hardware

IDMT – Inverse definite minimum time

IGBT – Insulated-gate bipolar transistor

I/O – Input and output

IRIG-B – Inter-range instruction group, timecode B

LCD – Liquid-crystal display

LED – Light emitting diode

LV – Low voltage

NC – Normally closed

NO – Normally open

NTP – Network Time Protocol

RMS – Root mean square

RSTP – Rapid Spanning Tree Protocol

RTD – Resistance temperature detector

RTU – Remote terminal unit

SCADA – Supervisory control and data acquisition

SG – Setting group

SOTF – Switch-on-to-fault

SW – Software

THD – Total harmonic distortion

TRMS – True root mean square

VT – Voltage transformer

VTM – Voltage transformer module

VTS – Voltage transformer supervision

2 General

The AQ-F210 feeder protection device is a member of the AQ 200 product line. The hardware and software are modular: the hardware modules are assembled and configured according to the application's I/O requirements and the software determines the available functions. This manual describes the specific application of the AQ-F210 feeder protection device. For other AQ 200 and AQ 250 series products please consult their respective device manuals.

AQ-F210 offers a modular feeder protection and control solution for non-directional overcurrent and earth fault protection with automatic reclosing. There are up to four (4) option card slots available for additional I/O or communication cards for more comprehensive monitoring and control applications. AQ-F210 communicates using various protocols including the IEC 61850 substation communication standard.

3 Device user interface

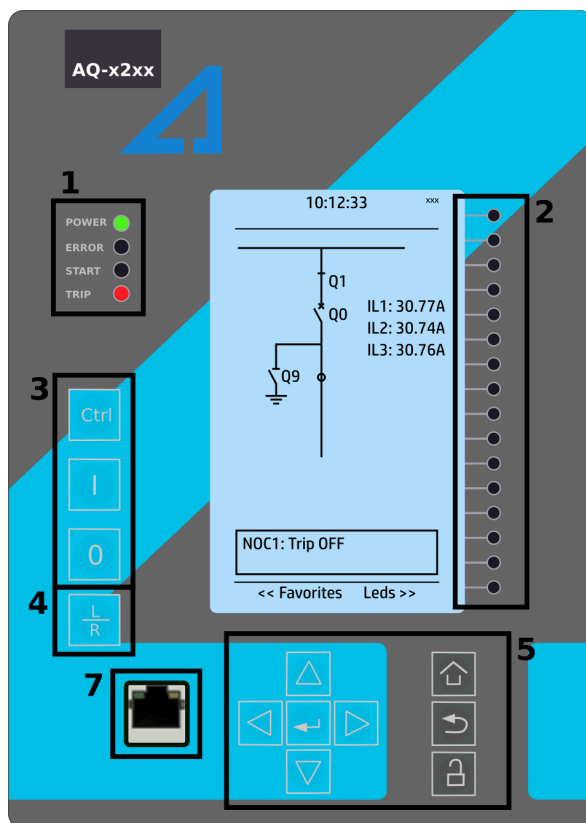
3.1 Panel structure

The user interface section of an AQ 200 or AQ 250 series device is divided into two user interface sections: one for the hardware and the other for the software. You can access the software interface either through the front panel or through the AQtivate 200 freeware software suite.

3.1.1 Local panel structure

The front panel of AQ 200 series devices have multiple LEDs, control buttons and a local RJ-45 Ethernet port for configuration. Each unit is also equipped with an RS-485 serial interface and an RJ-45 Ethernet interface on the back of the device.

Figure. 3.1.1 - 1. Local panel structure.



1. Four (4) default LEDs: "Power", "Error", "Start" (configurable) and "Trip" (configurable).
2. Sixteen (16) freely configurable LEDs with programmable legend texts.
3. Three (3) object control buttons: Choose the controllable object with the Ctrl button and control the breaker or other object with the I and O buttons.
4. The L/R button switches between the local and the remote control modes.
5. Eight (8) buttons for device local programming: the four navigation arrows and the Enter button in the middle, as well as the Home, the Back and the password activation buttons.
6. One (1) RJ-45 Ethernet port for device configuration.

When the unit is powered on, the green "Power" LED is lit. When the red "Error" LED is lit, the device has an internal (hardware or software) error that affects the operation of the unit. The activation of the yellow "Start" LED and the red "Trip" LED are based on the setting the user has put in place in the software.

The sixteen freely configurable LEDs are located on the right side of the display. Their activation and color (green or yellow) are based on the settings the user has put in place in the software.

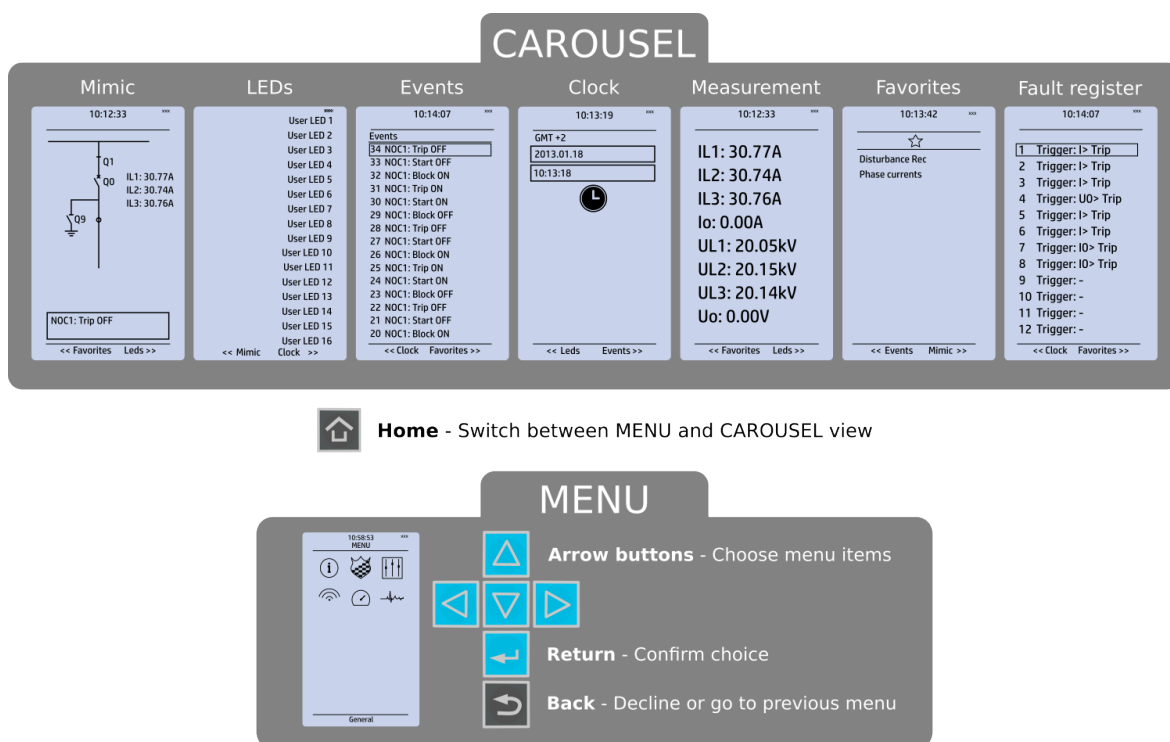
Holding the I (object control) button down for five seconds brings up the button test menu. It displays all the physical buttons on the front panel. Pressing any of the listed buttons marks them as tested. When all buttons are marked as having been tested, the device will return back to the default view.

3.2 Mimic and main menu

3.2.1 Basic configuration

The user interface is divided into seven (7) quick displays: "Mimic", "LEDs", "Events", "Clock", "Measurement", "Favorites" and "Fault register". The default quick display (as presented in the image below) is the mimic view; you can move through these menus by pressing the left and right arrow buttons. Please note that the available quick display carousel view might be different if you have changed the view with AQtivate's Carousel Designer tool.

Figure. 3.2.1 - 2. Basic navigation (general).



The **Home** button switches between the quick display carousel and the main display with the six (6) main configuration menus (*General, Protection, Control, Communication, Measurements and Monitoring*). Note that the available menus vary depending on the device type. You can select one of the menus by using the four navigation arrows and pressing **Enter** in the middle. The **Back** button takes you back one step. If you hold it down for three seconds, it takes you back to the main menu. You can also use it to reset the alarm LEDs you have set. The password activation button (with the padlock icon) takes you to the password menu where you can enter the passwords for the various user levels (User, Operator, Configurator, and Super-user).

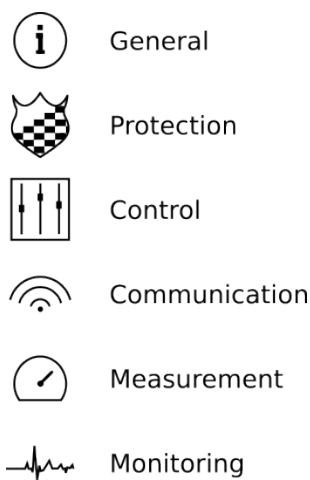
3.2.2 Navigation in the main configuration menus

All the settings in this device have been divided into the following six (6) main configuration menus:

- General
- Protection
- Control
- Communication
- Measurement
- Monitoring.

They are presented in the image below. The available menus vary according to the device type.

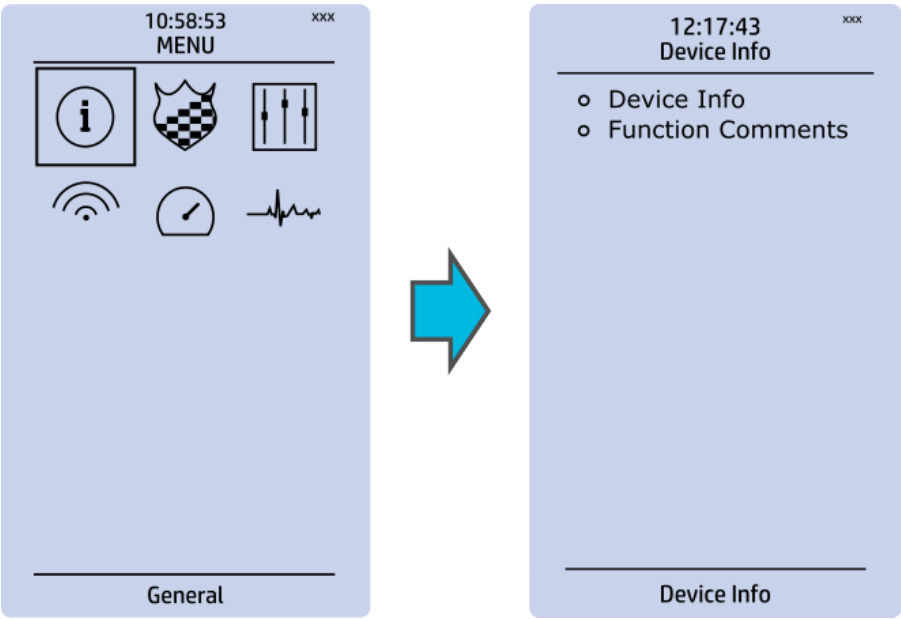
Figure. 3.2.2 - 3. Main configuration menus.



3.3 General menu

The *General* main menu is divided into two submenus: the *Device info* tab presents the information of the device, while the *Function comments* tab allows you to view all comments you have added to the functions.

Figure. 3.3 - 4. General menu structure.



Device info

Figure. 3.3 - 5. Device info.

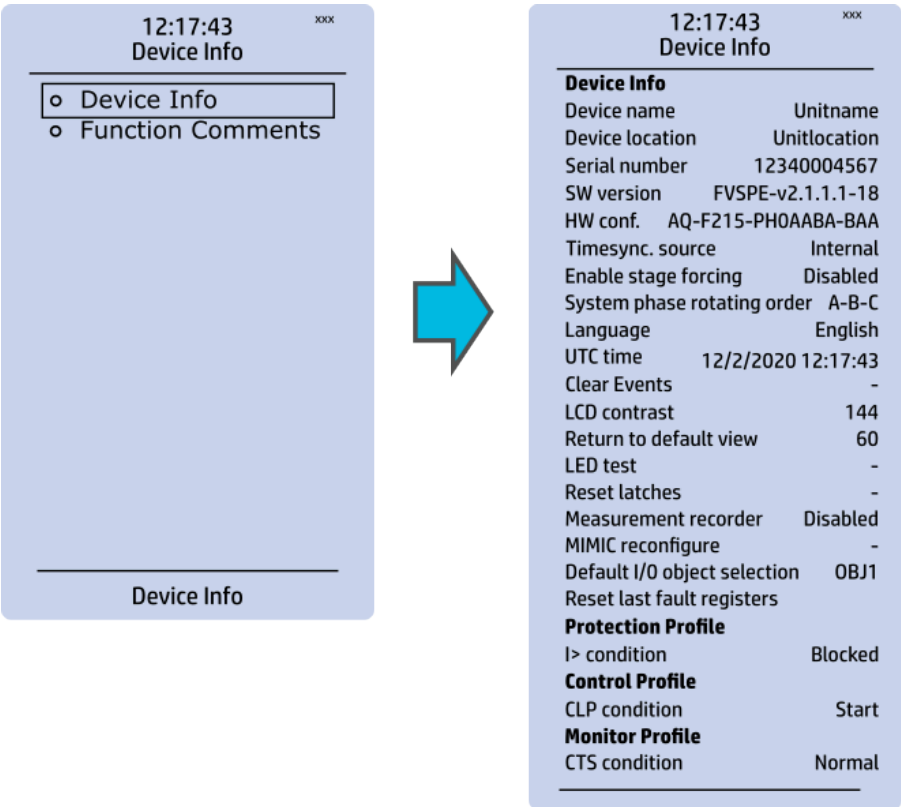


Table. 3.3 - 3. Parameters and indications in the *General* menu.

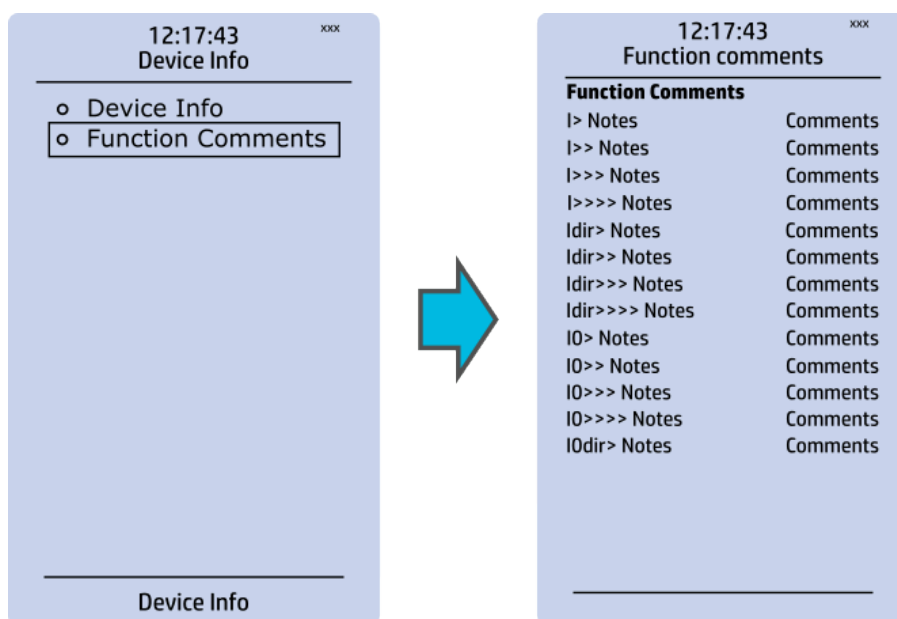
| Name | Range | Step | Default | Description |
|-----------------------------|--|------|--|--|
| Device name | - | - | Unitname | The file name uses these fields when loading the .aqs configuration file from the AQ-200 unit. |
| Device location | - | - | Unitlocation | |
| Serial number | - | - | - | Displays the unit's unique serial number. The serial number is also printed on the sticker located on the side of the unit. |
| Firmware version | - | - | - | Displays the software version (firmware) used by the unit. Upgradable by the user if a newer version is available. |
| Hardware configuration | - | - | - | Displays the hardware configuration of the unit. The hardware configuration is also printed on the sticker located on the side of the unit. |
| Time synchronization source | <ul style="list-style-type: none"> • Internal • External NTP • External Serial • IRIG-B | - | <ul style="list-style-type: none"> • Internal | If an external clock time synchronization source is available, the type is defined with this parameter. In the internal mode there is no external Timesync source. IRIG-B requires a serial fiber communication option card. |
| Enable stage forcing | <ul style="list-style-type: none"> • Disabled • Enabled | - | <ul style="list-style-type: none"> • Disabled | When this parameter is enabled it is possible for the user to force the protection, control and monitoring functions to different statuses like START and TRIP. This is done in the function's <i>Info</i> page with the <i>Force status to</i> parameter. |
| System phase rotating order | <ul style="list-style-type: none"> • A-B-C • A-C-B | - | <ul style="list-style-type: none"> • A-B-C | Allows the user to switch the expected order in which the voltage and current phases are wired to the unit. |
| Language | <ul style="list-style-type: none"> • User defined • English • Finnish • Chinese • Spanish • French • German • Russian • Ukrainian • Kazakh | - | <ul style="list-style-type: none"> • English | Changes the language of the parameter descriptions in the HMI. If the language has been set to "Other" in the settings of the AQtivate 200 setting tool, AQtivate follows the value set into this parameter. |
| UTC time | - | - | - | Displays the UTC time used by the unit without time zone corrections. |
| Clear events | <ul style="list-style-type: none"> • - • Clear | - | <ul style="list-style-type: none"> • - | Clears the event history recorded in the device. |
| LCD Contrast | 0...255 | 1 | 120 | Changes the contrast of the LCD display. |

| Name | Range | Step | Default | Description |
|------------------------------------|---|------|--|---|
| Return to default view | 0...3600 s | 10 s | 0 s | If the user navigates to a menu and gives no input after a period of time defined with this parameter, the unit automatically returns to the default view. If set to 0 s, this feature is not in use. |
| LED test | <ul style="list-style-type: none"> - Activated | - | <ul style="list-style-type: none"> - | When activated, all LEDs are lit up. LEDs with multiple possible colors blink each color. |
| Reset latches | <ul style="list-style-type: none"> - Reset | - | <ul style="list-style-type: none"> - | Resets the latched signals in the logic and the matrix. When a reset command is given, the parameter automatically returns back to "-". |
| Measurement recorder | <ul style="list-style-type: none"> Disabled Enabled | - | <ul style="list-style-type: none"> Disabled | Enables the measurement recorder tool, further configured in <i>Tools</i> → <i>Misc</i> → <i>Measurement recorder</i> . |
| Reconfigure mimic | <ul style="list-style-type: none"> - Reconfigure | - | <ul style="list-style-type: none"> - | Reloads the mimic to the unit. |
| Reset last fault registers | - | - | - | Activation of input selected here resets the values in "Fault registers" view in carousel. |
| Protection/Control/Monitor profile | - | - | - | Displays the status of all enabled functions. |

Function comments

Function comments displays notes of each function that has been activated in the Protection, Control and Monitoring menu. Function notes can be edited by the user.

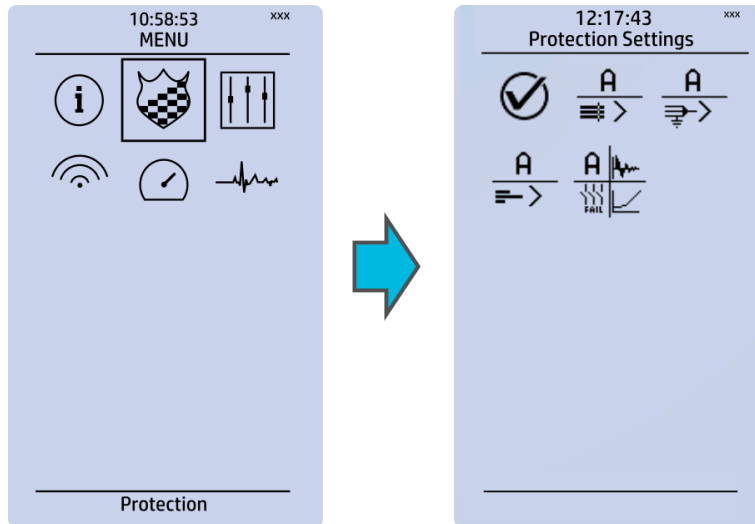
Figure. 3.3 - 6. Function comments.



3.4 Protection menu

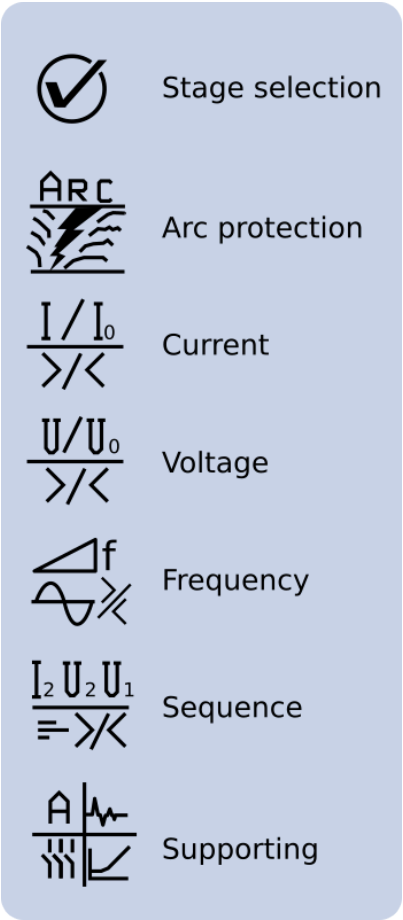
General

Figure. 3.4 - 7. Protection menu structure.



The *Protection* main menu includes the *Stage activation* submenu as well as the submenus for all the various protection functions, categorized under the following modules: "Arc protection", "Current", "Voltage", "Frequency", "Sequence" and "Supporting" (see the image below). The available functions depend on the device type in use.

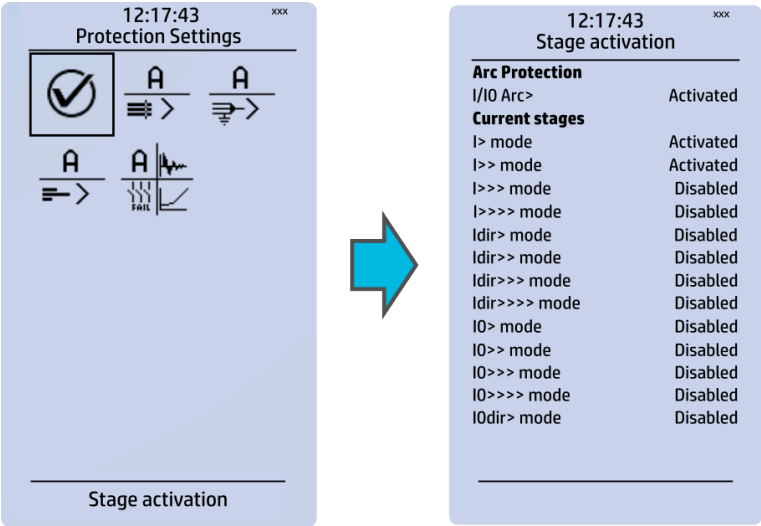
Figure. 3.4 - 8. Protection menu view.



Stage activation

You can activate the various protection stages in the *Stage activation* submenu (see the images below). Each protection stage and supporting function is disabled by default. When you activate one of the stages, its activated menu appears in the stage-specific submenu. For example, the I> (overcurrent) protection stage can be found in the "Current" module, whereas the U< (undervoltage) protection stage can be found in the "Voltage" module.

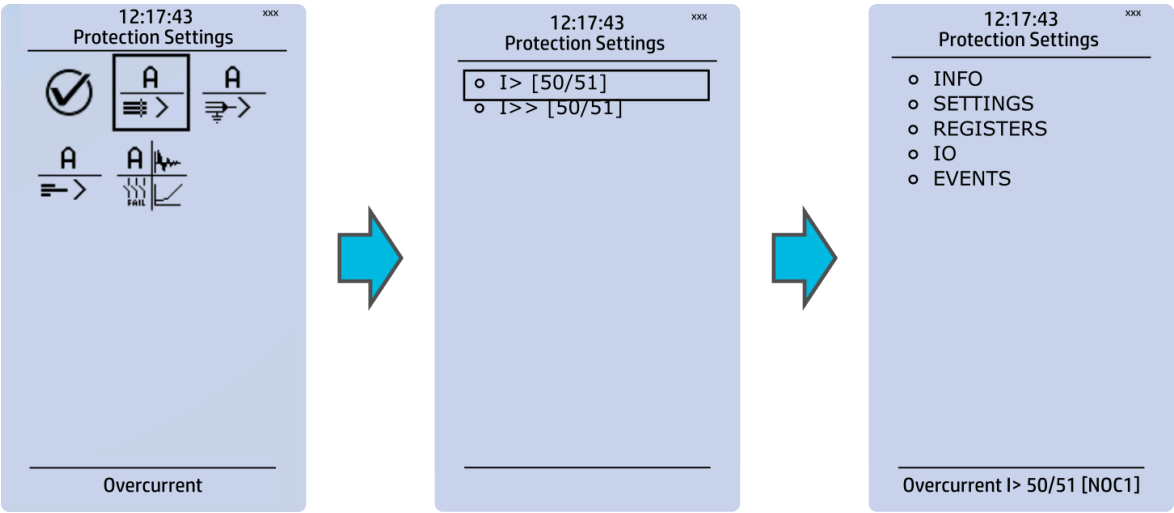
Figure. 3.4 - 9. Submenus for Stage activation.



Example of a protection stage and its use

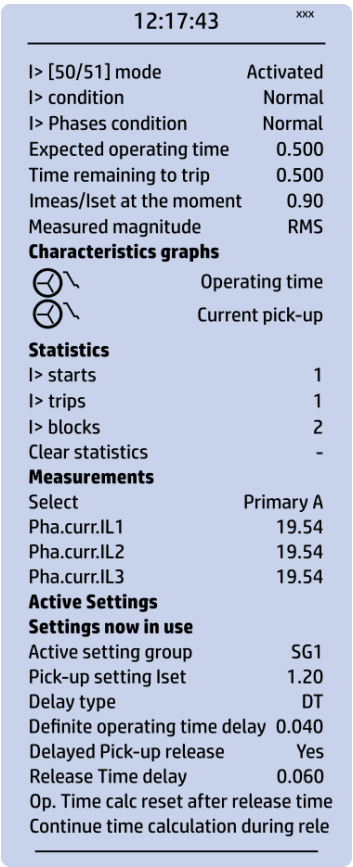
Once a protection stage has been activated in the *Stage activation* submenu, you can open its own submenu. In the image series below, the user has activated three current stages. The user accesses the list of activated current stages through the "Current" module, and selects the I> stage for further inspection.

Figure. 3.4 - 10. Accessing the submenu of an individual activated stage.



Each protection stage and supporting function has five sections in their stage submenus: "Info", "Settings", "Registers", "I/O" and "Events".

Figure. 3.4 - 11. Info.

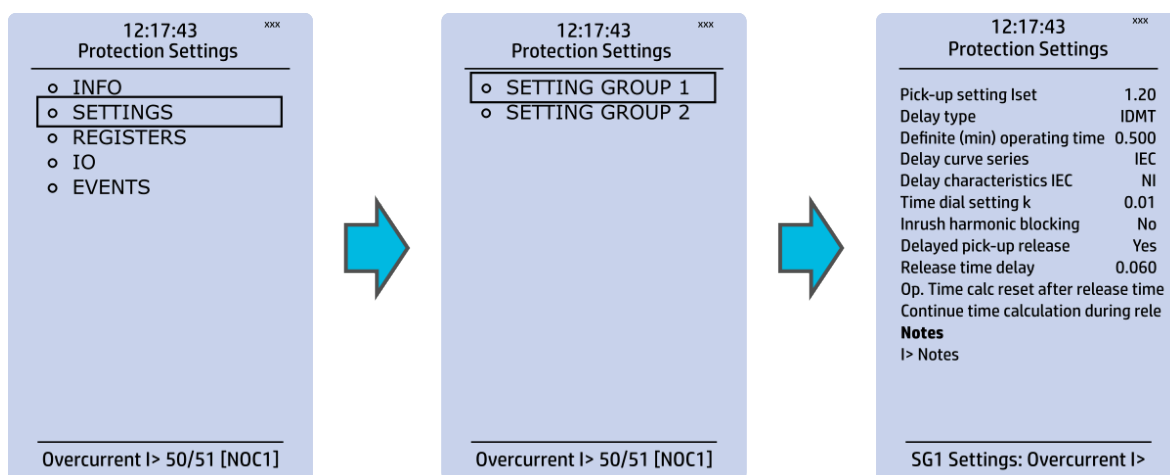


The "Info" section offers many details concerning the function and its status:

- Function condition: indicates the stage's condition which can be Normal, Start, Trip, or Blocked.
- Expected operating time: Expected time delay from detecting a fault to tripping the breaker. This value can vary during a fault if an inverse curve time delay (IDMT) is used.
- Time remaining to trip: When a fault is detected this value counts down towards zero. When zero is reached, the function will trip.
- Im_{meas}/I_{set} at the moment: Displays the ratio between the measured value and the pick-up level.
- Measured magnitude: In some functions it is possible to choose the monitored magnitude between Peak-to-peak, TRMS, or RMS (the default is RMS; the available magnitudes depend on the function).
- Characteristics graphs: opens graphs related to the protection function.
- Statistics: indicates the number of function starts, trips and blocks (can be cleared through "Clear statistics" → "Clear").
- Measurements: displays the measurements carried out by the function.
- Active settings: displays the setting group that is currently in use and its settings (other setting groups can be set in the "Settings" section).

While the function is activated and disabled in the *Stage activation* submenu, you can disable the function through the "Info" section ("Function mode" at the top of the section).

Figure. 3.4 - 12. Settings.

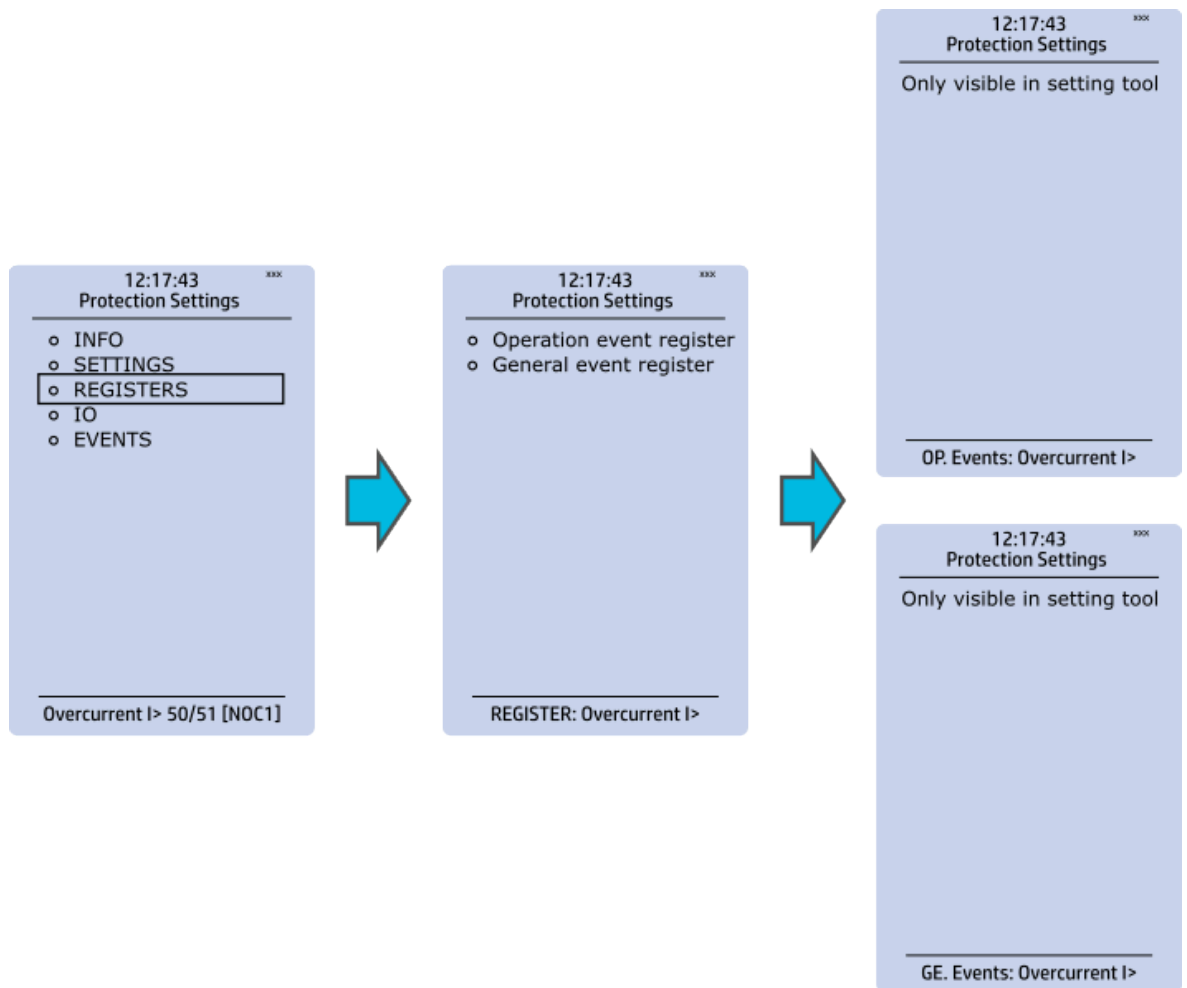


The stage settings vary depending on which protection function they are a part of. By default only one setting group of the eight available setting groups is activated. You can enable more groups in the *Control* → *Setting groups* menu, although they are set here in the "Settings" section.

Most protection functions follow the same structure:

- Pick-up setting: Defines the fault magnitude. Most functions pick-up value is in relation to the current transformer or voltage transformer nominal, but some functions use kW, ohm, Hz and other units. Voltage and current transformers nominal values can be set at *Measurement* → *Transformers*.
- Delay type and operating time delay settings are described in detail in [General properties of a protection function](#) chapter.

Figure. 3.4 - 13. Registers.

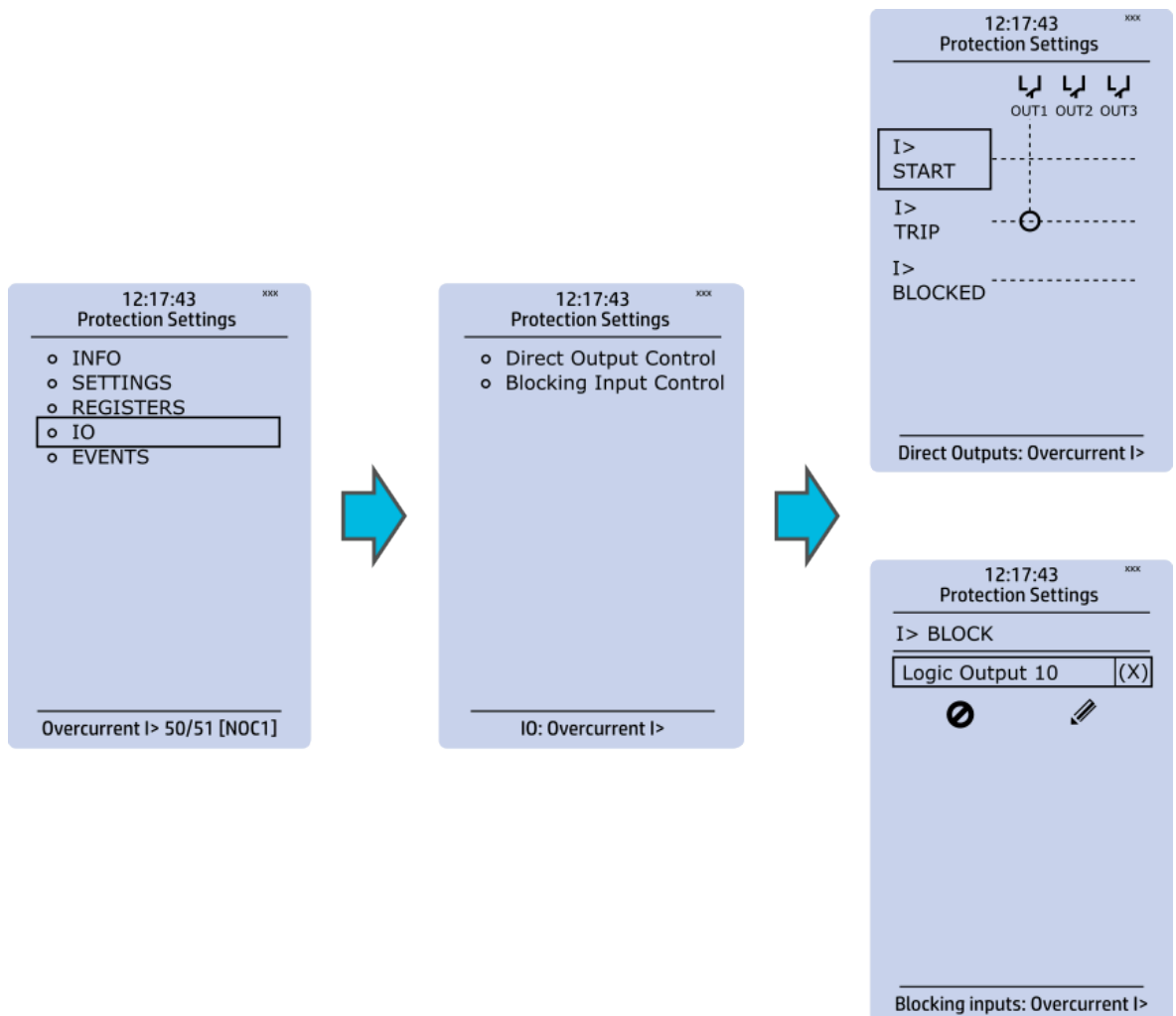


Register menu content is not available in the HMI. It can only be accessed with AQtivate setting tool. Stored in the "Registers" section you can find both "Operation event register" and "General event register".

"Operation event register" stores the function's specific fault data. There are twelve (12) registers, and each of them includes data like the pre-fault value, the fault value, the time stamp and the active group during the trigger. Data included in the register depend on the protection function. You can clear the the operation register by choosing "Clear registers" → "Clear".

"General event register" stores the event generated by the stage. These general event registers cannot be cleared.

Figure. 3.4 - 14. I/O.



The "I/O" section is divided into two subsections: "Direct output control" and "Blocking input control".

In "Direct output control" you can connect the stage's signals to physical outputs, either to an output relay or an LED (START or TRIP LEDs or one of the 16 user configurable LEDs). If the stage is blocked internally (DI or another signal), you can configure an output to indicate the stage that is blocked. A connection to an output can be either latched ("|x|") or non-latched ("x").

"Blocking input control" allows you to block stages. The blocking can be done by using any of the following:

- digital inputs
- logical inputs or outputs
- the START, TRIP or BLOCKED information of another protection stage
- object status information.

Figure. 3.4 - 15. Events.

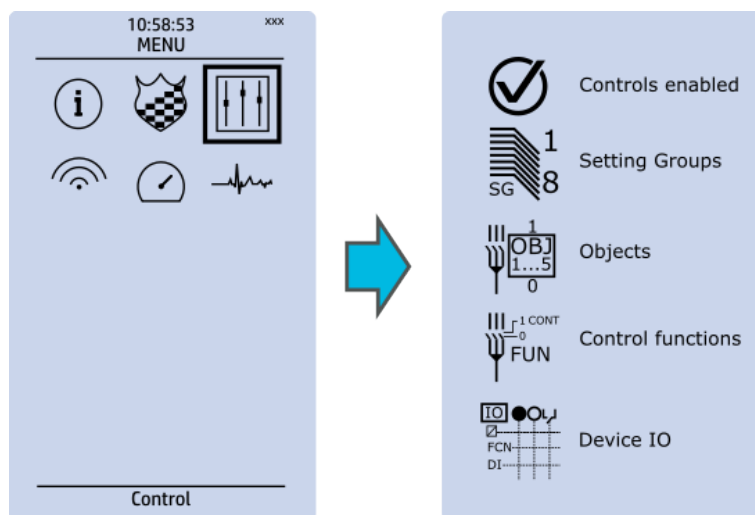


You can mask on and mask off the protection stage related events in "Event mask". By default events are masked off. You can activate the desired events by masking them ("x"). Remember to save your maskings by confirming the changes with the check mark icon. If you want to cancel the changes, select the strike-through circle to do so. Only masked events are recorded to event history (which can be accessed in the "Events" view in the user view section).

3.5 Control menu

Main menu

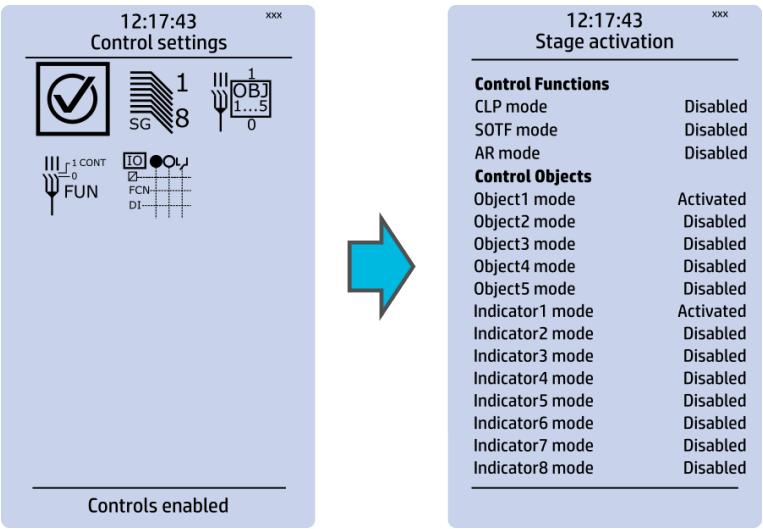
Figure. 3.5 - 16. Main menu structure.



The *Control* main menu includes submenus (see the image above) for enabling the various control functions and objects (*Controls enabled*), for enabling and controlling the setting groups (*Setting groups*), for configuring the objects (*Objects*), for setting the various control functions (*Control functions*), and for configuring the inputs and outputs (*Device I/O*). The available control functions depend on the model of the device in use.

Controls enabled

Figure. 3.5 - 17. Controls enabled submenu.

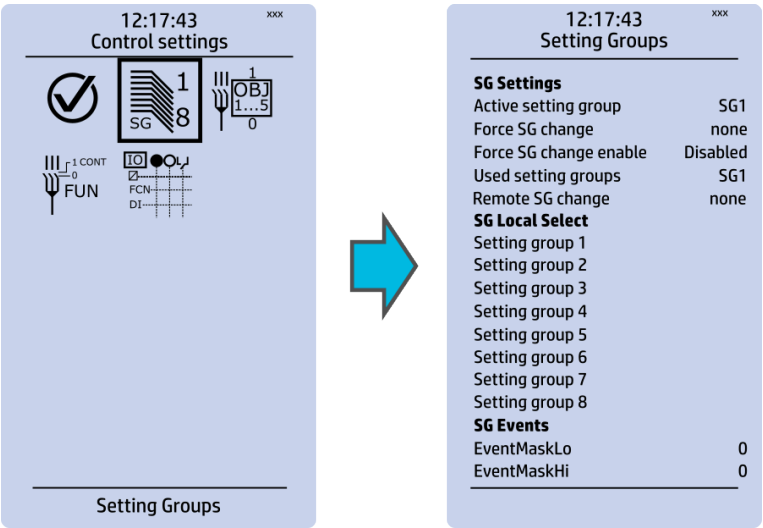


You can activate the selected control functions in the *Controls enabled* submenu. By default all the control functions are disabled. All activated functions can be viewed in the *Control functions* submenu (see the section "Control functions" below for more information).

In this submenu you can also activate and disable controllable objects. As with control functions, all objects are disabled by default. All activated objects can be viewed in the *Objects* submenu (see the section "Objects" below for more information).

Setting groups

Figure. 3.5 - 18. Setting groups submenu.



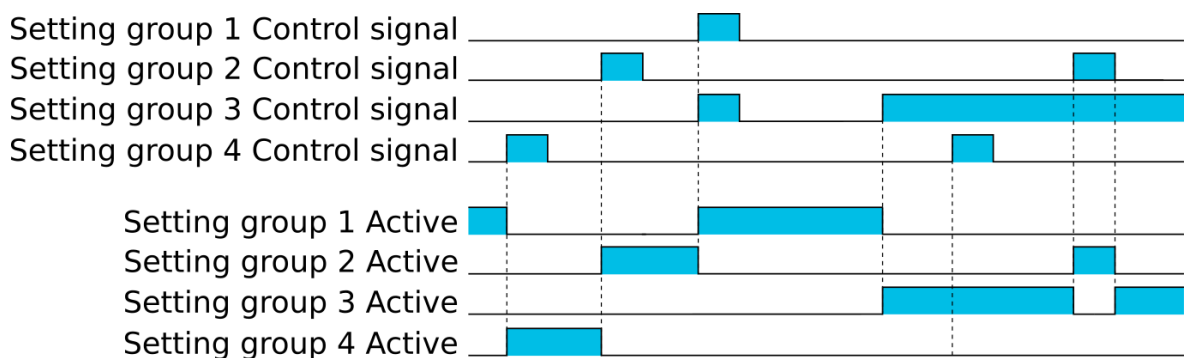
The *Setting groups* submenu displays all the information related to setting group changing, such as the following:

- **Active setting group:** displays the current active setting group (SG1...SG8).
- **Force setting group change:** this setting allows the activation of a setting group at will (please note that Force SG change enable must be "Enabled").

- **Used setting groups:** this setting allows the activation of setting groups SG1...SG8 (only one group is active by default).
- **SG local select:** selects the local control for the different setting groups (can use digital inputs, logical inputs or outputs, RTDs, object status information as well as stage starts, trips or blocks).
- **Remote setting group change:** When enabled it is possible to change the setting group manually through SCADA.
- **SG events:** event masking for setting groups (masks are OFF by default; please note that only masked events are recorded into the event history).

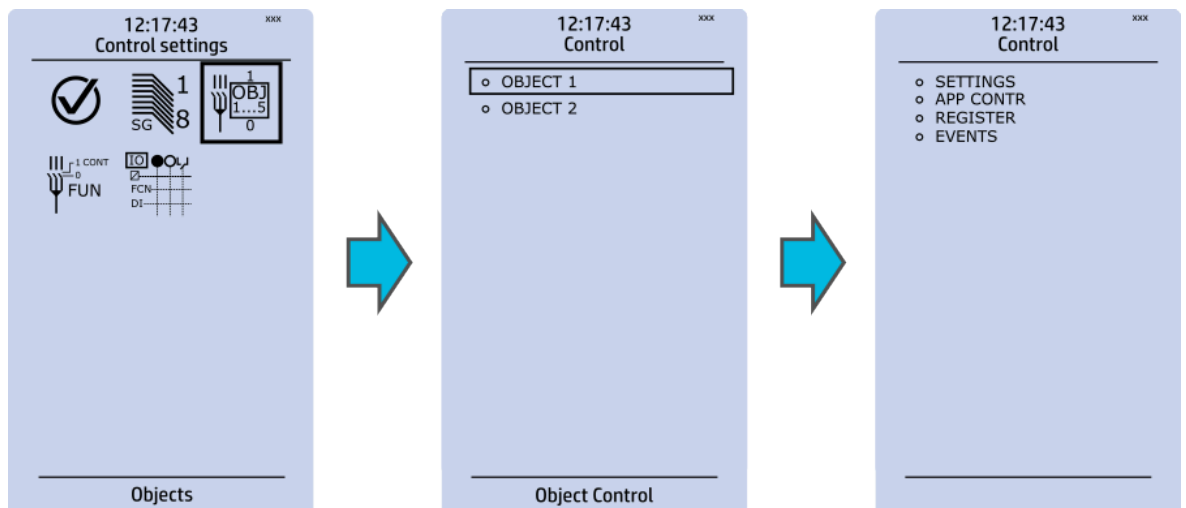
Setting group 1 (SG1) has the highest priority, while Setting group 8 (SG8) has the lowest priority. Setting groups can be controlled with pulses or with both pulses and static signals (see the image below).

Figure. 3.5 - 19. Example of setting group (SG) changing.



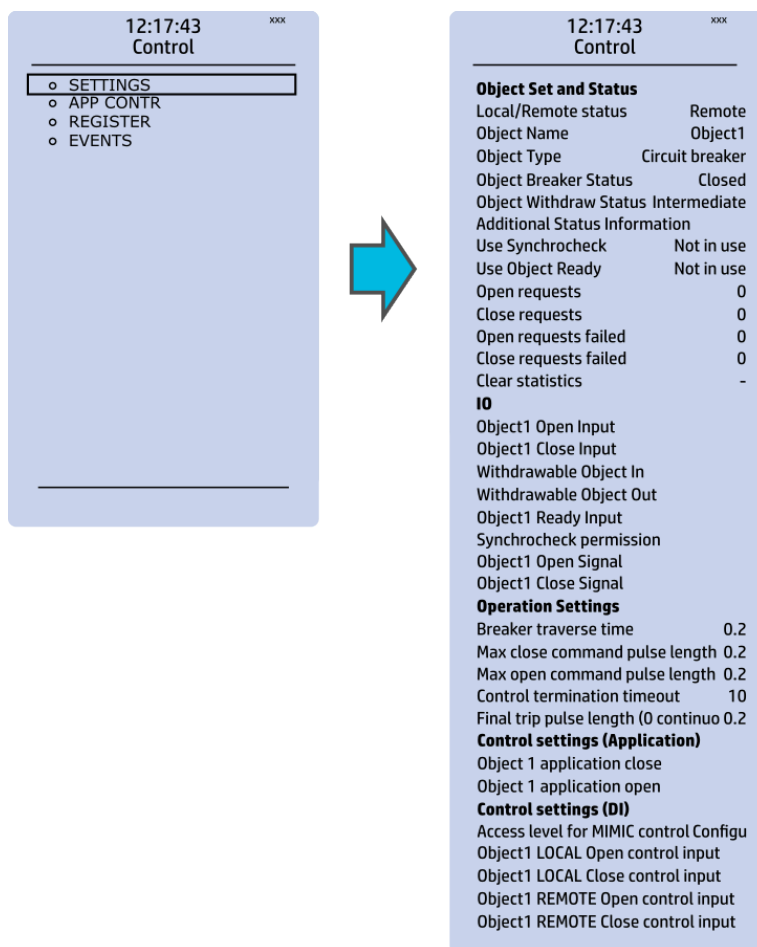
Objects

Figure. 3.5 - 20. Objects submenu.



Each activated object is visible in the *Objects* submenu. By default all objects are disabled unless specifically activated in the *Controls* → *Controls enabled* submenu. Each active object has four sections in their submenus: "Settings", "Application control" ("App contr"), "Registers" and "Events". These are described in further detail below.

Figure. 3.5 - 21. Settings section.



OBJECT SET AND STATUS

- **Local/Remote status:** control access may be set to Local or Remote (Local by default; please note that when local control is enabled, the object cannot be controlled through the bus and vice versa).
- **Object name:** the name of the object (objects are named "ObjectX" by default).
- **Object type:** selects the type of the object from Grounding disconnector, Motor-controlled disconnector, Circuit breaker and Withdrawable circuit breaker (Circuit breaker by default).
- **Object x status:** the status can be Bad, Closed, Open and Intermediate. The status "Intermediate" is the phase between "Open" and "Closed" where both status inputs are 0. The status "Bad" occurs when both status inputs of the object/cart are 1.
- **Additional status information:** gives feedback from the object on whether the opening and closing are allowed or blocked, whether the object is ready, and whether the synchronization status is ok.
- **Use synchrocheck and Use Object ready:** closing the object is forbidden when the sides are not synchronized or when the object is not ready to be closed.
- **Open requests and Close requests:** displays the statistics, i.e. the number of Open and Close requests.
- **Open requests failed and Close requests failed:** displays the statistics of Open and Close request failures. A request is considered to have failed when the object does not change its status as a result of that request.
- **Clear statistics:** statistics can be cleared by choosing "Clear statistics" and then "Clear".

I/O

- An object has both **Open input** and **Close input** signals which are used for indicating the status of the breaker on the HMI and in SCADA. Status can be indicated by any of the following: digital inputs, logical inputs or outputs.
- A withdrawable object has both **In** and **Out** inputs. The status can be indicated by any of the following: digital inputs, logical inputs or outputs.
- Both **Object ready** and **Synchrocheck permission** have status inputs. If either one is used, the input(s) must be active for the device to be able to give the "Object Close" command.
- **Object open** and **Object close** signals define which digital output is controlled.

OPERATION SETTINGS

- **Breaker traverse time:** determines how long a gap there can be between a status change from "Open" to "Closed" before an intermediate status is reported by the function.
- **Max close/open command pulse length:** defines the maximum length of "Open" and "Close" commands. If the status has changed before the maximum pulse length has elapsed, the pulse is cut short.
- **Control termination timeout:** If the status of the object does not change during the set time, an "Open/Close request failed" event is recorded.
- After the set delay, if the controlled object does not respond accordingly, the procedure is terminated and a fail message is issued.

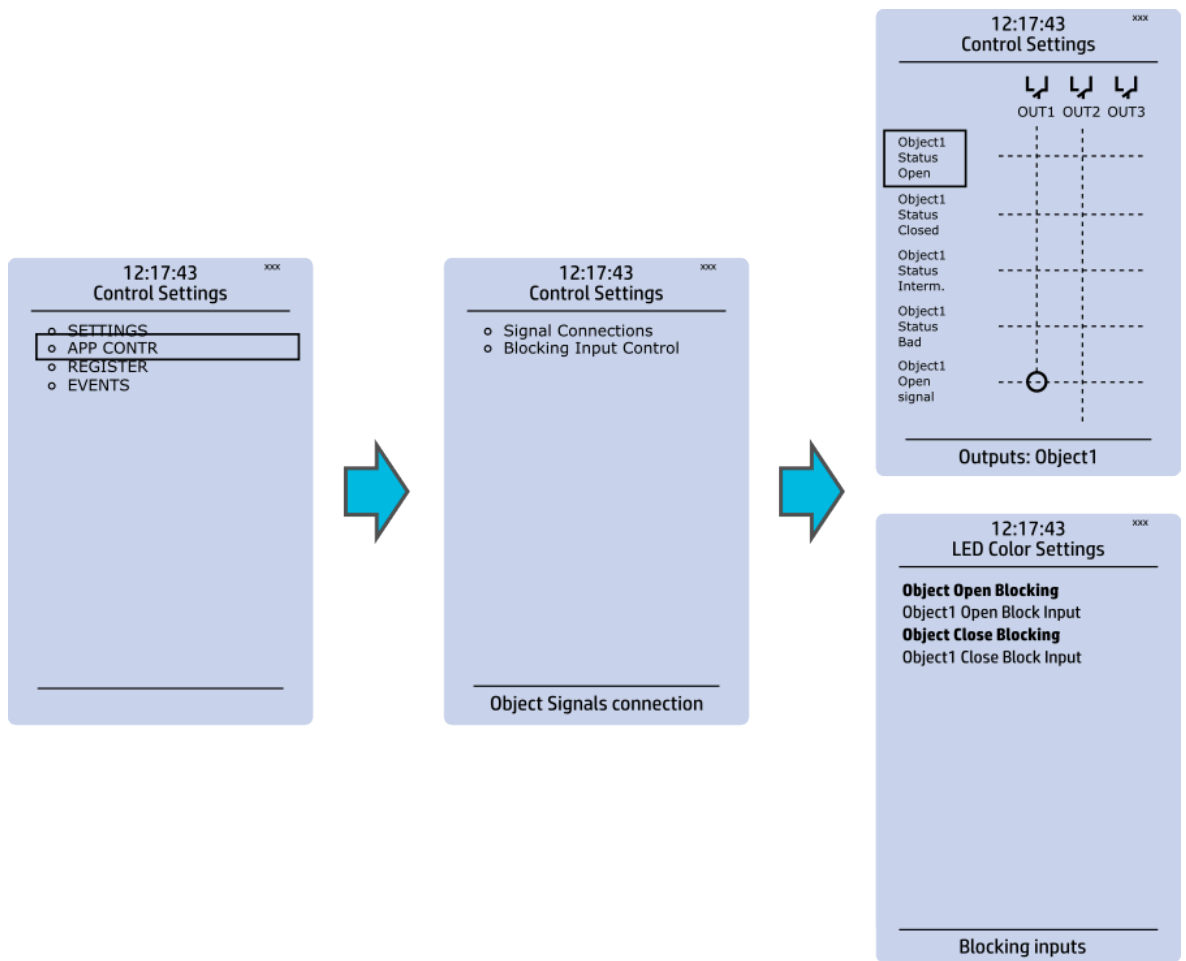
CONTROL SETTINGS (APPLICATION)

- **Object application close** and **Object application open:** a signal set to these points can be used to open and close the object. Controlling the object through this point does not follow the local/remote status of the device.

CONTROL SETTINGS (DI)

- **Access level for MIMIC control:** determines the access level required to control the MIMIC (each level has its own password). By default, the access level is set to "Configurator".
- You can use digital inputs to control the object locally or remotely. Remote controlling via the bus is configured on the protocol level.

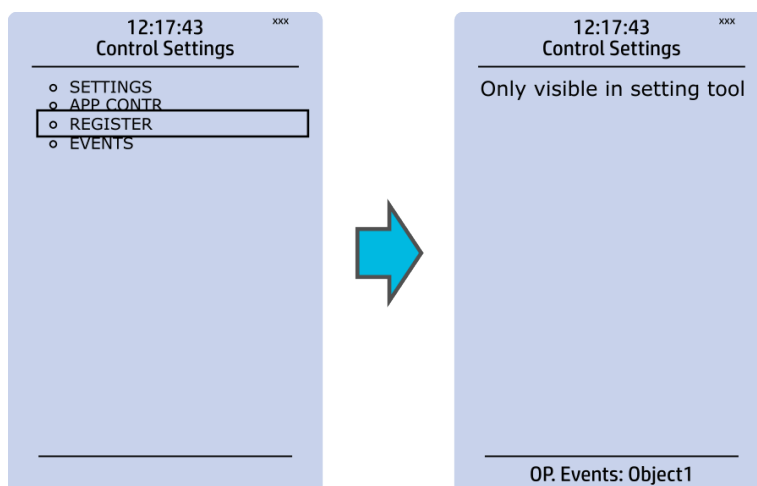
Figure. 3.5 - 22. Application control section.



You can connect object statuses directly to specific physical outputs in the "Signal connections" subsection (*Control* → *Application control*). A status can be connected to output relays, as well as to user-configurable LEDs. A connection to an output can be either latched ("|x|") or non-latched ("x").

Object blocking is done in the "Blocking input control" subsection. It can be done by any of the following: digital inputs, logical inputs or outputs, object status information as well as stage starts, trips or blocks.

Figure. 3.5 - 23. Registers section.



The "Registers" section stores the function's specific fault data. There are twelve (12) registers, and each of them includes data such as opening and closing times, command types and request failures. The data included in the register depend on the protection function. You can clear the the operation register by choosing "Clear registers" → "Clear".

Please note that the content of the *Registers* section is not available in the HMI. It can only be accessed via the AQtivate setting tool.

Figure. 3.5 - 24. Events section.

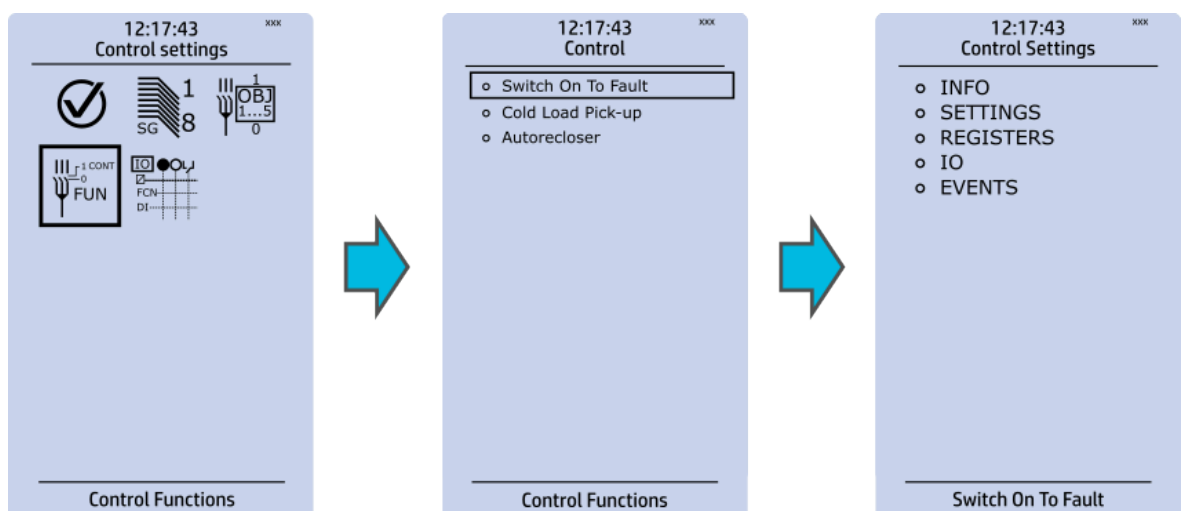


You can mask on and mask off events related to an object's stage in "Event mask". By default all events are masked off. You can activate the desired events by masking them ("x"). Please remember to save your maskings by confirming the changes with the check mark icon. If you want to cancel the changes, select the strike-through circle to do so. Only masked events are recorded to the event history (which can be accessed in the "Events" view in the user view section).

Control functions

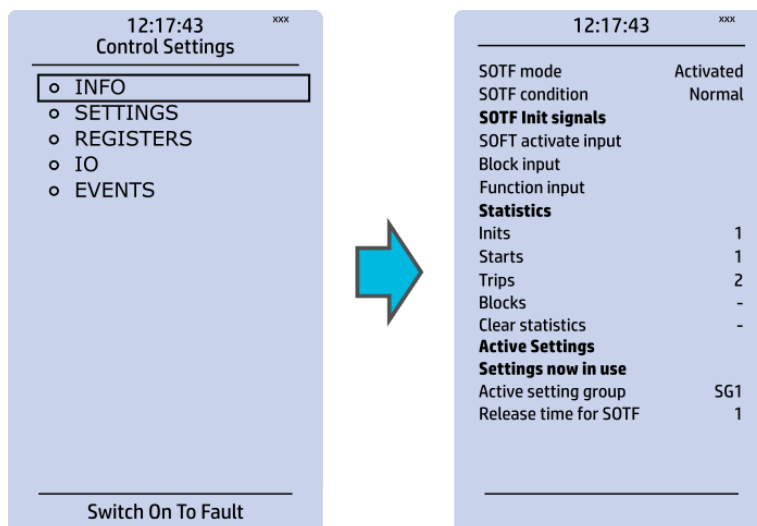
Once a control function has been activated in the *Controls* → *Controls enabled* submenu, its own submenu can be opened. In the image series below, the user has activated three control functions. The user accesses the list of activated control stages through the "Control functions" module, and selects the control function for further inspection.

Figure. 3.5 - 25. Control functions submenu.



Each control function that has been activated is listed in the *Control functions* submenu (see the middle image above). This submenu includes the following sections: "Info", "Settings", "Registers", "I/O" and "Events". The text below describes these in further detail.

Figure. 3.5 - 26. Info section.

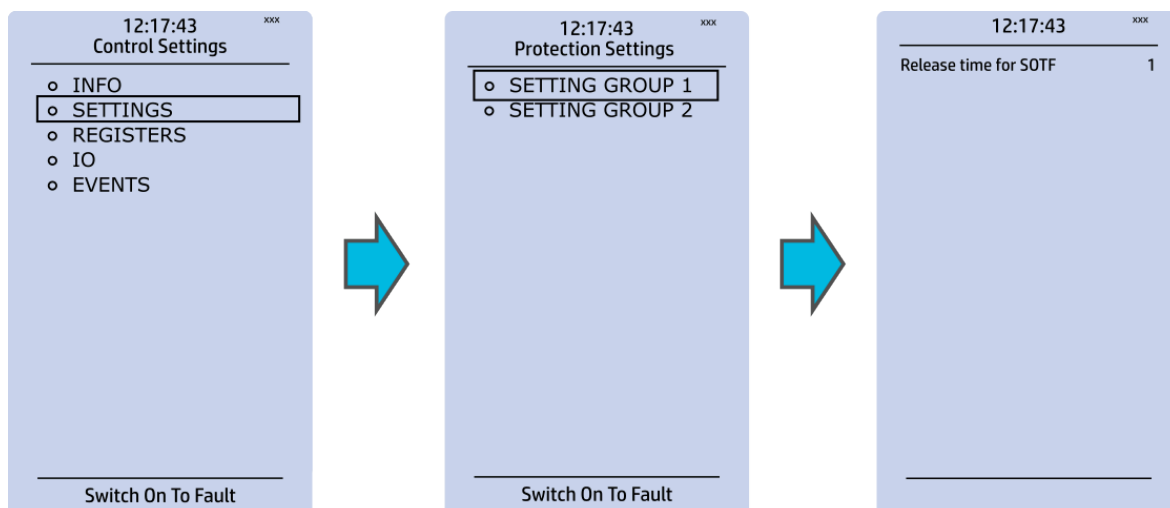


The "Info" section offers many details concerning the function and its status:

- **Function condition**: indicates the stage's condition which can be Normal, Start, Trip, or Blocked.
- **Measured magnitude**: In some functions it is possible to choose the monitored magnitude between Peak-to-peak, TRMS, or RMS (the default is RMS; the available magnitudes depend on the function).
- **Statistics**: indicates the number of function starts, trips and blocks (can be cleared through "Clear statistics" → "Clear").
- **Measurements**: displays the measurements carried out by the function.
- **Active settings**: displays the setting group that is currently in use and its settings (other setting groups can be set in the "Settings" section).

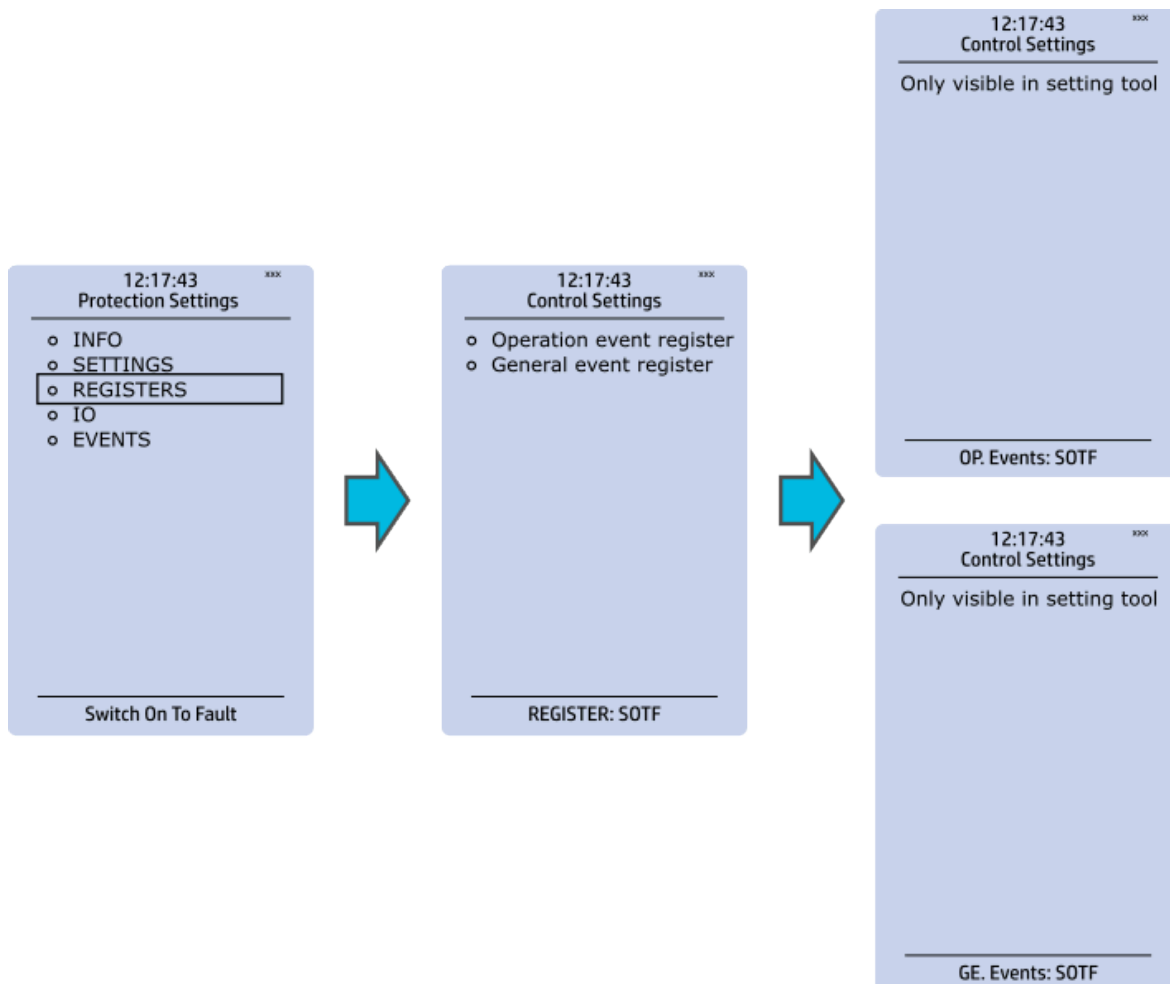
While the function is activated and disabled in the *Control* → *Controls enabled* submenu, you can disable the function through the "Info" section (the [function name] mode at the top of the section).

Figure. 3.5 - 27. Settings section.



The stage settings vary depending on which control function they are a part of. By default only one setting group of the eight available setting groups is activated. You can enable more groups in the *Control → Setting groups* menu, although they are set here in the "Settings" section.

Figure. 3.5 - 28. Registers section.

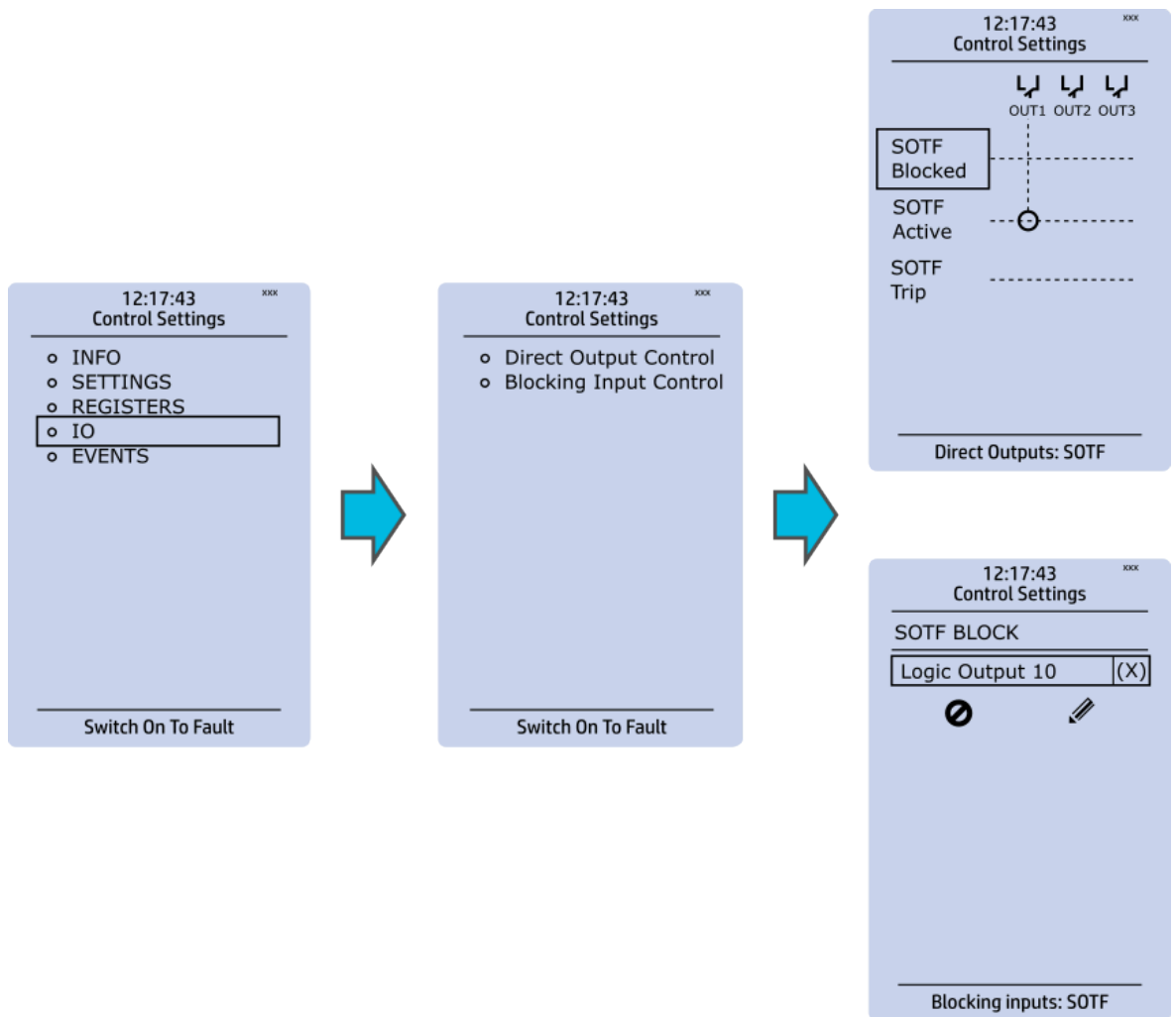


Please note that the content of the "Registers" section is not available in the HMI. It can only be accessed via the AQtivate setting tool. Stored in the "Registers" section you can find both "Operation event register" and "General event register".

"Operation event register" stores the function's specific operation data. There are twelve (12) registers, and each of them includes data like the pre-fault value, the fault value, the time stamp and the active group during the trigger. Data included in the register depend on the control function. You can clear the the operation register by choosing "Clear registers" → "Clear".

"General event register" stores the event generated by the stage. These general event registers cannot be cleared.

Figure. 3.5 - 29. I/O section.



The "I/O" section is divided into two subsections: "Direct output control" and "Blocking input control".

In "Direct output control" you can connect the stage's signals to physical outputs, either to an output relay or an LED (START or TRIP LEDs or one of the 16 user configurable LEDs). If the stage is blocked internally (by a digital input or another signal), you can configure an output to indicate the stage that is blocked. A connection to an output can be either latched ("X") or non-latched ("x").

"Blocking input control" allows you to block stages. The blocking can be done by using any of the following:

- digital inputs.
- logical inputs or outputs.
- the START, TRIP or BLOCKED information of another protection stage.
- object status information.

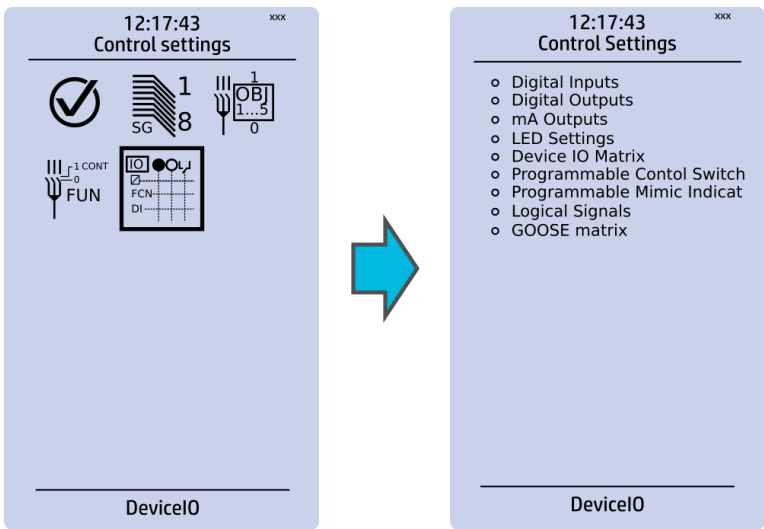
Figure. 3.5 - 30. Events section.



You can mask on and mask off events related to an object's stage in "Event mask". By default all events are masked off. You can activate the desired events by masking them ("x"). Please remember to save your maskings by confirming the changes with the check mark icon. If you want to cancel the changes, select the strike-through circle to do so. Only masked events are recorded to the event history (which can be accessed in the "Events" view in the user view section).

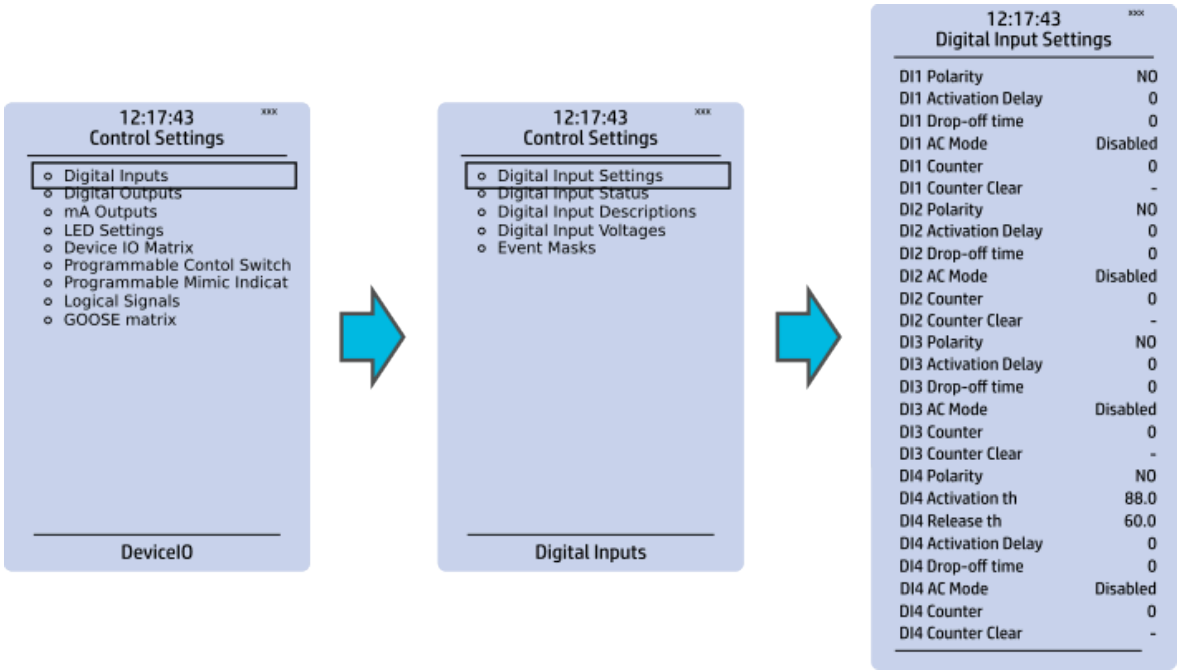
Device I/O

Figure. 3.5 - 31. Device I/O submenu.



The *Device I/O* submenu is divided into the following nine sections: "Digital inputs", "Digital outputs", "mA Outputs", "LED settings", "Device I/O matrix", "Programmable control switch", "Programmable Mimic Indicator", "Logic signals" and "GOOSE matrix". Please note that digital inputs, logic outputs, protection stage status signals (START, TRIP, BLOCKED, etc.) as well as object status signals can be connected to an output relay or to LEDs in the "Device I/O matrix" section.

Figure. 3.5 - 32. Digital input section.

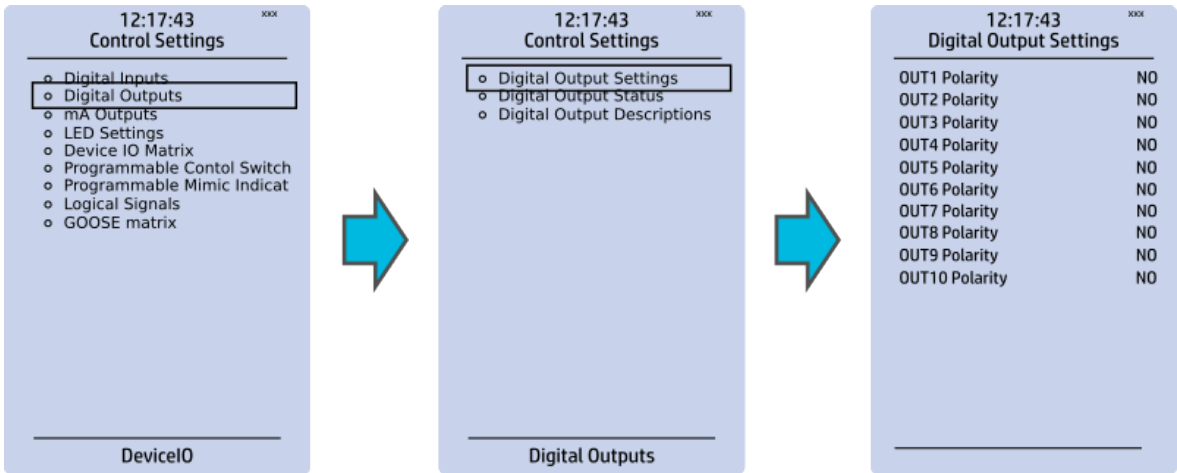


All settings related to digital inputs can be found in the "Digital inputs" section.

The "Digital inputs settings" subsection includes various settings for the inputs: the polarity selection determines whether the input is Normal Open (NO) or Normal Closed (NC) as well as the activation threshold voltage (16...200 V AC/DC, step 0.1 V) and release threshold voltage (10...200 V AC/DC, step 0.1 V) for each available input. There is also a setting to determine the wanted activation and release delay (0...1800 s, step 1 ms). Digital input activation and release threshold follow the measured peak value. The activation time of an input is 5...10 ms. The release time with DC is 5...10 ms, while with AC it is less than 25 ms. The first three digital inputs don't have activation and release threshold voltage settings as these have already been defined when the unit was ordered.


Digital input statuses can be checked from the corresponding subsection ("Digital input status"). The "Digital input descriptions" subsection displays the texts the user has written for each digital input. In the "Event masks" subsection you can determine which events are masked –and therefore recorded into the event history– and which are not.

Figure. 3.5 - 33. Digital outputs section.



All settings related to digital outputs can be found in the "Digital outputs" section.

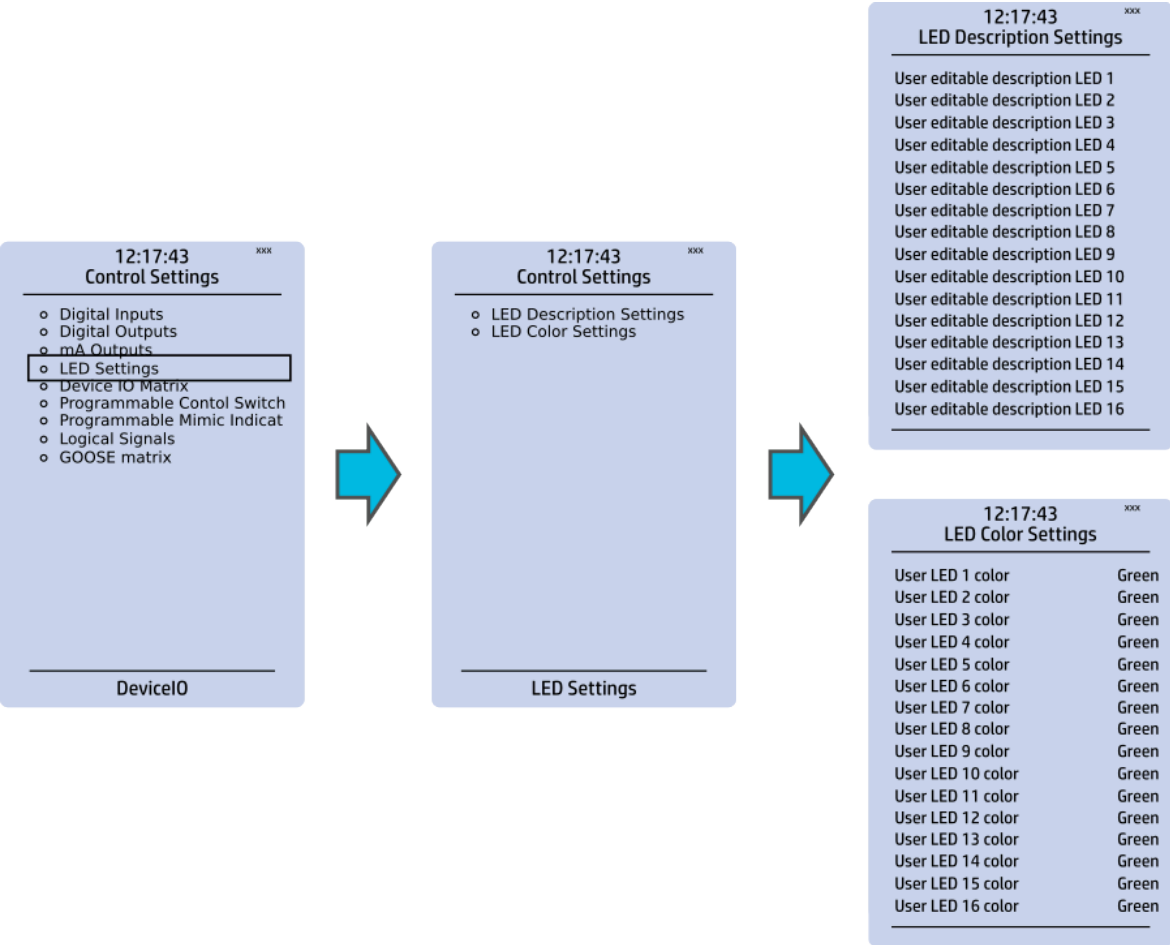
The "Digital outputs settings" subsection lets you select the polarity for each output; they can be either Normal Open (NO) or Normal Closed (NC). The default polarity is Normal Open. The operational delay of an output contact is approximately 5 ms. You can view the digital output statuses in the corresponding subsection ("Digital output status"). The "Digital output descriptions" subsection allows you to configure the description text for each output. All name changes affect the matrices as well as input–output selection lists.



NOTICE!

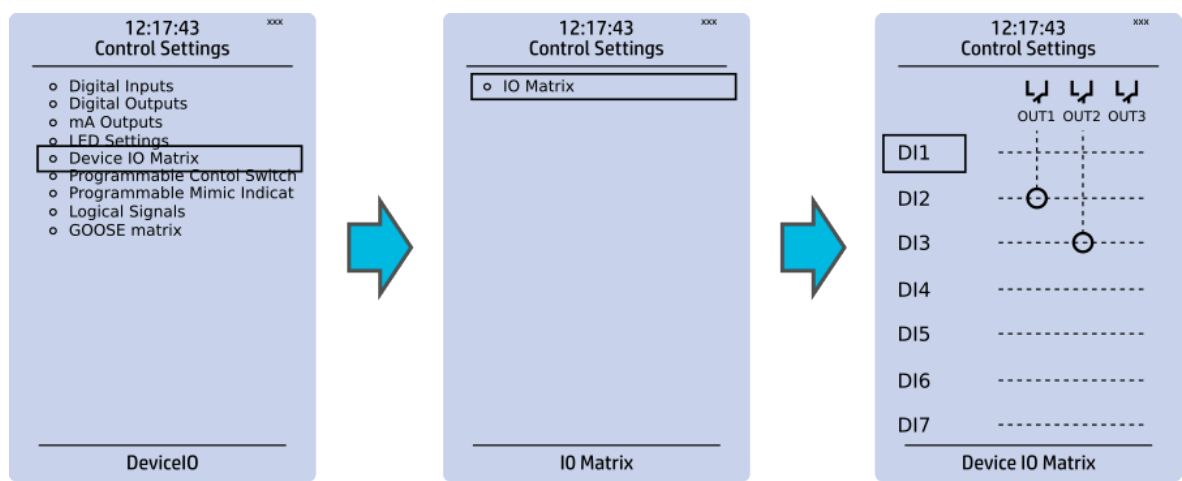
An NC signal goes to the default position (NO) if the device loses the auxiliary voltage or if the system is fully reset. However, an NC signal does not open during voltage or during System full reset. An NC output signal does not open during a Communication or Protection reset.

Figure. 3.5 - 34. LED settings section.



The "LED settings" section allows you to modify the individual label text attached to an LED ("LED description settings"); that label is visible in the LED quick displays and the matrices. You can also modify the color of the LED ("LED color settings") between green and yellow; by default all LEDs are green.

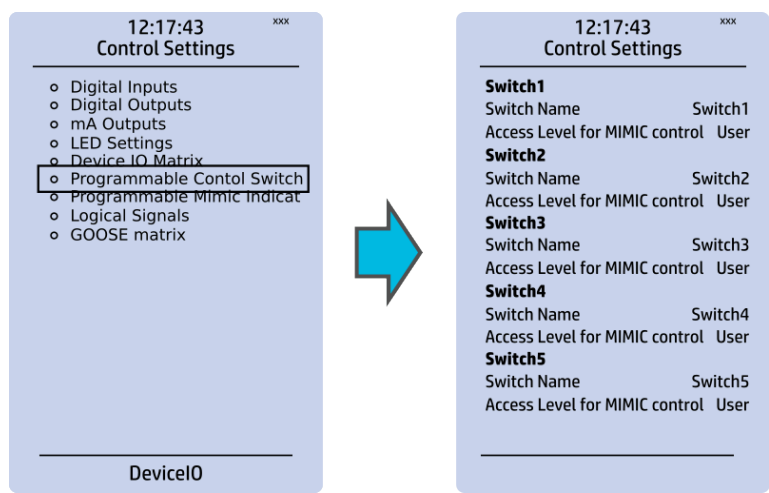
Figure. 3.5 - 35. Device I/O matrix section.



Through the "Device I/O matrix" section you can connect digital inputs, logical outputs, protection stage status signals (START, TRIP, BLOCKED, etc.), object status signals and many other binary signals to output relays, or to LEDs configured by the used. A connection can be latched ("|x|") or non-latched ("x"). Please note that a non-latched output is deactivated immediately when the triggering signal is disabled, while a latched signal stays active until the triggering signal deactivates and the latched function is manually cleared.

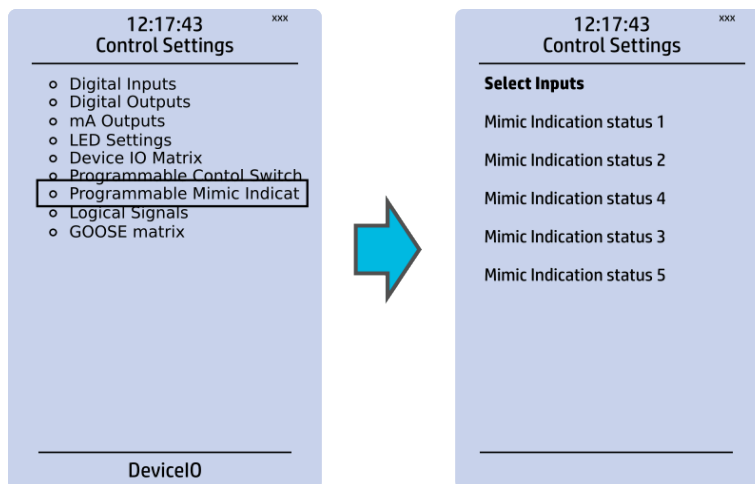
You can clear latched signals by entering the mimic display and the pressing the **Back** button on the panel.

Figure. 3.5 - 36. Programmable control switch section.



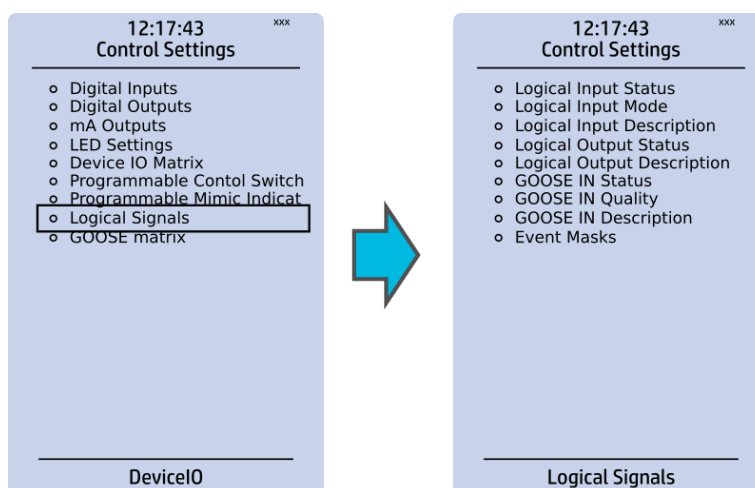
Programmable control switches (PCSs) are switches that can be used to control signals while in the mimic view. These signals can be used in a variety of situations, such as for controlling the logic program, for function blocking, etc. You can name each switch and set the access level to determine who can control the switch.

Figure. 3.5 - 37. Programmable mimic indicators section.



Programmable mimic indicators can be placed into the mimic to display a text based on the status of a given binary signal (digital input, logical signal, status of function start/tripped/blocked signals etc.). When configuring the mimic with the AQtivate 200 setting tool, it is possible to set a text to be shown when an input signal is ON and a separate text for when the signal is OFF.

Figure. 3.5 - 38. Logical signals section.



All AQ 200 series units have the following types of logical signals:

- 32 logical input signal status bits; the status of a bit is either 0 or 1.
- 32 logical output signal status bits; the status of a bit is either 0 or 1.
- 64 GOOSE input signal status bits; the status of a bit is either 0 or 1.
- 64 quality bits for GOOSE input signals; the status of a bit is either 0 or 1.

Logical input signals can be used when building a logic with the AQtivate 200 setting tool. The status of a logical input signal can be changed either from the mimic or through SCADA. By default logical inputs use "Hold" mode in which the status changes from 0 to 1 and from 1 to 0 only through user input. The mode of each input can be changed to "Pulse" in which a logical input's status changes from 0 to 1 through user input and then immediately back to 0.

Logical output signals can be used as the end result of a logic that has been built in the AQtivate 200 setting tool. The end result can then be connected to a digital output or a LED in the matrix, block functions and much more.

GOOSE inputs are mainly used for controlling purposes and in conjunction with the IEC 61850 communication protocol. There are 64 GOOSE inputs signal status bits, and their status can be either 0 or 1. "GOOSE IN quality" checks the quality of a GOOSE input message. There are 64 GOOSE input quality signals, and their status can be either 0 ("Good" or "Valid") or 1 ("Bad" or "Invalid"). Logical outputs can be used when building a programmable logic. Activating a logic gate does not create an event but when a logical output is connected to a logic gate it is possible to create an event from the gate's activation. All logical inputs and outputs have both ON and OFF events, and they can be masked on when necessary (they are masked off by default).

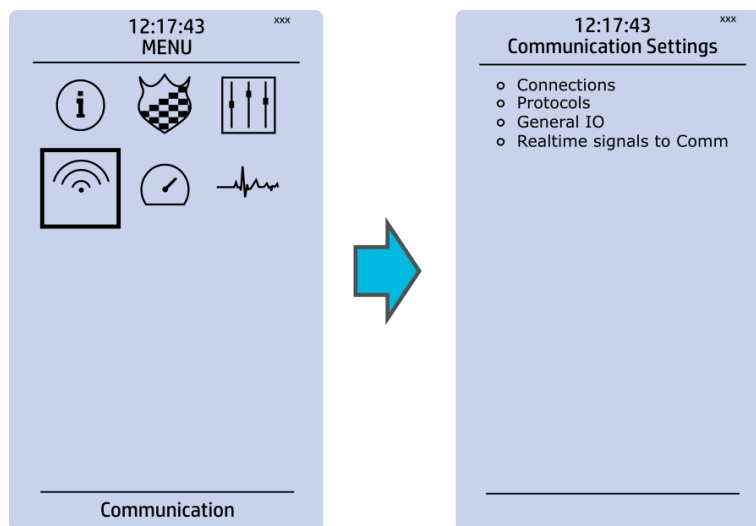


NOTICE!

Please refer to the "[Communication](#)" chapter for a more detailed description of the use of logical signals.

3.6 Communication menu

Figure. 3.6 - 39. Communication menu.

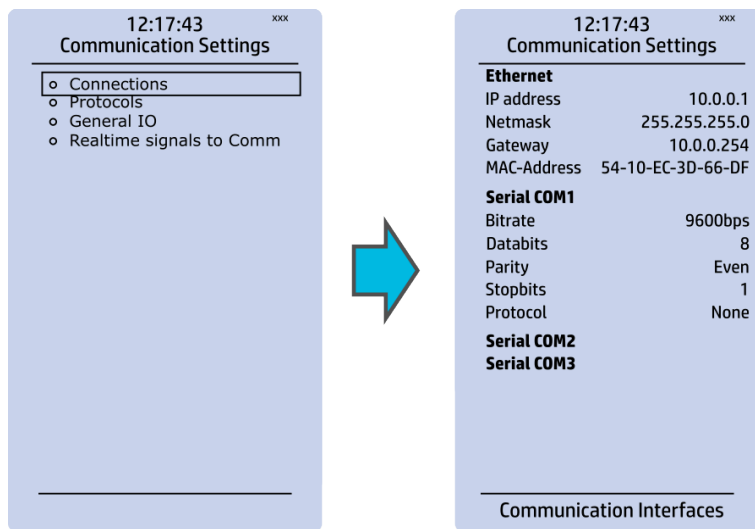


The *Communication* main menu includes four submenus (as seen in the figure above): *Connections*, *Protocols*, *General IO* and *Realtime signals to Comm*. All devices can be configured through the Ethernet connection in the back panel with the AQtivate 200 setting tool software. Connecting to AQtivate requires knowing the IP address of your device: this can be found in the *Communication* → *Connections* submenu. As a standard, the devices support the following communication protocols:

- NTP
- IEC 61850
- Modbus/TCP
- Modbus/RTU
- IEC-103
- IEC -101/104
- SPA
- DNP3
- ModbusIO.

Connections

Figure. 3.6 - 40. View of the Connections submenu.



The *Connections* submenu offers the following bits of information and settings:

ETHERNET

This section defines the IP settings for the Ethernet port in the back panel of the unit.

- IP address: the IP address of the device which can be set by the user (the default IP address depends on the device).
- Network: the network subnet mask is entered here.
- Gateway: the gateway is configured only when communicating with devices in a separate subnet.
- MAC-Address: The unique MAC address of the device, which is **not** configurable by the user.

SERIAL COM

This section defines the basic settings of the RS-485 port in the back panel of the unit.

- Baudrate: displays the baudrate of the RS-485 serial communication interface (9600 bps as standard, although it can be changed to 19,200 bps or to 38,400 bps if an external device supports the faster speed).
- Databits, Parity and Stopbits: these can be set according to the connected external devices.
- Protocol: by default the device does not have any serial protocol activated, although IEC 103, Modbus I/O and Modbus/RTU can be used for communication.



NOTICE!

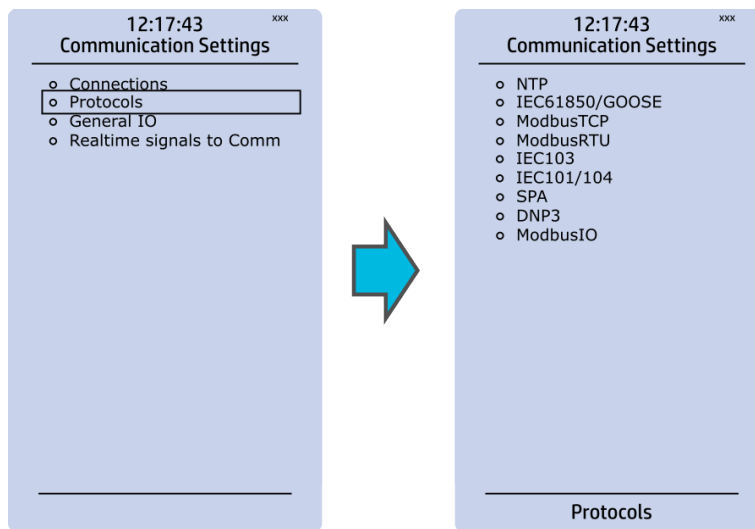
When communicating with a device via the front Ethernet port connection, the IP address is always 192.168.66.9.

SERIAL COM1 & COM2

SERIAL COM1 and SERIAL COM2 are reserved for serial communication option cards. They have the same settings as the RS-485 port.

Protocols

Figure. 3.6 - 41. View of the Protocols submenu.



The *Protocols* submenu offers access to the various communication protocol configuration menus. Some of the communication protocols use serial communication and some use Ethernet communication. Serial communication protocols can be used either with the RS-485 port that is in AQ 200 series units by default, or with a serial communication option card. Ethernet communication protocols can be used either with the RJ-45 port in the back of the unit or with an Ethernet communication option card.

The communication protocols are:

- NTP: this protocol is used for time synchronization over Ethernet, and can be used simultaneously with Ethernet-based communication protocols.
- IEC 61850: an Ethernet-based communication protocol.
- Modbus/TCP: an Ethernet-based communication protocol.
- Modbus/RTU: a serial communication protocol.
- IEC-103: a serial communication protocol.
- IEC-101/104: since the standards IEC 60870-5-101 and IEC 60870-5-104 are closely related, the IEC-101 protocol uses serial communication on the physical layer, whereas the IEC-104 protocol uses Ethernet communication.
- SPA: a serial communication protocol.
- DNP3: supports both serial and Ethernet communication.
- ModbusIO: used for connecting external devices like ADAM RTD measurement units.

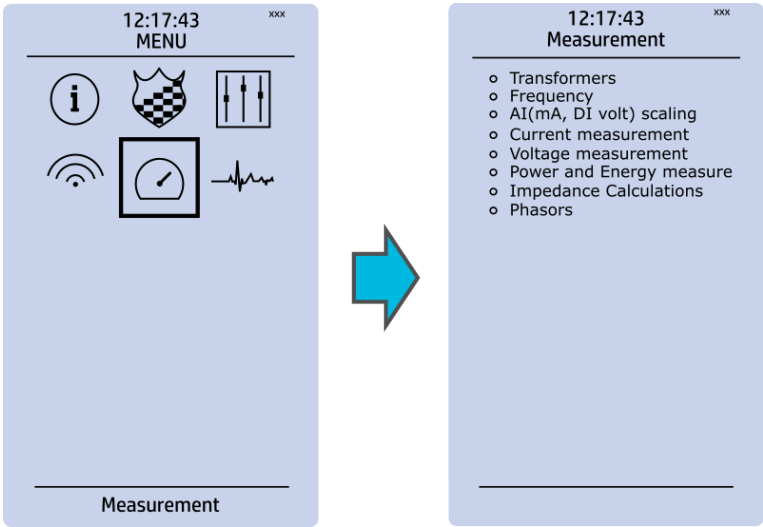


NOTICE!

Please refer to the "[Communication](#)" chapter for a more detailed text on the various communication options.

3.7 Measurement menu

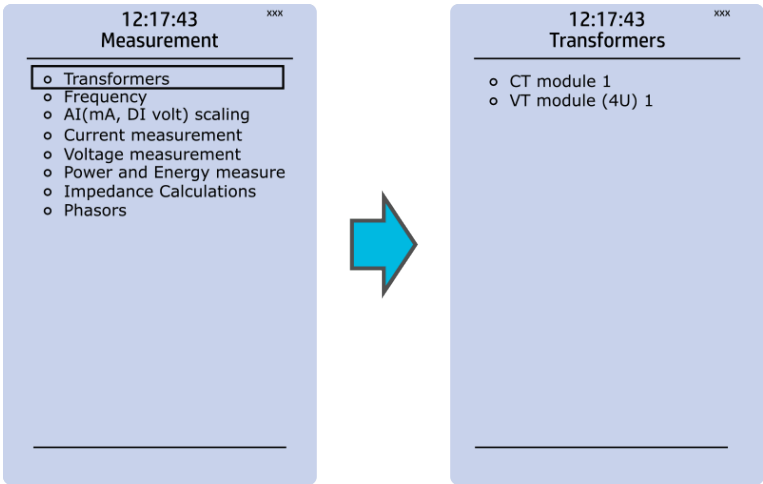
Figure. 3.7 - 42. Measurement section.



The *Measurement* menu includes the following submenus: *Transformers*, *Frequency*, *Current measurement*, *Voltage measurement*, *Power and energy measurement*, *Impedance calculations*, and *Phasors*. The available measurement submenus depends on the type of device in use. The ratio used by the current and voltage transformers is defined in the *Transformers* submenu, while the system nominal frequency is specified in the *Frequency* submenu. Other submenus are mainly for monitoring purposes.

Transformers

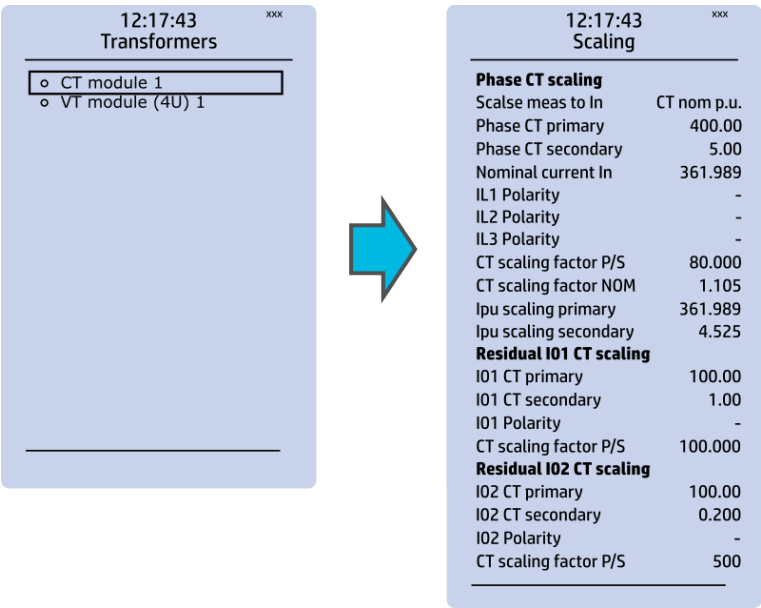
Figure. 3.7 - 43. Transformers section.



Transformers menu is used for setting up the measurement settings of available current transformer modules or voltage transformer modules. Some unit types have more than one CT or VT module. Some unit types like AQ-S214 do not have current or voltage transformers at all.

CT module

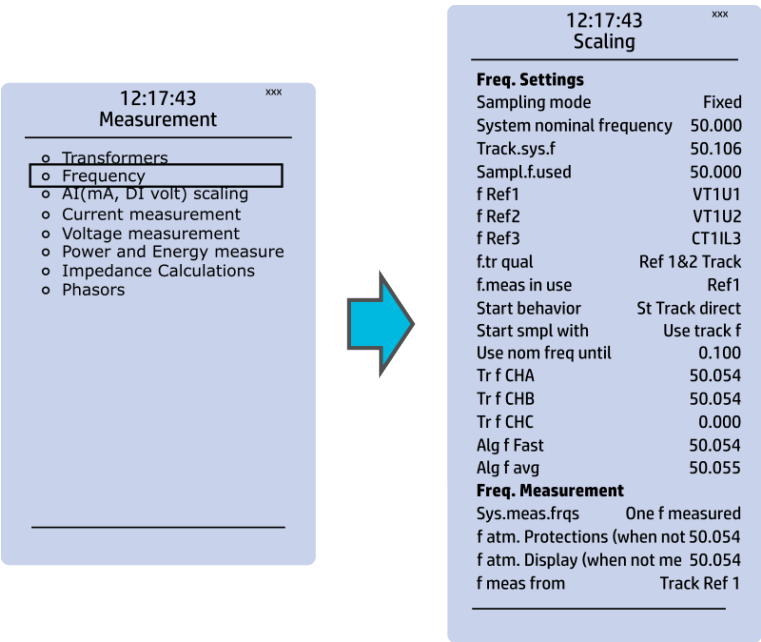
Figure. 3.7 - 44. CT module section.



The three main sections ("Phase CT scaling", "Residual I01 CT scaling" and "Residual I02 CT scaling") determine the ratio of the used transformers. Additionally, the nominal values are also determined in the *CT module* submenu. Sometimes a mistake in the wiring can cause the polarity to be changed; in such cases, you can invert the polarity of each phase current individually. The *CT module* submenu also displays additional information such as CT scaling factors and per-unit scaling factors.

Frequency

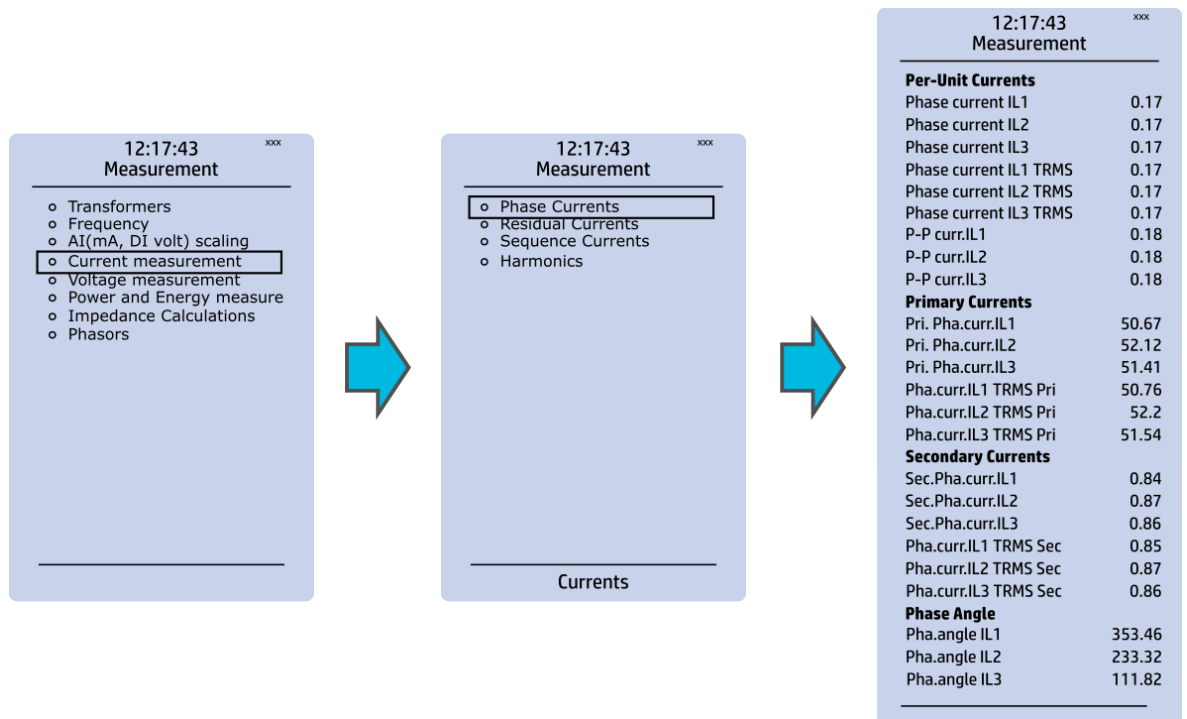
Figure. 3.7 - 45. Frequency submenu.



Frequency measurements use the fixed sampling mode as the default, and "System nominal frequency" should be set to the desired level. When "Sampling mode" is set to "Tracking", the device uses the measured frequency value as the system nominal frequency. There are three frequency reference channels: f Ref1, fRef2 and fRef3. With these parameters it is possible to set up three voltage or current channels to be used for frequency sampling. Parameter "f.meas in use" indicates which of the three channels are used for sampling if any.

Current measurement

Figure. 3.7 - 46. Current measurement submenu.



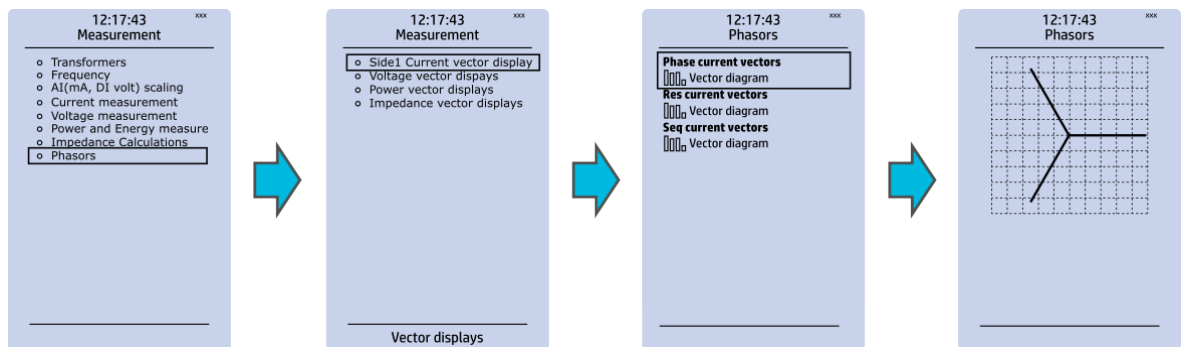
Current measurement submenu includes various individual measurements for each phase or phase-to-phase measurement.

The *Current measurement* submenu has been divided into four sections: "Phase currents", "Residual currents", "Sequence currents", and "Harmonics".

- "Phase currents" and "Residual currents" have been further divided into four subsections ("Per-unit currents", "Primary currents", "Secondary currents" and "Phase angle"), and they display the RMS, TRMS and peak-to-peak values, amplitude and power THD values as well as the angle of each measured component.
- "Sequence currents" has also been further divided into the four above-mentioned sections, and it calculates the positive, negative and zero sequence currents.
- "Harmonics" displays current harmonics up to the 31st harmonic for the three phase current (IL1, IL2, IL3) as well as the two residual currents (I01, I02); each component can be displayed as absolute or percentage values, and as primary or secondary amperages or in per-unit values.

Phasors

Figure. 3.7 - 47. Phasors submenu.

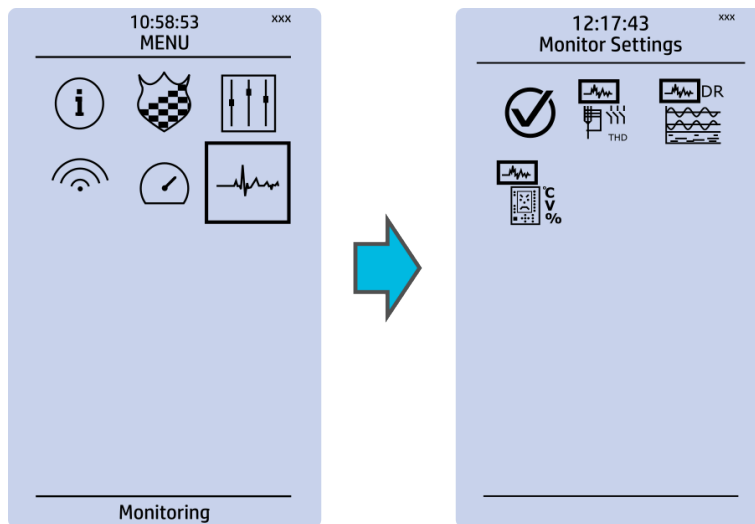


The *Phasors* submenu holds the vector displays for voltages and currents, as well as the various calculated components the device may have (e.g. power, impedance). Phasors are helpful when solving incorrect wiring issues.

3.8 Monitoring menu

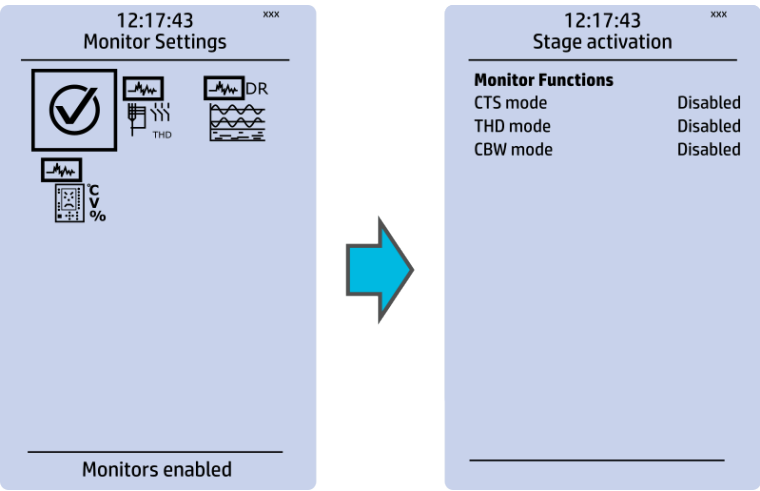
The *Monitoring* main menu includes submenus (see the image below) for enabling the various monitoring functions (*Monitors enabled*), setting the various monitoring functions (*Monitor functions*), controlling the disturbance recorder (*Disturbance REC*) and accessing the device diagnostics (*Device diagnostics*). The available monitoring functions depend on the type of the device in use.

Figure. 3.8 - 48. Monitoring menu view.



Monitors enabled

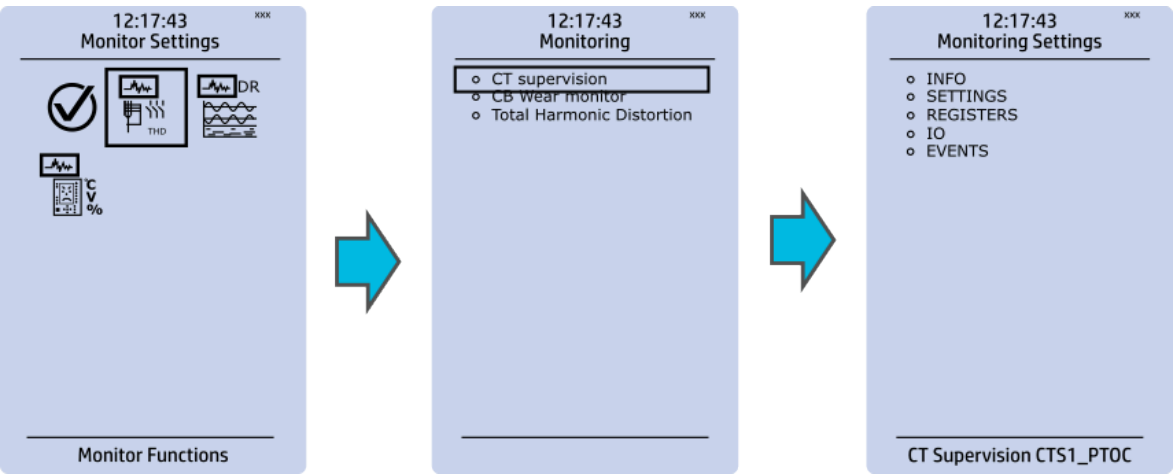
Figure. 3.8 - 49. Monitors enabled submenu.



You can activate the selected monitor functions in the *Monitors enabled* submenu. By default all the control functions are disabled. All activated functions can be viewed in the *Monitor functions* submenu (see the section "Monitor functions" below for more information).

Monitor functions

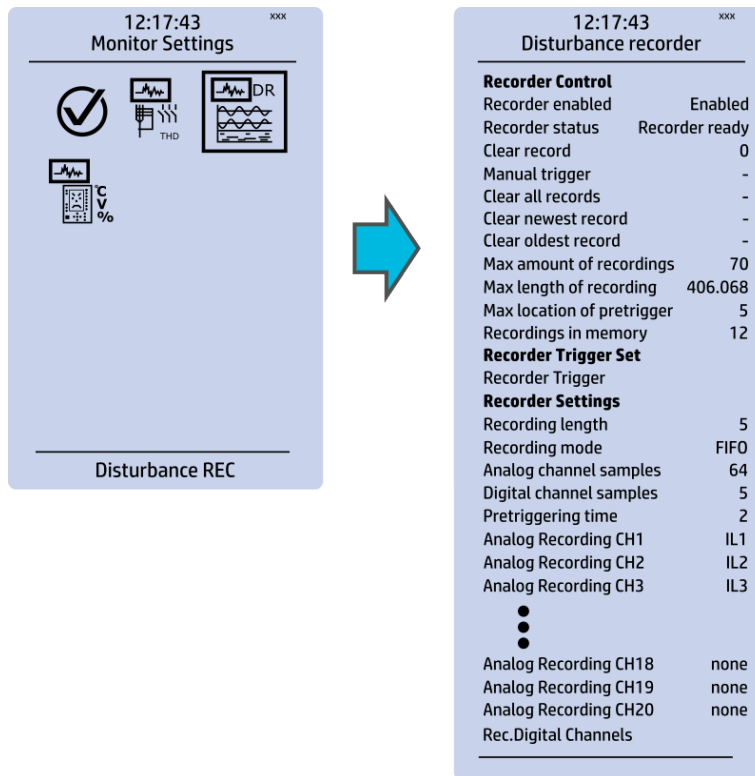
Figure. 3.8 - 50. Monitor function view.



Configuring monitor functions is very similar to configuring protection and control stages. They, too, have the five sections that display information ("Info"), set the parameters ("Settings"), show the inputs and outputs ("I/O") and present the events and registers ("Events" and "Registers").

Disturbance recorder

Figure. 3.8 - 51. Disturbance recorder settings.



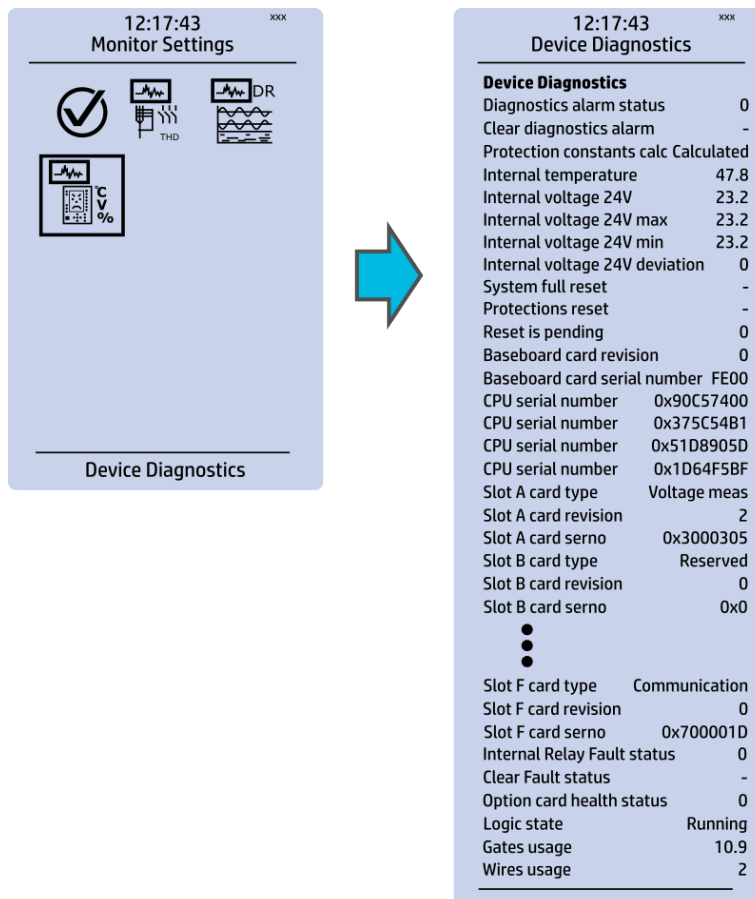
The *Disturbance recorder* submenu has the following settings:

- "Recorder enabled" enables or disables the recorder.
- "Recorder status" indicates the status of the recorder.
- "Clear record" records the chosen record in the memory.
- "Manual trigger" triggers the recorder when set to "Clear". Goes back to "-" when afterwards.
- "Clear all records", "Clear newest record" and "Clear oldest record" allows the clearing of all, the latest, or the oldest recording.
- "Max. amount of recordings" displays the maximum number of recordings; depends on the number of channels, the sample rate and the length of the file.
- "Max. length of recording" displays the maximum length of a single recording; depends on the number of chosen channels and the sample rate.
- "Recordings in memory" displays the number of recordings currently in the disturbance recorder's memory.
- "Recorder trigger" shows which signals or other states has been selected to trigger the recording (digital input, logical input or output, signals of a stage, object position, etc.); by default nothing triggers the recorder.
- "Recording length" displays the length of a single recording and can be set between 0.1...1,800.0 seconds.
- "Recording mode" can be selected to replace the oldest recording ("FIFO") or to keep the old recordings ("FILO").
- "Analog channel samples" determines the sample rate of analog channels, and it can be selected to be 8/16/32/62 samples per cycle.
- "Digital channel samples" displays the sample rate in a digital channel; this is a fixed 5 ms.
- "Pretriggering time" can be selected between 0.1...15.0 s.
- The device can record up to 20 (20) analog channels that can be selected from the twenty (20) available channels. Every measured current or voltage signal can be selected to be recorded.

- Enabling "Auto. get recordings" allows the device to automatically upload recordings to the designated FTP folder (which, in turn, allows any FTP client to read the recordings from the device's memory).
- "Rec. digital channels" is a long list of the possible digital channels that can be recorded (including primary and secondary amplitudes and currents, calculated signals, TRMS values, sequence components, inputs and outputs, etc.).

Device diagnostics

Figure. 3.8 - 52. Device diagnostics submenu.



The *Device Diagnostics* submenu gives a detailed feedback of the device's current condition. It also shows whether option cards have been installed correctly without problems. If you see something out of the ordinary in the *Device diagnostics* submenu and cannot reset it, please contact the closest representative of the manufacturer or the manufacturer of the device itself.

3.9 Configuring user levels and their passwords

As a factory default, no user level is locked with a password in a device. In order to activate the different user levels, click the **Lock** button in the device's HMI and set the desired passwords for the different user levels.

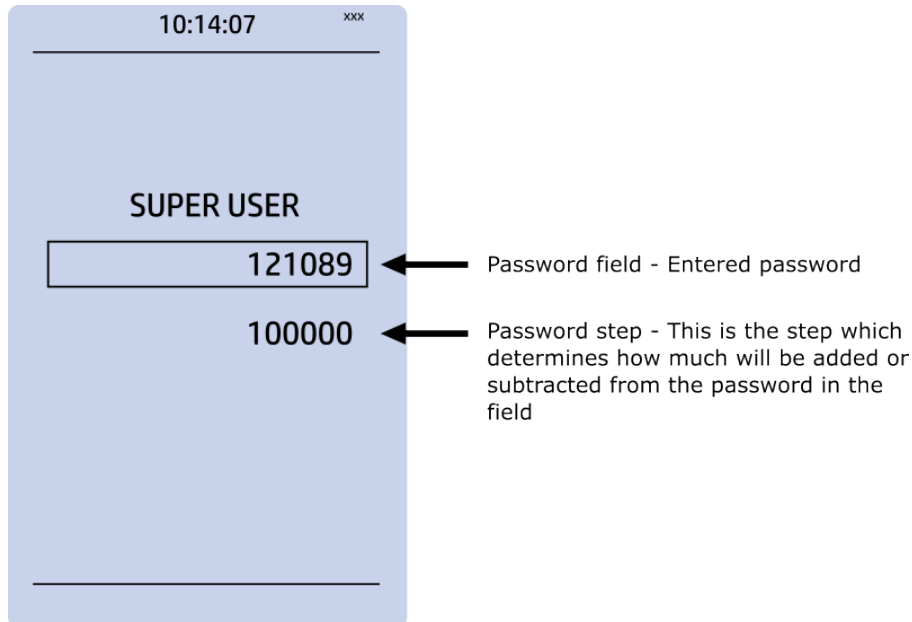
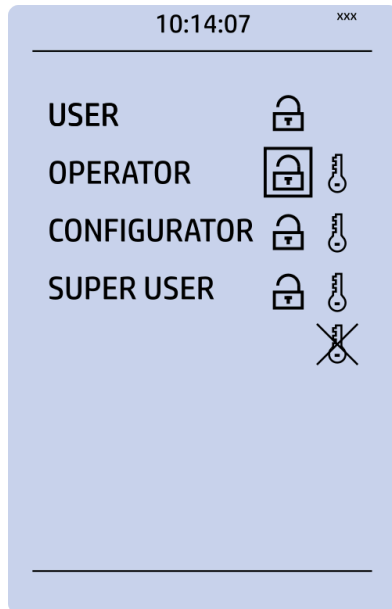


NOTICE!

Passwords can only be set locally in an HMI.

A number of stars are displayed in the upper right corner of the HMI; these indicate the current user level. The different user levels and their star indicators are as follows (also, see the image below for the HMI view):

- Super user (***)
- Configurator (**)
- Operator (*)
- User (-)



You can set a new password for a user level by selecting the key icon next to the user level's name. After this you can lock the user level by pressing the **Return** key while the lock is selected. If you need to change the password, you can select the key icon again and give a new password. To remove the password, set the password to "0" (zero). Please note that in order to do this the user level whose password is being changed must be unlocked.

As mentioned above, the access level of the different user levels is indicated by the number of stars. The required access level to change a parameter is indicated with a star (*) symbol if such is required. As a general rule the access levels are divided as follows:

- *User*: Can view any menus and settings but cannot change any settings, nor operate breakers or other equipment.
- *Operator*: Can view any menus and settings but cannot change any settings BUT can operate breakers and other equipment.
- *Configurator*: Can change most settings such as basic protection pick-up levels or time delays, breaker control functions, signal descriptions etc. and can operate breakers and other equipment.
- *Super user*: Can change any setting and can operate breakers and other equipment.

**NOTICE!**

Any user level with a password automatically locks itself after half an hour (30 minutes) of inactivity.

4 Functions

4.1 Functions included in AQ-F210

The AQ-F210 feeder protection device includes the following functions as well as the number of stages in those functions.

Table. 4.1 - 4. Protection functions of AQ-F210.

| Name (number of stages) | IEC | ANSI | Description |
|-------------------------|--------------------------------|--------------|---|
| NOC (4) | I> I>> I>>> I>>>> | 50/51 | Non-directional overcurrent protection |
| NEF (4) | I0> I0>> I0>>> I0>>>> | 50N/51N | Non-directional earth fault protection |
| CUB (4) | I2> I2>> I2>>> I2>>>> | 46/46R/46L | Negative sequence overcurrent/ phase current reversal/ current unbalance protection |
| HOC (4) | Ih> Ih>> Ih>>> Ih>>>> | 50H/51H/68H | Harmonic overcurrent protection |
| CBFP (1) | CBFP | 50BF/52BF | Circuit breaker failure protection |
| REF (1) | I0d> | 87N | Low-impedance or high-impedance restricted earth fault/ cable end differential protection |
| TOLF (1) | TF> | 49F | Line thermal overload protection |
| RTD (1...16) | - | - | RTD alarms (Resistance temperature detector) |
| PGS (1) | PGx>/< | 99 | Programmable stage |
| ARC (1) | IArc>/I0Arc> | 50Arc/50NArc | Arc fault protection (optional) |

Table. 4.1 - 5. Control functions of AQ-F210.

| Name | IEC | ANSI | Description |
|------|-----|------|---|
| SGS | - | - | Setting group selection |
| OBJ | - | - | Object control and monitoring (5 objects available) |
| CIN | - | - | Indicator object monitoring (5 indicators available) |

| Name | IEC | ANSI | Description |
|-----------|-------|------|-----------------------------|
| CLPU | CLPU | - | Cold load pick-up |
| SOTF | SOTF | - | Switch-on-to-fault |
| AR | 0 → 1 | 79 | Auto-recloser |
| PCS | - | - | Programmable control switch |
| mA output | - | - | Milliampere output control |

Table. 4.1 - 6. Monitoring functions of AQ-F210.

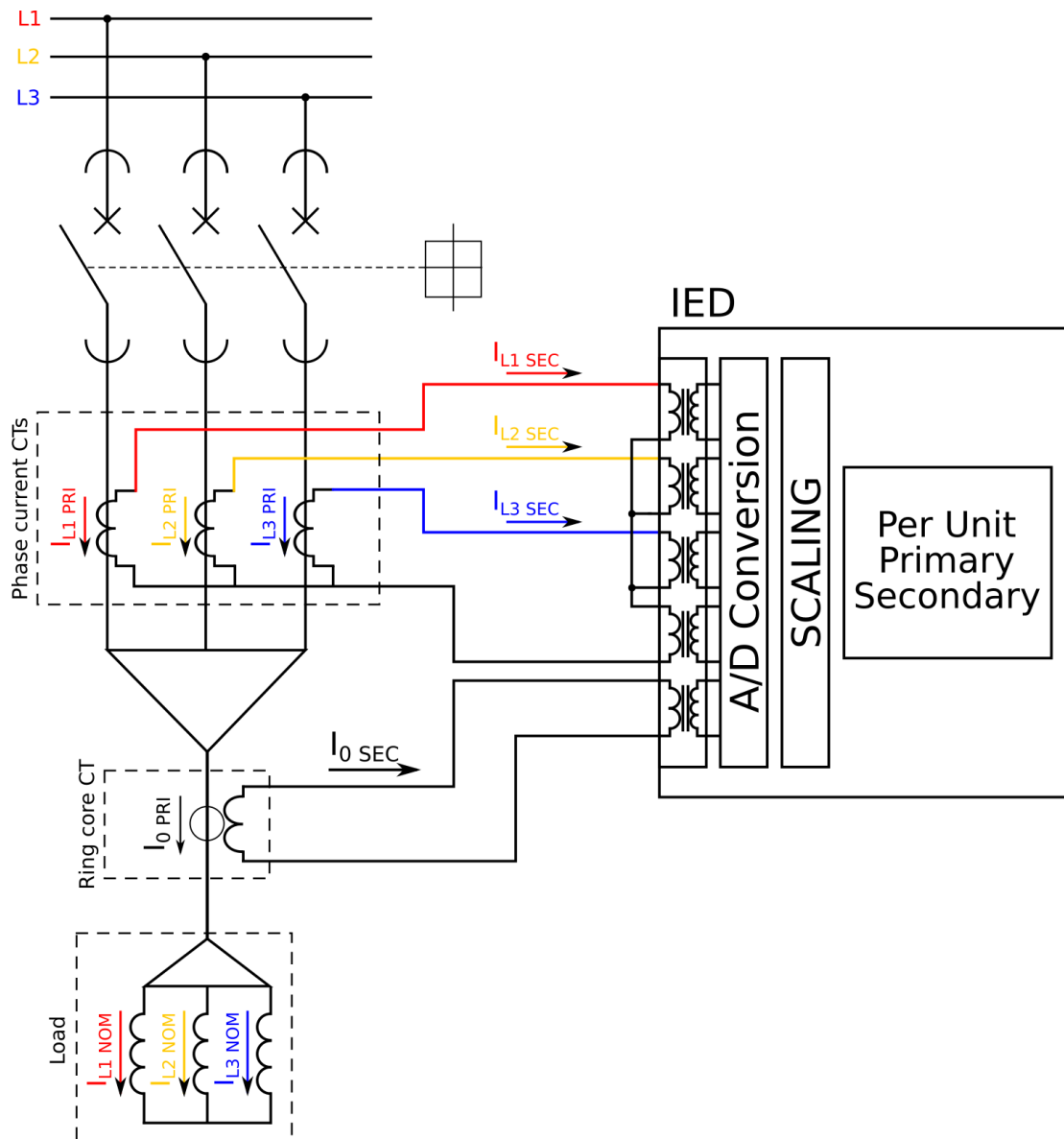
| Name | IEC | ANSI | Description |
|------|-----|------|---------------------------------|
| CTS | - | - | Current transformer supervision |
| DR | - | - | Disturbance recorder |
| CBW | - | - | Circuit breaker wear monitor |
| THD | - | - | Total harmonic distortion |
| MREC | - | - | Measurement recorder |
| VREC | - | - | Measurement value recorder |

4.2 Measurements

4.2.1 Current measurement and scaling

The current measurement module (CT module, or CTM) is used for measuring the currents from current transformers. The current measurements are updated every 5 milliseconds. The measured values are processed into the measurement database and they are used by measurement and protection functions. It is essential to understand the concept of current measurements to be able to get correct measurements.

Figure. 4.2.1 - 53. Current measurement terminology.



PRI: The primary current, i.e. the current which flows in the primary circuit and through the primary side of the current transformer.

SEC: The secondary current, i.e. the current which the current transformer transforms according to its ratios. This current is measured by the device.

NOM: The nominal primary current of the protected object.

For the measurements to be correct the user needs to ensure that the measurement signals are connected to the correct inputs, that the current direction is connected to the correct polarity, and that the scaling is set according to the nominal values of the current transformer.

The device calculates the scaling factors based on the set values of the CT primary, the CT secondary and the nominal current settings. The device measures the secondary current, the current output from the current transformer installed into application's primary circuit. The rated primary and secondary currents of the CT need to be set for the device to "know" the primary and per-unit values. With motors and other specific electrical apparatus protections, the motor's nominal current should be set for the values to be in per unit with regards to the apparatus nominal instead of the CT nominal. This is not always mandatory as some devices still require manual calculations for the correct settings; however, setting the motors nominal current makes motor protection much easier and more straightforward. In modern protection devices this scaling calculation is done internally after the current transformer's primary current, secondary current and motor nominal current are set.

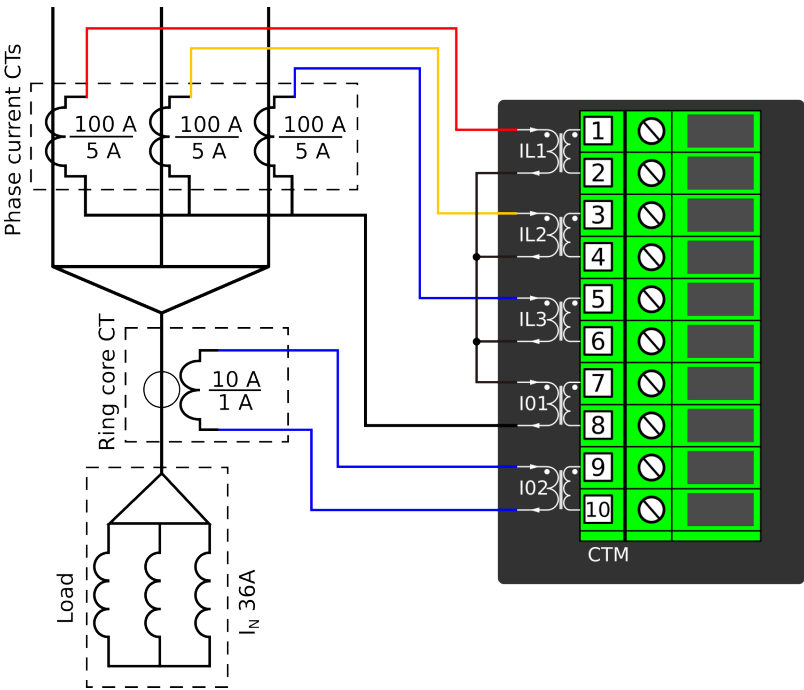
Normally, the primary current ratings for phase current transformers are 10 A, 12.5 A, 15 A, 20 A, 25 A, 30 A, 40 A, 50 A, 60 A and 75 A as well as their decimal multiples, while the secondary current ratings are 1 A and 5 A. Other, non-standard ratings can be directly connected as the scaling settings are flexible and have large ranges. For example, the ring core current transformer ratings may vary. Ring core current transformers are commonly used for sensitive earth fault protection and their rated secondary current may be as low as 0.2 A in some cases.

The following chapter is an example on how to set the scaling of the current measurements for the selected current transformer and system load.

Example of CT scaling

The following figure presents how CTs are connected to the device's measurement inputs. It also shows example CT ratings and nominal current of the load.

Figure. 4.2.1 - 54. Connections.



The following table presents the initial data of the connection.

Table. 4.2.1 - 7. Initial data.

| | | |
|---|---|--------------------------------|
| Phase current CT: <ul style="list-style-type: none"> CT primary: 100 A CT secondary: 5 A | Ring core CT in Input I02: <ul style="list-style-type: none"> I0CT primary: 10 A I0CT secondary: 1 A | Load (nominal): 36 A |
| <ul style="list-style-type: none"> The phase currents are connected to the I01 residual via a Holmgren connection. The starpoint of the phase current CT's secondary current is towards the line. | | |

Phase CT scaling

Next, to scale the current to per-unit values, we have to select whether the basis of the phase CT scaling is the protected object's nominal current or the CT primary value.

If the CT values are chosen to be the basis for the per-unit scaling, the option "CT nom. p.u." is selected for the "Scale meas to In" setting (see the image below).

Figure. 4.2.1 - 55. Setting the phase current transformer scalings to CT nominal.

Phase CT scaling

Scale meas to In: CT nom p.u.

Phase CT primary: 100 A

Phase CT secondary: 5 A

IL1 Polarity: -

IL2 Polarity: -

IL3 Polarity: -

CT scaling factor P/S: 20

Ipu scaling primary: 100

Ipu scaling secondary: 5

Once the settings have been sent to the device, the device calculates the scaling factors and displays them for the user. The "CT scaling factor P/S" describes the ratio between the primary current and the secondary current. The per-unit scaling factors ("Ipu scaling") for both primary and secondary values are also displayed (in this case they are the set primary and secondary currents of the CT).

If the protected object's nominal current is chosen to be the basis for the per-unit scaling, the option "Object in p.u." is selected for the "Scale meas to In" setting (see the image below).

Figure. 4.2.1 - 56. Setting the phase current transformer scalings to the protected object's nominal current.

Phase CT scaling

Scale meas to In

Object In p.u.

Phase CT primary

100 A

1.000_25000.000 [0.001]

Phase CT secondary

5 A

0.200_10.000 [0.001]

Nominal current In

36 A

1.000_25000.000 [0.001]

IL1 Polarity

-

IL2 Polarity

-

IL3 Polarity

-

CT scaling factor P/S

20

0.001_100000.000 [0.001]

CT scaling factor NOM

2.778

0.001_100000.000 [0.001]

Ipu scaling primary

36

0.001_100000.000 [0.001]

Ipu scaling secondary

1.8

0.001_100000.000 [0.001]

Once the measurement scaling is tied to the protected object's nominal current, the user must set the appropriate input for the "Nominal current In" setting. One can now see the differences between the two scaling options (CT nominal vs. object nominal). The "CT scaling factor P/S" is the direct ratio between the set CT current values, and the "CT scaling factor NOM" is now the ratio between the set CT primary and the nominal current. The "Ipu scaling primary" is now equal to the set nominal current, and the "Ipu scaling secondary" is the ratio between the nominal current and the "CT scaling factor P/ S".

Residual IO CT scaling

Next, we set the residual IO CT scalings according to how the phase current CTs and the ring core CT are connected to the module (see the Connections image at the beginning of this chapter).

The phase current CTs are connected to the module via a Holmgren (summing) connection, which requires the use of coarse residual current measurement settings: the "I01 CT" settings are set according to the phase current CTs' ratings (100/5 A).

Figure. 4.2.1 - 57. Residual I01 CT scaling (coarse).

Residual I01 CT scaling

I01 CT primary

100 A

0.20000_25000.00000 [0.00001]

I01 CT secondary

5 A

0.10000_10.00000 [0.00001]

I01 Polarity

-

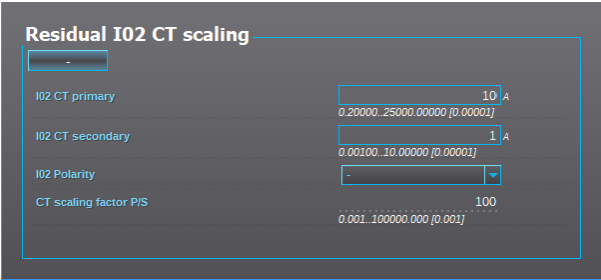
CT scaling factor P/S

20

0.001_100000.000 [0.001]

The ring core CT is connected to the CTM directly, which requires the use of sensitive residual current measurement settings: the "I02 CT" settings are set according to the ring core CT's ratings (10/1 A).

Figure. 4.2.1 - 58. Residual I02 CT scaling (sensitive).



Displaying the scaling

Depending on whether the scaling was done based on the CT primary values or the protected object's nominal current, the measurements are displayed slightly differently. The first of the two images shows how the measurements are displayed when the CT primary values are the basis for the scaling; the second shows them when the protected object's nominal current is the basis for the scaling.

Figure. 4.2.1 - 59. Scalings display (based on the CT nominal).

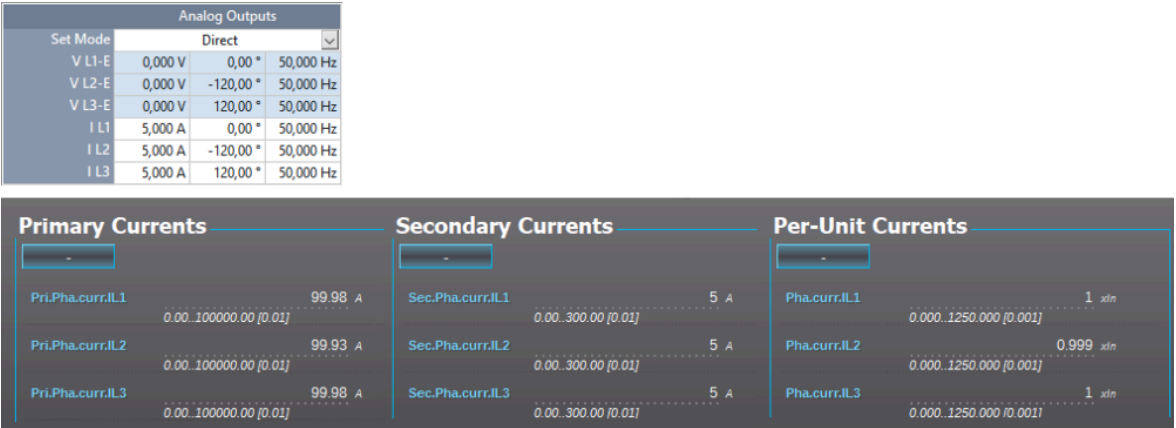
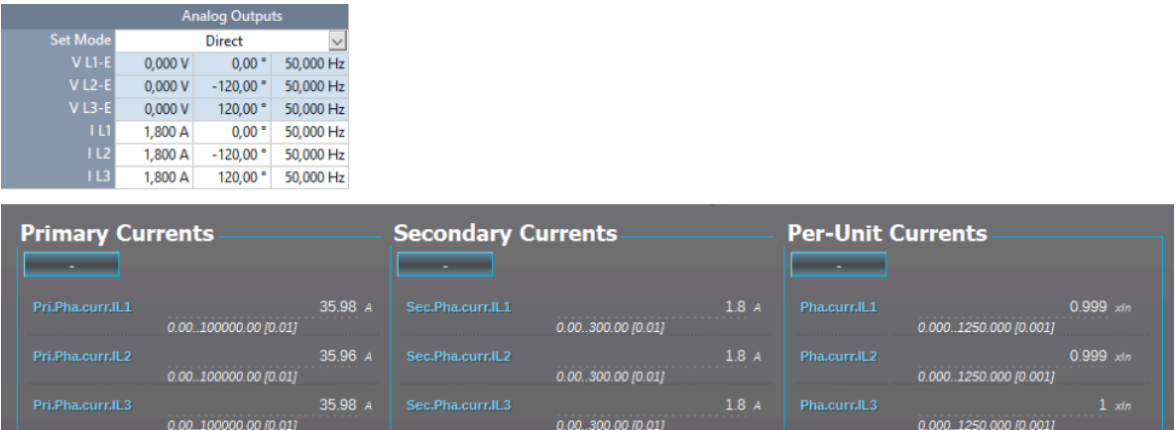


Figure. 4.2.1 - 60. Scalings display (based on the protected object's nominal current).

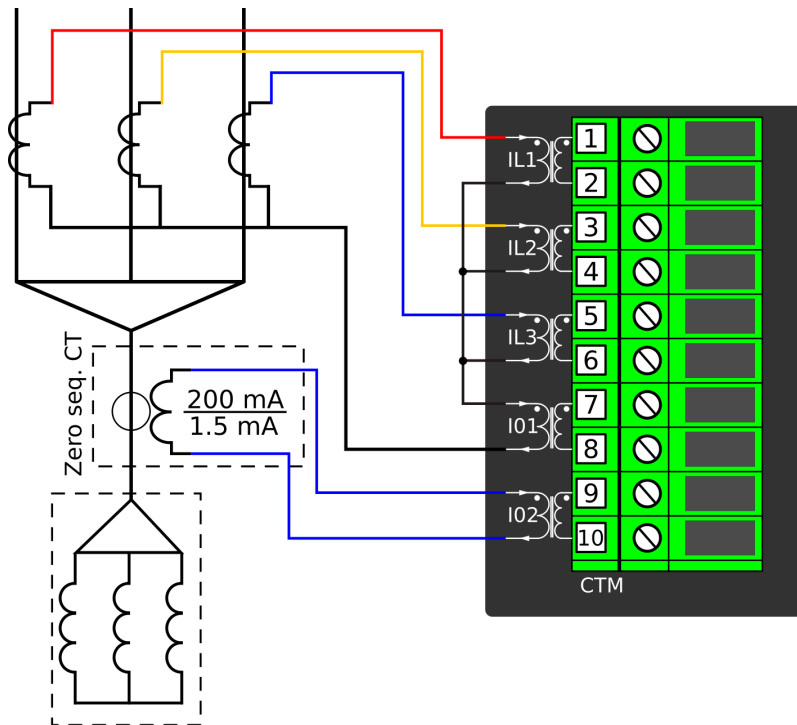


As the images above show, the scaling selection does not affect how primary and secondary currents are displayed (as actual values). The only effect is that the per-unit system in the device is scaled either to the CT nominal or to the object nominal, making the settings input straightforward.

Example of zero sequence CT scaling

Zero sequence CT scaling (ZCT scaling) is done when a zero sequence CT instead of a ring core CT is part of the measurement connection. In such a case the zero sequence CT should be connected to the I02 channel which has lower CT scaling ranges (see the image below).

Figure. 4.2.1 - 61. Connections of ZCT scaling.

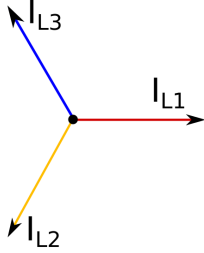


Troubleshooting

When the measured current values differ from the expected current values, the following table offers possible solutions for the problems.

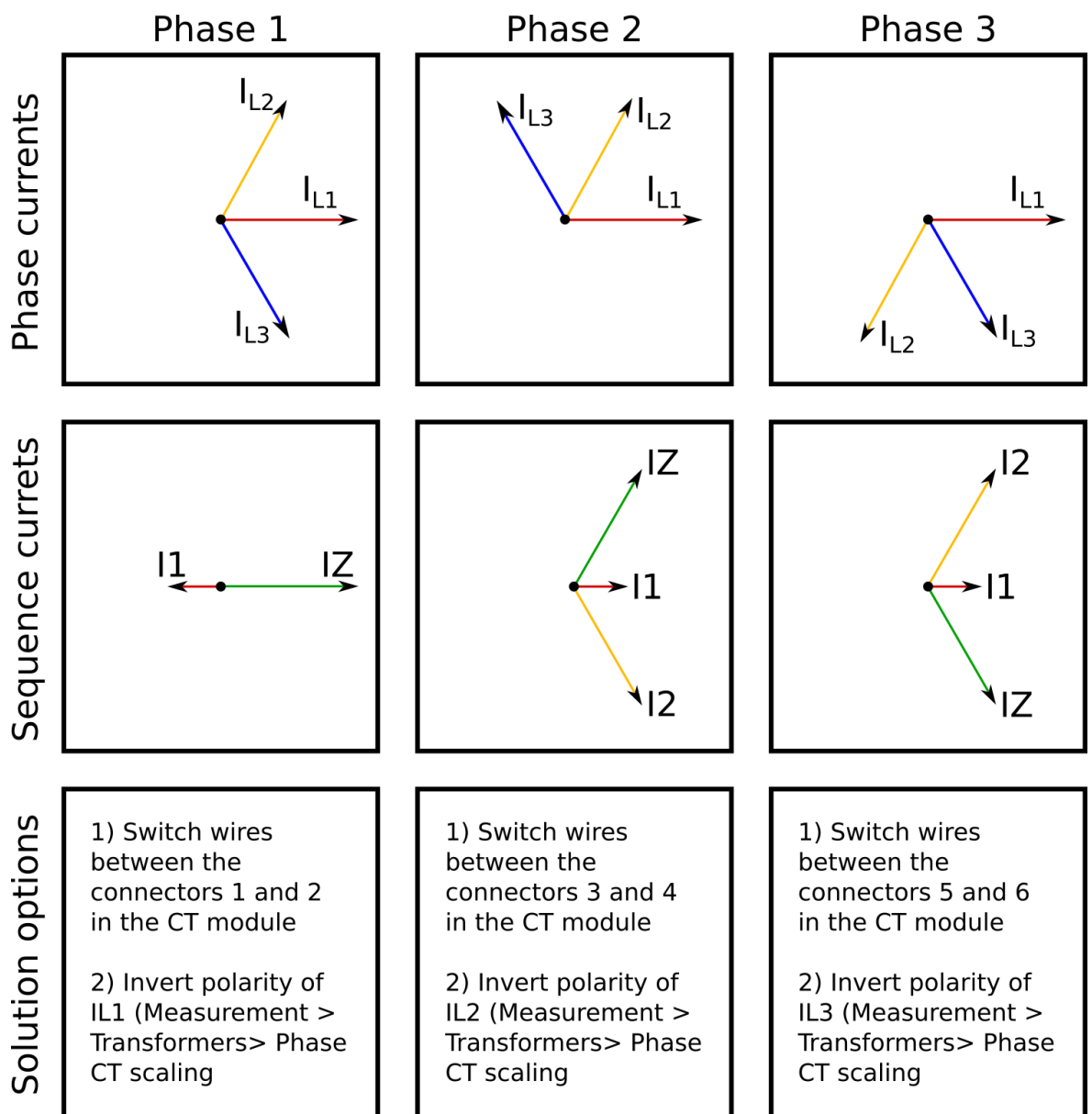
WARNING! If you work with energized CTs, extreme caution needs to be taken when checking the connections! An opened CT secondary circuit may generate dangerously high voltages. A "buzzing" sound from the connector can indicate an open circuit.

| Problem | Solution |
|--|--|
| The measured current amplitude in all phases does not match the injected current. | The scaling settings may be wrong, check that the settings match with the connected current transformer (<i>Measurement</i> → <i>Transformers</i> → <i>Phase CT scaling</i>). Also check that the "Scale meas. to In" is set accordingly. If possible, check the actual CTs and their ratings as there may have been a need to change the original plan. |
| The measured current amplitude does not match one of the measured phases./ The calculated I0 is measured even though it should not. | Check the wiring connections between the injection device or the CTs and the device. |

| Problem | Solution |
|---|--|
| <p>The measured current amplitudes are OK but the angles are strange./</p> <p>The phase unbalance protection trips immediately after activation./</p> <p>The earth fault protection trips immediately after activation.</p> | <p>The phase currents are connected to the measurement module but the order or polarity of one or all phases is incorrect. In device settings, go to <i>Measurement</i> → <i>Phasors</i> and check the "Phase current vectors" diagram. When all connections are correct, the diagram (symmetric feeding) should look like this:</p>  <p>See the following tables for the most common problems with phase polarity and network rotation (mixed phases).</p> |

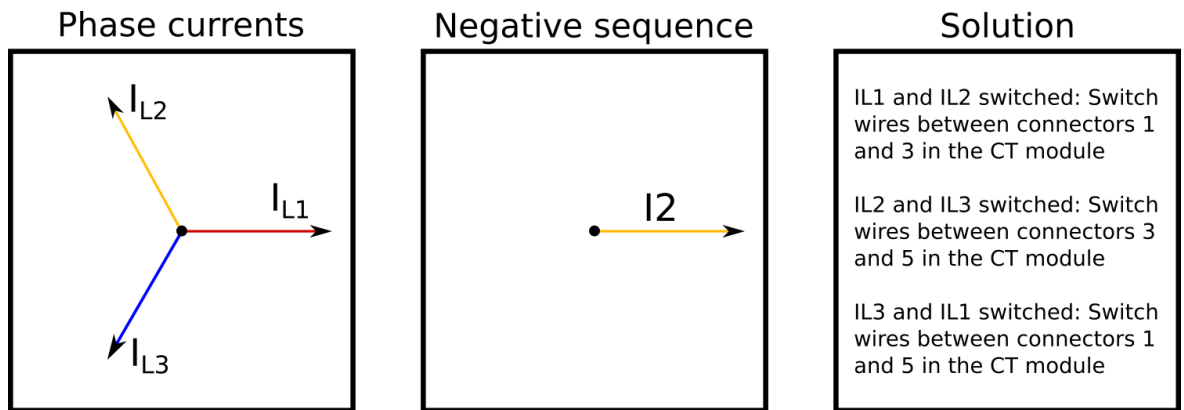
The following image presents the most common problems with phase polarity. Problems with phase polarity are easy to find because the vector diagram points towards the opposite polarity when a phase has been incorrectly connected.

Figure. 4.2.1 - 62. Common phase polarity problems.



The following image presents the most common problems with network rotation (mix phases). These problems can be difficult to find because the measurement result is always the same in the device. If two phases are mixed together, the network rotation always follows the pattern IL1-IL3-IL2 and the measured negative sequence current is therefore always 1.00 (in. p.u.).

Figure. 4.2.1 - 63. Common network rotation (mixed phases) problems.



Settings

Table. 4.2.1 - 8. Settings of the Phase CT scaling.

| Name | Range | Step | Default | Description |
|-------------------------|---|-------|---|--|
| Scale measurement to In | <ul style="list-style-type: none"> CT nom p.u. Object In p.u. | - | <ul style="list-style-type: none"> CT nom p.u. | The selection of the reference used in the device's per-unit system scaling. Either the set phase current CT primary or the protected object's nominal current. |
| Phase CT primary | 1.000...25 000.000A | 0.001 | 100.000 | The rated primary current of the current transformer. |
| Phase CT secondary | 0.200...10.000A | 0.001 | 5.000 | The rated secondary current of the current transformer. |
| Nominal current In | 1.000...25 000.000A | 0.001 | 100.000 | The nominal current of the protected object. This setting is only visible if the option "Object In p.u." has been selected in the "Scale measurement to In" setting. |
| IL1 Polarity | <ul style="list-style-type: none"> - Invert | - | - | The selection of the first current measurement channel's (IL1) polarity (direction). The default setting is for the positive current to flow from connector 1 to connector 2, with the secondary currents' starpoint pointing towards the line. |
| IL2 Polarity | <ul style="list-style-type: none"> - Invert | - | - | The selection of the second current measurement channel's (IL2) polarity (direction). The default setting is for the positive current to flow from connector 3 to connector 4, with the secondary currents' starpoint pointing towards the line. |
| IL3 Polarity | <ul style="list-style-type: none"> - Invert | - | - | The selection of the third current measurement channel's (IL3) polarity (direction). The default setting is for the positive current to flow from connector 5 to connector 6, with the secondary currents' starpoint pointing towards the line. |
| CT scaling factor P/S | - | - | - | A feedback value; the calculated scaling factor that is the ratio between the primary current and the secondary current. |

| Name | Range | Step | Default | Description |
|-----------------------|-------|------|---------|--|
| CT scaling factor NOM | - | - | - | A feedback value; the calculated scaling factor that is the ratio between the set primary current and the set nominal current. This parameter is only visible if the option "Object In p.u." has been selected in the "Scale measurement to In" setting. |
| Ipu scaling primary | - | - | - | A feedback value; the scaling factor for the primary current's per-unit value. |
| Ipu scaling secondary | - | - | - | A feedback value; the scaling factor for the secondary current's per-unit value. |

Table. 4.2.1 - 9. Settings of the Residual I01 CT scaling.

| Name | Unit | Range | Step | Default | Description |
|-----------------------|------|---|-------------|---------------|---|
| I01 CT primary | A | 0.200 00...25 000.000 00 | 0.000 01 | 100.000 00 | The rated primary current of the current transformer. |
| I01 CT secondary | A | 0.100 00...10.000 00 | 0.000 01 | 1.000 00 | The rated secondary current of the current transformer. |
| I01 Polarity | - | <ul style="list-style-type: none"> - Invert | - | - | The selection of the coarse residual measurement channel's (I01) polarity (direction). The default setting is for the positive current to flow from connector 7 to connector 8. |
| CT scaling factor P/S | - | - | - | - | A feedback value; the calculated scaling factor that is the ratio between the primary current and the secondary current. |

Table. 4.2.1 - 10. Settings of the Residual I02 CT scaling.

| Name | Unit | Range | Step | Default | Description |
|-----------------------|------|---|-------------|---------------|---|
| I02 CT primary | A | 0.200 00...25 000.000 00 | 0.000 01 | 100.000 00 | The rated primary current of the current transformer. |
| I02 CT secondary | A | 0.001 00...10.000 00 | 0.000 01 | 0.200 00 | The rated secondary current of the current transformer. |
| I02 Polarity | - | <ul style="list-style-type: none"> - Invert | - | - | The selection of the sensitive residual measurement channel's (I02) polarity (direction). The default setting is for the positive current to flow from connector 9 to connector 10. |
| CT scaling factor P/S | - | - | - | - | A feedback value; the calculated scaling factor that is the ratio between the primary current and the secondary current. |

Measurements

The following measurements are available in the measured current channels.

Table. 4.2.1 - 11. Per-unit phase current measurements.

| Name | Unit | Range | Step | Description |
|---|------|----------------------|-------|--|
| Phase current ILx ("Pha.curr.ILx") | × In | 0.000...1 250.000 | 0.001 | The current fundamental frequency component (in p.u.) from each of the phase current channels. |
| Phase current ILx TRMS ("Pha.curr.ILx TRMS") | × In | 0.00...1 250.00 | 0.01 | The TRMS current (inc. harmonics up to 31 st) measurement (in p.u.) from each of the phase current channels. |
| Peak-to-peak current ILx ("P-P curr.ILx") | × In | 0.00...500.00 | 0.01 | The peak-to-peak current measurement (in p.u.) from each of the phase current channels. |

Table. 4.2.1 - 12. Primary phase current measurements.

| Name | Unit | Range | Step | Description |
|---|------|---------------------------|------|--|
| Primary phase current ILx ("Pri.Pha.curr.ILx") | A | 0.00...1 000 000.00 | 0.01 | The primary current measurement fundamental frequency component from each of the phase current channels. |
| Primary phase current ILx TRMS ("Pha.curr.ILx TRMS Pri") | A | 0.00...1 000 000.00 | 0.01 | The primary TRMS current (inc. harmonics up to 31 st) measurement from each of the phase current channels. |

Table. 4.2.1 - 13. Secondary phase current measurements.

| Name | Unit | Range | Step | Description |
|---|------|---------------|------|--|
| Secondary phase current ILx ("Sec.Pha.curr.ILx") | A | 0.00...300.00 | 0.01 | The primary current measurement fundamental frequency component from each of the phase current channels. |
| Secondary phase current ILx TRMS ("Pha.curr.ILx TRMS Sec") | A | 0.00...300.00 | 0.01 | The primary TRMS current (inc. harmonics up to 31 st) measurement from each of the phase current channels. |

Table. 4.2.1 - 14. Phase angle measurements.

| Name | Unit | Range | Step | Description |
|--------------------------------------|------|---------------|------|--|
| Phase angle ILx ("Pha.angle ILx") | deg | 0.00...360.00 | 0.01 | The phase angle measurement from each of the three phase current inputs. |

Table. 4.2.1 - 15. Per-unit residual current measurements.

| Name | Unit | Range | Step | Description |
|---|------|--------------------|------|---|
| Residual current I0x ("Res.curr.I0x") | × In | 0.00...1 250.00 | 0.01 | The current measurement fundamental frequency component (in p.u.) from the residual current channel I01 or I02. |
| Calculated I0 | × In | 0.00...1 250.00 | 0.01 | The current measurement fundamental frequency component (in p.u.) from the calculated I0 current channel. |
| Phase current I0x TRMS ("Res.curr.I0x TRMS") | × In | 0.00...1 250.00 | 0.01 | The TRMS current (inc. harmonics up to 31 st) measurement (in p.u.) from the residual current channel I01 or I02. |
| Peak-to-peak current I0x ("P-P curr.I0x") | × In | 0.00...500.00 | 0.01 | The peak-to-peak current measurement (in p.u.) from the residual current channel I01 or I02. |

Table. 4.2.1 - 16. Primary residual current measurements.

| Name | Unit | Range | Step | Description |
|--|------|---------------------------|------|---|
| Primary residual current I0x ("Pri.Res.curr.I0x") | A | 0.00...1 000 000.00 | 0.01 | The primary current measurement fundamental frequency component from the residual current channel I01 or I02. |
| Primary calculated I0 ("Pri.calc.I0") | A | 0.00...1 000 000.00 | 0.01 | The primary current measurement fundamental frequency component from the calculated current channel I0. |
| Primary residual current I0x TRMS ("Res.curr.I0x TRMS Pri") | A | 0.00...1 000 000.00 | 0.01 | The TRMS current (inc. harmonics up to 31 st) measurement from the primary residual current channel I01 or I02. |

Table. 4.2.1 - 17. Secondary residual current measurements.

| Name | Unit | Range | Step | Description |
|--|------|---------------|------|---|
| Secondary residual current I0x ("Sec.Res.curr.I0x") | A | 0.00...300.00 | 0.01 | The secondary current measurement fundamental frequency component from the residual current channel I01 or I02. |
| Secondary calculated I0 ("Sec.calc.I0") | A | 0.00...300.00 | 0.01 | The secondary current measurement fundamental frequency component from the calculated current channel I0. |
| Secondary residual current I0x TRMS ("Res.curr.I0x TRMS Sec") | A | 0.00...300.00 | 0.01 | The secondary TRMS current (inc. harmonics up to 31 st) measurement from the secondary residual current channel I01 or I02. |

Table. 4.2.1 - 18. Residual phase angle measurements.

| Name | Unit | Range | Step | Description |
|--|------|---------------|------|---|
| Residual current angle I0x ("Res.curr.angle I0x") | deg | 0.00...360.00 | 0.01 | The residual current angle measurement from the I01 or I02 current input. |
| calc.I0 Pha.angle | deg | 0.00...360.00 | 0.01 | The calculated residual current angle measurement. |

Table. 4.2.1 - 19. Per-unit sequence current measurements.

| Name | Unit | Range | Step | Description |
|---------------------------|------|--------------------|------|--|
| Positive sequence current | × In | 0.00...1 250.00 | 0.01 | The measurement (in p.u.) from the calculated positive sequence current. |
| Negative sequence current | × In | 0.00...1 250.00 | 0.01 | The measurement (in p.u.) from the calculated negative sequence current. |
| Zero sequence current | × In | 0.00...1 250.00 | 0.01 | The measurement (in p.u.) from the calculated zero sequence current. |

Table. 4.2.1 - 20. Primary sequence current measurements.

| Name | Unit | Range | Step | Description |
|--|------|------------------------|------|--|
| Primary positive sequence current ("Pri.Positivesequence curr.") | A | 0.00...1 000 000.00 | 0.01 | The primary measurement from the calculated positive sequence current. |
| Primary negative sequence current ("Pri.Negative sequence curr.") | A | 0.00...1 000 000.00 | 0.01 | The primary measurement from the calculated negative sequence current. |
| Primary zero sequence current ("Pri.Zero sequence curr.") | A | 0.00...1 000 000.00 | 0.01 | The primary measurement from the calculated zero sequence current. |

Table. 4.2.1 - 21. Secondary sequence current measurements.

| Name | Unit | Range | Step | Description |
|--|------|---------------|------|--|
| Secondary positive sequence current ("Sec.Positive sequence curr.") | A | 0.00...300.00 | 0.01 | The secondary measurement from the calculated positive sequence current. |
| Secondary negative sequence current ("Sec.Negative sequence curr") | A | 0.00...300.00 | 0.01 | The secondary measurement from the calculated negative sequence current. |

| Name | Unit | Range | Step | Description |
|--|------|---------------|------|--|
| Secondary zero sequence current ("Sec.Zero sequence curr.") | A | 0.00...300.00 | 0.01 | The secondary measurement from the calculated zero sequence current. |

Table. 4.2.1 - 22. Sequence phase angle measurements.

| Name | Unit | Range | Step | Description |
|---|------|---------------|------|---|
| Positive sequence current angle ("Positive sequence curr.angle") | deg | 0.00...360.00 | 0.01 | The calculated positive sequence current angle. |
| Negative sequence current angle ("Negative sequence curr.angle") | deg | 0.00...360.00 | 0.01 | The calculated negative sequence current angle. |
| Zero sequence current angle ("Zero sequence curr.angle") | deg | 0.00...360.00 | 0.01 | The calculated zero sequence current angle. |

Table. 4.2.1 - 23. Harmonic current measurements.

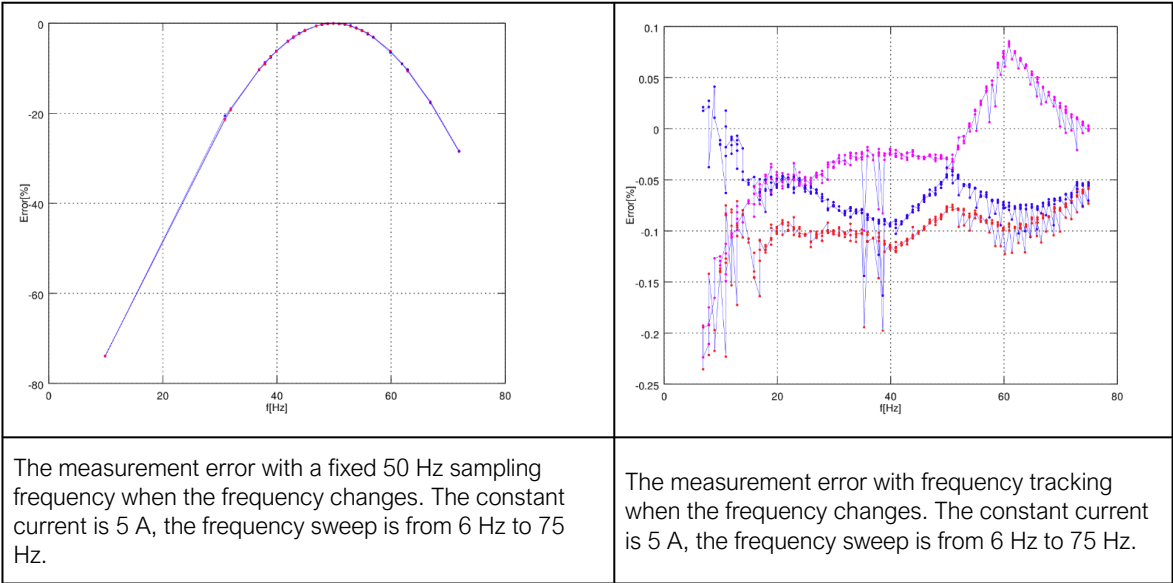
| Name | | Range | Step | Description |
|---|---|--|-------|---|
| Harmonics calculation values ("Harm Abs.or Perc.") | - | <ul style="list-style-type: none"> Percent Absolute | - | Defines whether the harmonics are calculated as percentage or absolute values. |
| Harmonics display | - | <ul style="list-style-type: none"> Per unit Primary A Secondary A | - | Defines how the harmonics are displayed: in p.u values, as primary current values, or as secondary current values. |
| Maximum harmonics value ("Ixx maximum harmonic") | A | 0.00...100 000.00 | 0.01 | Displays the maximum harmonics value of the selected current input ILx or IOx. |
| Fundamental frequency ("Ixx fundamental") | A | 0.00...100 000.00 | 0.01 | Displays the current value of the fundamental frequency component (RMS) from the selected current input ILx or IOx. |
| Ixx harmonics (2 nd ...31 st harmonic) | A | 0.00...100 000.00 | 0.01 | Displays the selected harmonic from the current input ILx or IOx. |
| Ixx Amplitude THD | % | 0.000...100.000 | 0.001 | Amplitude ratio THD voltage. Recognized by IEC. |
| Ixx Power THD | % | 0.000...100.000 | 0.001 | Power ratio THD voltage. Recognized by the IEEE. |

4.2.2 Frequency tracking and scaling

Measurement sampling can be set to the frequency tracking mode or to the fixed user-defined frequency sampling mode. The benefit of frequency tracking is that the measurements are within a pre-defined accuracy range even when the fundamental frequency of the power system changes.

Frequency independent current and voltage measurement accuracy is achieved with algorithms specified in patent US 10,809,287.

Table. 4.2.2 - 24. Frequency tracking effect (FF changes from 6 Hz to 75 Hz).



As the figures above show, the sampling frequency has a major effect on the device's measurement accuracy. If the sampling is not tracked to the system frequency, for example a 10 Hz difference between the measured and the set system frequency can give a measurement error of over 5 %. The figures also show that when the frequency is tracked and the sampling is adjusted according to the detected system frequency, the measurement accuracy has an approximate error of 0.1...- 0.2 % error in the whole frequency range.

AQ -200 series devices have a measurement accuracy that is independent of the system frequency. This has been achieved by adjusting the sample rate of the measurement channels according to the measured system frequency; this way the FFT calculation always has a whole power cycle in the buffer. The measurement accuracy is further improved by Arcteq's patented calibration algorithms that calibrate the analog channels against eight (8) system frequency points for both magnitude and angle. This frequency-dependent correction compensates the frequency dependencies in the used, non-linear measurement hardware and improves the measurement accuracy significantly. Combined, these two methods give an accurate measurement result that is independent of the system frequency.

Troubleshooting

When the measured current, voltage or frequency values differ from the expected values, the following table offers possible solutions for the problems.

| Problem | Check / Resolution |
|---|---|
| The measured current or voltage amplitude is lower than it should be. The values are "jumping" and are not stable. | The set system frequency may be wrong. Please check that the frequency settings match the local system frequency, or change the measurement mode to "Tracking" (<i>Measurement</i> → <i>Frequency</i> → "Sampling mode") so the device adjusts the frequency itself. |
| The frequency readings are wrong. | In Tracking mode the device may interpret the frequency incorrectly if no current is injected into the CT (or voltage into the VT). Please check the frequency measurement settings (<i>Measurement</i> → <i>Frequency</i>). |

Settings

Table. 4.2.2 - 25. Settings of the frequency tracking.

| Name | Range | Step | Default | Description |
|--|--|----------|----------|--|
| Sampling mode | <ul style="list-style-type: none"> Fixed Tracking | - | Fixed | Defines which measurement sampling mode is in use: the fixed user-defined frequency, or the tracked system frequency. |
| Max. tracking frequency allowed (+Nom freq.) | 0.001...75.000 Hz | 0.001 Hz | 0.001 Hz | Defines the upper limit for the deviation from the system nominal frequency to be tracked. If the frequency increases more than allowed from the nominal value, the tracking is discarded and the value of the nominal frequency will be used. |
| System nominal frequency | 7.000...75.000Hz | 0.001Hz | 50Hz | The user-defined system nominal frequency that is used when the "Sampling mode" setting has been set to "Fixed". |
| Min. tracking frequency allowed (-Nom freq.) | 0.001...75.000 Hz | 0.001 Hz | 0.001 Hz | Defines the lower limit for the deviation from the system nominal frequency to be tracked. If the frequency decreases more than allowed from the nominal value, the tracking is discarded and the value of the nominal frequency will be used. |
| Tracked system frequency | 0.000...75.000Hz | 0.001Hz | - | Displays the rough measured system frequency. |
| Sampling frequency in use | 0.000...75.000Hz | 0.001Hz | - | Displays the tracking frequency that is in use at that moment. |
| Frequency reference 1 | <ul style="list-style-type: none"> None CT1IL1 CT2IL1 VT1U1 VT2U1 | - | CT1IL1 | The first reference source for frequency tracking. |
| Frequency reference 2 | <ul style="list-style-type: none"> None CT1IL2 CT2IL2 VT1U2 VT2U2 | - | CT1IL2 | The second reference source for frequency tracking. |

| Name | Range | Step | Default | Description |
|------------------------------|---|---------|----------------------------|--|
| Frequency reference 3 | <ul style="list-style-type: none"> None CT1IL3 CT2IL3 VT1U3 VT2U3 | - | CT1IL3 | The third reference source for frequency tracking. |
| Frequency tracking quality | <ul style="list-style-type: none"> No trackable channels Reference 1 trackable Reference 2 trackable References 1 & 2 trackable Reference 3 trackable Reference 1 & 3 trackable References 2 & 3 trackable All references trackable | - | - | Defines the frequency tracker quality. If the measured current (or voltage) amplitude is below the threshold, the channel tracking quality is 0 and cannot be used for frequency tracking. If all channels' magnitudes are below the threshold, there are no trackable channels. |
| Frequency measurement in use | <ul style="list-style-type: none"> No track ch Ref1 Ref2 Ref3 | - | - | Indicates which reference is used at the moment for frequency tracking. |
| Start behavior | <ul style="list-style-type: none"> Start tracking immediately First nominal or tracked | - | Start tracking immediately | Defines the how the tracking starts. Tracking can start immediately, or there can be a set delay time between the receiving of the first trackable channel and the start of the tracking. |
| Start sampling with | <ul style="list-style-type: none"> Use track frequency Use nom frequency | - | Use track frequency | Defines the start of the sampling. Sampling can begin with a previously tracked frequency, or with a user-set nominal frequency. |
| Use nominal frequency until | 0...1800.000s | 0.005s | 0.100s | Defines how long the nominal frequency is used after the tracking has started. This setting is only valid when the "Sampling mode" setting is set to "Tracking" and when the "Start behavior" is set to "First nominal or tracked". |
| Tracked f channel A | 0.000...75.000Hz | 0.001Hz | - | Displays the rough value of the tracked frequency in Channel A. |
| Tracked f channel B | 0.000...75.000Hz | 0.001Hz | - | Displays the rough value of the tracked frequency in Channel B. |
| Tracked f channel C | 0.000...75.000Hz | 0.001Hz | - | Displays the rough value of the tracked frequency in Channel C. |
| System measured frequency | <ul style="list-style-type: none"> One f measured Two f measured Three f measured | - | - | Displays the amount of frequencies that are measured. |

| Name | Range | Step | Default | Description |
|--------------------------|--|---------|---------|---|
| f.atm. Protections | 0.000...75.000Hz | 0.001Hz | - | Frequency measurement value used by protection functions. When frequency is not measurable this value returns to value set to "System nominal frequency" parameter. |
| f.atm. Display | 0.000...75.000Hz | 0.001Hz | - | Frequency measurement value used in display. When frequency is not measurable this value is "0 Hz". |
| f measurement from | <ul style="list-style-type: none"> • Not measurable • Avg Ref 1 • Avg Ref 2 • Avg Ref 3 • Track Ref 1 • Track Ref 2 • Track Ref 3 • Fast Ref 1 • Fast Ref 2 • Fast Ref 3 | - | - | Displays which reference is used for frequency measurement. |
| SS1.meas.frqs | 0.000...75.000Hz | 0.001Hz | - | Displays frequency used by "system set" channel 1 and 2. |
| SS2.meas.frqs | | | | |
| SS1f meas.from | <ul style="list-style-type: none"> • Not measurable • Fast Ref U3 • Fast Ref U4 | - | - | Displays which voltage channel frequency reference is used by "system set" voltage channel. |
| SS2f meas.from | <ul style="list-style-type: none"> • Not measurable • Fast Ref U4 | - | - | Displays if U4 channel frequency reference is measurable or not when the channel has been set to "system set" mode. |

4.3 General menu

The *General* menu consists of basic settings and indications of the device. Additionally, the all activated functions and their status are displayed in the *Protection*, *Control* and *Monitor* profiles.

Table. 4.3 - 26. The *General* menu read-only parameters

| Name | Description |
|---|--|
| Serial number | The unique serial number identification of the unit. |
| Firmware version | The firmware software version of the unit. |
| Hardware configuration | The order code identification of the unit. |
| System phase rotating order at the moment | The selected system phase rotating order. Can be changed with parameter "System phase rotating order". |
| UTC time | The UTC time value which the device's clock uses. |

Table. 4.3 - 27. Parameters and indications in the *General* menu.

| Name | Range | Default | Description |
|-----------------------------|--|--------------|--|
| Device name | - | Unitname | The file name uses these fields when loading the .aqs configuration file from the AQ-200 unit. |
| Device location | - | Unitlocation | |
| Time synchronization source | <ul style="list-style-type: none"> Internal External NTP External Serial IRIG-B | Internal | If an external clock time synchronization source is available, the type is defined with this parameter. In the internal mode there is no external Timesync source. IRIG-B requires a serial fiber communication option card. |
| Enable stage forcing | <ul style="list-style-type: none"> Disabled Enabled | Disabled | When this parameter is enabled it is possible for the user to force the protection, control and monitoring functions to different statuses like START and TRIP. This is done in the function's <i>Info</i> page with the <i>Force status to</i> parameter. |
| System phase rotating order | <ul style="list-style-type: none"> A-B-C A-C-B | A-B-C | Allows the user to switch the expected order in which the phase measurements are wired to the unit. |
| Language | <ul style="list-style-type: none"> User defined English Finnish Chinese Spanish French German Russian Ukrainian Kazakh | English | Changes the language of the parameter descriptions in the HMI. If the language has been set to "Other" in the settings of the AQtivate setting tool, AQtivate follows the value set into this parameter. |
| AQtivate ethernet port | <ul style="list-style-type: none"> All COM A Double Ethernet card | All | If the device has a double Ethernet option card it is possible to choose which ports are available for connecting with AQtivate software. |
| Clear events | <ul style="list-style-type: none"> - Clear | - | Clears the event history recorded in the AQ-200 device. |
| LCD Contrast | 0...255 | 120 | Changes the contrast of the LCD display. |
| Return to default view | 0...3600s | 0s | If the user navigates to a menu and gives no input after a period of time defined with this parameter, the unit automatically returns to the default view. If set to 0 s, this feature is not in use. |
| LED test | <ul style="list-style-type: none"> - Activated | - | When activated, all LEDs are lit up. LEDs with multiple possible colors blink each color. |
| Reset latches | <ul style="list-style-type: none"> - Reset | - | Resets the latched signals in the logic and the matrix. When a reset command is given, the parameter automatically returns back to "-". |
| Measurement recorder | <ul style="list-style-type: none"> Disabled Enabled | Disabled | Enables the measurement recorder tool, further configured in <i>Tools</i> → <i>Misc</i> → <i>Measurement recorder</i> . |

| Name | Range | Default | Description |
|------------------------------|---|---------|---|
| I/O default object selection | <ul style="list-style-type: none"> • OBJ1 • OBJ2 • OBJ3 • OBJ4 • OBJ5 • OBJ6 • OBJ7 • OBJ8 • OBJ9 • OBJ10 | OBJ1 | "I" and "O" push buttons on the front panel of the device have an indication LED. This parameter defines which objects' status push buttons follow when lighting up the LEDs. |
| Reconfigure mimic | <ul style="list-style-type: none"> • - • Reconfigure | - | Reloads the mimic to the unit. |

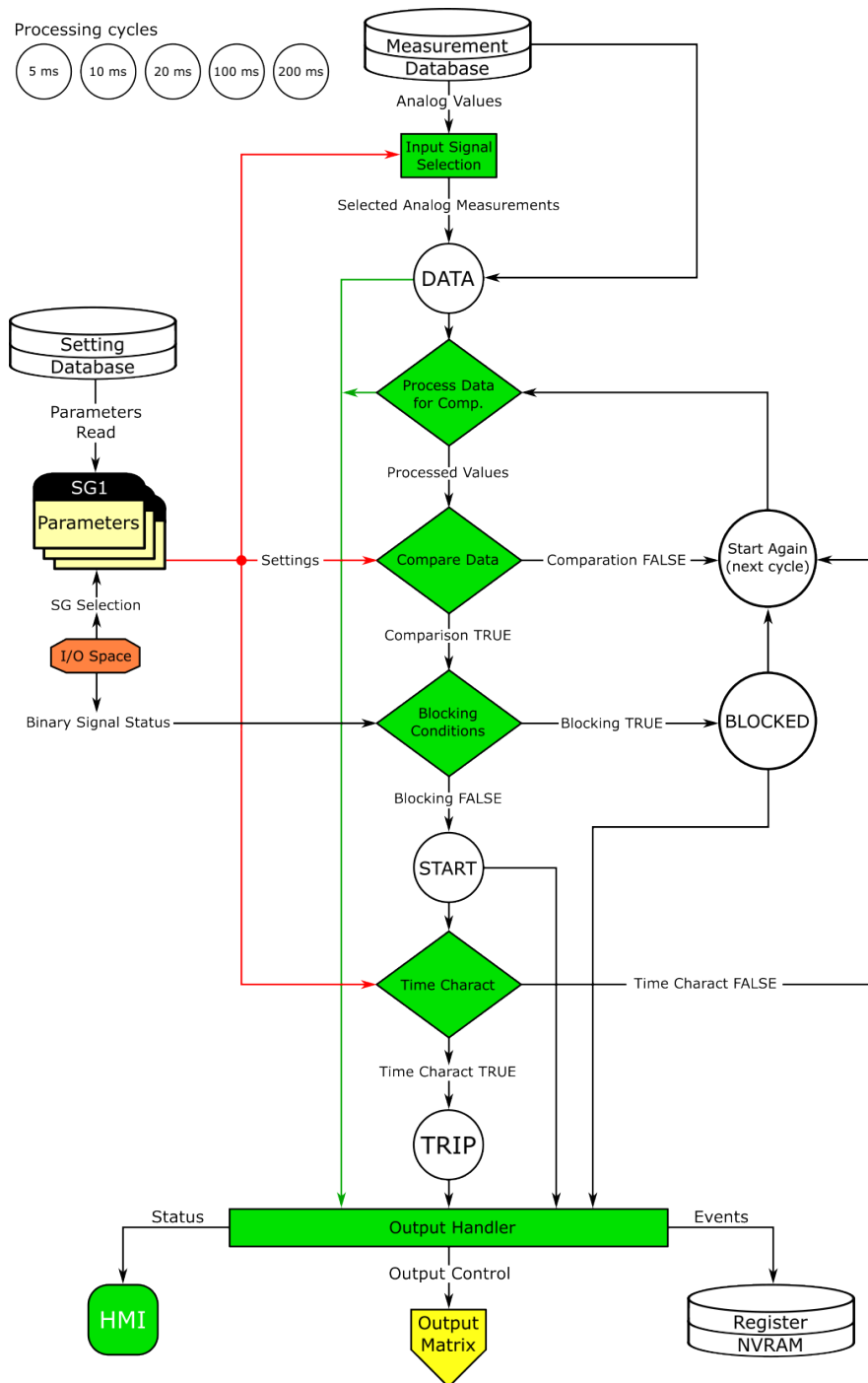
Table. 4.3 - 28. General menu logical inputs.

| Name | Description |
|----------------------------|--|
| Reset last fault registers | Signal set to this point can be used for resetting latest recorded fault register. |

4.4 Protection functions

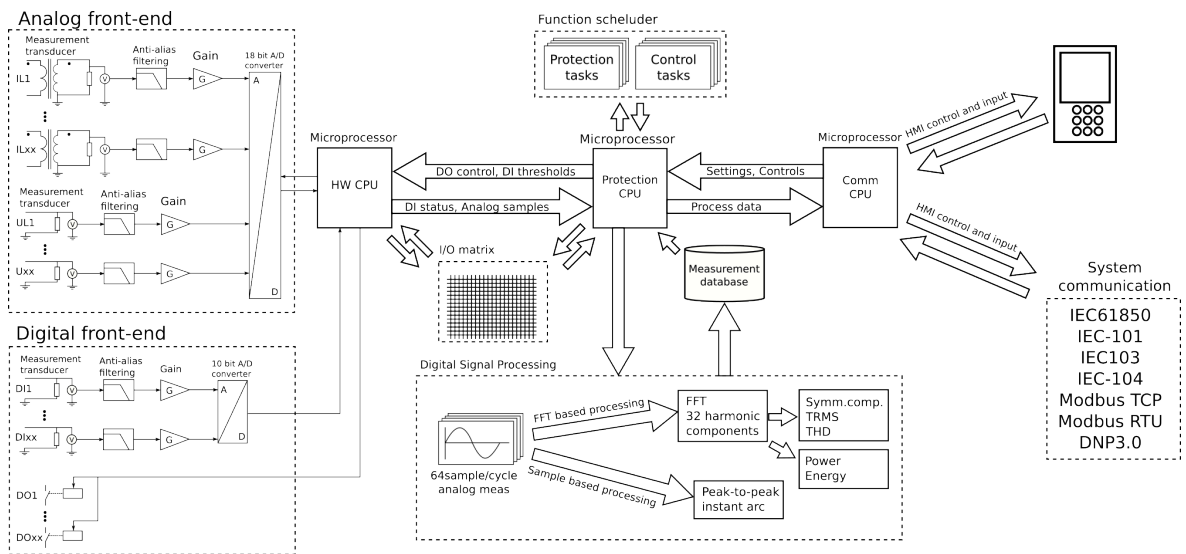
4.4.1 General properties of a protection function

The following flowchart describes the basic structure of any protection function. The basic structure is composed of analog measurement values being compared to the pick-up values and operating time characteristics.



The protection function is run in a completely digital environment with a protection CPU microprocessor which also processes the analog signals transformed into the digital form.

Figure. 4.4.1 - 64. Principle diagram of the protection device platform.



In the following chapters the common functionalities of protection functions are described. If a protection function deviates from this basic structure, the difference is described in the corresponding chapter of the manual.

Pick-up

The X_{set} parameter defines the pick-up level of the function, and this in turn defines the maximum or minimum allowed measured magnitude (in per unit, absolute or percentage value) before the function takes action. The function constantly calculates the ratio between the pick-up parameter set by the user and the measured magnitude (X_m). The reset ratio of 97 % is built into the function and is always relative to the X_{set} value. If a function's pick-up characteristics vary from this description, they are defined in the function section in the manual.

Figure. 4.4.1 - 65. Pick up and reset.

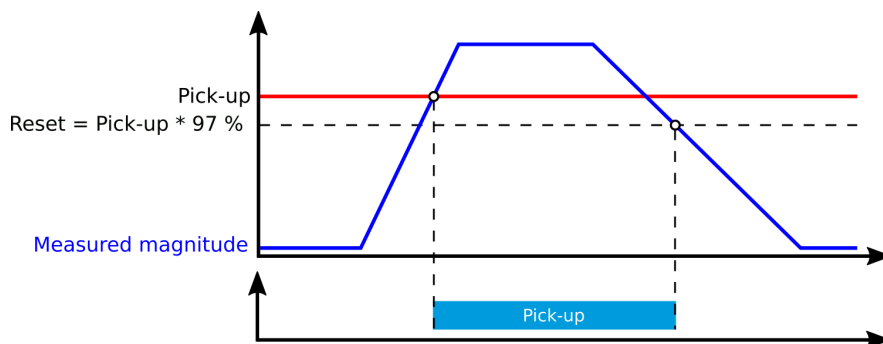
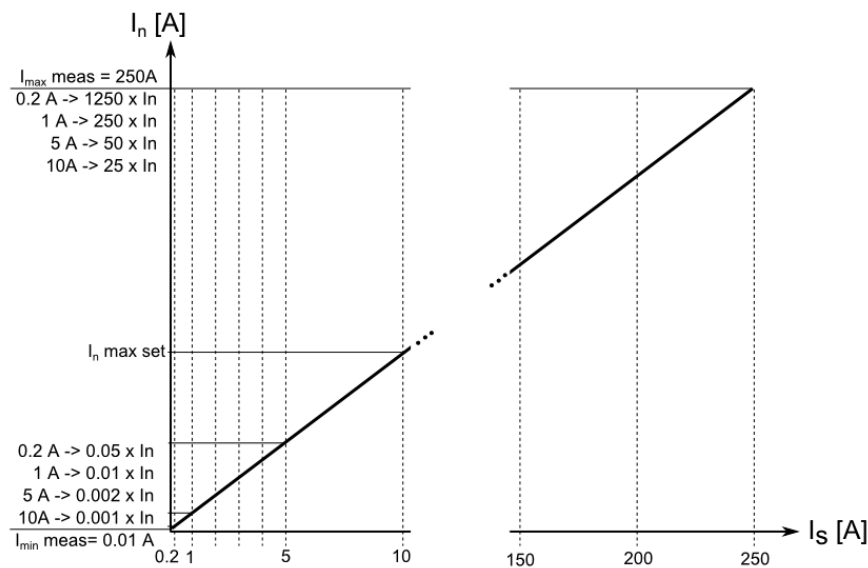


Figure. 4.4.1 - 66. Measurement range in relation to the nominal current.



The I_n magnitude refers to the user set nominal current which can range from 0.2...10 A, typically 0.2 A, 1 A or 5 A. With its own current measurement card, the device will measure secondary currents from 0.001 A up to 250 A. To this relation the pick-up setting in secondary amperes will vary.

Function blocking

The blocking signals are checked in the beginning of each program cycle. A blocking signal is received from the blocking matrix for the function dedicated input. If the blocking signal is not activated when the pick-up element activates, a START signal is generated and the function proceeds to the time characteristics calculation.

If the blocking signal is active when pick-up element activates, a BLOCKED signal is generated and the function will not process the situation further. If the START function has been activated before the blocking signal, it resets and the release time characteristics are processed similarly to when the pick-up signal is reset.

The blocking of the function causes an HMI display event and a time stamped blocking event with information of the startup current values and its fault type to be issued.

The variables users can set are binary signals from the system. The blocking signal needs to reach the device minimum of 5 ms before the set operating delay has passed in order for the blocking to activate in time.

Operating time characteristics for trip and reset

The operating timers' behavior during a function can be set for trip signal and for the release of the function in case the pick-up element is reset before the trip time has been reached. There are three basic operating modes available for the function:

- Instant operation: activates the trip signal with no additional time delay simultaneously with the start signal.
- Definite time operation (DT): activates the trip signal after a user-defined time delay regardless of the measured current as long as the current is above or below the X_{set} value and thus the pick-up element is active (independent time characteristics).
- Inverse definite minimum time (IDMT): activates the trip signal after a time which is in relation to the set pick-up value X_{set} and the measured value X_m (dependent time characteristics).

Both IEC and IEEE/ANSI standard characteristics as well as user settable parameters are available for the IDMT operation. Please note that in the IDMT mode *Definite (Min)* operating time delay is also determines the minimum time for protection tripping (see the figure below). If this function is not desired the parameter should be set to 0 seconds.

Figure. 4.4.1 - 67. Operating time delay: *Definite (Min)* and the minimum for tripping.

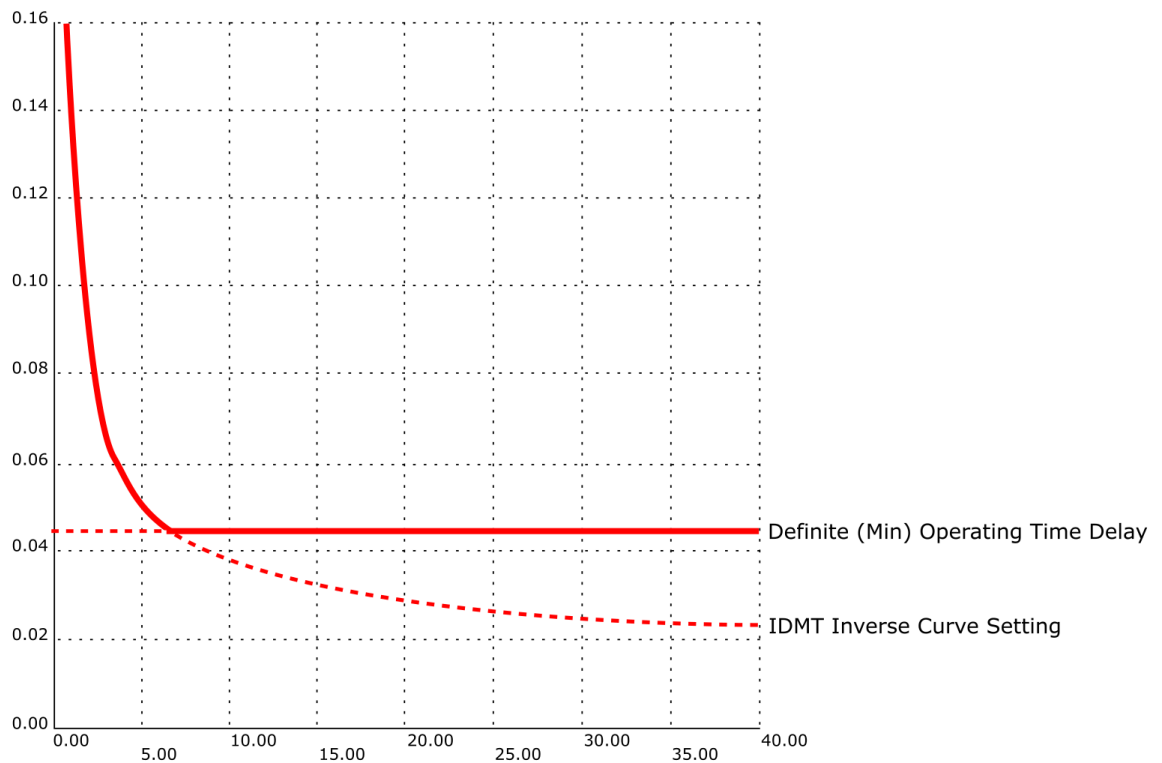


Table. 4.4.1 - 29. Operating time characteristics setting parameters (general).

| Name | Range | Step | Default | Description |
|-------------------------------------|---|--------|---------|--|
| Delay type | <ul style="list-style-type: none"> DT IDMT | - | DT | Selects the delay type for the time counter. The selection is made between dependent (IDMT) and independent (DT) characteristics. |
| Definite (min) operating time delay | 0.000...1800.000s | 0.005s | 0.040s | <p>When the "Delay type" parameter is set to "DT", this parameter acts as the expected operating time for the protection function.</p> <p>When set to 0 s, the stage operates instantaneously without any additional delay. When the parameter is set to 0.005...1800 s, the stage operates as independent delayed.</p> <p>When the "Delay type" parameter has been set to "IDMT", this parameter can be used to determine the minimum operating time for the protection function. Example of this is presented in the figure above.</p> |
| Delay curve series | <ul style="list-style-type: none"> IEC IEEE | - | IEC | <p>Selects whether the delay curve series for an IDMT operation follows either IEC or IEEE/ANSI standard defined characteristics.</p> <p>This setting is active and visible when the "Delay type" parameter is set to "IDMT".</p> |

| Name | Range | Step | Default | Description |
|----------------------------|---|--------|---------|--|
| Delay characteristics IEC | <ul style="list-style-type: none"> NI EI VI LTI Param | - | NI | <p>Selects the IEC standard delay characteristics. The options include the following: Normally Inverse ("NI"), Extremely Inverse ("EI"), Very Inverse ("VI") and Long Time Inverse ("LTI") characteristics. Additionally, the "Param" option allows the tuning of the constants A and B which then allows the setting of characteristics following the same formula as the IEC curves mentioned here.</p> <p>This setting is active and visible when the "Delay type" parameter is set to "IDMT" and the "Delay curve series" parameter is set to "IEC".</p> |
| Delay characteristics IEEE | <ul style="list-style-type: none"> ANSI NI ANSI VI ANSI EI ANSI LTI IEEE MI IEEE VI IEEE EI Param | - | ANSI NI | <p>Selects the IEEE and ANSI standard delay characteristics. The options for ANSI include the following: Normal Inverse ("ANSI NI"), Very Inverse ("ANSI VI"), Extremely inverse ("ANSI EI"), Long time inverse ("ANSI LTI") characteristics. IEEE: Moderately Inverse ("IEEE MI"), Very Inverse ("IEEE VI"), Extremely Inverse ("IEEE EI") characteristics. Additionally, the "Param" option allows the tuning of the constants A, B and C which then allows the setting of characteristics following the same formula as the IEEE curves mentioned here.</p> <p>This setting is active and visible when the "Delay type" parameter is set to "IDMT" and the "Delay curve series" parameter is set to "IEEE".</p> |
| Time dial setting k | 0.01...25.00s | 0.01s | 0.05s | <p>Defines the time dial/multiplier setting for IDMT characteristics.</p> <p>This setting is active and visible when the "Delay type" parameter is set to "IDMT".</p> |
| A | 0.0000...250.0000 | 0.0001 | 0.0860 | <p>Defines the Constant A for IEC/IEEE characteristics. This setting is active and visible when the "Delay type" parameter is set to "IDMT" and the "Delay characteristic" parameter is set to "Param".</p> |
| B | 0.0000...5.0000 | 0.0001 | 0.1850 | <p>Defines the Constant B for IEC/IEEE characteristics. This setting is active and visible when the "Delay type" parameter is set to "IDMT" and the "Delay characteristic" parameter is set to "Param".</p> |
| C | 0.0000...250.0000 | 0.0001 | 0.0200 | <p>Defines the Constant C for IEEE characteristics. This setting is active and visible when the "Delay type" parameter is set to "IDMT" and the "Delay characteristic" parameter is set to "Param".</p> |

Figure. 4.4.1 - 68. Inverse operating time formulas for IEC and IEEE standards.

| IEC | IEEE/ANSI | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|--|---|---------|-------|--------------------------------|------|----------------------------------|---------------------------------|-------|------|----------------------------|-------|-------|----------------------------------|---------------------------------|------|---|------|---|---|---|--------------------------------|-------|--------|-------|----------------------------|-------|--------|---|---------------------------------|------|---------|---|----------------------------------|-------|-------|---|
| $t = \frac{kA}{\left(\frac{I_m}{I_{set}}\right)^B - 1}$ | $t = k \left(\frac{A}{\left(\frac{I_m}{I_{set}}\right)^C - 1} + B \right)$ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| <p>t = Operating delay (s) k = Time dial setting I_m = Measured maximum current I_{set} = Pick-up setting A = Operating characteristics constant B = Operating characteristics constant</p> | <p>t = Operating delay (s) k = Time dial setting I_m = Measured maximum current I_{set} = Pick-up setting A = Operating characteristics constant B = Operating characteristics constant C = Operating characteristics constant</p> | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Standard delays IEC constants | Standard delays ANSI constants | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| <table><tr><th>Type</th><th>A</th><th>B</th></tr><tr><td>Normally Inverse (<i>NI</i>)</td><td>0,14</td><td>0,02</td></tr><tr><td>Extremely Inverse (<i>EI</i>)</td><td>80</td><td>2</td></tr><tr><td>Very Inverse (<i>VI</i>)</td><td>13,5</td><td>1</td></tr><tr><td>Long Time Inverse (<i>LTI</i>)</td><td>120</td><td>1</td></tr></table> | Type | A | B | Normally Inverse (<i>NI</i>) | 0,14 | 0,02 | Extremely Inverse (<i>EI</i>) | 80 | 2 | Very Inverse (<i>VI</i>) | 13,5 | 1 | Long Time Inverse (<i>LTI</i>) | 120 | 1 | <table><tr><th>Type</th><th>A</th><th>B</th><th>C</th></tr><tr><td>Normally Inverse (<i>NI</i>)</td><td>8,934</td><td>0,1797</td><td>2,094</td></tr><tr><td>Very Inverse (<i>VI</i>)</td><td>3,922</td><td>0,0982</td><td>2</td></tr><tr><td>Extremely Inverse (<i>EI</i>)</td><td>5,64</td><td>0,02434</td><td>2</td></tr><tr><td>Long Time Inverse (<i>LTI</i>)</td><td>5,614</td><td>2,186</td><td>1</td></tr></table> | Type | A | B | C | Normally Inverse (<i>NI</i>) | 8,934 | 0,1797 | 2,094 | Very Inverse (<i>VI</i>) | 3,922 | 0,0982 | 2 | Extremely Inverse (<i>EI</i>) | 5,64 | 0,02434 | 2 | Long Time Inverse (<i>LTI</i>) | 5,614 | 2,186 | 1 |
| Type | A | B | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Normally Inverse (<i>NI</i>) | 0,14 | 0,02 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Extremely Inverse (<i>EI</i>) | 80 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Very Inverse (<i>VI</i>) | 13,5 | 1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Long Time Inverse (<i>LTI</i>) | 120 | 1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Type | A | B | C | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Normally Inverse (<i>NI</i>) | 8,934 | 0,1797 | 2,094 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Very Inverse (<i>VI</i>) | 3,922 | 0,0982 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Extremely Inverse (<i>EI</i>) | 5,64 | 0,02434 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Long Time Inverse (<i>LTI</i>) | 5,614 | 2,186 | 1 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | Standard delays IEEE constants | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | <table><tr><th>Type</th><th>A</th><th>B</th><th>C</th></tr><tr><td>Moderately Inverse (<i>MI</i>)</td><td>0,0515</td><td>0,114</td><td>0,02</td></tr><tr><td>Very Inverse (<i>VI</i>)</td><td>19,61</td><td>0,491</td><td>2</td></tr><tr><td>Extremely Inverse (<i>EI</i>)</td><td>28,2</td><td>0,1217</td><td>2</td></tr></table> | Type | A | B | C | Moderately Inverse (<i>MI</i>) | 0,0515 | 0,114 | 0,02 | Very Inverse (<i>VI</i>) | 19,61 | 0,491 | 2 | Extremely Inverse (<i>EI</i>) | 28,2 | 0,1217 | 2 | | | | | | | | | | | | | | | | | | | |
| Type | A | B | C | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Moderately Inverse (<i>MI</i>) | 0,0515 | 0,114 | 0,02 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Very Inverse (<i>VI</i>) | 19,61 | 0,491 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Extremely Inverse (<i>EI</i>) | 28,2 | 0,1217 | 2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

Non-standard delay characteristics

In addition to the previously mentioned delay characteristics, some functions also have delay characteristics that deviate from the IEC or IEEE standards. These functions are the following:

- overcurrent stages
- residual overcurrent stages
- directional overcurrent stages
- directional residual overcurrent stages.

The setting parameters and their ranges are documented in the chapters of the respective function blocks.

Table. 4.4.1 - 30. Inverse operating time formulas for nonstandard characteristics.

| RI-type | RD-type |
|---|---|
| Used to get time grading with mechanical relays. | Mostly used in earth fault protection which grants selective tripping even in non-directional protection. NOTE: when "k" has been set lower than 0.3 calculated operation time can be lower than 0 seconds with some measurement values. In these cases operation time will be instant. |
| $t = \frac{k}{0.339 - 0.236 * \frac{I_{set}}{I_m}}$ | $t = 5.8 - 1.35 * \ln \left(\frac{I_m}{k * I_{set}} \right)$ |

| RI-type | RD-type |
|---|---|
| t = Operating delay (s) k = Time dial setting I_m = Measured maximum current I_{set} = Pick-up setting | t = Operating delay (s) k = Time dial setting I_m = Measured maximum current I_{set} = Pick-up setting |

**NOTICE!**

When using RD-type and "k" has been set lower than 0.3 calculated operation time can be lower than 0 seconds with some measurement values. In these cases operation time will be instant.

Table. 4.4.1 - 31. Setting parameters for reset time characteristics.

| Name | Range | Step | Default | Description |
|---|---|--------|---------|--|
| Delayed pick-up release | <ul style="list-style-type: none"> No Yes | - | Yes | Resetting characteristics selection (either time-delayed or instant) after the pick-up element is released. If activated, the START signal is reset after a set release time delay. |
| Release time delay | 0.000...150.000s | 0.005s | 0.06s | Resetting time. The time allowed between pick-ups if the pick-up has not led into a trip operation. If the "Delayed pick-up release" setting is active, the START signal is held on for the duration of the timer. |
| Op.Time calculation reset after release time | <ul style="list-style-type: none"> No Yes | - | Yes | Operating timer resetting characteristics selection. When active, the operating time counter is reset after a set release time if the pick-up element is not activated during this time. When disabled, the operating time counter is reset directly after the pick-up element is reset. |
| Continue time calculation during release time | <ul style="list-style-type: none"> No Yes | - | No | Time calculation characteristics selection. If activated, the operating time counter continues until a set release time even if the pick-up element is reset. |

The behavior of the stages with different release time configurations are presented in the figures below.

Figure. 4.4.1 - 69. No delayed pick-up release.

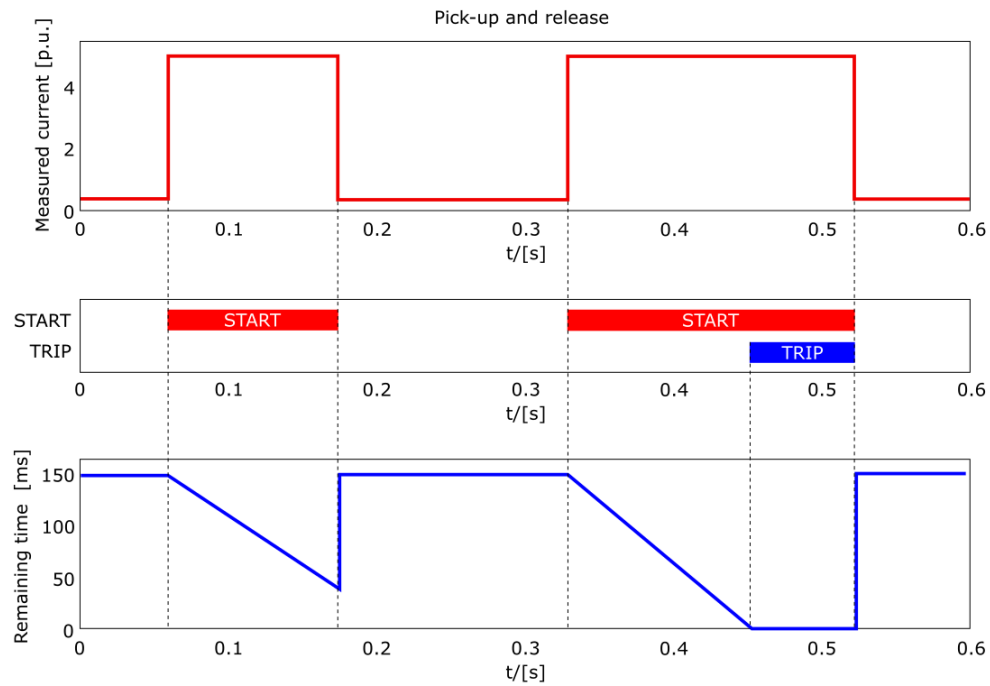
Delayed pick-up release: Disabled

Figure. 4.4.1 - 70. Delayed pick-up release, delay counter is reset at signal drop-off.

Delayed pick-up release: Enabled

Op.time calc reset after release time: Disabled

Continue time calculation during release time: Disabled

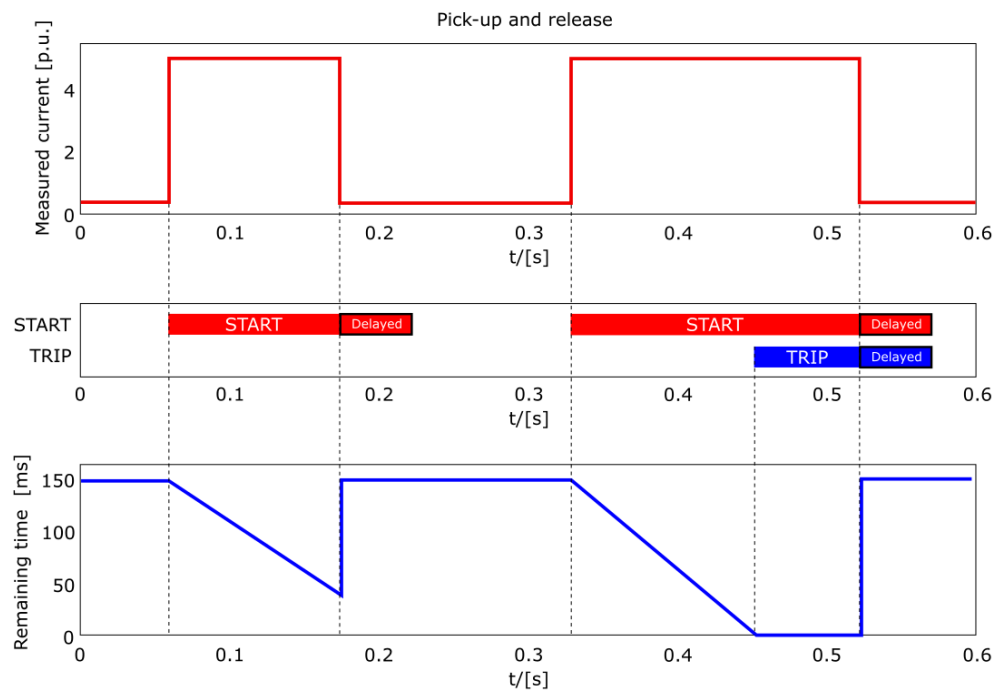


Figure. 4.4.1 - 71. Delayed pick-up release, delay counter value is held during the release time.

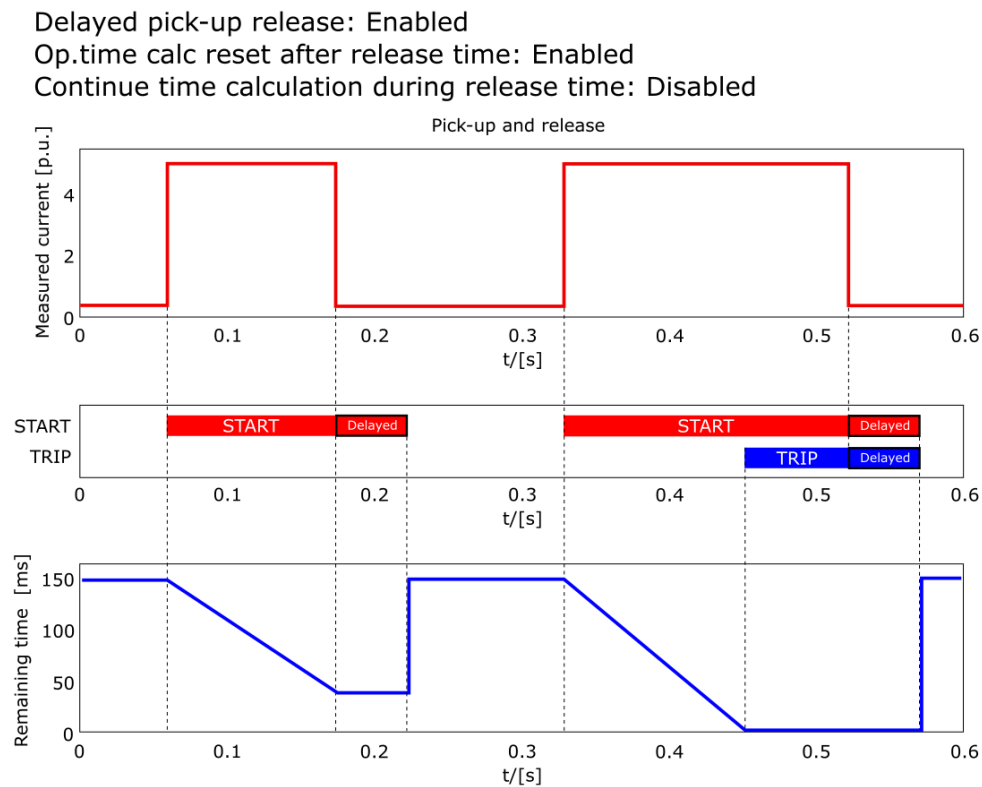
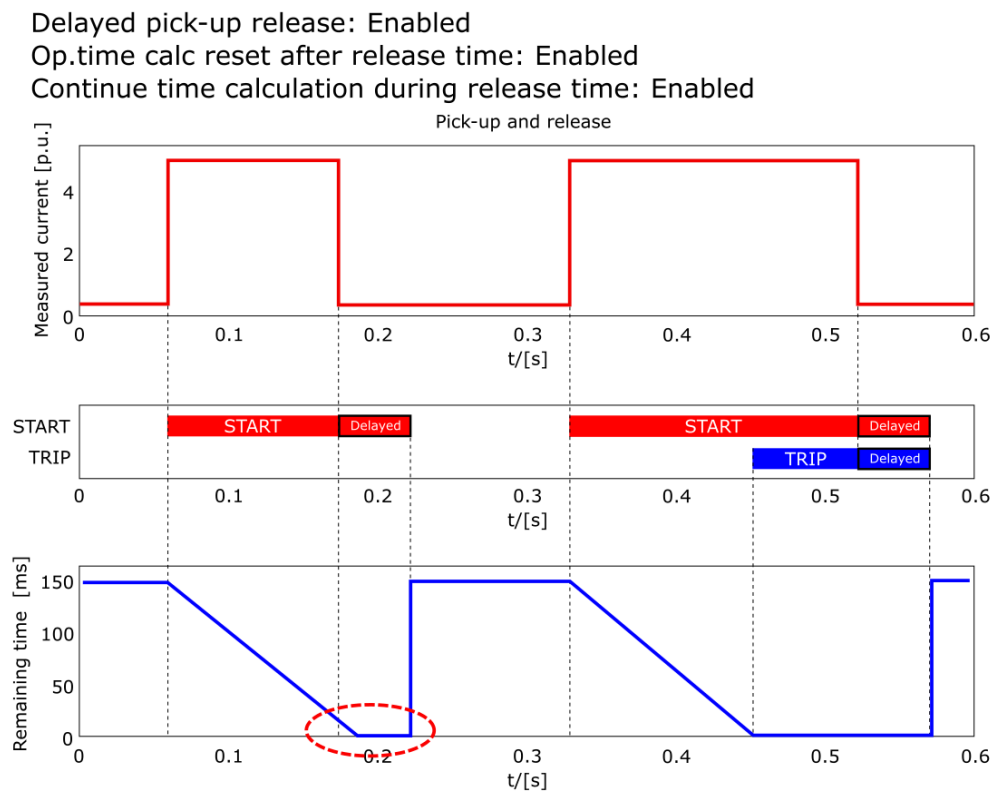


Figure. 4.4.1 - 72. Delayed pick-up release, delay counter value is decreasing during the release time.



The resetting characteristics can be set according to the application. The default setting is delayed 60 ms and the time calculation is held during the release time.

When using the release delay option where the operating time counter is calculating the operating time during the release time, the function will not trip if the input signal is not activated again during the release time counting.

Stage forcing

It is possible to test the logic, event processing and the operation of the device's logic by controlling the state of the protection functions manually without injecting any current into the device with stage forcing. To enable *Stage forcing* set the *Enable stage forcing* to ENABLED in the *General* menu. After this it is possible to control the status of a protection function (Normal, Start, Trip, Blocked etc.) in the *Info* page of the function.



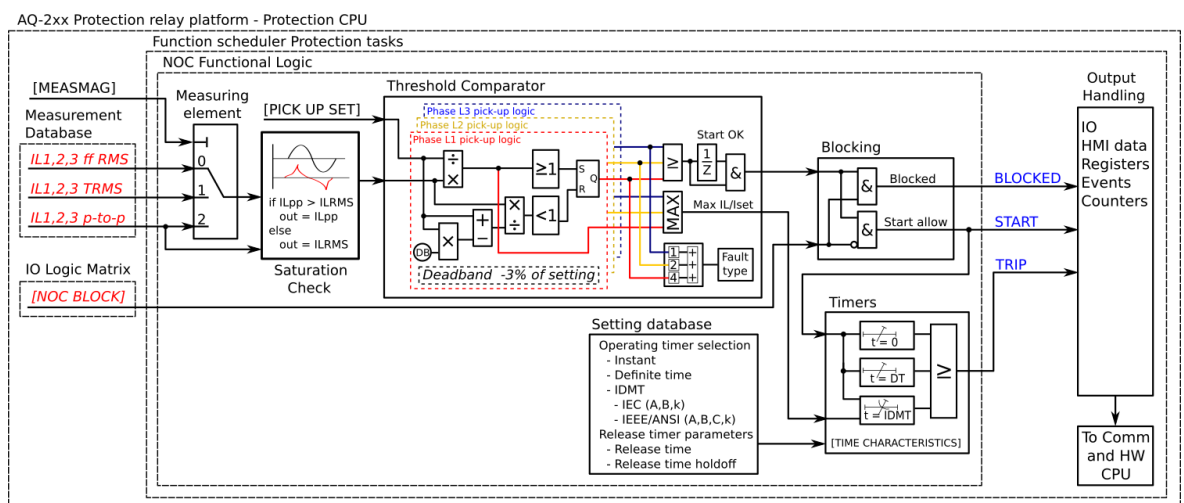
NOTICE!

When *Stage forcing* is enabled protection functions will also change state through user input. Injected currents/voltages also affect the behavior of the device. Regardless, it is recommended to disable *Stage Forcing* after testing has ended.

4.4.2 Non-directional overcurrent protection ($I>$; 50/51)

The non-directional overcurrent function is used for instant and time-delayed overcurrent and short-circuit protection. The function is used for one-phase, two-phase or three-phase overcurrent and short circuit protection. The function offers four (4) independent stages. The operating decisions are based on phase current magnitude, constantly measured by the function.

Figure. 4.4.2 - 73. Simplified function block diagram of the $I>$ function.



Measured input

The function block uses phase current measurement values. The user can select the monitored magnitude to be equal either to RMS values (fundamental frequency component), to TRMS values from the whole harmonic spectrum of 32 components, or to peak-to-peak values.

Table. 4.4.2 - 32. Measurement inputs of the $I>$ function.

| Signal | Description | Time base |
|-------------|---|-----------|
| $I_{L1}RMS$ | Fundamental frequency component of phase L1 (A) current measurement | 5ms |
| $I_{L2}RMS$ | Fundamental frequency component of phase L2 (B) current measurement | 5ms |

| Signal | Description | Time base |
|----------------------|---|-----------|
| I _{L3} RMS | Fundamental frequency component of phase L3 (C) current measurement | 5ms |
| I _{L1} TRMS | TRMS measurement of phase L1 (A) current | 5ms |
| I _{L2} TRMS | TRMS measurement of phase L2 (B) current | 5ms |
| I _{L3} TRMS | TRMS measurement of phase L3 (C) current | 5ms |
| I _{L1} PP | Peak-to-peak measurement of phase L1 (A) current | 5ms |
| I _{L2} PP | Peak-to-peak measurement of phase L2 (B) current | 5ms |
| I _{L3} PP | Peak-to-peak measurement of phase L3 (C) current | 5ms |

General settings

The following general settings define the general behavior of the function. These settings are static i.e. it is not possible to change them by editing the setting group.

Table. 4.4.2 - 33. General settings of the function.

| Name | Range | Default | Description |
|-------------------------------|---|--|--|
| Setting control from comm bus | <ul style="list-style-type: none"> Disabled Allowed | <ul style="list-style-type: none"> Disabled | Activating this parameter allows changing the pick-up level of the protection stage via SCADA. |
| I> force status to | <ul style="list-style-type: none"> Normal Start Trip Blocked Start A Start B Start C Trip A Trip B Trip C Start AB Start BC Start CA Start ABC Trip AB Trip BC Trip CA Trip ABC | <ul style="list-style-type: none"> Normal | Force the status of the function. Visible only when <i>Enable stage forcing</i> parameter is enabled in <i>General</i> menu. |
| Measured magnitude | <ul style="list-style-type: none"> RMS TRMS Peak-to-peak | <ul style="list-style-type: none"> RMS | Defines which available measured magnitude is used by the function. |

Pick-up settings

The I_{set} setting parameter controls the pick-up of the $I>$ function. This defines the maximum allowed measured current before action from the function. The function constantly calculates the ratio between the I_{set} and the measured magnitude (I_m) for each of the three phases. The reset ratio of 97 % is built into the function and is always relative to the I_{set} value. The setting value is common for all measured phases, and when the I_m exceeds the I_{set} value (in single, dual or all phases) it triggers the pick-up operation of the function.

Setting group selection controls the operating characteristics of the function, i.e. the user or user-defined logic can change function parameters while the function is running.

Table. 4.4.2 - 34. Pick-up settings.

| Name | Range | Step | Default | Description |
|-----------|-------------------------------|-------------------|-------------------|-----------------|
| I_{set} | $0.10 \dots 50.00 \times I_n$ | $0.01 \times I_n$ | $1.20 \times I_n$ | Pick-up setting |

Read-only parameters

The function's *Info* page displays useful, real-time information on the state of the protection function. It is accessed either through the device's HMI display, or through the setting tool software when it is connected to the device and its Live Edit mode is active.

Table. 4.4.2 - 35. Information displayed by the function.

| Name | Range | Step | Description |
|-------------------------|---|----------|---|
| $I>$ condition | <ul style="list-style-type: none"> Normal Start Trip Blocked | - | Displays status of the protection function. |
| $I>$ phases condition | <ul style="list-style-type: none"> Normal Start A Start B Start C Trip A Trip B Trip C Start AB Start BC Start CA Start ABC Trip AB Trip BC Trip CA Trip ABC | - | Displays the status of phases individually. |
| Expected operating time | $0.000 \dots 1800.000s$ | $0.005s$ | Displays the expected operating time when a fault occurs. When IDMT mode is used, the expected operating time depends on the measured highest phase current value. If the measured current changes during a fault, the expected operating time changes accordingly. |
| Time remaining to trip | $-1800.000 \dots 1800.000s$ | $0.005s$ | When the function has detected a fault and counts down time towards a trip, this displays how much time is left before tripping occurs. |

| Name | Range | Step | Description |
|----------------------------------|----------------|------|---|
| I_{meas}/I_{set} at the moment | 0.00...1250.00 | 0.01 | The ratio between the highest measured phase current and the pick-up value. |

Function blocking

The block signal is checked in the beginning of each program cycle. The blocking signal is received from the blocking matrix in the function's dedicated input. Additionally, the function includes an internal inrush harmonic blocking option which is applied according to the parameters set by the user. If the blocking signal is not activated when the pick-up element activates, a START signal is generated and the function proceeds to the time characteristics calculation.

Table. 4.4.2 - 36. Internal inrush harmonic blocking settings.

| Name | Range | Step | Default | Description |
|---|---|------------------|--|---|
| Inrush harmonic blocking (internal-only trip) | <ul style="list-style-type: none"> No Yes | - | <ul style="list-style-type: none"> No | Enables and disables the 2 nd harmonic blocking. |
| 2 nd harmonic blocking limit (I_{harm}/I_{fund}) | 0.10...50.00% I_{fund} | 0.01% I_{fund} | 0.01% I_{fund} | Defines the limit of the 2 nd harmonic blocking. |

If the blocking signal is active when the pick-up element activates, a BLOCKED signal is generated and the function does not process the situation further. If the START function has been activated before the blocking signal, it resets and the release time characteristics are processed similarly to when the pick-up signal is reset.

The variables the user can set are binary signals from the system. The blocking signal needs to reach the device minimum of 5 ms before the set operating delay has passed in order for the blocking to activate in time.

Operating time characteristics for trip and reset

This function supports definite time delay (DT) and inverse definite minimum time delay (IDMT). For detailed information on these delay types please refer to the chapter ["General properties of a protection function"](#) and its section ["Operating time characteristics for trip and reset"](#).

Events and registers

The non-directional overcurrent function (abbreviated "NOC" in event block names) generates events and registers from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

The function's output can be used for direct I/O controlling and user logic programming. The function also provides a resettable cumulative counter for the START, TRIP and BLOCKED events.

Table. 4.4.2 - 37. Event messages.

| Event block name | Event names |
|------------------|-------------|
| NOC1...NOC4 | Start ON |
| NOC1...NOC4 | Start OFF |

| Event block name | Event names |
|------------------|-------------------|
| NOC1...NOC4 | Trip ON |
| NOC1...NOC4 | Trip OFF |
| NOC1...NOC4 | Block ON |
| NOC1...NOC4 | Block OFF |
| NOC1...NOC4 | Phase A Start ON |
| NOC1...NOC4 | Phase A Start OFF |
| NOC1...NOC4 | Phase B Start ON |
| NOC1...NOC4 | Phase B Start OFF |
| NOC1...NOC4 | Phase C Start ON |
| NOC1...NOC4 | Phase C Start OFF |
| NOC1...NOC4 | Phase A Trip ON |
| NOC1...NOC4 | Phase A Trip OFF |
| NOC1...NOC4 | Phase B Trip ON |
| NOC1...NOC4 | Phase B Trip OFF |
| NOC1...NOC4 | Phase C Trip ON |
| NOC1...NOC4 | Phase C Trip OFF |

The function registers its operation into the last twelve (12) time-stamped registers; this information is available for all provided instances separately. The register of the function records the ON event process data for START, TRIP or BLOCKED. The table below presents the structure of the function's register content.

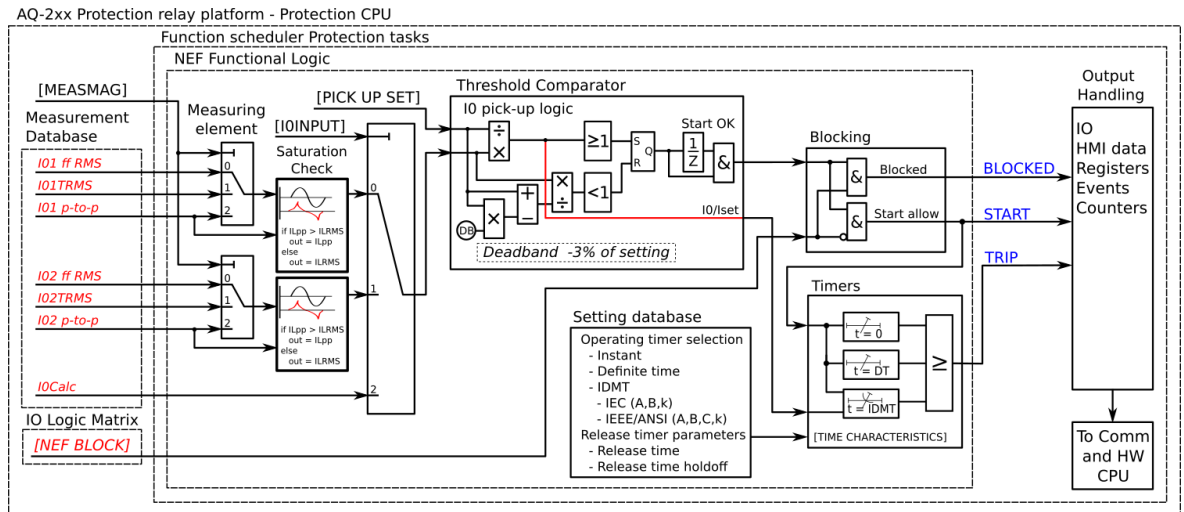
Table. 4.4.2 - 38. Register content.

| Name | Description |
|----------------------|-----------------------------|
| Date and time | dd.mm.yyyy hh:mm:ss.mss |
| Event | Event name |
| Fault type | L1-E...L1-L2-L3 |
| Pre-trigger current | Start/Trip -20ms current |
| Fault current | Start/Trip current |
| Pre-fault current | Start -200ms current |
| Trip time remaining | 0 ms...1800s |
| Setting group in use | Setting group 1...8 active. |

4.4.3 Non-directional earth fault protection ($I_{0>}$; 50N/51N)

The non-directional earth fault function is used for instant and time-delayed earth fault protection. The number of stages in the function depend on the device model. The operating characteristics are based on the selected neutral current magnitude which the function measures constantly.

Figure. 4.4.3 - 74. Simplified function block diagram of the $I_{0>}$ function.



Measured input

The function block uses residual current measurement values. The available analog measurement channels are I_{01} and I_{02} (residual current measurement) and I_{0Calc} (residual current calculated from phase current). The user can select the monitored magnitude to be equal either to RMS values (fundamental frequency component), to TRMS values from the whole harmonic spectrum of 32 components, or to peak-to-peak values.

Table. 4.4.3 - 39. Measurement inputs of the $I_{0>}$ function.

| Signal | Description | Time base |
|--------------|--|-----------|
| $I_{01}RMS$ | Fundamental frequency component of coarse residual current measurement input I_{01} | 5 ms |
| $I_{01}TRMS$ | TRMS measurement of coarse residual current measurement input I_{01} | 5 ms |
| $I_{01}PP$ | Peak-to-peak measurement of coarse residual current measurement input I_{01} | 5 ms |
| $I_{02}RMS$ | Fundamental frequency component of sensitive residual current measurement input I_{02} | 5 ms |
| $I_{02}TRMS$ | TRMS measurement of coarse sensitive current measurement input I_{02} | 5 ms |
| $I_{02}PP$ | Peak-to-peak measurement of sensitive residual current measurement input I_{02} | 5 ms |
| I_{0Calc} | Fundamental frequency component of the calculated zero sequence current calculated from the three phase currents | 5 ms |

General settings

The following general settings define the general behavior of the function. These settings are static i.e. it is not possible to change them by editing the setting group.

Table. 4.4.3 - 40. General settings of the function.

| Name | Range | Default | Description |
|-------------------------------|--|----------|--|
| Setting control from comm bus | <ul style="list-style-type: none"> Disabled Allowed | Disabled | Activating this parameter permits changing the pick-up level of the protection stage via SCADA. |
| I0> force status to | <ul style="list-style-type: none"> Normal Start Trip Blocked | Normal | Force the status of the function. Visible only when <i>Enable stage forcing</i> parameter is enabled in <i>General</i> menu. |
| Measured magnitude | <ul style="list-style-type: none"> RMS TRMS Peak-to-peak | RMS | Defines which available measured magnitude is used by the function. This parameter is available when "Input selection" has been set to "I01" or "I02". |
| Input selection | <ul style="list-style-type: none"> I01 I02 I0Calc | I01 | Defines which measured residual current is used by the function. |

Pick-up settings

The I_{0set} setting parameter controls the the pick-up of the I0> function. This defines the maximum allowed measured current before action from the function. The function constantly calculates the ratio between the I_{0set} and the measured magnitude (I_m) for each of the three phases. The reset ratio of 97 % is built into the function and is always relative to the I_{0set} value. The setting value is common for all measured phases. When the I_m exceeds the I_{0set} value (in single, dual or all phases) it triggers the pick-up operation of the function.

Setting group selection controls the operating characteristics of the function, i.e. the user or user-defined logic can change function parameters while the function is running.

Table. 4.4.3 - 41. Pick-up settings.

| Name | Range | Step | Default | Description |
|------------|---------------------------------|---------------------|-------------------|-----------------|
| I_{0set} | $0.0001 \dots 40.00 \times I_n$ | $0.0001 \times I_n$ | $1.20 \times I_n$ | Pick-up setting |

Read-only parameters

The function's *Info* page displays useful, real-time information on the state of the protection function. It is accessed either through the device's HMI display, or through the setting tool software when it is connected to the device and its Live Edit mode is active.

Table. 4.4.3 - 42. Information displayed by the function.

| Name | Range | Step | Description |
|---------------|--|------|---|
| I0> condition | <ul style="list-style-type: none"> Normal Start Trip Blocked | - | Displays status of the protection function. |

| Name | Range | Step | Description |
|---|---|----------|---|
| Detected I0 angle | -360.00...360.00 deg | 0.01 deg | Angle of I0 against reference. If phase voltages are available, positive sequence voltage angle is used as reference. If voltages are not available, positive sequence current angle is used as reference. |
| Detected fault type | <ul style="list-style-type: none"> - A-G-R B-G-F C-G-R A-G-F B-G-R C-G-F | - | Displays the detected fault type and direction of previous fault. "A/B/C" stand for one of the three phases. "G" stands for "ground". "F" stands for "forward" direction and "R" stands for "reverse" direction. |
| Expected operating time | -1800.000...1800.000 s | 0.005 s | Displays the expected operating time when a fault occurs. When IDMT mode is used, the expected operating time depends on the measured current value. If the measured current changes during a fault, the expected operating time changes accordingly. |
| Time remaining to trip | 0.000...1800.000 s | 0.005 s | When the function has detected a fault and counts down time towards a trip, this displays how much time is left before tripping occurs. |
| I _{meas} /I _{set} at the moment | 0.00...1250.00 | 0.01 | The ratio between the measured current and the pick-up value. |

Function blocking

The block signal is checked in the beginning of each program cycle. The blocking signal is received from the blocking matrix in the function's dedicated input. Additionally, the function includes an internal inrush harmonic blocking option which is applied according to the parameters set by the user. If the blocking signal is not activated when the pick-up element activates, a START signal is generated and the function proceeds to the time characteristics calculation.

Table. 4.4.3 - 43. Internal inrush harmonic blocking settings.

| Name | Range | Step | Default | Description |
|--|---|------------------------|------------------------|--|
| Inrush harmonic blocking (internal-only trip) | <ul style="list-style-type: none"> No Yes | - | No | 2 nd harmonic blocking enable/disable |
| 2 nd harmonic block limit (I _{harm} /I _{fund}) | 0.10...50.00%I _{fund} | 0.01%I _{fund} | 0.01%I _{fund} | 2 nd harmonic blocking limit |

If the blocking signal is active when the pick-up element activates, a BLOCKED signal is generated and the function does not process the situation further. If the START function has been activated before the blocking signal, it resets and processes the release time characteristics similarly to when the pick-up signal is reset.

The variables the user can set are binary signals from the system. The blocking signal needs to reach the device minimum of 5 ms before the set operating delay has passed in order for the blocking to activate in time.

Operating time characteristics for trip and reset

This function supports definite time delay (DT) and inverse definite minimum time delay (IDMT). For detailed information on these delay types please refer to the chapter "[General properties of a protection function](#)" and its section "[Operating time characteristics for trip and reset](#)".

Events and registers

The non-directional earth fault function (abbreviated "NEF" in event block names) generates events and registers from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

The function's outputs can be used for direct I/O controlling and user logic programming. The function also provides a resettable cumulative counter for the START, TRIP and BLOCKED events.

The function offers four (4) independent stages; the events are segregated for each stage operation.

Table. 4.4.3 - 44. Event messages.

| Event block name | Event names |
|------------------|-------------|
| NEF1...NEF4 | Start ON |
| NEF1...NEF4 | Start OFF |
| NEF1...NEF4 | Trip ON |
| NEF1...NEF4 | Trip OFF |
| NEF1...NEF4 | Block ON |
| NEF1...NEF4 | Block OFF |

The function registers its operation into the last twelve (12) time-stamped registers. The register of the function records the ON event process data for START, TRIP or BLOCKED. The table below presents the structure of the function's register content.

Table. 4.4.3 - 45. Register content.

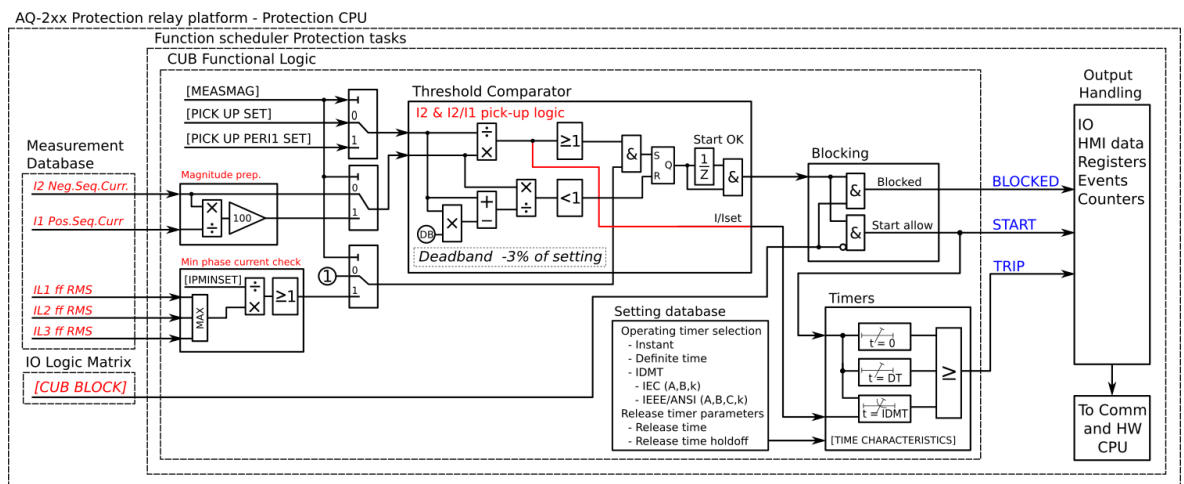
| Name | Description |
|----------------------|-----------------------------|
| Date and time | dd.mm.yyyy hh:mm:ss.mss |
| Event | Event name |
| Fault type | A-G-R...C-G-F |
| Pre-trigger current | Start/Trip -20ms current |
| Fault current | Start/Trip current |
| Pre-fault current | Start -200ms current |
| Trip time remaining | 0 ms...1800s |
| Setting group in use | Setting group 1...8 active. |

4.4.4 Negative sequence overcurrent/ phase current reversal/ current unbalance protection ($I_{2>}$; 46/46R/46L)

The current unbalance function is used for instant and time-delayed unbalanced network protection and for detecting broken conductors. The number of stages in the function depends on the device model. The operating decisions are based on negative and positive sequence current magnitudes which the function constantly measures. In the broken conductor mode ($I_{2/I1}$) the minimum allowed loading current is also monitored in the phase current magnitudes.

There are two possible operating modes available: the I_2 mode monitors the negative sequence current, while the $I_{2/I1}$ mode monitors the ratio between the negative sequence current and the positive sequence current. The device calculates the symmetrical component magnitudes in use from the phase current inputs I_{L1} , I_{L2} and I_{L3} . The zero sequence current is also recorded into the registers as well as the angles of the positive, negative and zero sequence currents in order to better verify any fault cases.

Figure. 4.4.4 - 75. Simplified function block diagram of the $I_{2>}$ function.



Measured input

The function block uses positive and negative sequence currents calculated from the phase current measurement channels. In the broken conductor mode ($I_{2/I1}$) the function also uses fundamental frequency component of all phase currents to check the minimum current. Zero sequence and component sequence angles are used for fault registering and for fault analysis processing.

Table. 4.4.4 - 46. Measurement inputs of the $I_{2>}$ function.

| Signal | Description | Time base |
|--------|-------------------------------------|-----------|
| I1 | Positive sequence current magnitude | 5 ms |
| I2 | Negative sequence current magnitude | 5 ms |
| IZ | Zero sequence current magnitude | 5 ms |
| I1 ANG | Positive sequence current angle | 5 ms |
| I2 ANG | Negative sequence current angle | 5 ms |
| IZ ANG | Zero sequence current angle | 5 ms |

| Signal | Description | Time base |
|-------------|---|-----------|
| I_{L1RMS} | Fundamental frequency component of phase L1 (A) current measurement | 5 ms |
| I_{L2RMS} | Fundamental frequency component of phase L2 (B) current measurement | 5 ms |
| I_{L3RMS} | Fundamental frequency component of phase L3 (C) current measurement | 5 ms |

General settings

The following general settings define the general behavior of the function. These settings are static i.e. it is not possible to change them by editing the setting group.

Table. 4.4.4 - 47. General settings of the function.

| Name | Range | Default | Description |
|---------------------|--|---------|--|
| I2> force status to | <ul style="list-style-type: none"> Normal Start Trip Blocked | Normal | Force the status of the function. Visible only when <i>Enable stage forcing</i> parameter is enabled in <i>General</i> menu. |
| Measured magnitude | <ul style="list-style-type: none"> I2pu I2/I1 | I2pu | Defines whether the ratio between the positive and the negative sequence currents are supervised or whether only the negative sequence is used in detecting unbalance. |

Pick-up settings

The setting parameters I_{2set} and $I_{2/I1set}$ control the the pick-up of the I2> function. They define the maximum allowed measured negative sequence current or the negative/positive sequence current ratio before action from the function. The function constantly calculates the ratio between the I_{set} and the measured magnitude (I_m). The reset ratio of 97 % is built into the function and is always relative to the I_{xset} value. The reset ratio is the same for both modes.

Setting group selection controls the operating characteristics of the function, i.e. the user or user-defined logic can change function parameters while the function is running.

Table. 4.4.4 - 48. Pick-up settings.

| Name | Range | Step | Default | Description |
|----------|---------------------|-------------|------------|--------------------------------|
| I2set | 0.01...40.00× I_n | 0.01× I_n | 0.2× I_n | Pick-up setting for I2 mode |
| I2/I1set | 1...200% | 0.01% | 20% | Pick-up setting for I2/I1 mode |

Read-only parameters

The function's *Info* page displays useful, real-time information on the state of the protection function. It is accessed either through the device's HMI display, or through the setting tool software when it is connected to the device and its Live Edit mode is active.

Table. 4.4.4 - 49. Information displayed by the function.

| Name | Range | Description |
|-------------------------|------------------------------------|---|
| I2> condition | Normal Start Trip Blocked | Displays the status of the protection function. |
| I2> I2I1 relation | 0.00...100 000.00 | Ratio between the negative sequence current and positive sequence current. |
| I2 meas / I2 set | 0.00...100 000.00 | Ratio between measured negative sequence current and the pick-up value. |
| Expected operating time | 0.000...1800.000s | Displays the expected operating time when a fault occurs. When IDMT mode is used, the expected operating time depends on the measured highest phase current value. If the measured current changes during a fault, the expected operating time changes accordingly. |
| Time remaining to trip | -1800.000...1800.000s | When the function has detected a fault and counts down time towards a trip, this displays how much time is left before tripping occurs. |

Function blocking

The block signal is checked in the beginning of each program cycle. The blocking signal is received from the blocking matrix in the function's dedicated input. If the blocking signal is not activated when the pick-up element activates, a START signal is generated and the function proceeds to the time characteristics calculation.

If the blocking signal is active when the pick-up element activates, a BLOCKED signal is generated and the function does not process the situation further. If the START function has been activated before the blocking signal, it resets and processes the release time characteristics similarly to when the pick-up signal is reset.

The variables the user can set are binary signals from the system. The blocking signal needs to reach the device minimum of 5 ms before the set operating delay has passed in order for the blocking to activate in time.

Operating time characteristics for trip and reset

The operating timers' behavior during a function can be set for TRIP signal and also for the release of the function in case the pick-up element is reset before the trip time has been reached. There are three basic operating modes available for the function:

- Instant operation: gives the TRIP signal with no additional time delay simultaneously with the start signal.
- Definite time operation (DT): gives the TRIP signal after a user-defined time delay regardless of the measured current as long as the current is above or below the I_{set} value and thus the pick-up element is active (independent time characteristics).
- Inverse definite minimum time (IDMT): gives the TRIP signal after a time which is in relation to the set pick-up value I_{set} and the measured current I_m (dependent time characteristics).

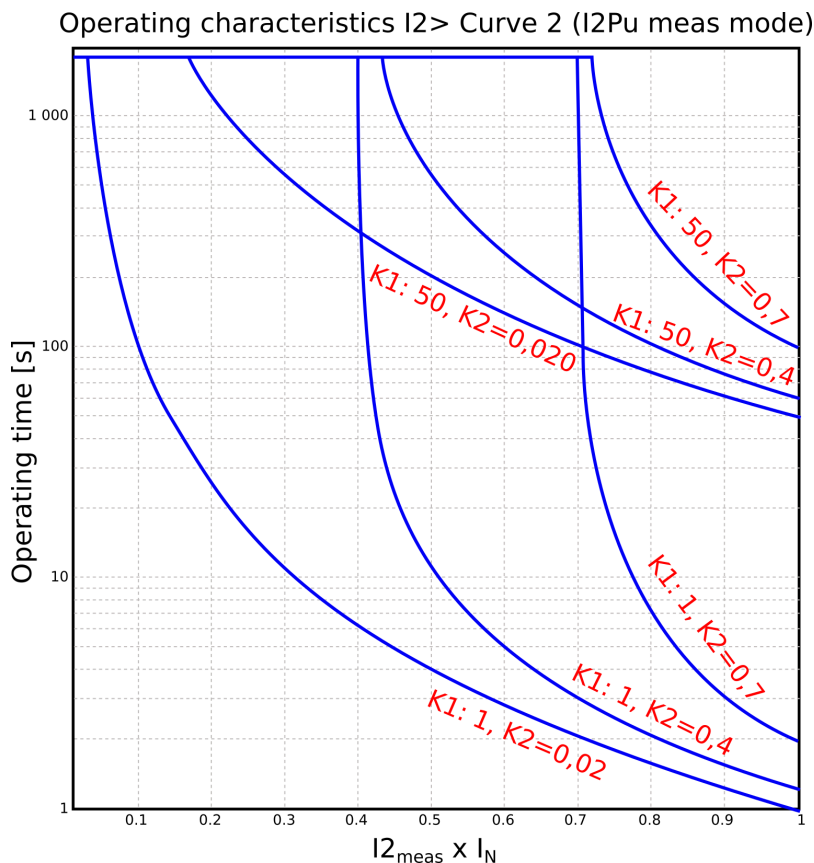
Both IEC and IEEE/ANSI standard characteristics as well as user settable parameters are available for the IDMT operation.

Unique to the current unbalance protection is the availability of the "Curve2" delay which follows the formula below:

$$t = \frac{k}{I_{2meas}^2 - I_{set}^2}$$

- t = Operating time
- I_{2meas} = Calculated negative sequence
- k = Constant k value (user settable delay multiplier)
- I_{set} = Pick-up setting of the function

Figure. 4.4.4 - 76. Operation characteristics curve for I2> Curve2.



For a more detailed description on the time characteristics and their setting parameters, please refer to the "[General properties of a protection function](#)" chapter and its "[Operating time characteristics for trip and reset](#)" section.

Events and registers

The current unbalance function (abbreviated "CUB" in event block names) generates events and registers from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

The function's outputs can be used for direct I/O controlling and user logic programming. The function also provides a resettable cumulative counter for the START, TRIP and BLOCKED events.

The function offers four (4) independent stages; the events are segregated for each stage operation.

Table. 4.4.4 - 50. Event messages.

| Event block name | Event names |
|------------------|-------------|
| CUB1...CUB4 | Start ON |
| CUB1...CUB4 | Start OFF |
| CUB1...CUB4 | Trip ON |
| CUB1...CUB4 | Trip OFF |
| CUB1...CUB4 | Block ON |
| CUB1...CUB4 | Block OFF |

The function registers its operation into the last twelve (12) time-stamped registers. The register of the function records the ON event process data for START, TRIP or BLOCKED. The table below presents the structure of the function's register content.

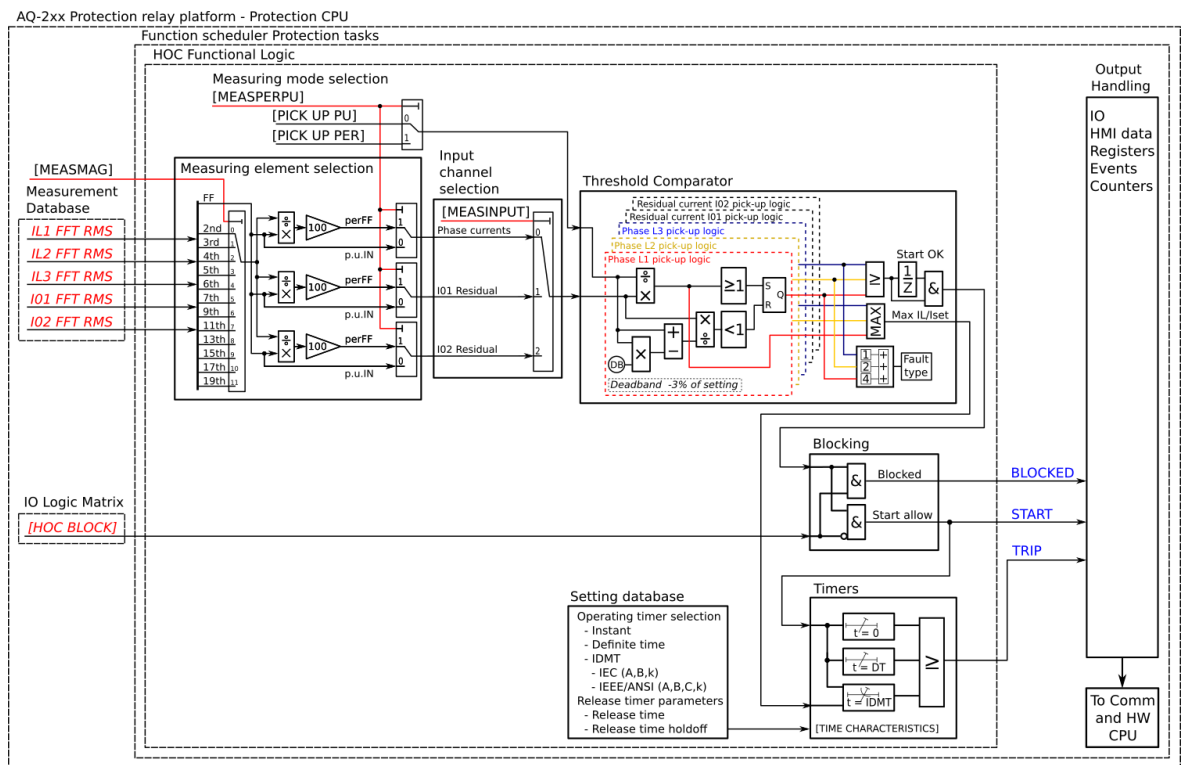
Table. 4.4.4 - 51. Register content.

| Register | Description |
|----------------------|----------------------------|
| Event | Event name |
| Date and time | dd.mm.yyyy hh:mm:ss.mss |
| Pre-trigger current | Start/Trip -20ms current |
| Fault current | Start/Trip current |
| Pre-fault current | Start -200ms current |
| Fault currents | I1, I2, IZ mag. and ang. |
| Trip time remaining | 0 ms...1800s |
| Setting group in use | Setting group 1...8 active |

4.4.5 Harmonic overcurrent protection (Ih>; 50H/51H/68H)

The harmonic overcurrent function is used for non-directional instant and time-delayed overcurrent detection and clearing. The number of stages in the function depends on the device model. The function constantly measures the selected harmonic component of the selected measurement channels, the value being either absolute value or relative to the RMS value.

Figure. 4.4.5 - 77. Simplified function block diagram of the Ih> function.



Measured input

The function block uses analog current measurement values from phase or residual currents. Each measurement input of the function block uses RMS (fundamental frequency component) values and harmonic components of the selected current input. The user can select the monitored magnitude to be equal to the per-unit RMS values of the harmonic component, or to the harmonic component percentage content compared to the RMS values.

Table. 4.4.5 - 52. Measurement inputs of the Ih> function.

| Signal | Description | Time base |
|--------|---|-----------|
| IL1FFT | <p>The magnitudes (RMS) of phase L1 (A) current components:</p> <ul style="list-style-type: none"> - Fundamental - 2nd harmonic - 3rd harmonic - 4th harmonic - 5th harmonic - 6th harmonic - 7th harmonic - 9th harmonic - 11th harmonic - 13th harmonic - 15th harmonic - 17th harmonic - 19th harmonic. | 5 ms |

| Signal | Description | Time base |
|---------------------|--|-----------|
| I _{L2} FFT | <p>The magnitudes (RMS) of phase L2 (B) current components:</p> <ul style="list-style-type: none"> - Fundamental - 2nd harmonic - 3rd harmonic - 4th harmonic - 5th harmonic - 6th harmonic - 7th harmonic - 9th harmonic - 11th harmonic - 13th harmonic - 15th harmonic - 17th harmonic - 19th harmonic. | 5 ms |
| I _{L3} FFT | <p>The magnitudes (RMS) of phase L3 (C) current components:</p> <ul style="list-style-type: none"> - Fundamental - 2nd harmonic - 3rd harmonic - 4th harmonic - 5th harmonic - 6th harmonic - 7th harmonic - 9th harmonic - 11th harmonic - 13th harmonic - 15th harmonic - 17th harmonic - 19th harmonic. | 5 ms |
| I ₀₁ FFT | <p>The magnitudes (RMS) of residual I₀₁ current components:</p> <ul style="list-style-type: none"> - Fundamental - 2nd harmonic - 3rd harmonic - 4th harmonic - 5th harmonic - 6th harmonic - 7th harmonic - 9th harmonic - 11th harmonic - 13th harmonic - 15th harmonic - 17th harmonic - 19th harmonic. | 5 ms |

| Signal | Description | Time base |
|---------------------|--|-----------|
| I ₀₂ FFT | <p>The magnitudes (RMS) of residual I₀₂ current components:</p> <ul style="list-style-type: none"> - Fundamental - 2nd harmonic - 3rd harmonic - 4th harmonic - 5th harmonic - 6th harmonic - 7th harmonic - 9th harmonic - 11th harmonic - 13th harmonic - 15th harmonic - 17th harmonic - 19th harmonic. | 5 ms |

General settings

The function can be set to monitor the ratio between the measured harmonic and either the measured fundamental component or the per unit value of the harmonic current. The user must select the correct measurement input.

Table. 4.4.5 - 53. Operating mode selection settings.

| Name | Range | Default | Description |
|---------------------|--|---------|--|
| Ih> force status to | <ul style="list-style-type: none"> • Normal • Start • Trip • Blocked | Normal | Force the status of the function. Visible only when <i>Enable stage forcing</i> parameter is enabled in <i>General</i> menu. |

| Name | Range | Default | Description |
|----------------------|---|--------------------------|--|
| Harmonic selection | <ul style="list-style-type: none"> • 2nd harmonic • 3rd harmonic • 4th harmonic • 5th harmonic • 6th harmonic • 7th harmonic • 9th harmonic • 11th harmonic • 13th harmonic • 15th harmonic • 17th harmonic • 19th harmonic | 2 nd harmonic | Selection of the monitored harmonic component. |
| Per unit or relative | <ul style="list-style-type: none"> • $\times I_n$ • I_h/IL | $\times I_n$ | Selection of the monitored harmonic mode. Either directly per unit $\times I_n$ or in relation to the fundamental frequency magnitude. |
| Measurement input | <ul style="list-style-type: none"> • IL1/IL2/IL3 • I01 • I02 | IL1/IL2/IL3 | Selection of the measurement input (either phase current or residual current). |

Pick-up settings

The setting parameter I_{hset} per unit or I_h/IL (depending on the selected operating mode) controls the pick-up of the I_h function. This defines the maximum allowed measured current before action from the function. The function constantly calculates the ratio between the I_{hset} per unit or I_h/IL and the measured magnitude (I_m) for each of the three phases. The reset ratio of 97 % is built into the function and is always relative to the I_{hset} per unit or I_h/IL value. The setting value is common for all measured phases, and when the I_m exceeds the I_{set} value (in single, dual or all phases) it triggers the pick-up operation of the function.

Setting group selection controls the operating characteristics of the function, i.e. the user or user-defined logic can change function parameters while the function is running.

Table. 4.4.5 - 54. Pick-up settings.

| Name | Range | Step | Default | Description |
|---------------|------------------------------|-------------------|-------------------|---------------------------------------|
| I_{hset} pu | $0.05 \dots 2.00 \times I_n$ | $0.01 \times I_n$ | $0.20 \times I_n$ | Pick-up setting (per unit monitoring) |

| Name | Range | Step | Default | Description |
|-------|----------------|-------|---------|---|
| Ih/IL | 5.00...200.00% | 0.01% | 20.00% | Pick-up setting (percentage monitoring) |

Read-only parameters

The function's *Info* page displays useful, real-time information on the state of the protection function. It is accessed either through the device's HMI display, or through the setting tool software when it is connected to the device and its Live Edit mode is active.

Table. 4.4.5 - 55. Information displayed by the function.

| Name | Range | Step | Description |
|-------------------------------|--|--------------------------------------|---|
| Ih> condition | <ul style="list-style-type: none"> Normal Start Trip Blocked | - | Displays the status of the protection function. |
| Ih meas/ Ih set now | 0.00...100000.00I _m /I _{set} | 0.01I _m /I _{set} | The ratio between the monitored residual current and the pick-up value. |
| Expected operating time | 0.000...1800.000s | 0.005s | Displays the expected operating time when a fault occurs. When IDMT mode is used, the expected operating time depends on the measured voltage value. If the measured voltage changes during a fault, the expected operating time changes accordingly. |
| Time remaining to trip | -1800.000...1800.000s | 0.005s | When the function has detected a fault and counts down time towards a trip, this displays how much time is left before tripping occurs. |

Function blocking

The block signal is checked in the beginning of each program cycle. The blocking signal is received from the blocking matrix in the function's dedicated input. If the blocking signal is not activated when the pick-up element activates, a START signal is generated and the function proceeds to the time characteristics calculation.

If the blocking signal is active when the pick-up element activates, a BLOCKED signal is generated and the function does not process the situation further. If the START function has been activated before the blocking signal, it resets and the release time characteristics are processed similarly to when the pick-up signal is reset.

The variables the user can set are binary signals from the system. The blocking signal needs to reach the device minimum of 5 ms before the set operating delay has passed in order for the blocking to activate in time.

Operating time characteristics for trip and reset

This function supports definite time delay (DT) and inverse definite minimum time delay (IDMT). For detailed information on these delay types please refer to the chapter "[General properties of a protection function](#)" and its section "[Operating time characteristics for trip and reset](#)".

Events and registers

The harmonic overcurrent function (abbreviated "HOC" in event block names) generates events and registers from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

The function's outputs can be used for direct I/O controlling and user logic programming. The START signal can be used to block other stages; if the situation lasts longer, the TRIP signal can be used on other actions as time-delayed. The function also provides a resettable cumulative counter for the START, TRIP and BLOCKED events.

The function offers four (4) independent stages; the events are segregated for each stage operation.

Table. 4.4.5 - 56. Event description.

| Event block name | Event names |
|------------------|-------------|
| HOC1...HOC4 | Start ON |
| HOC1...HOC4 | Start OFF |
| HOC1...HOC4 | Trip ON |
| HOC1...HOC4 | Trip OFF |
| HOC1...HOC4 | Block ON |
| HOC1...HOC4 | Block OFF |

The function registers its operation into the last twelve (12) time-stamped registers. The register of the function records the ON event process data for START, TRIP or BLOCKED. The table below presents the structure of the function's register content.

Table. 4.4.5 - 57. Register content.

| Register | Description |
|----------------------|----------------------------|
| Date and time | dd.mm.yyyy hh:mm:ss.mss |
| Event | Event name |
| Fault type | L1-G...L1-L2-L3 |
| Pre-trigger current | Start/Trip -20ms current |
| Fault current | Start/Trip current |
| Pre-fault current | Start -200ms current |
| Trip time remaining | 0 ms...1800s |
| Setting group in use | Setting group 1...8 active |

4.4.6 Circuit breaker failure protection (CBFP; 50BF/52BF)

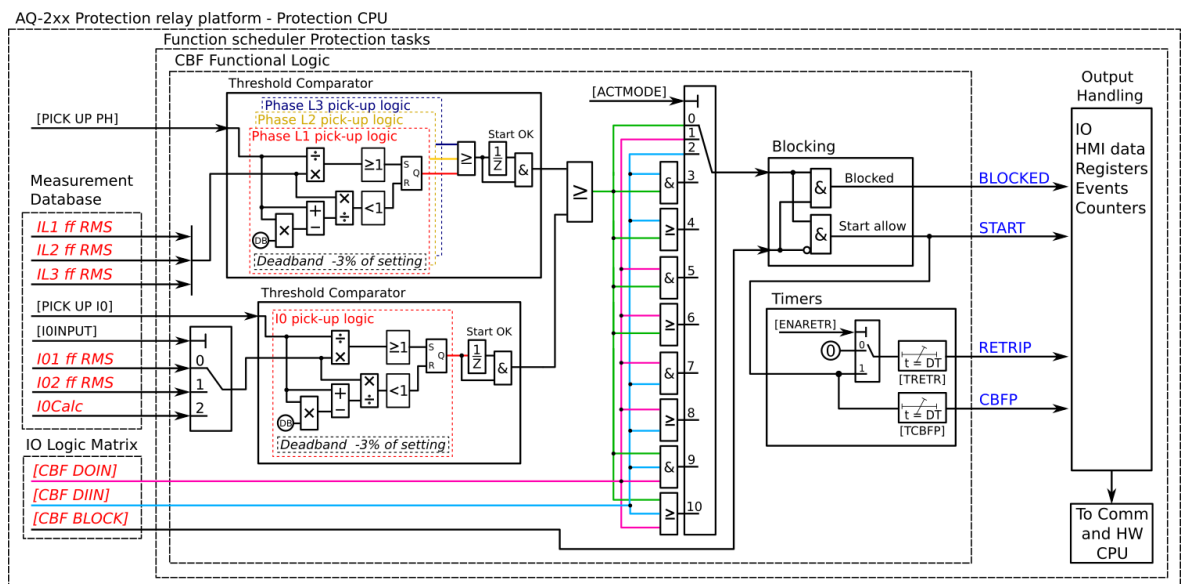
The circuit breaker failure protection function is used for monitoring the circuit breaker operation after it has received a TRIP signal. The function can also be used to retrip a failing breaker; if the retrip fails, an incoming feeder circuit breaker can be tripped by using the function's CBFP output. The retrip functionality can be disabled if the breaker does not have two trip coils.

The function can be triggered by the following:

- overcurrent (phase and residual)
- digital output monitor
- digital signal
- any combination of the above-mentioned triggers.

In the current-dependent mode the function constantly measures phase current magnitudes and the selected residual current. In the signal-dependent mode any of the device's binary signals (trips, starts, logical signals etc.) can be used to trigger the function. In the digital output-dependent mode the function monitors the status of the selected output relay control signal.

Figure. 4.4.6 - 78. Simplified function block diagram of the CBFP function.



Measured input

The function block uses fundamental frequency component of phase current and residual current measurement values. The user can select I01, I02 or the calculated I0 for the residual current measurement.

Table. 4.4.6 - 58. Measurement inputs of the CBFP function.

| Signal | Description | Time base |
|-------------|--|-----------|
| $I_{L1}RMS$ | Fundamental frequency component of phase L1 (A) current measurement | 5ms |
| $I_{L2}RMS$ | Fundamental frequency component of phase L2 (B) current measurement | 5ms |
| $I_{L3}RMS$ | Fundamental frequency component of phase L3 (C) current measurement | 5ms |
| $I_{01}RMS$ | Fundamental frequency component of residual input I_{01} measurement | 5ms |

| Signal | Description | Time base |
|---------------------|---|-----------|
| I ₀₂ RMS | Fundamental frequency component of residual input I ₀₂ measurement | 5ms |
| I ₀ Calc | Calculated residual current from the phase current inputs | 5ms |

General settings

The following general settings define the general behavior of the function. These settings are static i.e. it is not possible to change them by editing the setting group.

Table. 4.4.6 - 59. CBFP monitoring signal definitions.

| Name | Description |
|-------------------|--|
| Signal in monitor | Defines which TRIP events of the used protection functions trigger the CBFP countdown. For the CBFP function to monitor the signals selected here, the "Operation mode selection" parameter must be set to a mode that includes signals (e.g. "Signals only", "Signals or DO", "Current and signals and DO"). |
| Trip monitor | Defines which output relay of the used protection functions trigger the CBFP countdown. For the CBFP function to monitor the output relays selected here, the "Operation mode selection" parameter must be set to a mode that includes digital outputs (e.g. "DO only", "Current and DO", "Current or signals or DO"). |

Table. 4.4.6 - 60. General settings of the function.

| Name | Range | Default | Description |
|----------------------|--|---------|--|
| CBFP force status to | <ul style="list-style-type: none"> Normal Start ReTrip CBFP Blocked | Normal | Force the status of the function. Visible only when <i>Enable stage forcing</i> parameter is enabled in <i>General</i> menu. |

Pick-up settings

The setting parameters I_{set} and I_{0set} control the pick-up and the activation of the current-dependent CBFP function. They define the minimum allowed measured current before action from the function. The function constantly calculates the ratio between the I_{set} or the I_{0set} and the measured magnitude (I_m) for each of the three phases and the selected residual current input. The reset ratio of 97 % is built into the function and is always relative to the I_{set} value. The setting value is common for all measured phases. When the I_m exceeds the I_{set} value (in single, dual or all phases) it triggers the pick-up operation of the function.

Setting group selection controls the operating characteristics of the function, i.e. the user or user-defined logic can change function parameters while the function is running.

Table. 4.4.6 - 61. Operating mode and input signals selection.

| Name | Range | Step | Default | Description |
|---------|--|------|--------------|--|
| I0Input | <ul style="list-style-type: none"> Not in use I01 I02 I0Calc | - | Not in use | Selects the residual current monitoring source, which can be either from the two separate residual measurements (I01 and I02) or from the phase current's calculated residual current. |
| Actmode | <ul style="list-style-type: none"> Current only DO only Signals only Current and DO Current or DO Current and signals Current or signals Signals and DO Signals or DO Current or DO or signals Current and DO and Signals | - | Current only | Selects the operating mode. The mode can be dependent on current measurement, binary signal status, output relay status ("DO"), or a combination of the three. |

Table. 4.4.6 - 62. Pick-up settings.

| Name | Range | Step | Default | Description |
|-------------------|-------------------------------|----------------------|----------------------|---|
| I _{set} | 0.01...40.00×I _N | 0.01×I _N | 0.20×I _N | The pick-up threshold for the phase current measurement. This setting limit defines the upper limit for the phase current pick-up element. |
| I0 _{set} | 0.005...40.000×I _N | 0.001×I _N | 1.200×I _N | The pick-up threshold for the residual current measurement. This setting limit defines the upper limit for the phase current pick-up element. |

Read-only parameters

The function's *Info* page displays useful, real-time information on the state of the protection function. It is accessed either through the device's HMI display, or through the setting tool software when it is connected to the device and its Live Edit mode is active.

Table. 4.4.6 - 63. Information displayed by the function.

| Name | Range | Description |
|----------------|---|---|
| CBFP condition | <ul style="list-style-type: none"> • Normal • Start • ReTrip • CBFP On • Blocked | Displays status of the protection function. |

Function blocking

The block signal is checked in the beginning of each program cycle. The blocking signal is received from the blocking matrix in the function's dedicated input. If the blocking signal is not activated when the pick-up element activates, a START signal is generated and the function proceeds to the time characteristics calculation.

If the blocking signal is active when the pick-up element activates, a BLOCKED signal is generated and the function does not process the situation further. If the START function has been activated before the blocking signal, it resets and processes the release time characteristics similarly to when the pick-up signal is reset.

The variables the user can set are binary signals from the system. The blocking signal needs to reach the device minimum of 5 ms before the set operating delay has passed in order for the blocking to activate in time.

Operating time characteristics

The operating timers' behavior during a function can be set depending on the application. The same pick-up signal starts both timers. When retrip is used the time grading should be set as follows: the sum of specific times (i.e. the retrip time, the expected operating time, and the pick-up conditions' release time) is shorter the set CBFP time. This way, when retripping another breaker coil clears the fault, any unnecessary function triggers are avoided.

The following table presents the setting parameters for the function's operating time characteristics.

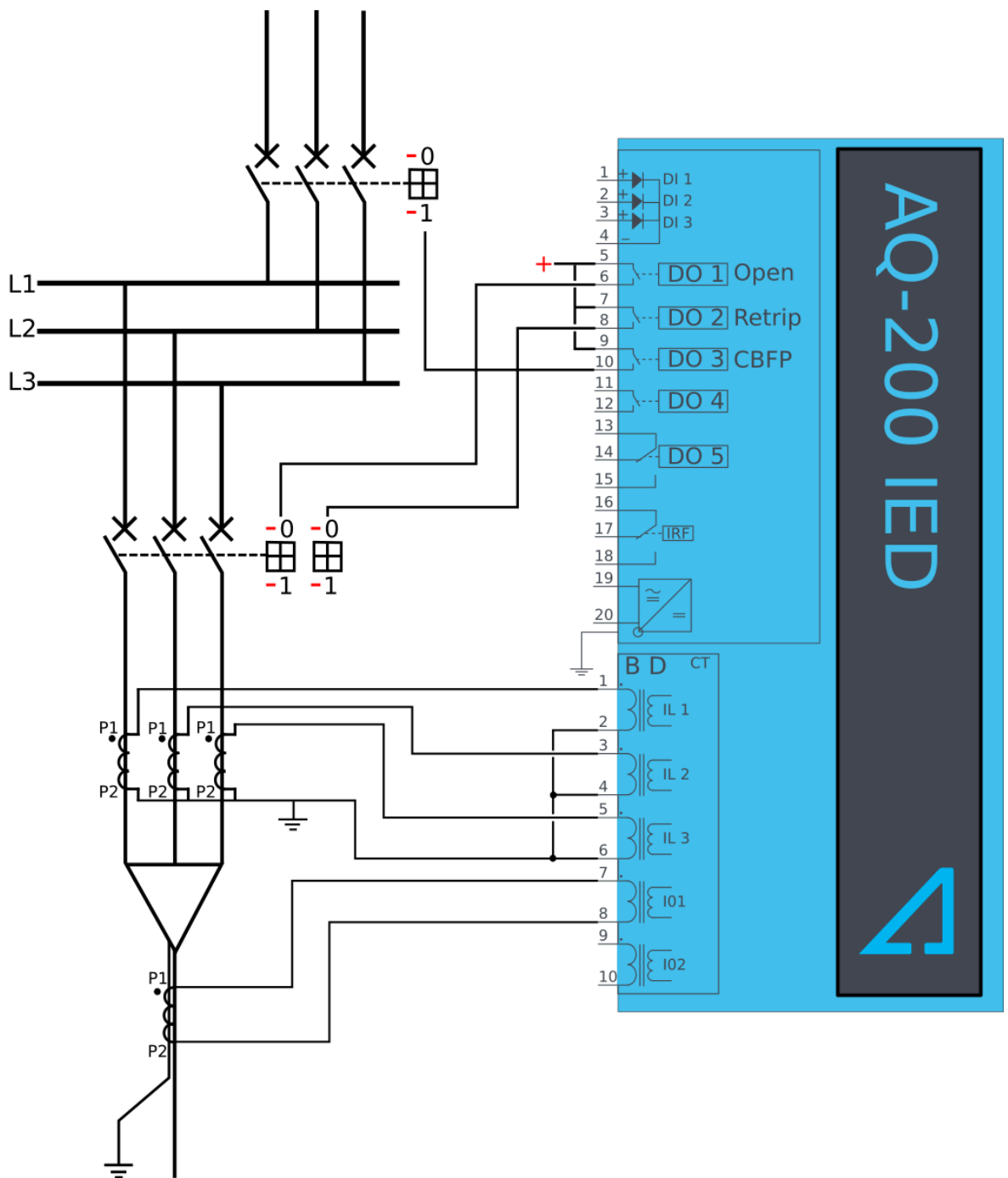
Table. 4.4.6 - 64. Setting parameters for operating time characteristics.

| Name | Range | Step | Default | Description |
|-------------------|---|--------|---------|--|
| Retrip | <ul style="list-style-type: none"> • No • Yes | - | Yes | Retrip enabled or disabled. When the retrip is disabled, the output will not be visible and the TRetr setting parameter will not be available. |
| Retrip time delay | 0.000...1800.000s | 0.005s | 0.100s | Retrip start the timer. This setting defines how long the starting condition has to last before a RETRIP signal is activated. |
| CBFP | 0.000...1800.000s | 0.005s | 0.200s | CBFP starts the timer. This setting defines how long the starting condition has to last before the CBFP signal is activated. |

The following figures present some typical cases of the CBFP function.

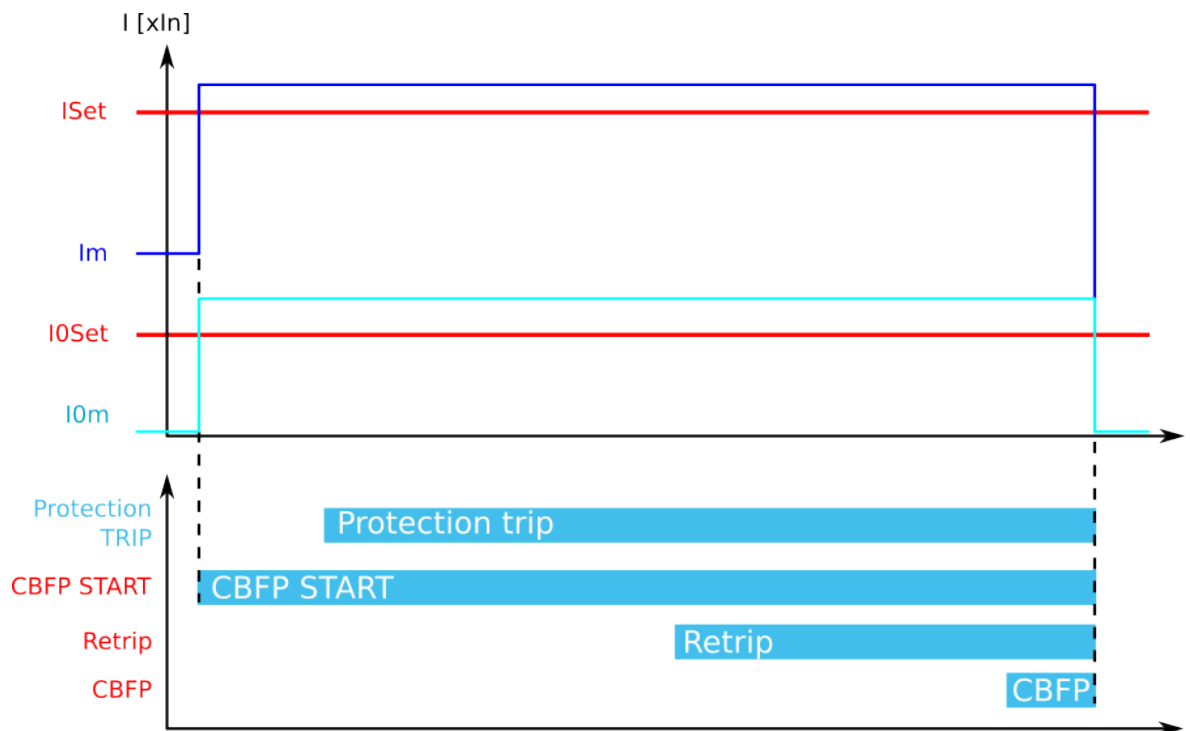
Trip, Retrip and CBFP in the device configuration

Figure. 4.4.6 - 79. Wiring diagram when Trip, Retrip and CBFP are configured to the device.



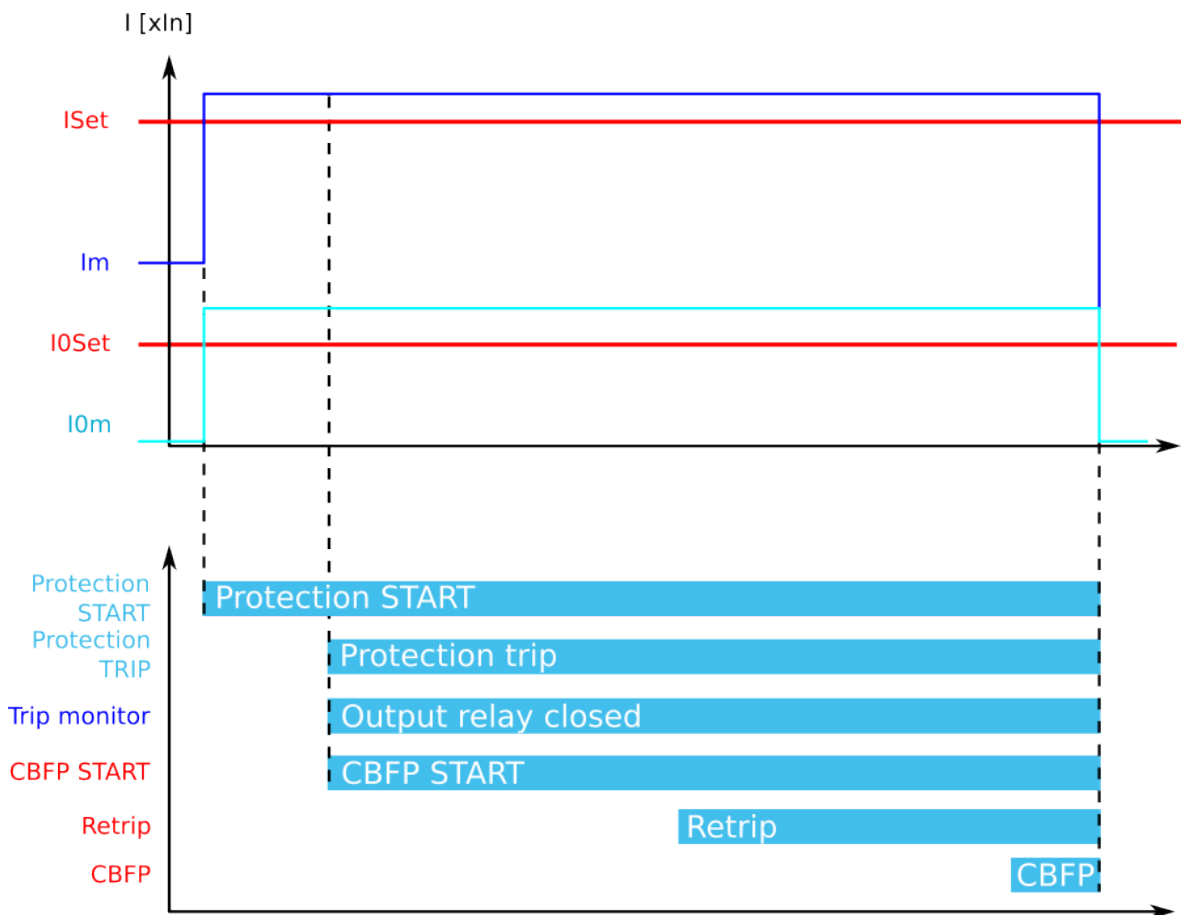
The retrip functionality can be used in applications whose circuit breaker has a retrip or a redundant trip coil available. The TRIP signal is normally wired to the breaker's trip coil from the device's trip output. The retrip is wired from its own device output contact in parallel with the circuit breaker's redundant trip coil. The CBFP signal is normally wired from its device output contact to the incoming feeder circuit breaker. Below are a few operational cases regarding the various applications.

Figure. 4.4.6 - 80. Retrip and CBFP when "Current" is the selected criterion.



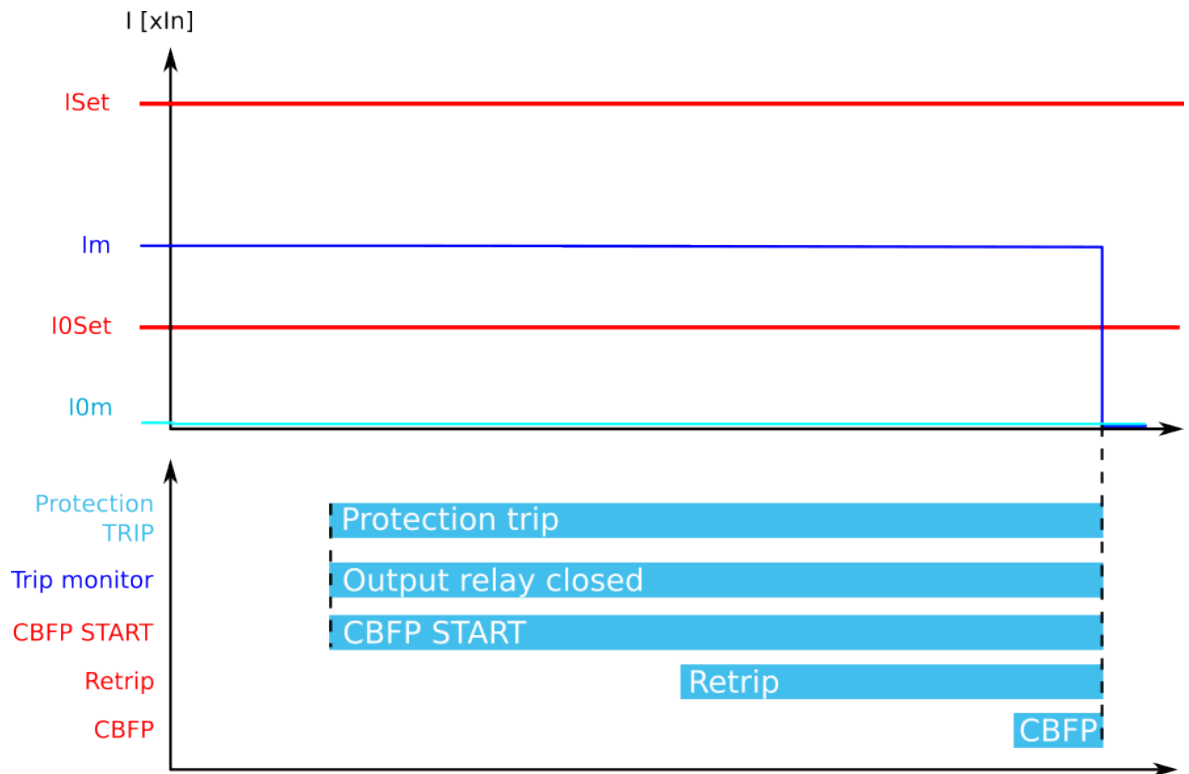
When the current threshold setting of I_{Set} and/or I_{OSet} is exceeded, the current-based protection is activated and the counters for RETRIP and CBFP start calculating the set operating time. The tripping of the primary protection stage is not monitored in this configuration. Therefore, if the current is not reduced below the setting limit, a RETRIP signal is sent to the redundant trip coil. If the current is not reduced within the set time limit, the function also sends a CBFP signal to the incoming feeder breaker. If the primary protection function clears the fault, both counters (RETRIP and CBFP) are reset as soon as the measured current is below the threshold settings.

Figure. 4.4.6 - 81. Retrip and CBFP when "Current and DO" is the selected criterion.



When the current threshold setting of I_{set} and/or I_{Oset} is exceeded, the current-based protection is activated. At the same time, the counters for RETRIP and CBFP are halted until the monitored output contact is controlled (that is, until the primary protection operates). When the tripping signal reaches the primary protection stage, the RETRIP and CBFP counters start calculating the set operating time. The tripping of the primary protection stage is constantly monitored in this configuration. If the current is not reduced below the setting limit or the primary stage tripping signal is not reset, a RETRIP signal is sent to the redundant trip coil. If the retripping fails and the current is not reduced below the setting limit or the primary stage tripping signal is not reset, the function also sends a CBFP signal to the incoming feeder circuit breaker. If the primary protection function clears the fault, both counters (RETRIP and CBFP) are reset as soon as the measured current is below the threshold settings or the tripping signal is reset. This configuration allows the CBFP to be controlled with current-based functions alone, and other function trips can be excluded from the CBFP functionality.

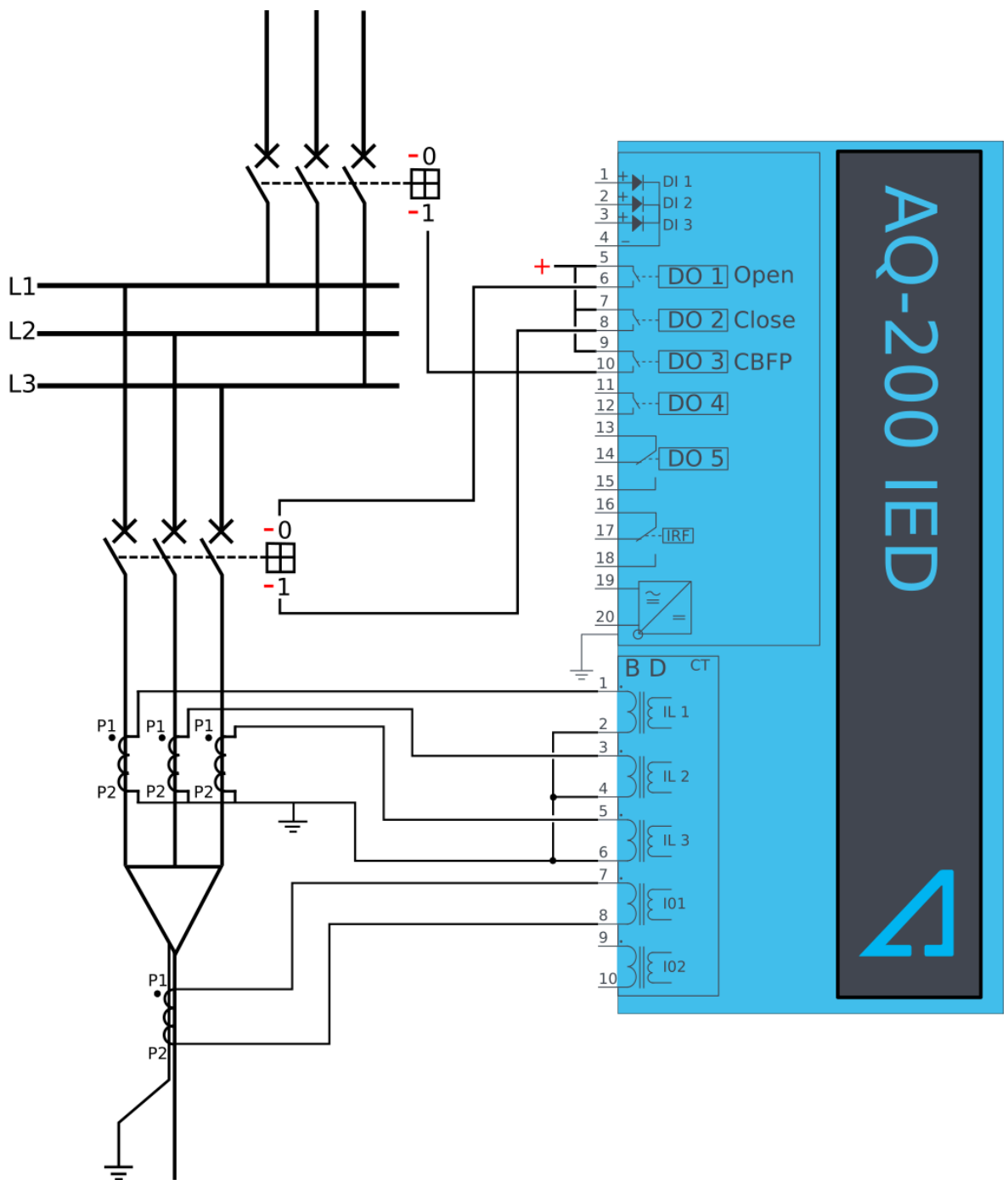
Figure. 4.4.6 - 82. Retrip and CBFP when "Current or DO" is the selected criterion.



When the current threshold setting of I_{Set} and/or I_{OSet} is exceeded, or the TRIP signal reaches the primary protection stage, the function starts counting down towards the RETRIP and CBFP signals. The tripping of the primary protection stage is constantly monitored in this configuration regardless of the current's status. The pick-up of the CBFP is active unless the current is reduced below the setting limit and the primary stage tripping signal is reset. If either of these conditions is met (i.e. the current is above the limit or the signal is active) for the duration of the set RETRIP time delay, a RETRIP signal is sent to the redundant trip coil. If either of the conditions is active for the duration of the set CBFP time delay, a CBFP signal is sent to the incoming feeder circuit breaker. If the primary protection function clears the fault, both counters (RETRIP and CBFP) are reset as soon as the measured current is below the threshold settings and the tripping signal is reset. This configuration allows the CBFP to be controlled with current-based functions alone, with added security from current monitoring. Other function trips can also be included in the CBFP functionality.

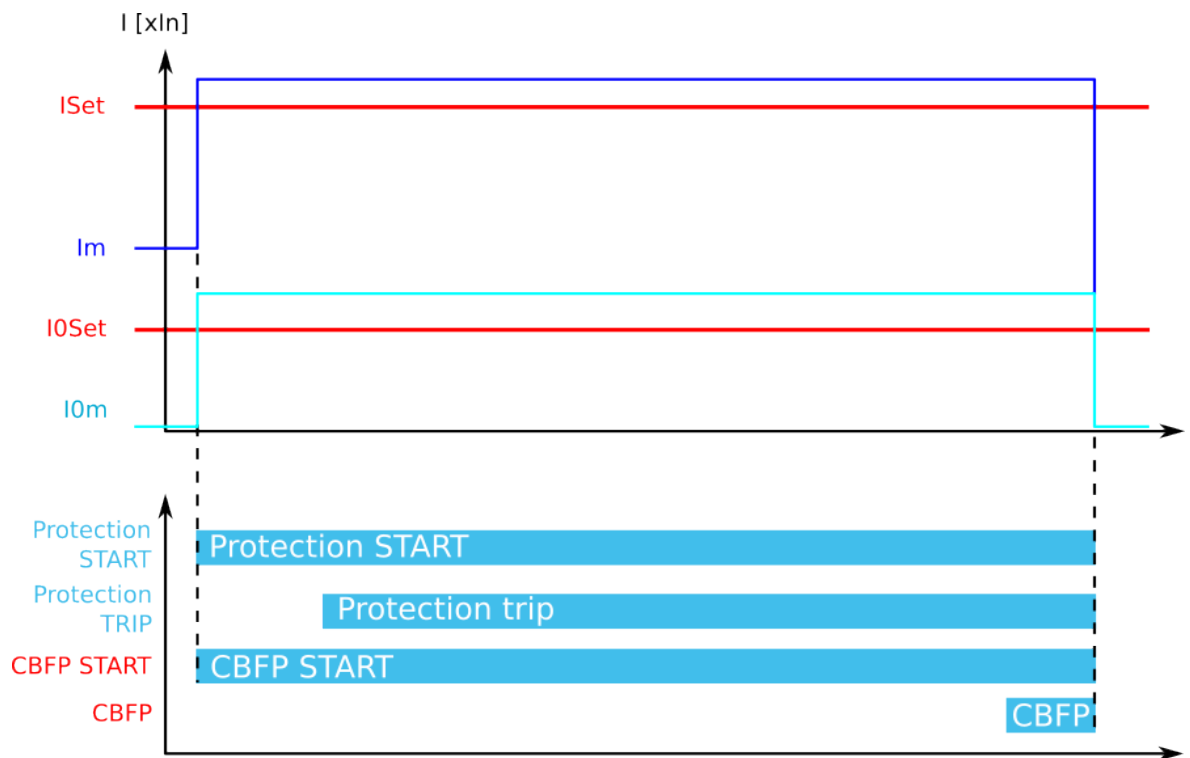
Trip and CBFP in the device configuration

Figure. 4.4.6 - 83. Wiring diagram when Trip and CBFP are configured to the device.



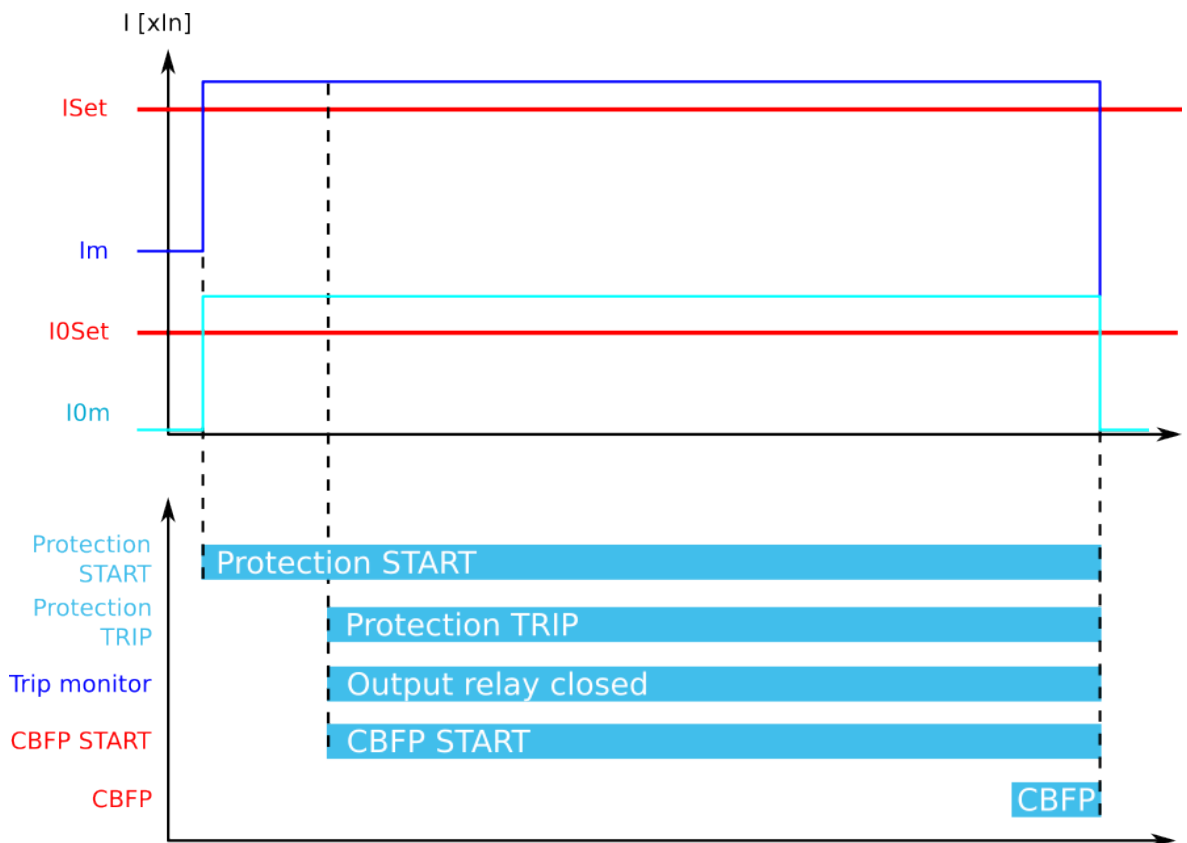
Probably the most common application is when the device's trip output controls the circuit breaker trip coil, while one dedicated CBFP contact controls the CBFP function. Below are a few operational cases regarding the various applications and settings of the CBFP function.

Figure. 4.4.6 - 84. CBFP when "Current" is the selected criterion.



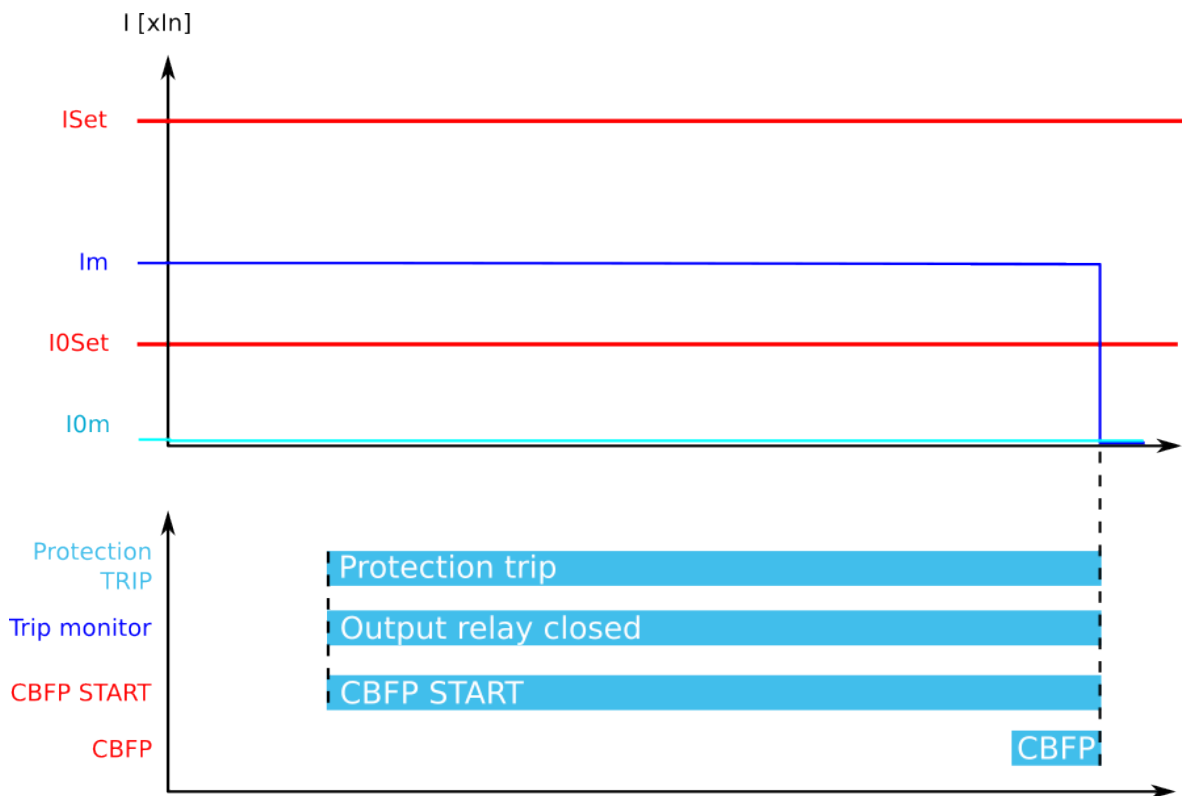
When the current threshold setting of I_{Set} and/or I_{OSet} is exceeded, the current-based protection is activated and the counter for CBFP starts calculating the set operating time. The tripping of the primary protection stage is not monitored in this configuration. Therefore, if the current is not reduced below the setting limit, a CBFP signal is sent to the incoming feeder circuit breaker. If the primary protection function clears the fault, the counter for CBFP resets as soon as the measured current is below the threshold settings.

Figure. 4.4.6 - 85. CBFP when "Current and DO" is the selected criterion.



When the current threshold setting of I_{Set} and/or I_{OSet} is exceeded, the current-based protection is activated. At the same time, the counter for CBFP is halted until the monitored output contact is controlled (that is, until the primary protection operates). When the tripping signal reaches the primary protection stage, the CBFP counter starts calculating the set operating time. The tripping of the primary protection stage is constantly monitored in this configuration. If the current is not reduced below the setting limit or the primary stage tripping signal is not reset, a CBFP signal is sent to the incoming feeder circuit breaker. The time delay counter for CBFP is reset as soon as the measured current is below the threshold settings or the tripping signal is reset. This configuration allows the CBFP to be controlled by current-based functions alone, and other function trips can be excluded from the CBFP functionality.

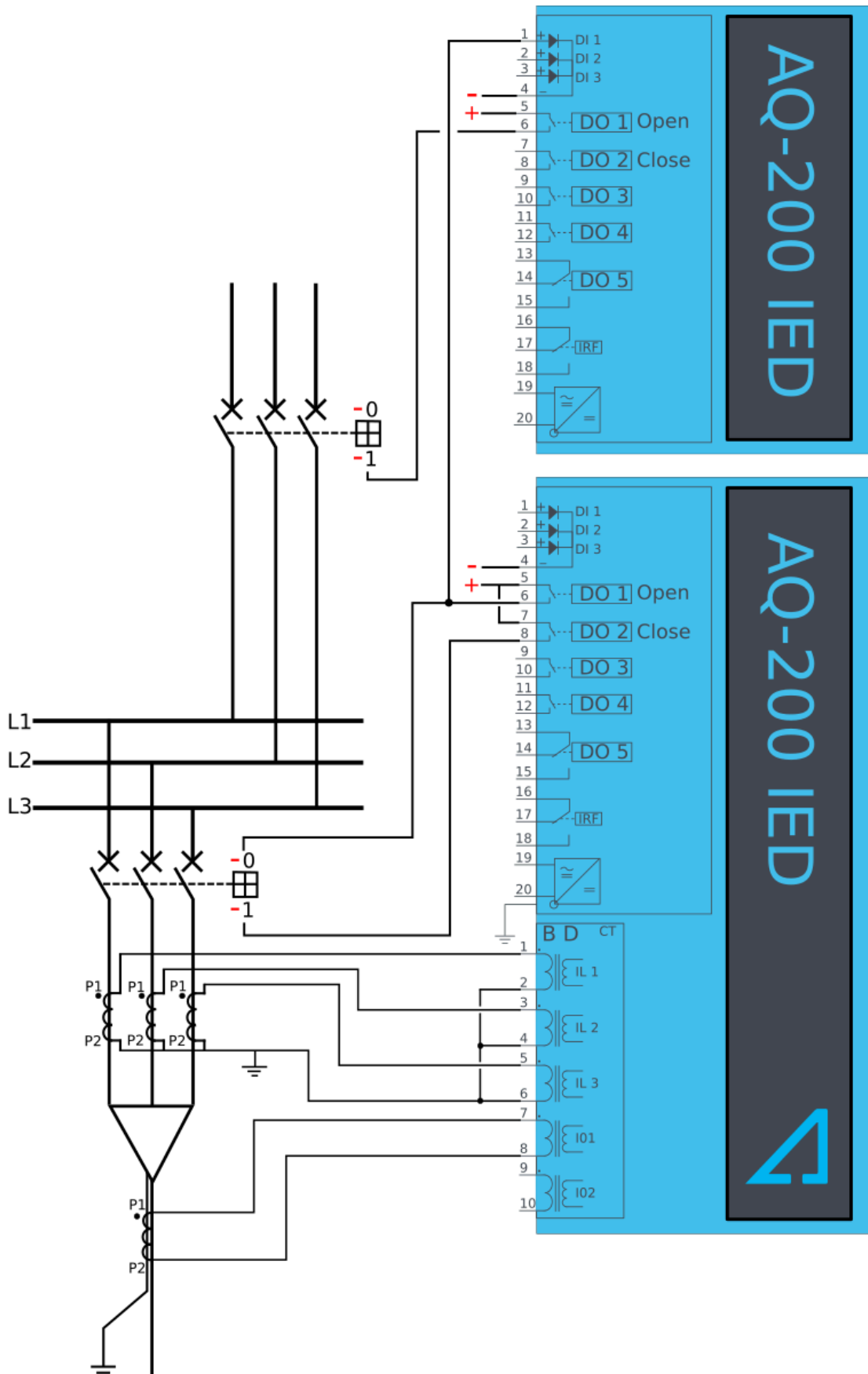
Figure. 4.4.6 - 86. CBFP when "Current or DO" is the selected criterion.



When the current threshold setting of I_{Set} and/or IO_{Set} is exceeded, or the TRIP signal reaches the primary protection stage, the function starts counting down towards the CBFP signal. The tripping of the primary protection stage is constantly monitored in this configuration regardless of the current's status. The pick-up of the CBFP is active unless the current is reduced below the setting limit and the primary stage tripping signal is reset. If either of these conditions is met (i.e. the current is above the limit or the signal is active) for the duration of the set CBFP time delay, a CBFP signal is sent to the incoming feeder circuit breaker. The time delay counter for CBFP is reset as soon as the measured current is below the threshold settings and the tripping signal is reset. This configuration allows the CBFP to be controlled by current-based functions alone, with added security from current monitoring. Other function trips can also be included to the CBFP functionality.

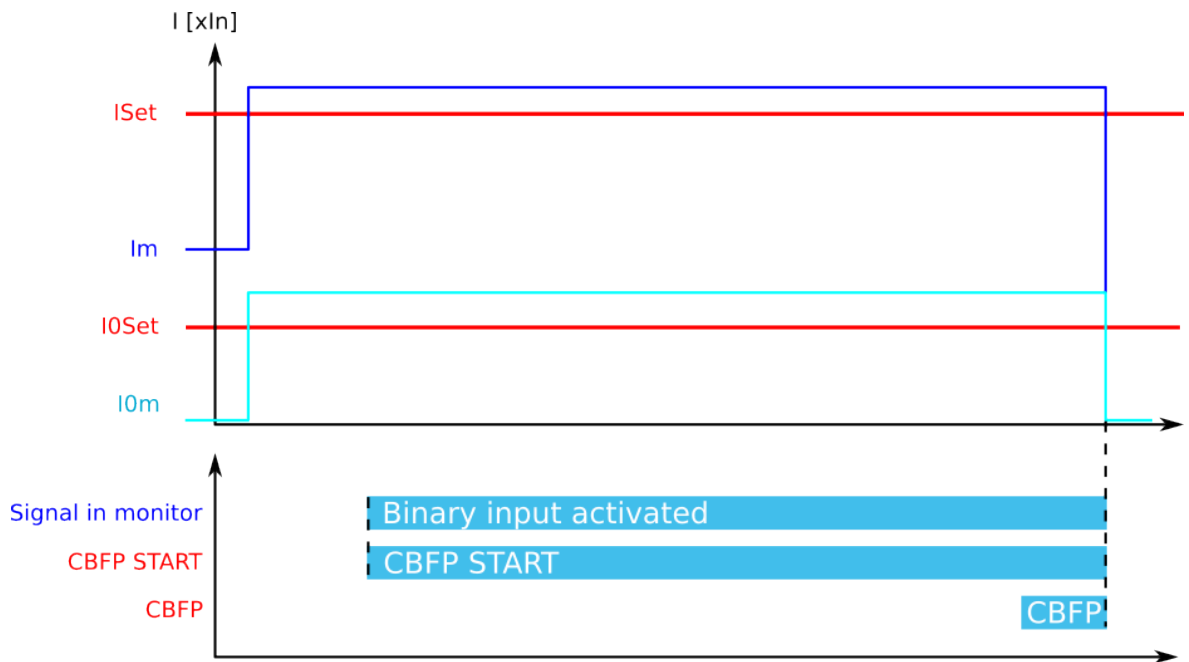
Device configuration as a dedicated CBFP unit

Figure. 4.4.6 - 87. Wiring diagram when the device is configured as a dedicated CBFP unit.



Some applications require a dedicated circuit breaker protection unit. When the CBFP function is configured to operate with a digital input signal, it can be used in these applications. When a device is used for this purpose, the tripping signal is wired to the device's digital input and the device's own TRIP signal is used only for the CBFP purpose. In this application's incoming feeder the RETRIP and CBFP signals are also available with different sets of requirements. The RETRIP signal can be used for tripping the section's feeder breaker and the CBFP signal for tripping the incoming feeder. The following example does not use retripping and the CBFP signal is used as the incoming feeder trip from the outgoing breaker trip signal. The TRIP signal can also be transported between different devices by using GOOSE messages.

Figure. 4.4.6 - 88. Dedicated CBFP operation from digital input signal.



In this mode the CBFP operates only from a digital input signal. Both current and output relay monitoring can be used. The counter for the CBFP signal begins when the digital input is activated. If the counter is active until the CBFP counter is used, the device issues a CBFP command to the incoming feeder circuit breaker. In this application the device tripping signals from all outgoing feeders can be connected to one, dedicated CBFP device which operates either on current-based protection or on all possible faults' CBFP protection.

Events and registers

The circuit breaker failure protection function (abbreviated "CBF" in event block names) generates events and registers from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

The function's outputs can be used for direct I/O controlling and user logic programming. The function also provides a resettable cumulative counters for RETRIP, CBFP, CBFP START and BLOCKED events.

Table. 4.4.6 - 65. Event messages.

| Event block name | Event names |
|------------------|-------------|
| CBF1 | Start ON |
| CBF1 | Start OFF |

| Event block name | Event names |
|------------------|-------------------|
| CBF1 | Retrip ON |
| CBF1 | Retrip OFF |
| CBF1 | CBFP ON |
| CBF1 | CBFP OFF |
| CBF1 | Block ON |
| CBF1 | Block OFF |
| CBF1 | DO monitor ON |
| CBF1 | DO monitor OFF |
| CBF1 | Signal ON |
| CBF1 | Signal OFF |
| CBF1 | Phase current ON |
| CBF1 | Phase current OFF |
| CBF1 | Res current ON |
| CBF1 | Res current OFF |

The function registers its operation into the last twelve (12) time-stamped registers. The register of the function records the ON event process data for ACTIVATED, BLOCKED, etc. The table below presents the structure of the function's register content.

Table. 4.4.6 - 66. Register content.

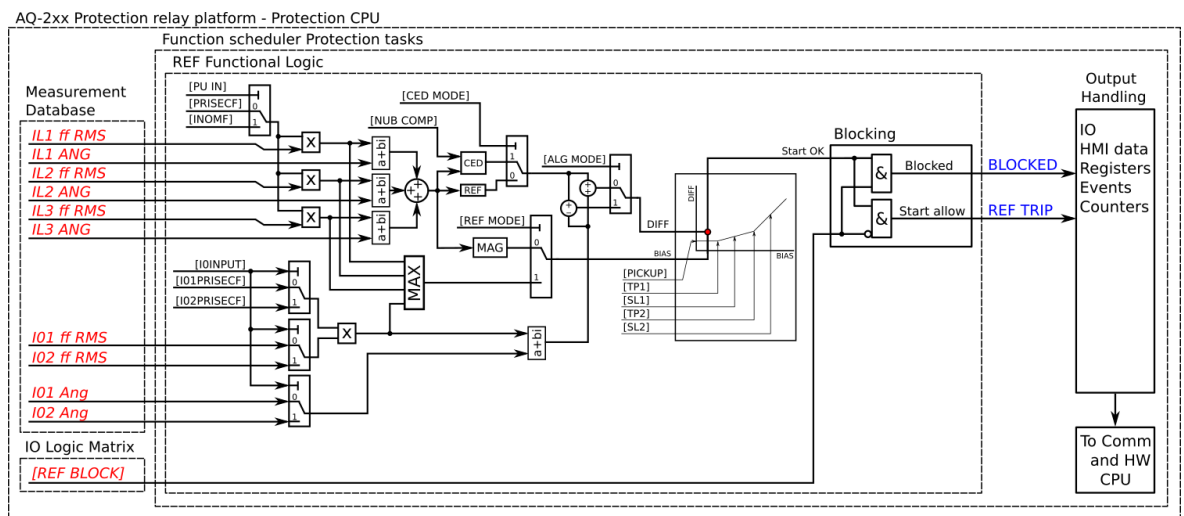
| Register | Description |
|----------------------|---|
| Date and time | dd.mm.yyyy hh:mm:ss.mss |
| Event | Event name |
| Max phase current | Highest phase current |
| Residual current | I01, I02 channel or calculated residual current |
| Time to RETR | Time remaining to retrip activation |
| Time to CBFP | Time remaining to CBFP activation |
| Setting group in use | Setting group 1...8 active |

4.4.7 Low-impedance or high-impedance restricted earth fault/ cable end differential protection ($I_{0d}>$; 87N)

The low-impedance or high-impedance restricted earth fault function is used for residual differential current measurement for transformers. This function can also be used as the cable end differential function. The operating principle is low-impedance differential protection with bias characteristics the user can set. A differential current is calculated with the sum of the phase currents and the selected residual current input. In cable end differential mode the function provides natural measurement unbalance compensation for higher operating sensitivity in monitoring cable end faults.

The restricted earth fault function constantly monitors phase currents and selected residual current instant values as well as calculated bias current and differential current magnitudes.

Figure. 4.4.7 - 89. Simplified function block diagram of the $I_{0d}>$ function.



Measured input

The function block uses fundamental frequency component of phase current and residual current measurement values. Both calculated residual currents and measured residual currents are always used. The user can select either I_{01} or I_{02} for residual current measurement.

Please note that when the function is in cable end differential mode, the difference is only calculated when the measured I_0 current is available.

Table. 4.4.7 - 67. Measurement inputs of the $I_{0d}>$ function.

| Signal | Description | Time base |
|-------------|--|-----------|
| I_{L1RMS} | Fundamental frequency component of phase L1 (A) current measurement | 5ms |
| I_{L2RMS} | Fundamental frequency component of phase L2 (B) current measurement | 5ms |
| I_{L3RMS} | Fundamental frequency component of phase L3 (C) current measurement | 5ms |
| I_{01RMS} | Fundamental frequency component of residual input I_{01} measurement | 5ms |
| I_{02RMS} | Fundamental frequency component of residual input I_{02} measurement | 5ms |
| I_{L1Ang} | Angle of phase L1 (A) current | 5ms |

| Signal | Description | Time base |
|---------------------|-------------------------------|-----------|
| I _{L2} Ang | Angle of phase L2 (B) current | 5ms |
| I _{L3} Ang | Angle of phase L3 (C) current | 5ms |
| I ₀₁ Ang | Angle of residual input I01 | 5ms |
| I ₀₂ Ang | Angle of residual input I02 | 5ms |

General settings

The following general settings define the general behavior of the function. These settings are static i.e. it is not possible to change them by editing the setting group.

Table. 4.4.7 - 68. General settings.

| Name | Range | Default | Description |
|--|---|---------|--|
| I0d> force status to | <ul style="list-style-type: none"> Normal Trip Blocked | Normal | Force the status of the function. Visible only when <i>Enable stage forcing</i> parameter is enabled in <i>General</i> menu. |
| Restricted earth fault (REF) or Cable End Differential | <ul style="list-style-type: none"> REF CED | REF | Selection of the operating characteristics. If REF is selected, the function operates with normal accuracies. If CED is selected, the natural unbalance created by the phase current CT:s can be compensated for more sensitive operation. The default setting is REF. |
| Compenstate natural unbalance | <ul style="list-style-type: none"> - Comp | - | When activated while the line is energized, the currently present calculated residual current is compensated to 0. This compensation only has an effect in the CED mode. |

Operating characteristics

The current-dependent pick-up and activation of the function are controlled by setting parameters, which define the current calculating method used as well as the operating characteristics.

Setting group selection controls the operating characteristics of the function, i.e. the user or user-defined logic can change function parameters while the function is running.

Table. 4.4.7 - 69. Pick-up settings.

| Name | Range | Step | Default | Description |
|--------------|---|------|---------|---|
| I0 Input | <ul style="list-style-type: none"> I01 I02 | - | I01 | Selection of the used residual current measurement input. |
| I0 Direction | <ul style="list-style-type: none"> Add Subtract | - | Add | Differential current calculation mode. This matches the directions of the calculated and measured residual currents to the application. The default setting (Add) means that $I0Calc + I01$ or $I0Calc + I02$ in a through fault yields no differential current. See figures below for connection examples. |

| Name | Range | Step | Default | Description |
|--------------------------|--|-------------------|-------------------|--|
| Bias current calculation | <ul style="list-style-type: none"> Residual current $(3I_0 + I_0Calc)/2$ Maximum (Phase and I_0 max) | - | Residual current | Selection of the bias current calculation. Differential characteristics biasing can use either the calculated residual current averages or the maximum of all measured currents. The residual current mode is more sensitive while the maximum current is coarser. |
| $I_0d>$ pick-up | 0.01...50.00% (of I_n) | 0.01% | 10% | Setting for basic sensitivity of the differential characteristics. |
| Turnpoint 1 | 0.01...50.00 $\times I_n$ | 0.01 $\times I_n$ | 1.00 $\times I_n$ | Setting for first turn point in the bias axe of the differential characteristics. |
| Slope 1 | 0.01...150.00% | 0.01% | 10.00% | Setting for the first slope of the differential characteristics. |
| Turnpoint 2 | 0.01...50.00 $\times I_n$ | 0.01 $\times I_n$ | 3.00 $\times I_n$ | Setting for second turn point in the bias axe of the differential characteristics. |
| Slope 2 | 0.01...250.00% | 0.01% | 40.00% | Setting for the second slope of the differential characteristics. |

Figure. 4.4.7 - 90. " I_0 direction" parameter must be set to "Subtract" when current transformers are facing the same direction.

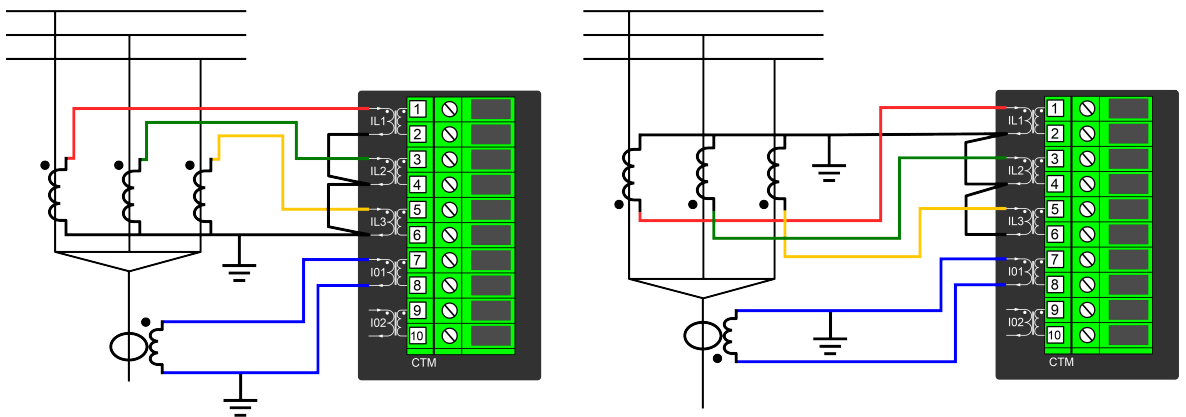
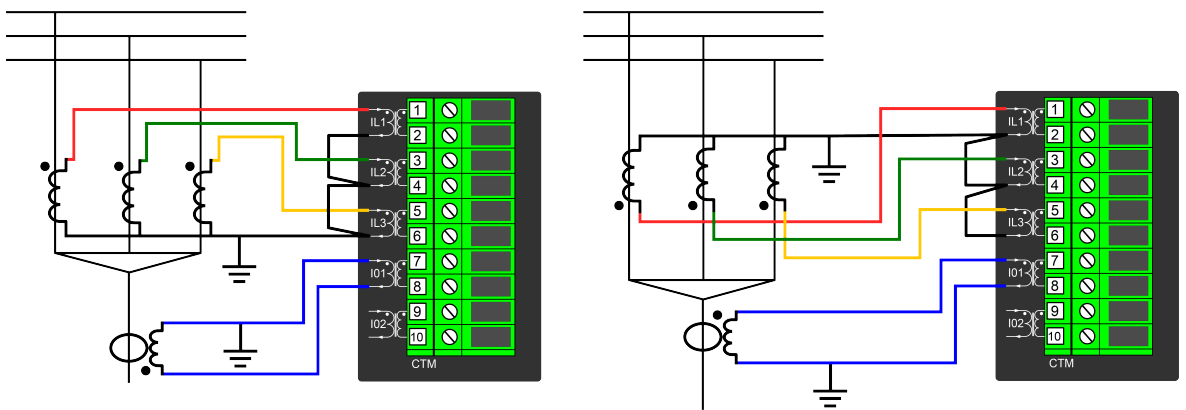
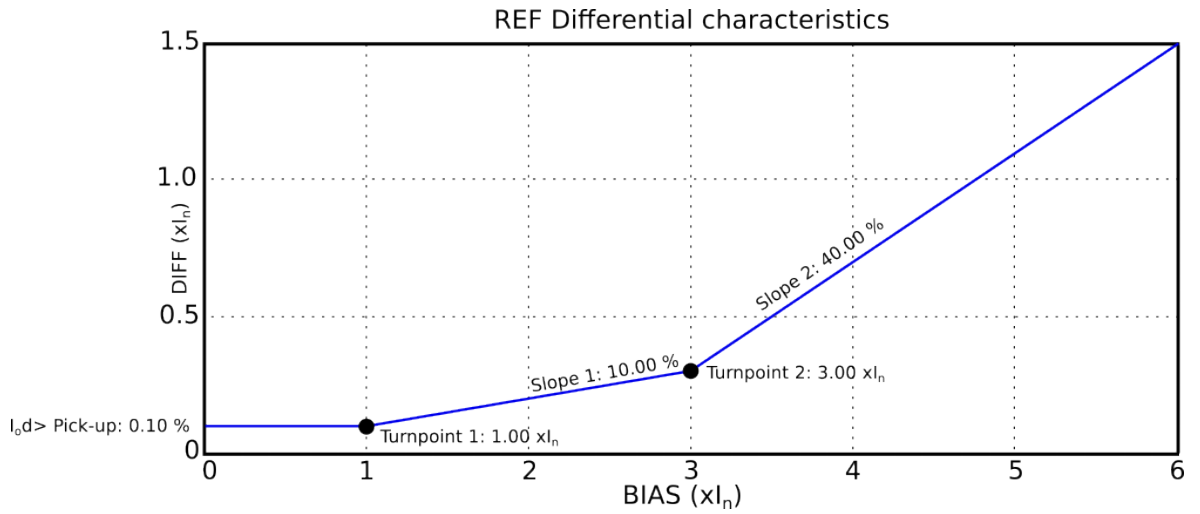


Figure. 4.4.7 - 91. " I_0 direction" parameter must be set to "Add" when current transformers are facing each other or away from each other.



The following figure presents the differential characteristics with default settings.

Figure. 4.4.7 - 92. Differential characteristics for the I0d> function with default settings.



The equations for the differential characteristics are the following:

Figure. 4.4.7 - 93. Differential current (the calculation is based on user-selected inputs and direction).

$$I_{Diff+I01} = (\overline{IL1} + \overline{IL2} + \overline{IL3}) + \overline{I01}$$

$$I_{Diff-I01} = (\overline{IL1} + \overline{IL2} + \overline{IL3}) - \overline{I01}$$

$$I_{Diff+I02} = (\overline{IL1} + \overline{IL2} + \overline{IL3}) + \overline{I02}$$

$$I_{Diff-I02} = (\overline{IL1} + \overline{IL2} + \overline{IL3}) - \overline{I02}$$

Figure. 4.4.7 - 94. Bias current (the calculation is based on the user-selected mode).

$$I_{Bias\ average\ I01} = \frac{|\overline{IL1} + \overline{IL2} + \overline{IL3}| + |\overline{I01}|}{2}$$

$$I_{Bias\ average\ I02} = \frac{|\overline{IL1} + \overline{IL2} + \overline{IL3}| + |\overline{I02}|}{2}$$

$$I_{Bias\ max\ I01} = MAX(|\overline{IL1}|, |\overline{IL2}|, |\overline{IL3}|, |\overline{I01}|)$$

$$I_{Bias\ max\ I02} = MAX(|\overline{IL1}|, |\overline{IL2}|, |\overline{IL3}|, |\overline{I02}|)$$

Figure. 4.4.7 - 95. Characteristics settings.

$$Diff_{bias < TP1} = I0_{d>pick-up}$$

$$Diff_{bias TP1...TP2} = SL1 \times (Ix - TP1) + I0_{d>pick-up}$$

$$Diff_{bias > TP2} = SL2 \times (Ix - TP2) + SL1 \times (TP2 - TP1) + I0_{d>pick-up}$$

Read-only parameters

The function's *Info* page displays useful, real-time information on the state of the protection function. It is accessed either through the device's HMI display, or through the setting tool software when it is connected to the device and its Live Edit mode is active.

Table. 4.4.7 - 70. Information displayed by the function.

| Name | Range | Description |
|----------------|---|---|
| I0d> condition | <ul style="list-style-type: none"> • Normal • Trip • Blocked | Displays the status of the protection function. |

Function blocking

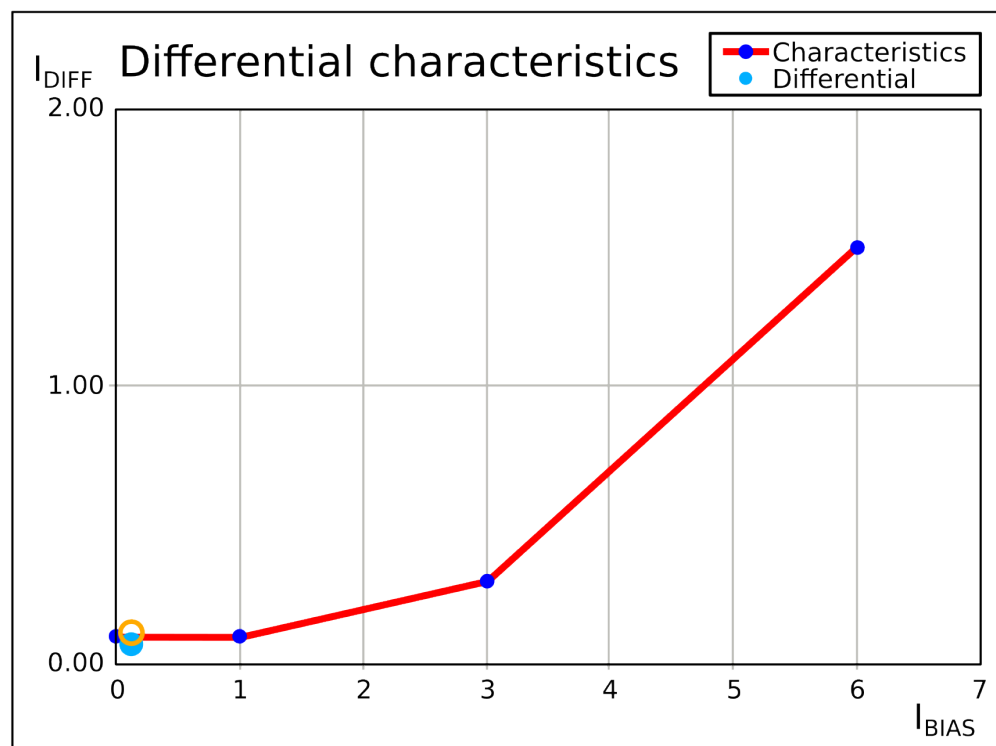
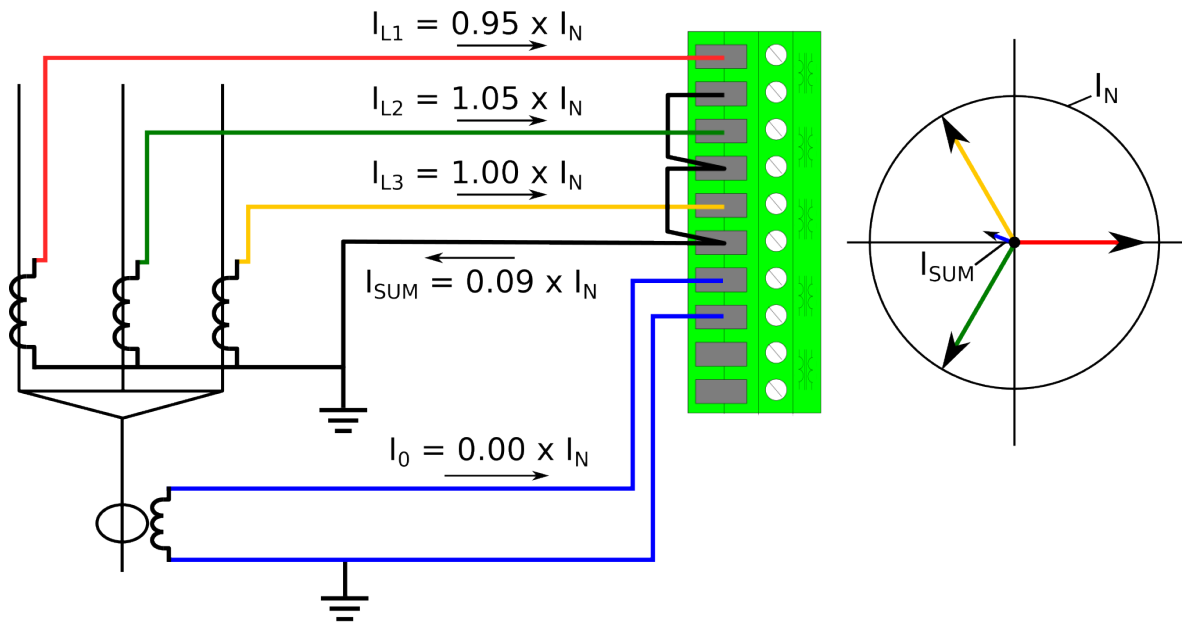
The block signal is checked in the beginning of each program cycle. The blocking signal is received from the blocking matrix in the function's dedicated input. If the blocking signal is not activated when the pick-up element activates, a TRIP signal is generated and the function proceeds to the time characteristics calculation.

If the blocking signal is active when the pick-up element activates, a BLOCKED signal is generated and the function does not process the situation further. If the TRIP function has been activated before the blocking signal, it resets and processes the release time characteristics similarly to when the pick-up signal is reset.

The variables the user can set are binary signals from the system. The blocking signal needs to reach the device minimum of 5 ms before the set operating delay has passed in order for the blocking to activate in time.

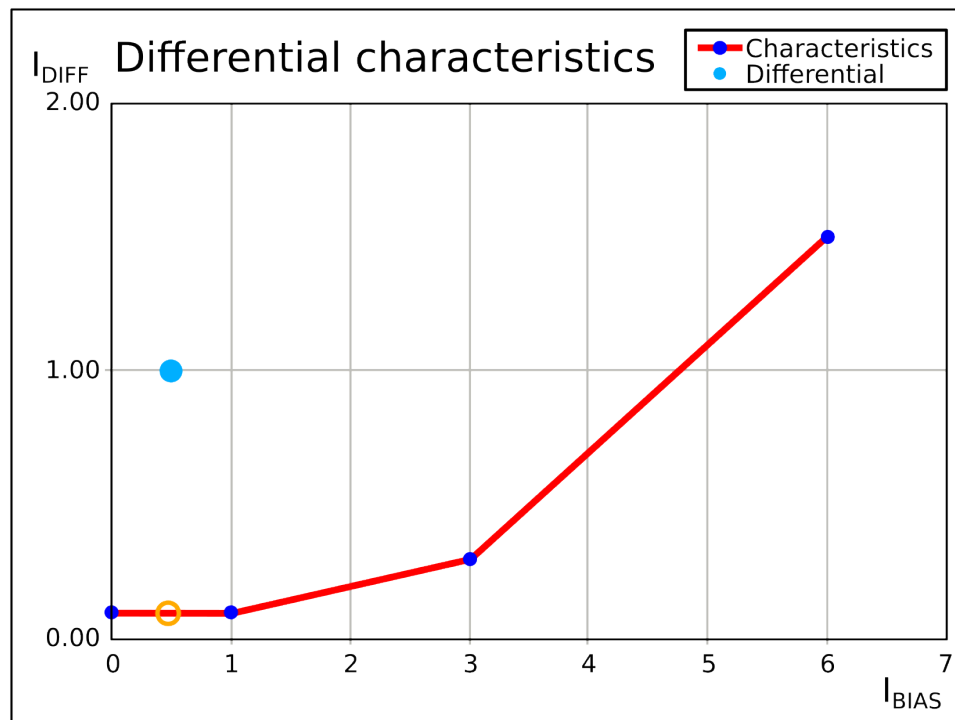
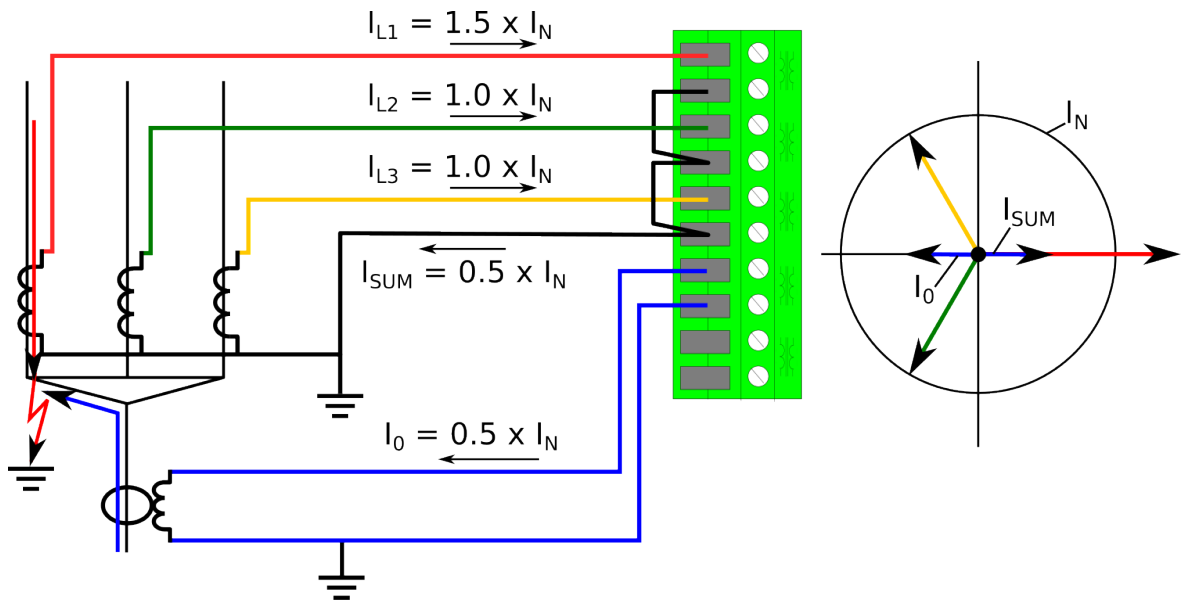
The following figures present some typical applications for this function.

Figure. 4.4.7 - 96. Cable end differential with natural unbalance in the phase current measurement.



When calculating residual current from the phase currents, the natural unbalance can be around 10 % while the used CTs are still within the promised 5P class (which is probably the most common CT accuracy class). When the current natural unbalance is compensated in this situation, the differential settings may be set to be more sensitive and the natural unbalance does not, therefore, affect the calculation.

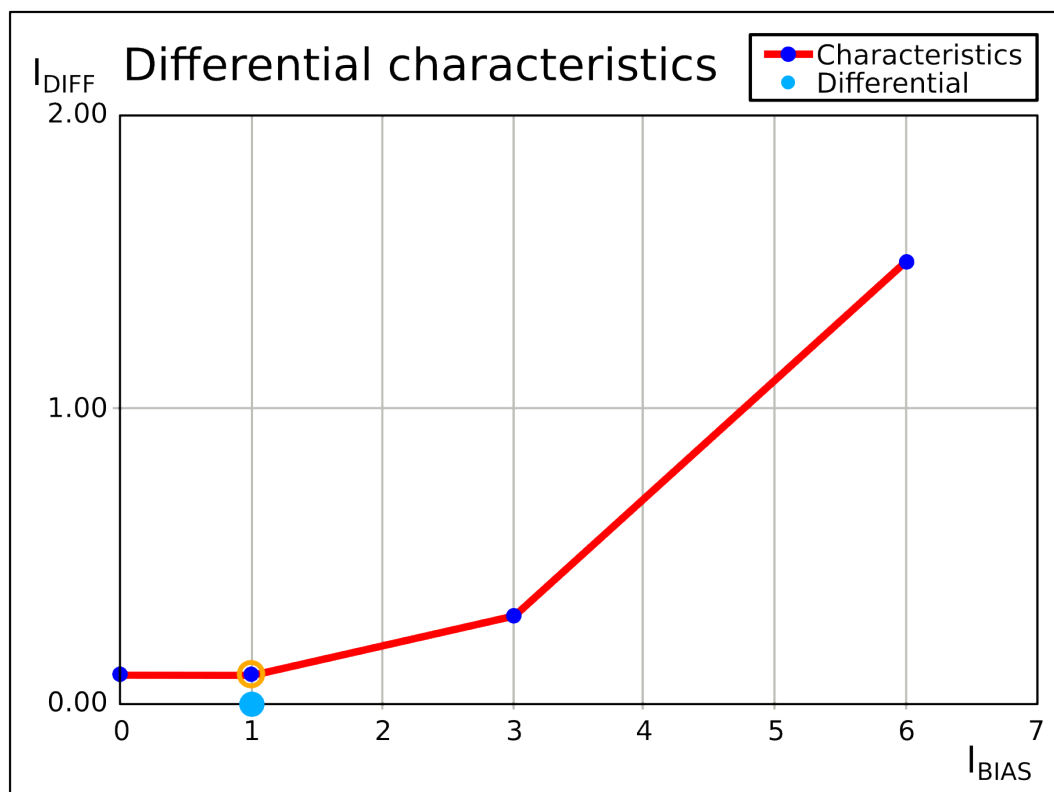
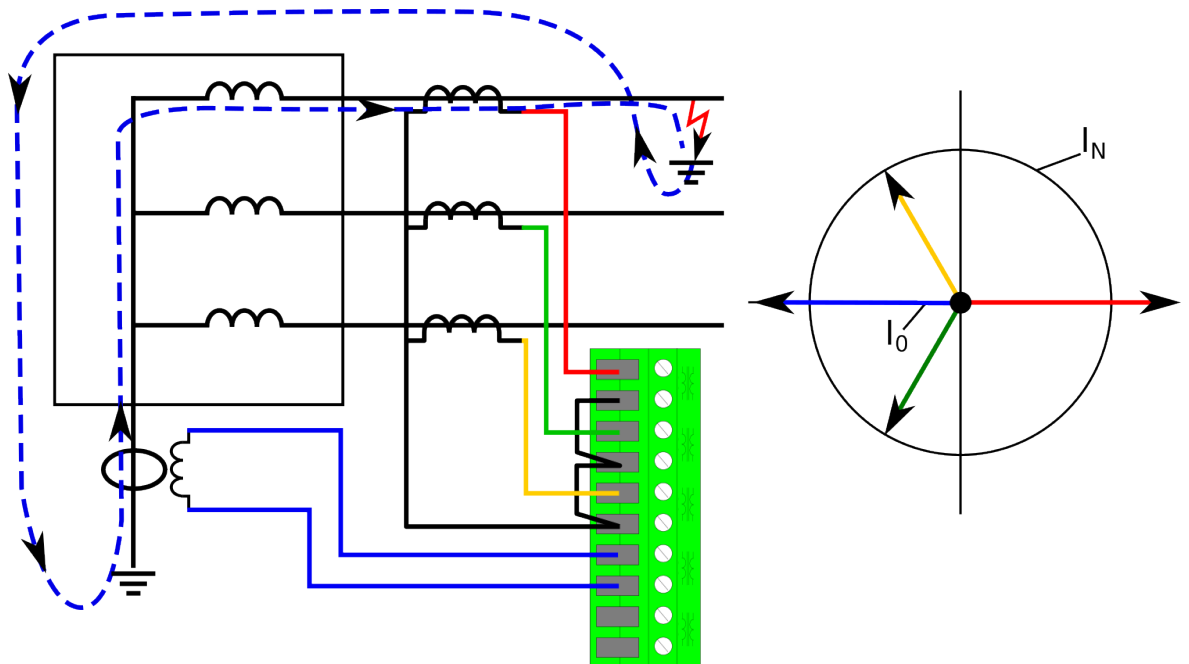
Figure. 4.4.7 - 97. Cable end differential when a fault occurs.



If a starting fault occurs in the cable end, the CED mode catches the difference between the ingoing and the outgoing residual currents. The resulting signal can be used for alarming or tripping purposes for the feeder with the failing cable end. The user can freely change both the settings and the sensitivity of the algorithm.

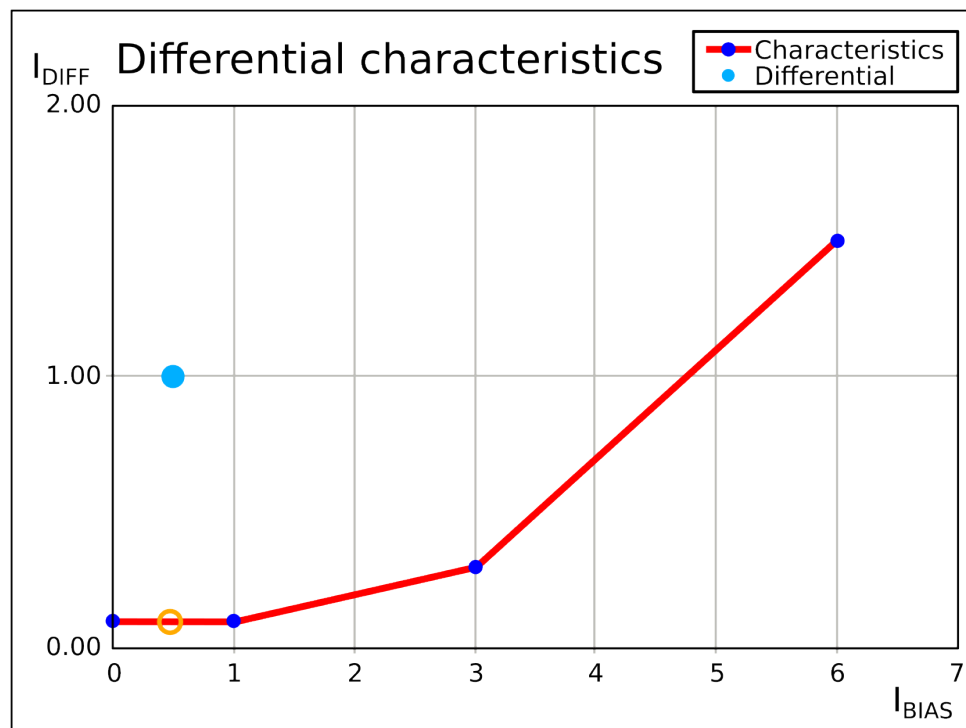
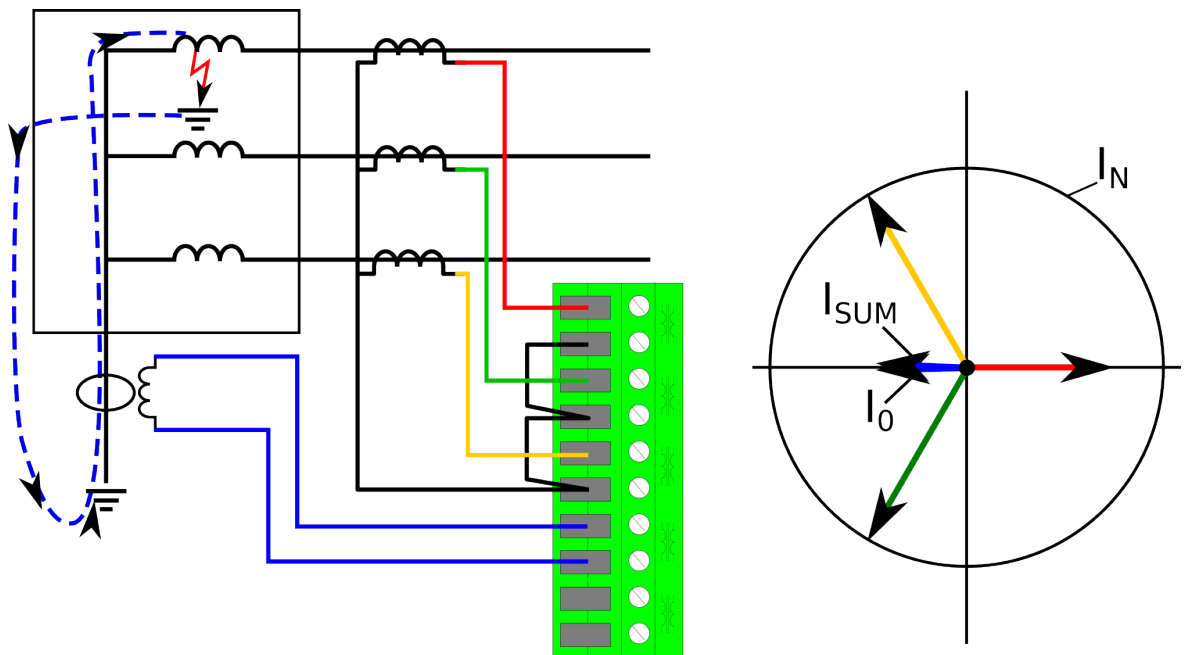
Restricted earth fault protection is usually used in the Y winding of a power transformer. This function is needed to prevent the main differential protection from being tripped by faults occurring outside the protection area; in some cases, the function has to be disabled or its sensitivity limited to catch earth faults inside the protection area. For this purpose, the restricted earth fault function is stable since it only monitors the side it is wired to, and compares the calculated and measured residual currents. During an outside earth fault the circulating residual current in the faulty phase winding does not cause a trip because the comparison of the measured starpoint current and the calculated residual current differential is close to zero.

Figure. 4.4.7 - 98. Restricted earth fault outside a Y winding transformer.



If the fault is located inside of the transformer and thus inside of the protection area, the function catches the fault with high sensitivity. Since the measured residual current now flows in the opposite direction than in the outside fault situation, the measured differential current is high.

Figure. 4.4.7 - 99. Restricted earth fault inside a Y winding transformer.



Events and registers

The restricted earth fault function (abbreviated "REF" in event block names) generates events and registers from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

The function's outputs can be used for direct I/O controlling and user logic programming. The function also provides a resettable cumulative counter for the TRIP and BLOCKED events.

Table. 4.4.7 - 71. Event messages.

| Event block name | Event names |
|------------------|----------------------|
| REF1 | I0d> (87N) Trip ON |
| REF1 | I0d> (87N) Trip OFF |
| REF1 | I0d> (87N) Block ON |
| REF1 | I0d> (87N) Block OFF |

The function registers its operation into the last twelve (12) time-stamped registers. The register of the function records the ON event process data for ACTIVATED, BLOCKED, etc. The table below presents the structure of the function's register content.

Table. 4.4.7 - 72. Register content.

| Register | Description |
|--------------------------|--|
| Date and time | dd.mm.yyyy hh:mm:ss.mss |
| Event | Event name |
| Trigger currents | <ul style="list-style-type: none"> • Biascurrent • Diffcurrent • Characteristics diff |
| Maximum trigger currents | <ul style="list-style-type: none"> • Biascurrent max • Diffcurrent max • Characteristics diff max |
| Residual currents | <ul style="list-style-type: none"> • I0Calc • I0 meas |
| Setting group in use | Setting group 1...8 active |

4.4.8 Line thermal overload protection (TF>; 49F)

The line thermal overload function is used for the thermal capacity monitoring and protection of cables and overhead lines. This function can also be used for any single time constant application like inductor chokes, certain types of transformers and any other static units which do not have active cooling apart from the cables and overhead lines.

The function constantly monitors the instant values of phase TRMS currents (including harmonics up to 31st) and calculates the set thermal replica status in 5 ms cycles. The function includes a total memory function of the load current conditions according to IEC 60255-8.

The function is based on a thermal replica which represents the protected object's or cable's thermal loading in relation to the current going through the object. The thermal replica includes the calculated thermal capacity that the "memory" uses; it is an integral function which tells this function apart from a normal overcurrent function and its operating principle for overload protection applications.

The thermal image for the function is calculated according to the equation described below:

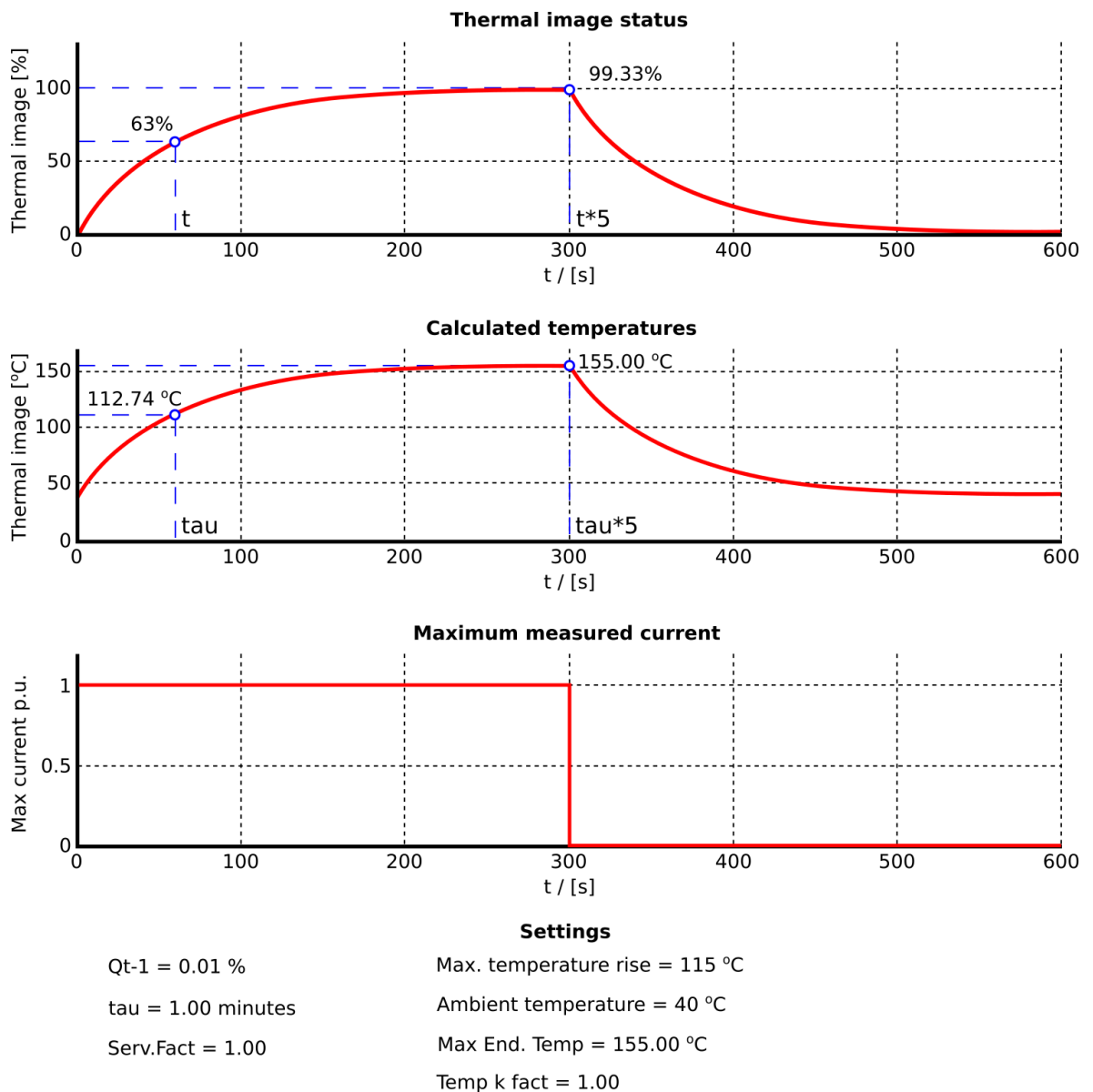
$$\theta_{t\%} = \left(\left(\theta_{t-1} - \left(\frac{I_{max}}{I_n \times k_{SF} \times k_{amb}} \right)^2 \times e^{-\frac{t}{\tau}} \right) + \left(\frac{I_{max}}{I_n \times k_{SF} \times k_{amb}} \right)^2 \right) \times 100\%$$

Where:

- $\theta_{t\%}$ = Thermal image status in percentages of the maximum thermal capacity available
- θ_{t-1} = Thermal image status in a previous calculation cycle (the memory of the function)
- I_{max} = Measured maximum of the three TRMS phase currents
- I_n = Current for the 100 % thermal capacity to be used (the pick-up current in p.u., t_{max} achieved in $\tau \times 5$)
- k_{SF} = Loading factor (service factor), the maximum allowed load current in p.u., dependent on the protected object or the cable/line installation
- k_{amb} = Temperature correction factor, either from a linear approximation or from a settable ten-point thermal capacity curve
- e = Euler's number
- t = Calculation time step in seconds (0.005 s)
- τ = Thermal time constant of the protected object (in minutes)

The basic operating principle of the thermal replica is based on the nominal temperature rise, which is achieved when the protected object is loaded with a nominal load in a nominal ambient temperature. When the object is loaded with a nominal load for a time equal to its heating constant tau (τ), 63% of the nominal thermal capacity is used. When the loading continues until five times this given constant, the used thermal capacity approaches 100 % indefinitely but never exceeds it. With a single time constant model the cooling of the object follows this same behavior, the reverse of the heating when the current feeding is zero.

Figure. 4.4.8 - 100. Example of thermal image calculation with nominal conditions.



The described behavior is based on the assumption that the monitored object (whether a cable, a line or an electrical device) has a homogenous body which generates and dissipates heat with a rate proportional to the temperature rise caused by the current squared. This is usually the case with cables and other objects while the heat dissipation of overhead lines is dependent on the weather conditions. Weather conditions considering the prevailing conditions in the thermal replica are compensated with the ambient temperature coefficient which is constantly calculated and changing when using RTD sensor for the measurement. When the ambient temperature of the protected object is stable it can be set manually (e.g. underground cables).

The ambient temperature compensation takes into account the set minimum and maximum temperatures and the load capacity of the protected object as well as the measured or set ambient temperature. The calculated coefficient is a linear correction factor, as the following formula shows:

$$t_{amb} < t_{min} = k_{min}$$

$$t_{amb} < t_{ref} = \left(\frac{1 - k_{min}}{t_{ref} - t_{min}} \times (t_{amb} - t_{min}) \right) + k_{min}$$

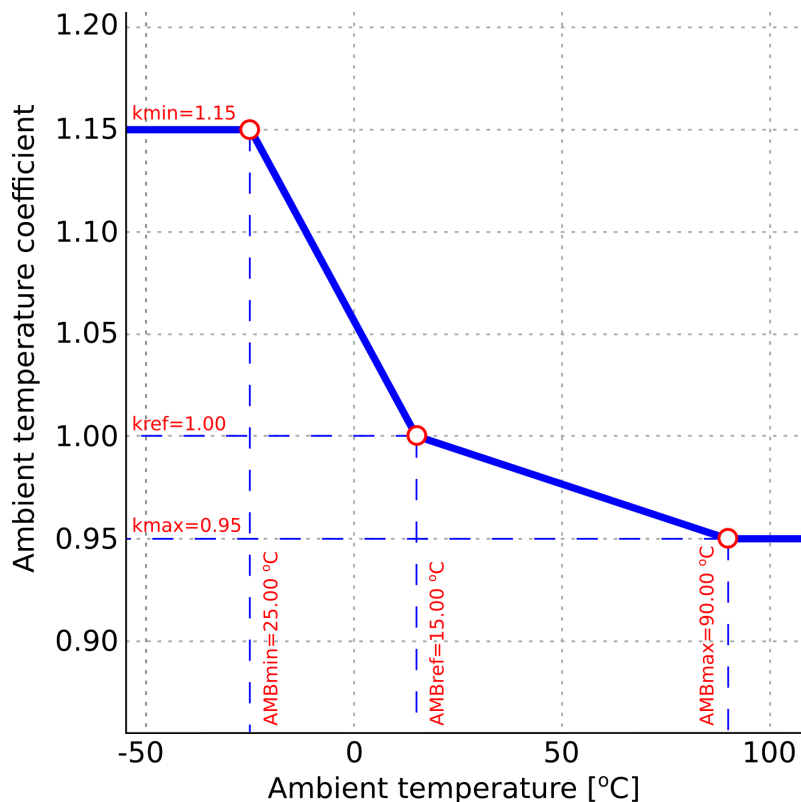
$$t_{amb} > t_{ref} = \left(\frac{k_{max} - 1}{t_{max} - t_{ref}} \times (t_{amb} - t_{ref}) \right) + 1.0$$

$$t_{amb} > t_{max} = k_{max}$$

Where:

- t_{amb} = Measured (or set) ambient temperature (can be set in °C or in °F)
- t_{max} = Maximum temperature (can be set in °C or in °F) for the protected object
- k_{max} = Ambient temperature correction factor for the maximum temperature
- t_{min} = Minimum temperature (can be set in °C or in °F) for the protected object
- k_{min} = Ambient temperature correction factor for the minimum temperature
- t_{ref} = Ambient temperature reference (can be set in °C or in °F, the temperature in which the manufacturer's temperature presumptions apply, the temperature correction factor is 1.0)

Figure. 4.4.8 - 101. Ambient temperature coefficient calculation (a three-point linear approximation and a settable correction curve).



As can be seen in the diagram above, the ambient temperature coefficient is relative to the nominal temperature reference. By default the temperature reference is +15 °C (underground cables) which gives the correction factor value of 1.00 for the thermal replica.

A settable thermal capacity curve uses the linear interpolation for ambient temperature correction with a maximum of ten (10) pairs of temperature–correction factor pairs.

Figure. 4.4.8 - 102. Example of the relationship between ground temperature and correction factor.

| Conductor temperature | | Ground temperature, C° | | | | | | | | | | |
|-----------------------|--|------------------------|------|------|------|------|------|------|------|------|------|------|
| C° | | -5 | 0 | 5 | 10 | 15 | 20 | 25 | 30 | 35 | 40 | 45 |
| 90 | | 1.13 | 1.10 | 1.06 | 1.03 | 1.00 | 0.96 | 0.93 | 0.89 | 0.86 | 0.82 | 0.77 |

The temperature coefficient may be informed in a similar manner to the figure above in a datasheet provided by the manufacturer.

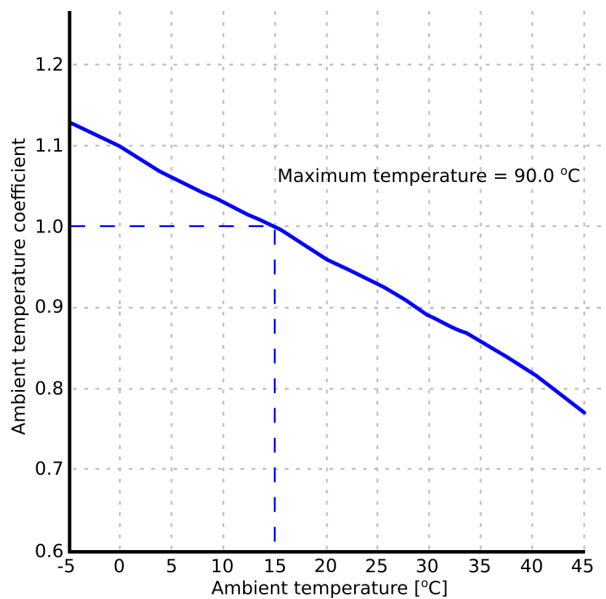
Figure. 4.4.8 - 103. Settings of the function's ambient temperature coefficient curve.

The screenshot shows the 'Protection Settings' window for the 'Supporting' function. The 'Protection Settings' tab is active, and the 'TF> [49F]' sub-tab is selected. The 'Ambient lin or curve' is set to 'Set Curve'. The 'Amb.Temp.ref1' is 0 deg, and 'Amb.Temp.k1' is 1.1 xIn. The 'Amb.Temp.ref2' is 5 deg, and 'Amb.Temp.k2' is 1.06 xIn. The 'Add curvepoint 3' is set to 'Used', and 'Amb.Temp.ref3' is 10 deg, and 'Amb.Temp.k3' is 1.03 xIn. The 'Add curvepoint 4' is set to 'Used', and 'Amb.Temp.ref4' is 15 deg, and 'Amb.Temp.k4' is 1 xIn. The 'Add curvepoint 5' is set to 'Not used'. The 'Environmental Settings' section is also visible at the bottom.

| Parameter | Value | Unit | Range | Resolution |
|---------------|-------|------|--------------|------------|
| Amb.Temp.ref1 | 0 | deg | -60.0..500.0 | 1.0 |
| Amb.Temp.k1 | 1.1 | xIn | 0.01..5.00 | 0.01 |
| Amb.Temp.ref2 | 5 | deg | -60.0..500.0 | 1.0 |
| Amb.Temp.k2 | 1.06 | xIn | 0.01..5.00 | 0.01 |
| Amb.Temp.ref3 | 10 | deg | -60.0..500.0 | 1.0 |
| Amb.Temp.k3 | 1.03 | xIn | 0.01..5.00 | 0.01 |
| Amb.Temp.ref4 | 15 | deg | -60.0..500.0 | 1.0 |
| Amb.Temp.k4 | 1 | xIn | 0.01..5.00 | 0.01 |

The temperature and correction factor pairs are set to the function's settable curve.

Figure. 4.4.8 - 104. Set correction curve for ambient temperature.



The correction curve for ambient temperature is shown in the figure above. The reference temperature for underground cables is usually +15 °C which gives a correction factor of 1.00 (in this case also the nominal temperature). The curve does not need to use as all the available points. The minimum setting is two pairs, resulting in a straight line.

For cables the ambient temperature correction is just one correction factor. The k_{sf} correction factor is used for non-changing corrections; its calculation is explained later in this manual. Calculating correction factors for a cable or overhead installation requires the consulting of the datasheet for the technical specifications of the used cable. This information is usually provided by the cable manufacturer. For example, cable data may be presented as in the figures below (an example from a Prysmian Group cable datasheet) which show the cable's temperature characteristics and voltage ratings (1st image) with different installations and copper or aluminum conductors (2nd and 3rd image).

Figure. 4.4.8 - 105. Example of a high-voltage cable datasheet.

Sample Constructions

Rated voltages

$U_o/U = 38/66$ kV

$U_m = 72.5$ kV

$U_p = 325$ kV

Rated temperatures

- Maximum permissible temp. of conductor in continuous use 90°C
- Maximum permissible temp. of conductor in short-circuit 250°C (for durations up to 5 sec.)

Standard IEC 60840

72 kV Cables 36/66 kV

Single core, XLPE-insulated high voltage power cables

| | | | | | | |
|---|-----------------|-----|-----|-----|------|------|
| Nominal cross-sectional area of conductor | mm ² | 300 | 500 | 800 | 1200 | 1600 |
|---|-----------------|-----|-----|-----|------|------|

Continuous current-carrying capacities

| Conductor | Cables laid | Conductor temperature | Laying formation | Screen circuit | | | | | | |
|-----------|-------------------|-----------------------|------------------|----------------|---|-----|------|------|------|------|
| Aluminium | In ground of 15°C | 65°C | Flat | Open | A | 435 | 575 | 750 | 910 | 1040 |
| | | | | Closed | A | 415 | 525 | 640 | 710 | 750 |
| | | | Trefoil | Open | A | 415 | 545 | 700 | 830 | 930 |
| | | | | Closed | A | 410 | 535 | 680 | 790 | 870 |
| | | 90°C | Flat | Open | A | 515 | 680 | 890 | 1080 | 1235 |
| | | | | Closed | A | 490 | 625 | 770 | 860 | 920 |
| | | | Trefoil | Open | A | 490 | 645 | 830 | 990 | 1110 |
| | | | | Closed | A | 485 | 635 | 805 | 945 | 1045 |
| | In air of 25°C | 90°C | Flat | Open | A | 685 | 930 | 1265 | 1555 | 1815 |
| | | | | Closed | A | 660 | 865 | 1105 | 1270 | 1390 |
| | | | Trefoil | Open | A | 605 | 820 | 1095 | 1335 | 1535 |
| | | | | Closed | A | 600 | 810 | 1085 | 1320 | 1515 |
| Copper | In ground of 15°C | 65°C | Flat | Open | A | 560 | 730 | 940 | 1200 | 1390 |
| | | | | Closed | A | 520 | 635 | 740 | 820 | 855 |
| | | | Trefoil | Open | A | 535 | 685 | 860 | 1095 | 1240 |
| | | | | Closed | A | 525 | 670 | 820 | 1005 | 1105 |
| | | 90°C | Flat | Open | A | 660 | 865 | 1115 | 1415 | 1645 |
| | | | | Closed | A | 620 | 765 | 900 | 1005 | 1055 |
| | | | Trefoil | Open | A | 630 | 815 | 1025 | 1305 | 1485 |
| | | | | Closed | A | 620 | 795 | 980 | 1205 | 1335 |
| | In air of 25°C | 90°C | Flat | Open | A | 880 | 1185 | 1585 | 2040 | 2420 |
| | | | | Closed | A | 830 | 1065 | 1305 | 1505 | 1620 |
| | | | Trefoil | Open | A | 775 | 1035 | 1355 | 1765 | 2065 |
| | | | | Closed | A | 770 | 1025 | 1340 | 1685 | 1940 |

Maximum permissible short-circuit currents for short-circuit duration of one second

| | | | | | | |
|---------------------|----|------|------|-------|-------|-------|
| Aluminium conductor | kA | 28.3 | 47.2 | 75.6 | 113.4 | 151.2 |
| Copper conductor | kA | 42.8 | 71.4 | 114.2 | 171.4 | 228.5 |

The datasheet shows the currents which in a combination with a specific installation and a specific construction method achieve a specific conductor temperature in give standard conditions (e.g. a copper conductor reaches a temperature of 90 °C when, for example, it has a continuous current-carrying capacity of 815 A, an open screen circuit, and is laid in a trefoil formation in soil whose temperature is 15 °C).

The most important parameters for setting a working thermal image are the cable's current and the installation place. In addition to the above-mentioned current-carrying capacity table, the manufacturer should also provide data to allow for fine-tuning the thermal image. Equally important to the ampere-temperature values are the presumptive conditions under which the given continuous current-carrying capacity values can be expected to apply. The following figure is an example of these general presumption as presented in a Prysmian Group cable datasheet.

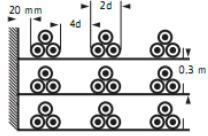
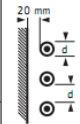

Figure. 4.4.8 - 106. General presumptions of high-voltage cables.

| | | |
|---|---|---|
| Continuous current-carrying capacity | <p>A separate group of three single core cables can be continuously loaded according to the tables on pages 8 to 14 if the presumptions below are fulfilled. Correction factors for other installations are given in tables 1-7.</p> <p>The current-carrying capacities are calculated in accordance with the IEC Publication 60287 and under the presumptions given below.</p> <p>Presumptions</p> <ul style="list-style-type: none"> • One three-phase group of single core cables • Maximum permissible temperature of inner conductor in continuous use: <ul style="list-style-type: none"> • XLPE insulated cables 90°C • Ambient air temperature 25°C • Ground temperature 15°C • Depth of laying of cables 1.0 m • Distance between single core cables: <ul style="list-style-type: none"> - in case of flat formation = one cable diam. - in case of trefoil formation = cables touching each other • Thermal resistivity of soil 1.0 K m/W • Cable in air = heat dissipation conditions same as if cables in free air. • Open screen circuit in single core cable group = circuit of metal sheaths, concentric conductors or metallic screens connected | <p>to each other and earthed at one point only = screens bonded at a single point. In addition, screen circuit is considered open when cross-bonded at equal interval.</p> <ul style="list-style-type: none"> • Closed screen circuit in single core cable group = circuit of metal sheaths, concentric conductors or metallic screens connected to each other at both ends of the group and earthed at least at one end = screens bonded at both ends. <p>XLPE-insulated cables buried directly in ground</p> <p>XLPE-insulated cables can continuously be loaded to a conductor temperature of 90°C. In underground installations, if a cable in the ground is continuously operated at this highest rated conductor temperature, the thermal resistivity of the soil surrounding the cable may in the course of time increase from its original value as a result of the drying-out processes. As a consequence, the conductor temperature may greatly exceed the highest rated value.</p> <p>Using single-point bonding or cross-bonding instead of both-end bonding results in considerable increase in current carrying capacity.</p> |
|---|---|---|

If the installation conditions vary from the presumed conditions manufacturers may give additional information on how to correct the the current-carrying capacity to match the changed conditions. Below is an example of the correction factors provided a manufacturer (Prysmian) for correcting the current-carrying capacity.

Figure. 4.4.8 - 107. Example of correction factors for the current-carrying capacity as given by a manufacturer.

| | | | | | | | | | | | | | | | | | | | | |
|--|--|-------------------|---|------|-----------|------|-----------|--|--|------|-----------|------|------|--|-----------|-----------|------|------|------|--|
| Correction factors for the current-carrying capacity | The following tables of correction factors are to be applied to the current-carrying capacity when installation conditions vary from the presumptions above. | | | | | | | The rating for most conditions can be quickly estimated by multiplying the continuous current-carrying capacity value by the correction factors given in the appropriate tables 1-7. | | | | | | | | | | | | |
| Table 1. Correction factors for groups of cables buried directly in ground | Spacing between groups of cables, mm | | 2 | | 3 | | 4 | | 5 | | 6 | | 8 | | 10 | | | | | |
| | 0 (touching) | | 0.79 | | 0.69 | | 0.63 | | 0.58 | | 0.55 | | 0.50 | | 0.46 | | | | | |
| | 70 | | 0.85 | | 0.75 | | 0.68 | | 0.64 | | 0.60 | | 0.56 | | 0.53 | | | | | |
| | 250 | | 0.87 | | 0.79 | | 0.75 | | 0.72 | | 0.69 | | 0.66 | | 0.64 | | | | | |
| | The values apply to groups of three single core cables (in trefoil or flat formation) without or with spacing between the cable groups horizontally placed. | | | | | | | | | | | | | | | | | | | |
| Table 2. Correction factors for different thermal resistivities of soil | Thermal resistivity of soil Km/W | | 0.7 | | 1.0 | | 1.2 | | 1.5 | | 2.0 | | 2.5 | | 3.0 | | | | | |
| | Correction factor | | 1.10 | | 1.00 | | 0.92 | | 0.85 | | 0.75 | | 0.69 | | 0.63 | | | | | |
| | Examples of thermal resistivities of soil: | | | | | | | | | | | | | | | | | | | |
| | • dry sand (moisture content 0%) | | 3.0 K m/W | | | | | | | | | | | | 1.2 K m/W | | | | | |
| | • dry gravel and clay | | 1.5 K m/W | | | | | | | | | | | | 1.0 K m/W | | | | | |
| | | | | | | | | | | | | | | | | 0.7 K m/W | | | | |
| Table 3. Correction factors for different installation depths in ground | Depth of laying, m | | 0.50-0.70 | | 0.71-0.90 | | 0.91-1.10 | | 1.11-1.30 | | 1.31-1.50 | | | | | | | | | |
| | Rating factor | | 1.05 | | 1.02 | | 1.00 | | 0.97 | | 0.95 | | | | | | | | | |
| Table 4. Correction factors for different ground temperatures | Conductor temperature | | Ground temperature, C° | | | | | | | | | | | | | | | | | |
| | C° | -5 | 0 | 5 | 10 | 15 | 20 | 25 | 30 | 35 | 40 | 45 | | | | | | | | |
| | 90 | 1.13 | 1.10 | 1.06 | 1.03 | 1.00 | 0.96 | 0.93 | 0.89 | 0.86 | 0.82 | 0.77 | | | | | | | | |
| | 80 | 1.14 | 1.11 | 1.07 | 1.04 | 1.00 | 0.96 | 0.92 | 0.88 | 0.83 | 0.78 | 0.73 | | | | | | | | |
| | 70 | 1.17 | 1.13 | 1.09 | 1.04 | 1.00 | 0.95 | 0.90 | 0.85 | 0.80 | 0.73 | 0.67 | | | | | | | | |
| | 65 | 1.18 | 1.14 | 1.10 | 1.05 | 1.00 | 0.95 | 0.89 | 0.84 | 0.77 | 0.71 | 0.63 | | | | | | | | |
| Table 5. Correction factors for different cables in unfilled plastic pipes | Spacing between the tubes, mm | | 1 | | 2 | | 3 | | 4 | | 5 | | 6 | | 8 | | 10 | | | |
| | 0 (touching) | | 0.80 | | 0.75 | | 0.65 | | 0.60 | | 0.60 | | 0.55 | | 0.55 | | 0.50 | | | |
| | 70 | | | | 0.75 | | 0.70 | | 0.65 | | 0.60 | | 0.60 | | 0.55 | | 0.55 | | | |
| | 250 | | | | 0.75 | | 0.70 | | 0.70 | | 0.70 | | 0.65 | | 0.65 | | 0.65 | | | |
| | For parallel ducts with a group of three single core cables in each and with the cables equally loaded the current-carrying capacity indicated on pages 8 to 14 for cables buried directly in ground shall be reduced by correction factors given above. | | | | | | | | | | | | | | | | | | | |
| The reduction in current carrying capacity can be avoided if the pipes after cable pulling are filled with material thermally equal to the ambient ground. | | | | | | | | | | | | | | | | | | | | |
| If factors in table 5 are used, factors in table 1 are not applicable. | | | | | | | | | | | | | | | | | | | | |
| Table 6. Correction factors for different ambient air temperatures | Conductor temperature | | Ambient air temperature, C° | | | | | | | | | | | | | | | | | |
| | C° | 10 | 15 | 20 | 25 | 30 | 35 | 40 | 45 | 50 | 55 | | | | | | | | | |
| | 90 | 1.12 | 1.08 | 1.04 | 1.00 | 0.95 | 0.90 | 0.85 | 0.80 | 0.74 | 0.68 | | | | | | | | | |
| | 80 | 1.14 | 1.09 | 1.05 | 1.00 | 0.95 | 0.89 | 0.84 | 0.77 | 0.69 | 0.61 | | | | | | | | | |
| | 70 | 1.18 | 1.12 | 1.06 | 1.00 | 0.93 | 0.86 | 0.79 | 0.71 | 0.62 | 0.52 | | | | | | | | | |
| | | 65 | 1.20 | 1.14 | 1.07 | 1.00 | 0.93 | 0.85 | 0.77 | 0.68 | 0.57 | 0.45 | | | | | | | | |
| Table 7. Correction factors for different groups of three single core cables laid in the air | Type of laying | | Cables laid in flat formation Spacing = One cable diameter (d). Distance from the wall not less than 20 mm. | | | | | | Cables laid in trefoil formation Spacing = Two cable diameters (2d). Distance from the wall not less than 20 mm. | | | | | | | | | | | |
| | Number of groups | | 1 | | | 2 | | | 3 | | | 1 | | | 2 | | | 3 | | |
| | On floor | | 0.92 | | | 0.89 | | | 0.88 | | | 0.95 | | | 0.90 | | | 0.88 | | |
| | On metal trays (restricted air circulation) | Number of trays | | | | | | | | | | | | | | | | | | |
| | | 1 | 0.92 | | | 0.89 | | | 0.88 | | | 0.95 | | | 0.90 | | | 0.88 | | |
| | | 2 | 0.87 | | | 0.84 | | | 0.83 | | | 0.90 | | | 0.85 | | | 0.83 | | |
| | | 3 | 0.84 | | | 0.82 | | | 0.81 | | | 0.88 | | | 0.83 | | | 0.81 | | |
| | On metal ladders | Number of ladders | | | | | | | | | | | | | | | | | | |
| | | 1 | 1.00 | | | 0.97 | | | 0.96 | | | 1.00 | | | 0.98 | | | 0.96 | | |
| | | 2 | 0.97 | | | 0.94 | | | 0.93 | | | 1.00 | | | 0.95 | | | 0.93 | | |
| | | 3 | 0.96 | | | 0.93 | | | 0.92 | | | 1.00 | | | 0.94 | | | 0.92 | | |
| | | | 6 | 0.82 | | | 0.80 | | | 0.79 | | | 0.86 | | | 0.81 | | | 0.79 | |

| | | | | |
|--|--|------|------|---|
| Arrangements where reduction of current is not necessary | The cooling of cables in flat formation by increased spacing will get better while the losses in metallic screens and sheaths will increase reducing the current-carrying capacity. Each case must be calculated separately. | | |  |
| Systems placed on top of each other | 1 | 2 | 3 |  |
| On structures or on wall | 1 | 2 | 3 |  |
| | Correction factor | | | Correction factor |
| | 0.94 | 0.91 | 0.89 | 0.89 0.86 0.84 |

To demonstrate the importance of the k_{SF} (service factor, current-carrying capacity), let us calculate a cable installation with the correct k factor but without setting it to correct value.

First we read the initial data for the setup of the thermal image:

A 66 kV copper cable with a cross-section of 500 mm^2 is installed into ground. Its 1 s permissible short-circuit current is 71.4 kA and its insulation is XLPE. The cable's screen circuit is open and the laying formation is flat. Its current-carrying capacity is 575 A in 65°C and 680 A in 90°C . The reference temperature for ground installation is 15°C .

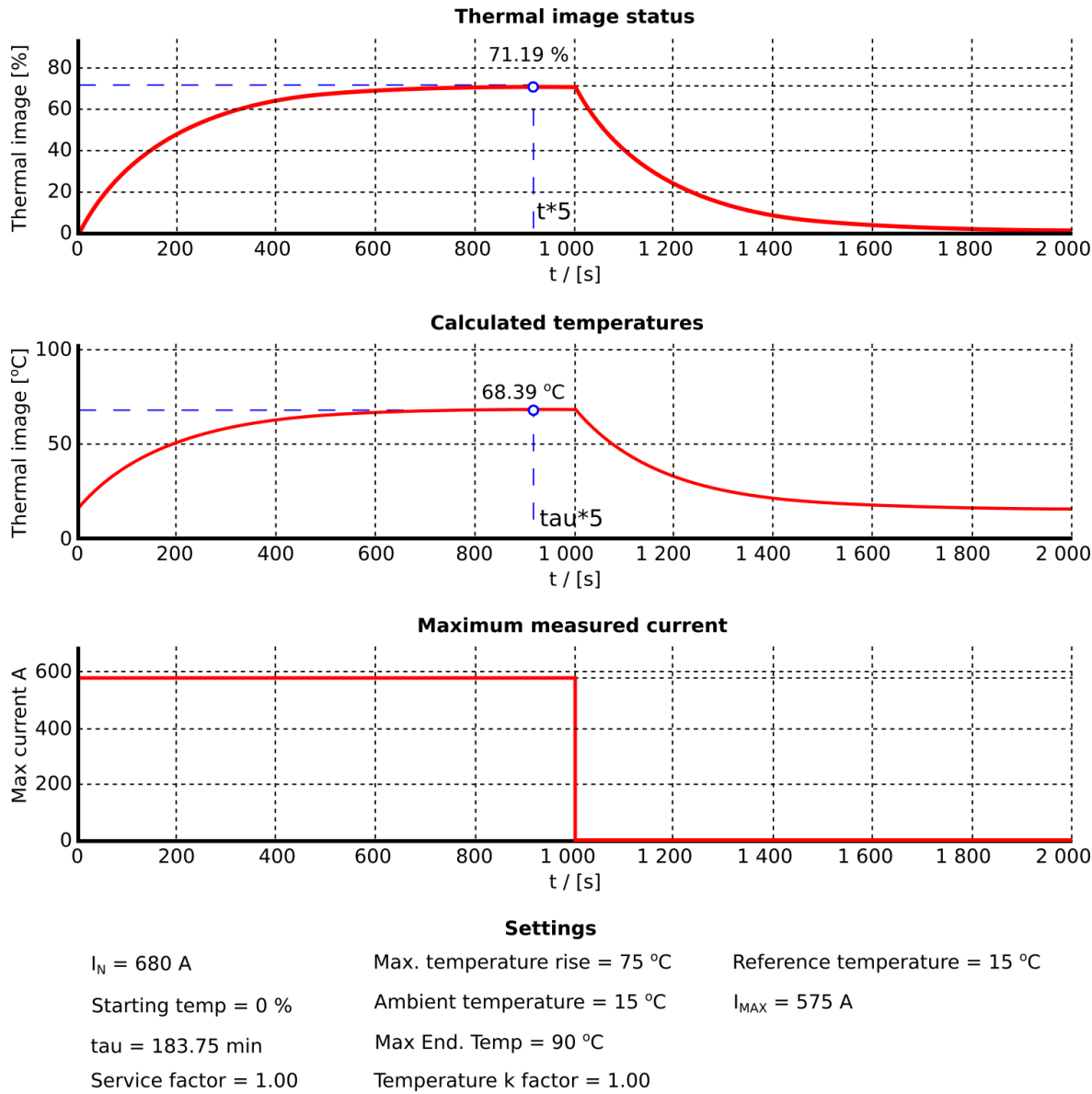
Let us calculate an estimation of the time constant τ based on the known one-second short-circuit current related to I_n . If the manufacturer has not provided the time constant, it can be estimated from the maximum permissible short-circuit current (usually a one second value). The function uses this same method to estimate the heating time constant.

$$\tau_{cable} = \frac{1 \text{ s}}{60 \text{ s}} \times \left(\frac{I_{1s}}{I_n} \right)^2 = \frac{1 \text{ s}}{60 \text{ s}} \times \left(\frac{71\,400 \text{ A}}{680 \text{ A}} \right)^2 = 183.75 \text{ min}$$

The rest of the settings are in the initial data text above:

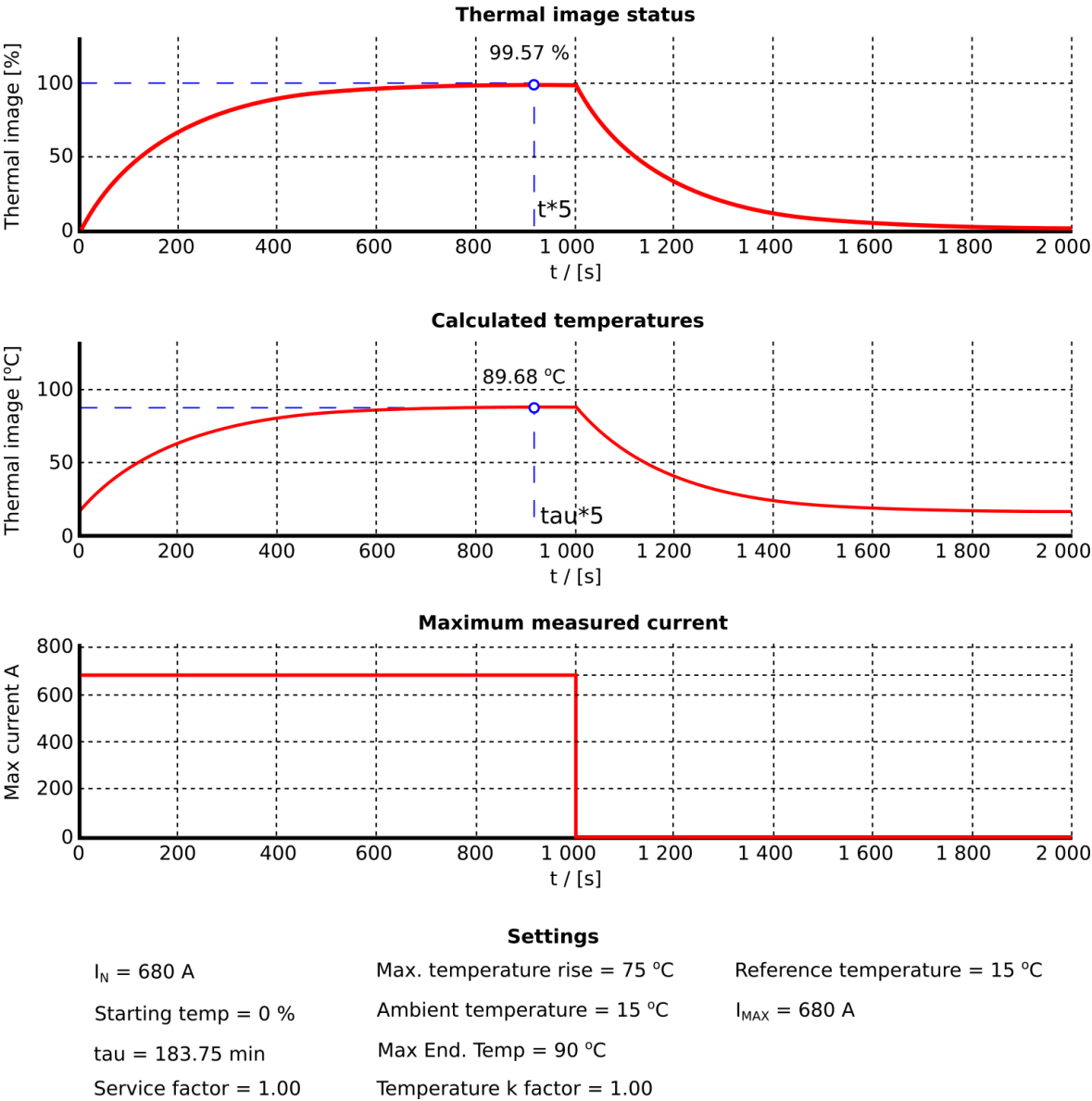
- $I_n = 680 \text{ A}$
- $T_{\max} = 90^\circ\text{C}$
- $T_{\text{amb}} = 15^\circ\text{C}$
- $T_{\text{ref}} = 15^\circ\text{C}$
- $k_{SF} = 1.0$.

Figure. 4.4.8 - 108. Thermal image response with nominal load (installation according to presumptions).



As the results show, the end temperature of 68.39 °C is reached when the cable is loaded with a stable current for time equalling five times the time constant τ . This uses approximately 71 % of the thermal capacity. According to the datasheet, this current should set the temperature around 65 °C; therefore, the model overprotects by three degrees.

Figure. 4.4.8 - 109. Thermal image response with maximum load (installation according presumptions).



The maximum allowed load results in the end temperature of 89.68 °C which means that 99.57 % of the thermal capacity is used. This result matches the expectations of the thermal image perfectly. The user can now securely set the cable's overheating alarm.

When comparing the result to the fully-tuned model in the application, let us include all of the installation correction factors to the image.

A 66 kV copper cable with a cross-section of 500 mm² is installed *with no adjacent cables* ($k=1$) into a *ground consisting of dry gravel and clay* ($k=0.85$) and *into the depth of 1.5 meters* ($k=0.95$). The cable's 1 s permissible short-circuit current is 71.4 kA and its insulation is XLPE. The cable's screen circuit is open and the laying formation is flat. Its current-carrying capacity is 575 A in 65 °C and 680 A in 90 °C. The reference temperature for ground installation is 15 °C. The cable's thermal time constant is 183.8 min.

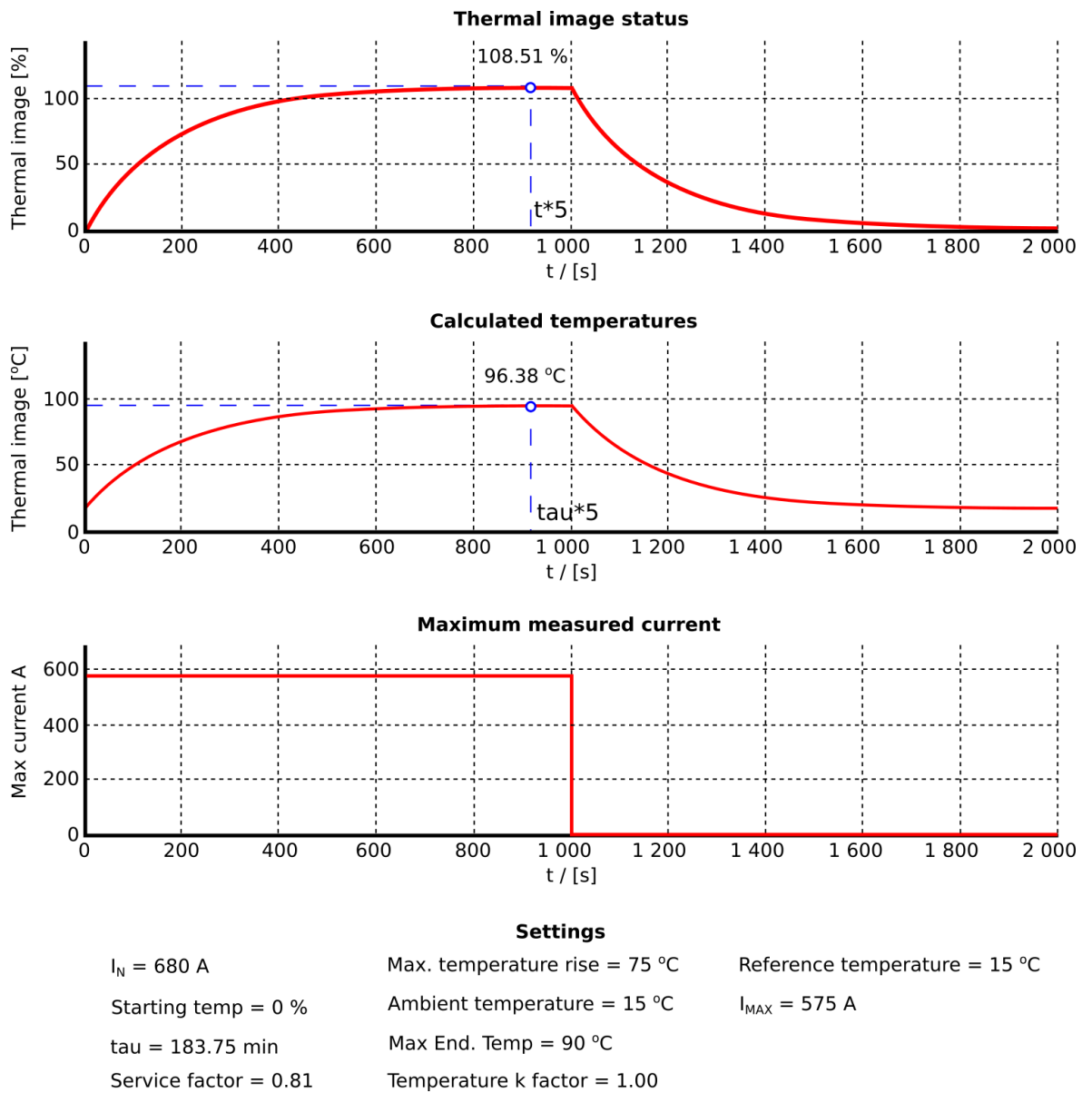
From this initial data one can calculate the k_{SF} correction factor according to the following formula (k factor related information in *italics*):

$$k_{SF} = 1 \times 0.85 \times 0.95 = 0.81$$

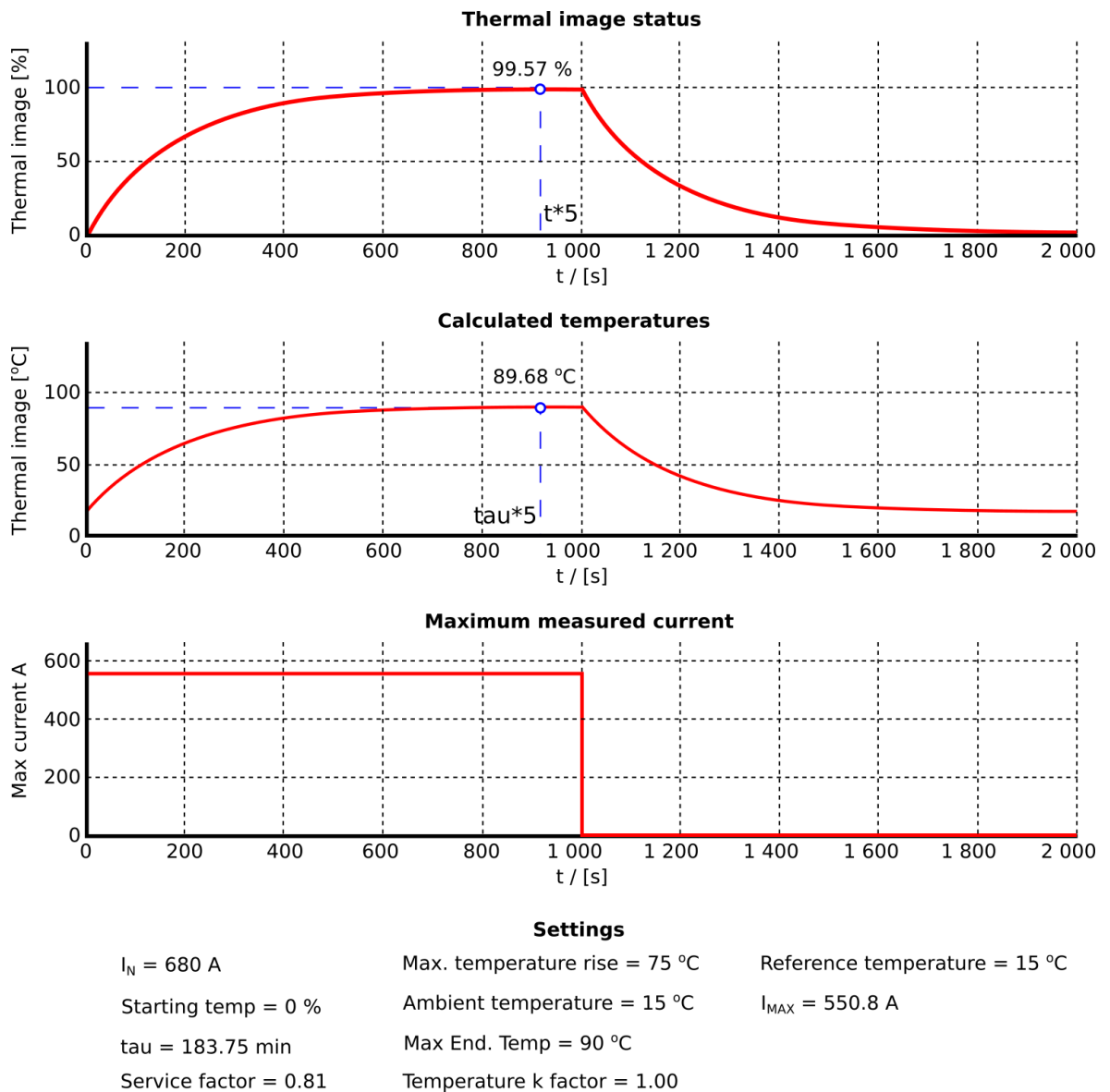
Therefore, the settings are as follows:

- $I_n = 680 \text{ A}$
- $T_{\max} = 90 \text{ }^{\circ}\text{C}$
- $T_{\text{amb}} = 15 \text{ }^{\circ}\text{C}$
- $T_{\text{ref}} = 15 \text{ }^{\circ}\text{C}$
- $\tau = 183.8 \text{ min}$
- $k_{SF} = 0.81$.

Figure. 4.4.8 - 110. Thermal image response with nominal currents and fine-tuned k_{SF} correction factor.



When trying to load the cable with the nominal current one can see the actual current-carrying capacity of the cable is much lower than in the presumptive conditions. A normal loading current can now warm up the cable too much and threaten its withstandability. If the k_{SF} had not been set, the thermal image would show a temperature of appr. $68 \text{ }^{\circ}\text{C}$ instead of the real temperature of $96 \text{ }^{\circ}\text{C}$.

Figure. 4.4.8 - 111. Thermal response with k_{sf} factor correctly set.

When the installation conditions vary from the presumptive conditions, the cable's current-carrying capacity can be reduced so that the temperature of 90 °C is achieved with a 550 A current instead of the 680 A current given in the initial data.

Estimating trip time

Calculated effective nominal current:

$$I_N = k_{SF} \times t_{amb} \times I_{Nom}$$

Where:

- I_N = calculated effective nominal current
- k_{SF} = the service factor
- k_{amb} = the ambient temperature factor
- I_{Nom} = the nominal current of the protected device

Calculated end heating:

$$\theta_{End} = (I_{meas}/I_N)^2$$

Where:

- I_{meas} = the measured current
- I_N = the calculated effective nominal current

Calculated time constant:

$$\tau = e^{(-0.005[s] \times (T_c[\text{min}] \times 60)[s])}$$

Where:

- e = Euler's number
- τ_c = the time constant set by the user
- 0.005s is the program cycle time

Calculated active thermal status:

$$\theta_{Calc} = ((\theta_{-1} - \theta_{End}) \times \tau) + \theta_{End}$$

Where:

- θ_{-1} = previous cycle calculation result (integrating function needs the memory to operate)
- θ_{End} = the calculated end heating (dependent on the measured current)
- τ = the calculated time constant

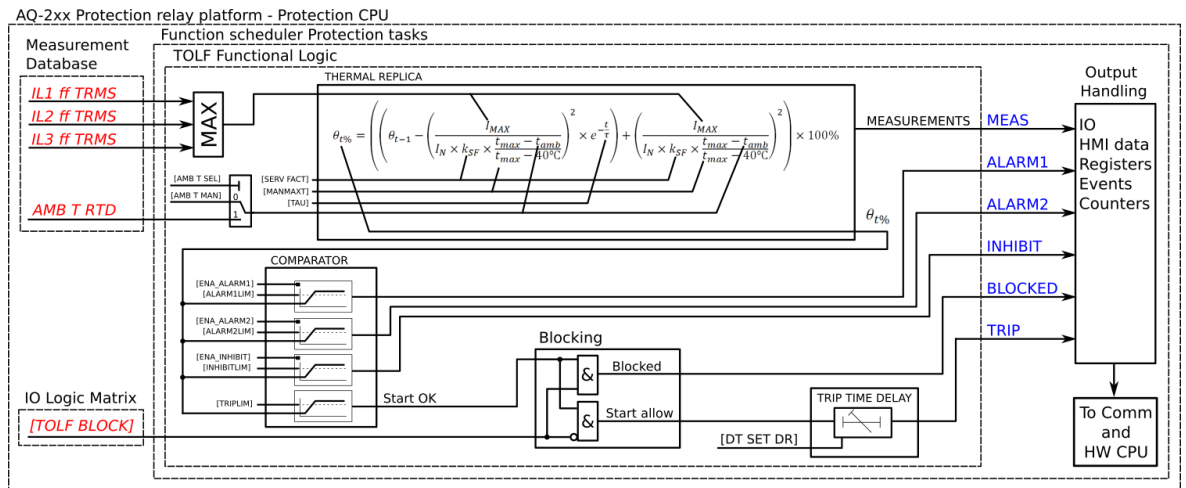
The tripping time can be calculated based on these previous calculations according to the following formula (the result in seconds). With this base information the tripping time can be calculated with the formula above (in seconds) when replacing the θ_{Calc} with the value of the thermal level which from the tripping time is wanted to be calculated (in per-unit value).

$$t_{est. trip} = I_n \left(\frac{I_{meas}^2 - (k_{fact} \times t_{amb} \times \sqrt{\theta_{Calc}} \times I_n)^2}{(I_{meas}^2 - I_n^2)} \right) \times \tau \times 60$$

Function inputs and outputs

The following figure presents a simplified function block diagram of the line thermal overload protection function.

Figure. 4.4.8 - 112. Simplified function block diagram of the TF> function.



Measured input

The function block uses phase current measurement values. The function block uses TRMS values from the whole harmonic spectrum of 32 components. RTD input can be used for measuring ambient temperature.

Table. 4.4.8 - 73. Measurement inputs of the TF> function.

| Signal | Description | Time base |
|----------------------|--|-----------|
| I _{L1} TRMS | TRMS measurement of phase L1 (A) current | 5ms |
| I _{L2} TRMS | TRMS measurement of phase L2 (B) current | 5ms |
| I _{L3} TRMS | TRMS measurement of phase L3 (C) current | 5ms |
| RTD | Temperature measurement for the ambient correction | 5ms |

Table. 4.4.8 - 74. General settings (not selectable under setting groups)

| Name | Range | Default | Description |
|---------------------|--|----------|--|
| TF> mode | <ul style="list-style-type: none"> Disabled Activated | Disabled | The selection of the function is activated or disabled in the configuration. By default it is not in use. |
| TF> force status to | <ul style="list-style-type: none"> Normal Blocked Alarm1 On Alarm2 On Inhibit On Trip On | Normal | Force the status of the function. Visible only when <i>Enable stage forcing</i> parameter is enabled in <i>General</i> menu. |
| Temp C or F deg | <ul style="list-style-type: none"> C F | C | The selection of whether the temperature values of the thermal image and RTD compensation are shown in Celsius or in Fahrenheit. |

Table. 4.4.8 - 75. Settings for thermal replica.

| Name | Range | Step | Default | Description |
|--|---|---------------------|--------------------------|---|
| IN thermal cap current | 0.10...40.00xI _n | 0.01xI _n | 1.00xI _n | The current for the 100 % thermal capacity to be used (the pick-up current in p.u., with t _{max} achieved in time τ x 5). |
| Set or Estimate tau (t const) | <ul style="list-style-type: none"> Set Estimate | - | Set | The selection of the time constant setting. If "Set" is selected, the Tau (t const) setting is available and the time constant to be used can be set there. If "Estimate" is selected, the cable's initial data parameters are visible. |
| Tau (t const) | 0.1...500.0min | 0.1min | 10.0min | The time constant setting. This time constant is used for heating and cooling of the protected object. This setting is visible if the "Set" is selected for the "Set or Estimate tau" setting. |
| Max. perm. OC. current (norm **ik**1s) | 1...1 000 000A | 1A | 75 000A | The maximum-rated short-circuit current of the protected object (cable). Usually this value is presented as a one second value. This setting is visible if "Estimate" is selected for the "Set or Estimate tau" setting. |
| Max. OC. time (norm 1 s) | 0.1...5s | 0.1s | 1.0s | The time of the maximum-rated short-circuit current of the protected object (usually 1 s). This setting is visible if "Estimate" is selected for the "Set or Estimate tau" setting. |
| Nominal current | 1...1 000 000A | 1A | 700A | The rated nominal current in the primary value of the protected object under nominal-rated conditions. This setting is visible if "Estimate" is selected for the "Set or Estimate tau" setting. |
| Estimated tau | 0...1800min | 0.005min | 191.3min (from defaults) | The estimated result which is used for the thermal replica's time constant. After the previous three required parameters are set the device will calculate this value. This setting is visible if "Estimate" is selected for the "Set or Estimate tau" setting. |
| k _{sf} (service factor) | 0.01...5.00 | 0.01 | 1.00 | The service factor which corrects the value of the maximum allowed current according to installation and other conditions varying from the presumptive conditions. |
| Cold reset default theta | 0.0...150.0% | 0.1% | 60.0% | <p>The thermal image status in the restart of the function/ device. The value is given in percentages of the used thermal capacity of the protected object. It is also possible to reset the thermal element.</p> <p>This parameter can be used when testing the function to manually set the current thermal cap to any value.</p> |

Table. 4.4.8 - 76. Environmental settings

| Name | Range | Step | Default | Description |
|---|------------|------|---------|---|
| Object max. temp. (t _{max} = 100%) | 0...500deg | 1deg | 90deg | The maximum allowed temperature for the protected object. The default suits for Celsius range and for PEX-insulated cables. |

| Name | Range | Step | Default | Description |
|--|--|---------------------|---------------------|---|
| Ambient temp. sel. | <ul style="list-style-type: none"> Manual set RTD | - | Manual set | The selection of whether fixed or measured ambient temperature is used for the thermal image biasing. |
| Man. amb. temp. set. | 0...500deg | 1deg | 15deg | The manual fixed ambient temperature setting for the thermal image biasing. Underground cables usually use 15 °C. This setting is visible if "Manual set" is selected for the "Ambient temp. sel." setting. |
| RTD amb. temp. read. | 0...500deg | 1deg | 15deg | The RTD ambient temperature reading for the thermal image biasing. This setting is visible if "RTD" is selected for the "Ambient temp. sel." setting. |
| Ambient lin. or curve | <ul style="list-style-type: none"> Linear est. Set curve | - | Linear est. | The selection of how to correct the ambient temperature, either by internally calculated compensation based on end temperatures or by a user-settable curve. The default setting is "Linear est." which means the internally calculated correction for ambient temperature. |
| Temp. reference (t _{ref}) k _{amb} =1.0 | -60...500deg | 1deg | 15deg | The temperature reference setting. The manufacturer's temperature presumptions apply and the thermal correction factor is 1.00 (rated temperature). For underground cables the set value for this is usually 15 °C and for cables in the air it is usually 25 °C. This setting is visible if "Ambient lin. or curve" is set to "Linear est." |
| Max. ambient temp. | 0...500deg | 1deg | 45deg | The maximum ambient temperature setting. If the measured temperature is more than the maximum set temperature, the set correction factor for the maximum temperature is used. This setting is visible if "Ambient lin. or curve" is set to "Linear est." |
| k at max. amb. temp. | 0.01...5.00x _{ln} | 0.01x _{ln} | 1.00x _{ln} | The temperature correction factor for the maximum ambient temperature setting. This setting is visible if "Ambient lin. or curve" is set to "Linear est." |
| Min. ambient temp. | -60...500deg | 1deg | 0deg | The minimum ambient temperature setting. If the measured temperature is below the minimum set temperature, the set correction factor for minimum temperature is used. This setting is visible if "Ambient lin. or curve" is set to "Linear est." |
| k at min. amb. temp. | 0.01...5.00x _{ln} | 0.01x _{ln} | 1.00x _{ln} | The temperature correction factor for the minimum ambient temperature setting. This setting is visible if "Ambient lin. or curve" is set to "Linear est." |
| Amb. temp. ref. 1...10 | -50.0...500.0deg | 0.1deg | 15deg | The temperature reference points for the user-settable ambient temperature coefficient curve. This setting is visible if "Ambient lin. or curve" is set to "Set curve". |
| Amb. temp. k1...k10 | 0.01...5.00 | 1.00 | 0.01 | The coefficient value for the temperature reference point. The coefficient and temperature reference points must be set as pairs. This setting is visible if "Ambient lin. or curve" is set to "Set curve". |

| Name | Range | Step | Default | Description |
|-----------------------|--|------|----------|--|
| Add curvepoint 3...10 | <ul style="list-style-type: none"> Not used Used | - | Not used | The selection of whether or not the curve temperature/coefficient pair is in use. The minimum number to be set for the temperature/coefficient curve is two pairs and the maximum is ten pairs. If the measured temperature is below the set minimum temperature reference or above the maximum set temperature reference, the used temperature coefficient is the first or last value in the set curve. This setting is visible if "Ambient lin. or curve" is set to "Set curve". |

Pick-up settings

The operating characteristics of the machine thermal overload protection function are completely controlled by the thermal image. The thermal capacity value calculated from the thermal image can set the I/O controls with ALARM 1, ALARM 2, INHIBIT and TRIP signals.

Setting group selection controls the operating characteristics of the function, i.e. the user or user-defined logic can change function parameters while the function is running.

Table. 4.4.8 - 77. Pick-up settings.

| Name | Range | Step | Default | Description |
|-------------------------|---|------|----------|--|
| Enable TF> Alarm 1 | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Enabling/disabling the ALARM 1 signal and the I/O. |
| TF> Alarm 1 level | 0.0...150.0% | 0.1% | 40% | ALARM 1 activation threshold. |
| Enable TF> Alarm 2 | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Enabling/disabling the ALARM 2 signal and the I/O. |
| TF> Alarm 2 level | 0.0...150.0% | 0.1% | 40% | ALARM 2 activation threshold. |
| Enable TF> Rest Inhibit | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Enabling/disabling the ALARM 1 signal and the I/O. |
| TF> Inhibit level | 0.0...150.0% | 0.1% | 80% | INHIBIT activation threshold. |
| Enable TF> Trip | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Enabling/disabling the ALARM 1 signal and the I/O. |
| TF> Trip level | 0.0...150.0% | 0.1% | 100% | TRIP activation threshold. |

| Name | Range | Step | Default | Description |
|-------------------|-------------------|--------|---------|---|
| TF> Trip delay | 0.000...3600.000s | 0.005s | 0.000s | The trip signal's additional delay. This delay delays the trip signal generation by a set time. The default setting is 0.000 s which does not give an added time delay for the trip signal. |

Function blocking

The block signal is checked in the beginning of each program cycle. The blocking signal is received from the blocking matrix in the function's dedicated input. If the blocking signal is not activated when the pick-up element activates, a START signal is generated and the function proceeds to the time characteristics calculation.

If the blocking signal is active when the pick-up element activates, a BLOCKED signal is generated and the function does not process the situation further. If the START function has been activated before the blocking signal, it resets and processes the release time characteristics similarly to when the pick-up signal is reset.

The variables the user can set are binary signals from the system. The blocking signal needs to reach the device minimum of 5 ms before the set operating delay has passed in order for the blocking to activate in time.

Measurements and indications

The function outputs measured process data from the following magnitudes:

Table. 4.4.8 - 78. General status codes.

| Name | Range | Description |
|----------------------|--|--|
| TF> Condition | <ul style="list-style-type: none"> Normal Alarm 1 ON Alarm 2 ON Inhibit ON Trip ON Blocked | The function's operating condition at the moment considering binary IO signal status. No outputs are controlled when the status is "Normal". |
| Thermal status | <ul style="list-style-type: none"> Light / No load High overload Overloading Load normal | The function's thermal image status. When the measured current is below 1 % of the nominal current, the status "Light/No load" is shown. When the measured current is below the trip limit, the status "Load normal" is shown. When the measured current is above the pick-up limit but below $2 \times I_n$, the status "Overloading" is shown. When the measured current is above $2 \times I_n$, the status "High overload" is shown. |
| TF> Setting alarm | <ul style="list-style-type: none"> SF setting ok Service factor set fault. Override to 1.0 | Indicates if SF setting has been set wrong and the actually used setting is 1.0. Visible only when there is a setting fault. |

| Name | Range | Description |
|-------------------|---|---|
| TF> Setting alarm | <ul style="list-style-type: none"> Ambient setting ok Ambient t set fault. Override to 1.0 | Indicates if ambient temperature settings have been set wrong and actually used setting is 1.0. Visible only when there is a setting fault. |
| TF> Setting alarm | <ul style="list-style-type: none"> Nominal current calc ok Nominal current set fault. Override to 1.0 | Indicates if nominal current calculation is set wrong and actually used setting is 1.0. Visible only when there is a setting fault. |
| TF> Setting alarm | <ul style="list-style-type: none"> Ambient setting ok Inconsistent setting of ambient k | Indicates if ambient k setting has been set wrong. Visible only when there is a setting fault. |

Table. 4.4.8 - 79. Measurements.

| Name | Range | Description/values |
|---------------|--|---|
| Currents | <ul style="list-style-type: none"> Primary A Secondary A Per unit | The active phase current measurement from IL1 (A), IL2 (B) and IL3 (C) phases in given scalings. |
| Thermal image | Thermal image calc. | <ul style="list-style-type: none"> - TF> Trip expect mode: No trip expected/Trip expected - TF> Time to 100 % theta: Time to reach the 100 % thermal cap - TF> Reference T curr.: reference/pick-up value (IEQ) - TF> Active meas. curr.: the measured maximum TRMS current at a given moment - TF> T est. with act. curr.: estimation of the used thermal capacity including the current at a given moment - TF> T at a given moment: the thermal capacity used at that moment |
| | Temp. estimates | <ul style="list-style-type: none"> - TF> Used k for amb. temp: the ambient correction factor at a given moment - TF> Max. temp. rise all.: the maximum allowed temperature rise - TF> Temp. rise atm: the calculated temperature rise at a given moment - TF> Hot spot estimate: the estimated hot spot temperature including the ambient temperature - TF> Hot spot max. all.: the maximum allowed temperature for the object |
| | Timing status | <ul style="list-style-type: none"> - TF> Trip delay remaining: the time to reach 100% theta - TF> Trip time to rel.: the time to reach theta while staying below the trip limit during cooling - TF> Alarm 1 time to rel.: the time to reach theta while staying below the Alarm 1 limit during cooling - TF> Alarm 2 time to rel.: the time to reach theta while staying below the Alarm 2 limit during cooling - TF> Inhibit time to rel.: the time to reach theta while staying below the Inhibit limit during cooling |

Table. 4.4.8 - 80. Counters.

| Name | Description / values |
|------------------|---|
| Alarm1 inits | The number of times the function has activated the Alarm 1 output |
| Alarm2 inits | The number of times the function has activated the Alarm 2 output |
| Restart inhibits | The number of times the function has activated the Restart inhibit output |
| Trips | The number of times the function has tripped |
| Trips Blocked | The number of times the function trips has been blocked |

Events and registers

The line thermal overload protection function (abbreviated "TOLF" in event block names) generates events and registers from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

The function's outputs can be used for direct I/O controlling and user logic programming. The function also provides a resettable cumulative counter for the ALARM, INHIBIT, TRIP and BLOCKED events.

Table. 4.4.8 - 81. Event messages.

| Event block name | Event names |
|------------------|-------------|
| TOLF1 | Alarm1 ON |
| TOLF1 | Alarm1 OFF |
| TOLF1 | Alarm2 ON |
| TOLF1 | Alarm2 OFF |
| TOLF1 | Inhibit ON |
| TOLF1 | Inhibit OFF |
| TOLF1 | Trip ON |
| TOLF1 | Trip OFF |
| TOLF1 | Block ON |
| TOLF1 | Block OFF |

The function registers its operation into the last twelve (12) time-stamped registers. The register of the function records the ON event process data for TRIP or BLOCKED. The table below presents the structure of the function's register content.

Table. 4.4.8 - 82. Register content.

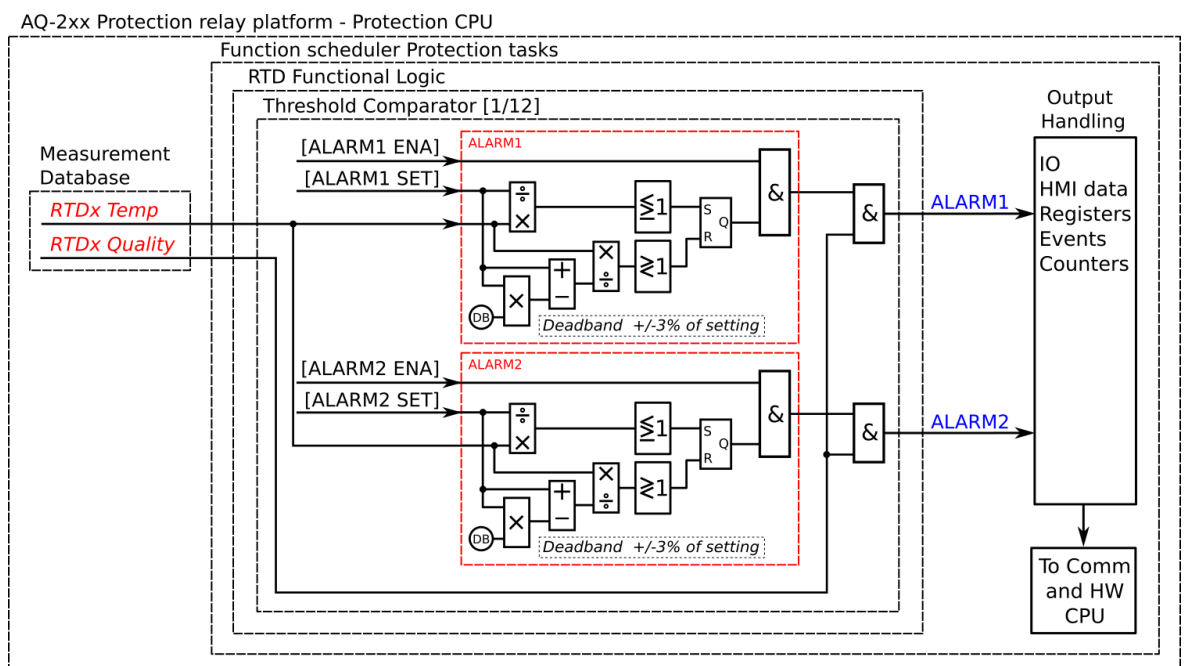
| Name | Description |
|---------------|-------------------------|
| Date and time | dd.mm.yyyy hh:mm:ss.mss |

| Name | Description |
|------------------------------|----------------------------|
| Event | Event name |
| Time to reach 100 % theta | seconds |
| Ref. T current | x I _N |
| Active meas. current | x I _N |
| T at a given moment | % |
| Max. temp. rise allowed | degrees |
| Temp. rise at a given moment | degrees |
| Hot spot estimate | degrees |
| Hot spot maximum allowed | degrees |
| Trip delay rem. | seconds |
| Setting group in use | Setting group 1...8 active |

4.4.9 Resistance temperature detectors (RTD)

Resistance temperature detectors (or RTDs) can be used to measure both temperatures of motors/generators and ambient temperatures. Typically an RTD is a thermocouple or of type PT100. Up to three (3) separate RTD modules based on an external Modbus are supported; each can hold up to eight (8) measurement elements. Up to two (2) separate RTD option cards are supported by this function. Sixteen (16) individual element monitors can be set for this alarm function, and each of those can be set to alarm two (2) separate alarms from one selected input. The user can set alarms and measurements to be either in degrees Celsius or Fahrenheit.

Figure. 4.4.9 - 113. Simplified function block diagram of the resistance temperature detection function.



Settings

Setting up an RTD measurement, the user first needs to set the measurement module to scan the wanted RTD elements. A multitude of Modbus-based modules are supported. Communication requires bitrate, databits, parity, stopbits and Modbus I/O protocol to be set; this is done at *Communication* → *Connections*. Once communication is set, the wanted channels are selected at *Communication* → *Protocols* → *ModbusI/O*. Then the user selects the measurement module from the three (3) available modules (A, B and C), as well as the poll address. Additionally, both the module type and the polled channels need to be set. When using a thermocouple module, the thermo element type also needs to be set for each of the measurement channels. Once these settings are done the RTDs are ready for other functions.

Table. 4.4.9 - 83. Function settings for Channel x (Sx).

| Name | Range | Step | Default | Description |
|-------------------------|--|--------|--------------|--|
| S1...S16 enable | No Yes | - | No | Enables/disables the selection of sensor measurements and alarms. |
| S1...S16 module | <ul style="list-style-type: none"> InternalRTD1 InternalRTD2 ExtModuleA ExtModuleB ExtModuleC | - | InternalRTD1 | Selects the measurement module. Internal RTD modules are option cards installed to the device. External modules are Modbus based external devices. |
| S1...S16 channel | <ul style="list-style-type: none"> Channel 0 Channel 1 Channel 2 Channel 3 Channel 4 Channel 5 Channel 6 Channel 7 | - | Channel 0 | Selects the measurement channel in the selected module. |
| S1...S16 Deg C/Deg F | <ul style="list-style-type: none"> Deg C Deg F | - | Deg C | Selects the measurement temperature scale (Celsius or Fahrenheit). |
| S1...S16 Measurement | - | - | - | Displays the measurement value in the selected temperature scale. |
| S1...S16 Sensor | <ul style="list-style-type: none"> Ok Invalid | - | - | Displays the measured sensor's data validity. If the sensor reading has any problems, the sensor data is set to "Invalid" and the alarms are not activated. |
| S1...S16 Enable alarm 1 | <ul style="list-style-type: none"> Disable Enable | - | Disable | Enables/disables the selection of Alarm 1 for the measurement channel x. |
| S1...S16 Alarm1 >/< | <ul style="list-style-type: none"> > < | - | > | Selects whether the alarm activates when measurement is above or below the pick-up setting value. |
| S1...S16 Alarm1 | -101.0...2000.0deg | 0.1deg | 0.0deg | Sets the pick-up value for Alarm 1. The alarm is activated if the measurement goes above or below this setting mode (depends on the selected mode in "Sx Alarm1 >/<"). |

| Name | Range | Step | Default | Description |
|-------------------------|---|--------|---------|--|
| S1...S16 sensor | <ul style="list-style-type: none"> Ok Invalid | - | - | Displays the measured sensor's data validity. If the sensor reading has any problems, the sensor data is set to "Invalid" and the alarms are not activated. |
| S1...S16 Enable alarm 2 | <ul style="list-style-type: none"> Disable Enable | - | Disable | Enables/disables the selection of Alarm 2 for the measurement channel x. |
| S1...S16 Alarm2 >/< | <ul style="list-style-type: none"> > < | - | > | Selects whether the measurement is above or below the setting value. |
| S1...S16 Alarm2 | -101.0...2000.0deg | 0.1deg | 0.0deg | Sets the value for Alarm 2. The alarm is activated if the measurement goes above or below this setting mode (depends on the selected mode in "Sx Alarm2 >/<"). |

Function can be set to monitor the measurement data from previously set RTD channels. A single channel can be set to have several alarms if the user sets the channel to multiple sensor inputs. In each sensor setting the user can select the monitored module and channel, as well as the monitoring and alarm setting units (°C or °F). The alarms can be enabled, given a setting value (in degrees), and be set to trigger either above or below the setting value. There are sixteen (16) available sensor inputs in the function. An active alarm requires a valid channel measurement. It can be invalid if communication is not working or if a sensor is broken.

When the RTDs have been set, the values can be read to SCADA (or some other control system). The alarms can also be used for direct output control as well as in logics.

Events

The resistance temperature detector function (abbreviated "RTD" in event block names) generates events and registers from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

The function's outputs can be used for direct I/O controlling and user logic programming. The function also provides a resettable cumulative counter for the ALARM events.

The function offers sixteen (16) independent stages; the events are segregated for each stage operation.

Table. 4.4.9 - 84. Event messages.

| Event block name | Event names |
|------------------|-----------------------|
| RTD1 | S1...S16 Alarm1 ON |
| RTD1 | S1...S16 Alarm1 OFF |
| RTD1 | S1...S16 Alarm2 ON |
| RTD1 | S1...S16 Alarm2 OFF |
| RTD1 | S1...S16 Meas Ok |
| RTD1 | S1...S16 Meas Invalid |

4.4.10 Programmable stage (PSx>/<; 99)

The programmable stage is a stage that the user can program to create more advanced applications, either as an individual stage or together with programmable logic. The device has ten programmable stages, and each can be set to follow one to three analog measurements. The programmable stages have three available pick up terms options: overX, underX and rate-of-change of the selected signal. Each stage includes a definite time delay to trip after a pick-up has been triggered.

The programmable stage cycle time is 5 ms. The pick-up delay depends on which analog signal is used as well as its refresh rate (typically under a cycle in a 50 Hz system).

The number of programmable stages to be used is set in the *INFO* tab. When this function has been set as "Activated", the number of programmable stages can be set anywhere between one (1) and ten (10) depending on how many the application needs. In the image below, the number of programmable stages have been set to two which makes PS1 and PS2 to appear. Inactive stages are hidden until they are activated.

Please note that setting the number of available stages does not activate those stages, as they also need to be enabled individually with the *PSx >/< Enabled* parameter. When enabled an active stage shows its current state (condition), the expected operating time and the time remaining to trip under the activation parameters. If a stage is not active the *PSx >/< condition* parameter will merely display "Disabled".

Setting group selection controls the operating characteristics of the function, i.e. the user or user-defined logic can change function parameters while the function is running.

Analog values

The numerous analog signals have been divided into categories to help the user find the desired value.

Table. 4.4.10 - 85. Phase and residual current measurements (IL1, IL2, IL3, Io1 and Io2)

| Name | Description |
|-------------------------|---|
| ILx ff (p.u.) | Fundamental frequency RMS value (in p.u.) |
| ILx 2 nd h. | ILx 2 nd harmonic value (in p.u.) |
| ILx 3 rd h. | ILx 3 rd harmonic value (in p.u.) |
| ILx 4 th h. | ILx 4 th harmonic value (in p.u.) |
| ILx 5 th h. | ILx 5 th harmonic value (in p.u.) |
| ILx 7 th h. | ILx 7 th harmonic value (in p.u.) |
| ILx 9 th h. | ILx 9 th harmonic value (in p.u.) |
| ILx 11 th h. | ILx 11 th harmonic value (in p.u.) |
| ILx 13 th h. | ILx 13 th harmonic value (in p.u.) |
| ILx 15 th h. | ILx 15 th harmonic value (in p.u.) |
| ILx 17 th h. | ILx 17 th harmonic value (in p.u.) |

| Name | Description |
|-------------------------|---|
| ILx 19 th h. | ILx 19 nd harmonic value (in p.u.) |
| ILx TRMS | ILx TRMS value (in p.u.) |
| ILx Ang | ILx Angle (degrees) |

Table. 4.4.10 - 86. Other current measurements

| Name | Description |
|------------|---|
| I0Z Mag | Zero sequence current value (in p.u.) |
| I0CALC Mag | Calculated I0 value (in p.u.) |
| I1 Mag | Positive sequence current value (in p.u.) |
| I2 Mag | Negative sequence current value (in p.u.) |
| I0CALC Ang | Angle of calculated residual current (degrees) |
| I1 Ang | Angle of positive sequence current (degrees) |
| I2 Ang | Angle of negative sequence current (degrees) |
| I01ResP | I01 primary current of a current-resistive component |
| I01CapP | I01 primary current of a current-capacitive component |
| I01ResS | I01 secondary current of a current-resistive component |
| I01CapS | I01 secondary current of a current-capacitive component |
| I02ResP | I02 primary current of a current-resistive component |
| I02CapP | I02 primary current of a current-capacitive component |
| I02ResS | I02 secondary current of a current-resistive component |
| I02CapS | I02 secondary current of a current-capacitive component |

Table. 4.4.10 - 87. Voltage measurements

| Name | Description |
|---------|------------------------|
| UL12Mag | UL12 Primary voltage V |
| UL23Mag | UL23 Primary voltage V |
| UL31Mag | UL31 Primary voltage V |
| UL1Mag | UL1 Primary voltage V |
| UL2Mag | UL2 Primary voltage V |
| UL3Mag | UL3 Primary voltage V |
| UL12Ang | UL12 angle (degrees) |

| Name | Description |
|------------------|---|
| UL23Ang | UL23 angle (degrees) |
| UL31Ang | UL31 angle (degrees) |
| UL1Ang | UL1 angle (degrees) |
| UL2Ang | UL2 angle (degrees) |
| UL3Ang | UL3 angle (degrees) |
| U0Ang | UL0 angle (degrees) |
| U0CalcMag | Calculated residual voltage |
| U1 pos.seq.V Mag | Positive sequence voltage |
| U2 neg.seq.V Mag | Negative sequence voltage |
| U0CalcAng | Calculated residual voltage angle (degrees) |
| U1 pos.seq.V Ang | Positive sequence voltage angle (degrees) |
| U2 neg.seq.V Ang | Negative sequence voltage angle (degrees) |

Table. 4.4.10 - 88. Power measurements

| Name | Description |
|----------|---|
| S3PH | Three-phase apparent power S (kVA) |
| P3PH | Three-phase active power P (kW) |
| Q3PH | Three-phase reactive power Q (kvar) |
| tanfi3PH | Three-phase active power direction |
| cosfi3PH | Three-phase reactive power direction |
| SLx | Phase apparent power L1 / L2 / L3 S (kVA) |
| PLx | Phase active power L1 / L2 / L3 P (kW) |
| QLx | Phase reactive power L1 / L2 / L3 Q (kVar) |
| tanfiLx | Phase active power direction L1 / L2 / L3 |
| cosfiLx | Phase reactive power direction L1 / L2 / L3 |

Table. 4.4.10 - 89. Phase-to-phase and phase-to-neutral impedances, resistances and reactances

| Name | Description |
|--------|---|
| RLxPri | Resistance R L12, L23, L31, L1, L2, L3 primary (Ω) |
| XLxPri | Reactance X L12, L23, L31, L1, L2, L3 primary (Ω) |
| ZLxPri | Impedance Z L12, L23, L31, L1, L2, L3 primary (Ω) |

| Name | Description |
|----------|---|
| RLxSec | Resistance R L12, L23, L31, L1, L2, L3 secondary (Ω) |
| XLxSec | Reactance X L12, L23, L31, L1, L2, L3 secondary (Ω) |
| ZLxSec | Impedance Z L12, L23, L31, L1, L2, L3 secondary (Ω) |
| ZLxAngle | Impedance Z L12, L23, L31, L1, L2, L3 angle |

Table. 4.4.10 - 90. Other impedances, resistances and reactances

| Name | Description |
|-----------|--|
| RSeqPri | Positive Resistance R primary (Ω) |
| XSeqPri | Positive Reactance X primary (Ω) |
| RSeqSec | Positive Resistance R secondary (Ω) |
| XSeqSec | Positive Reactance X secondary (Ω) |
| ZSeqPri | Positive Impedance Z primary (Ω) |
| ZSeqSec | Positive Impedance Z secondary (Ω) |
| ZSeqAngle | Positive Impedance Z angle |

Table. 4.4.10 - 91. Conductances, susceptances and admittances (L1, L2, L3)

| Name | Description |
|-----------|---|
| GLxPri | Conductance G L1, L2, L3 primary (mS) |
| BLxPri | Susceptance B L1, L2, L3 primary (mS) |
| YLxPriMag | Admittance Y L1, L2, L3 primary (mS) |
| GLxSec | Conductance G L1, L2, L3 secondary (mS) |
| BLxSec | Susceptance B L1, L2, L3 secondary (mS) |
| YLxSecMag | Admittance Y L1, L2, L3 secondary (mS) |
| YLxAngle | Admittance Y L1, L2, L3 angle (degrees) |

Table. 4.4.10 - 92. Other conductances, susceptances and admittances

| Name | Description |
|-------|-------------------------------|
| G0Pri | Conductance G0 primary (mS) |
| B0Pri | Susceptance B0 primary (mS) |
| G0Sec | Conductance G0 secondary (mS) |
| B0Sec | Susceptance B0 secondary (mS) |

| Name | Description |
|---------|------------------------------|
| Y0Pri | Admittance Y0 primary (mS) |
| Y0Sec | Admittance Y0 secondary (mS) |
| Y0Angle | Admittance Y0 angle |

Table. 4.4.10 - 93. Other measurements

| Name | Description |
|--------------------|--|
| System f. | System frequency |
| Ref f1 | Reference frequency 1 |
| Ref f2 | Reference frequency 2 |
| M Thermal T | Motor thermal temperature |
| F Thermal T | Feeder thermal temperature |
| T Thermal T | Transformer thermal temperature |
| RTD meas 1...16 | RTD measurement channels 1...16 |
| Ext RTD meas 1...8 | External RTD measurement channels 1...8 (ADAM) |
| mA input 7,8,15,16 | mA input channels 7, 8, 15, 16 |
| ASC 1...4 | Analog scaled curves 1...4 |

Magnitude multiplier

Programmable stages can be set to follow one, two or three analog measurements with the *PSx >/< Measurement setting* parameter. The user must choose a measurement signal value to be compared to the set value, and possibly also set a scaling for the signal. The image below is an example of scaling: a primary zero sequence voltage has been scaled to a percentage value for easier handling when setting up the comparator.

The scaling factor was calculated by taking the inverse value of a 20 kV system:

$$k = \frac{1}{20\,000\text{ V}/\sqrt{3}} = 0.008\,66$$

When this multiplier is in use, the full earth fault zero sequence voltage is 11 547 V primary which is then multiplied with the above-calculated scaling factor, inverting the final result to 100%. This way a pre-processed signal is easier to set, although it is also possible to just use the scaling factor of 1.0 and set the desired pick-up limit as the primary voltage. Similarly, any chosen measurement value can be scaled to the desired form.

Read-only parameters

The function's *Info* page displays useful, real-time information on the state of the protection function. It is accessed either through the device's HMI display, or through the setting tool software when it is connected to the device and its Live Edit mode is active.

Table. 4.4.10 - 94. Information displayed by the function.

| Name | Range | Description |
|---|--|---|
| Condition | <ul style="list-style-type: none"> • Normal • Start • Trip • Blocked | Displays status of the function. |
| Expected operating time | -1800.000...1800.000s | Displays the expected operating time when a fault occurs. |
| Time remaining to trip | 0.000...1800.000s | When the function has detected a fault and counts down time towards a trip, this displays how much time is left before tripping occurs. |
| PSx Scaled magnitude X | -5 000 000...5 000 000 | Displays measurement value after multiplying it the value set to <i>PSx Magnitude multiplier</i> . |
| PSx >/< MeasMag1/ MagSet1 at the moment | -5 000 000...5 000 000 | The ratio between measured magnitude and the pick-up setting. |
| PSx >/< MeasMag2/ MagSet2 at the moment | -5 000 000...5 000 000 | The ratio between measured magnitude and the pick-up setting. |
| PSx >/< MeasMag3/ MagSet3 at the moment | -5 000 000...5 000 000 | The ratio between measured magnitude and the pick-up setting. |
| PSx >/< CalcMeasMag/ MagSet at the moment | -5 000 000...5 000 000 | The ratio between calculated magnitude and the pick-up setting. |

Pick-up settings

The *Pick-up setting Mag* setting parameter controls the pick-up of the PSx>/< function. This defines the maximum or minimum allowed measured magnitude before action from the function. The function constantly calculates the ratio between the set and the measured magnitudes. The user can set the reset hysteresis in the function (by default 3 %). It is always relative to the *Pick-up setting Mag* value.

Table. 4.4.10 - 95. Pick-up settings.

| Name | Range | Step | Default | Description |
|-----------------------|--|------|---------|---|
| PS# Pick-up term Mag# | <ul style="list-style-type: none"> • Over > • Over (abs) > • Under < • Under (abs) < • Delta set (%) +/- > • Delta abs (%) > • Delta +/- measval • Delta abs measval | - | Over | Comparator mode for the magnitude. See "Comparator modes" section below for more information. |

| Name | Range | Step | Default | Description |
|--------------------------------------|--|---------|---------|-----------------------|
| PS# Pick-up setting Mag#/calc >/< | -5 000 000.0000...5 000 000.0000 | 0.0001 | 0.01 | Pick-up magnitude |
| PS# Setting hysteresis Mag# | 0.0000...50.0000% | 0.0001% | 3% | Setting hysteresis |
| Definite operating time delay | 0.000...1800.000s | 0.005s | 0.04s | Delay setting |
| Release time delays | 0.000...1800.000s | 0.005s | 0.06s | Pick-up release delay |

Comparator modes

When setting the comparators, the user must first choose a comparator mode.

Table. 4.4.10 - 96. Comparator modes

| Mode | Description |
|---------------------|--|
| Over > | Greater than. If the measured signal is greater than the set pick-up level, the comparison condition is fulfilled. |
| Over (abs) > | Greater than (absolute). If the absolute value of the measured signal is greater than the set pick-up level, the comparison condition is fulfilled. |
| Under < | Less than. If the measured signal is less than the set pick-up level, the comparison condition is fulfilled. The user can also set a blocking limit: the comparison is not active when the measured value is less than the set blocking limit. |
| Under (abs) < | Less than (absolute). If the absolute value of the measured signal is less than the set pick-up level, the comparison condition is fulfilled. The user can also set a blocking limit: the comparison is not active when the measured value is less than the set blocking limit. |
| Delta set (%) +/- > | Relative change over time. If the measured signal changes more than the set relative pick-up value in 20 ms, the comparison condition is fulfilled. The condition is dependent on direction. |
| Delta abs (%) > | Relative change over time (absolute). If the measured signal changes more than the set relative pick-up value in 20 ms in either direction, the comparison condition is fulfilled. The condition is not dependent on direction. |
| Delta +/- measval | Change over time. If the measured signal changes more than the set pick-up value in 20 ms, the comparison condition is fulfilled. The condition is dependent on direction. |
| Delta abs measval | Change over time (absolute). If the measured signal changes more than the set pick-up value in 20 ms in either direction, the comparison condition is fulfilled. The condition is not dependent on direction. |

The pick-up level is set individually for each comparison. When setting up the pick-up level, the user needs to take into account the modes in use as well as the desired action. The pick-up limit can be set either as positive or as negative. Each pick-up level has a separate hysteresis setting which is 3 % by default.

The user can set the operating and releasing time delays for each stage.

Function blocking

The block signal is checked in the beginning of each program cycle. The blocking signal is received from the blocking matrix in the function's dedicated input. If the blocking signal is not activated when the pick-up element activates, a START signal is generated and the function proceeds to the time characteristics calculation.

If the blocking signal is active when the pick-up element activates, a BLOCKED signal is generated and the function does not process the situation further. If the START function has been activated before the blocking signal, it resets and the release time characteristics are processed similarly to when the pick-up signal is reset.

The variables the user can set are binary signals from the system. The blocking signal needs to reach the device minimum of 5 ms before the set operating delay has passed in order for the blocking to activate in time.

Events and registers

The programmable stage function (abbreviated "PSx" in event block names) generates events and registers from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

The function's outputs can be used for direct I/O controlling and user logic programming. The function also provides a resettable cumulative counter for the START, TRIP and BLOCKED events.

Table. 4.4.10 - 97. Event messages.

| Event block name | Event names |
|------------------|------------------------|
| PSx | PS1...10 >/< Start ON |
| PSx | PS1...10 >/< Start OFF |
| PSx | PS1...10 >/< Trip ON |
| PSx | PS1...10 >/< Trip OFF |
| PSx | PS1...10 >/< Block ON |
| PSx | PS1...10 >/< Block OFF |

The function registers its operation into the last twelve (12) time-stamped registers. The register of the function records the ON event process data for START, TRIP or BLOCKED. The table below presents the structure of the function's register content.

Table. 4.4.10 - 98. Register content.

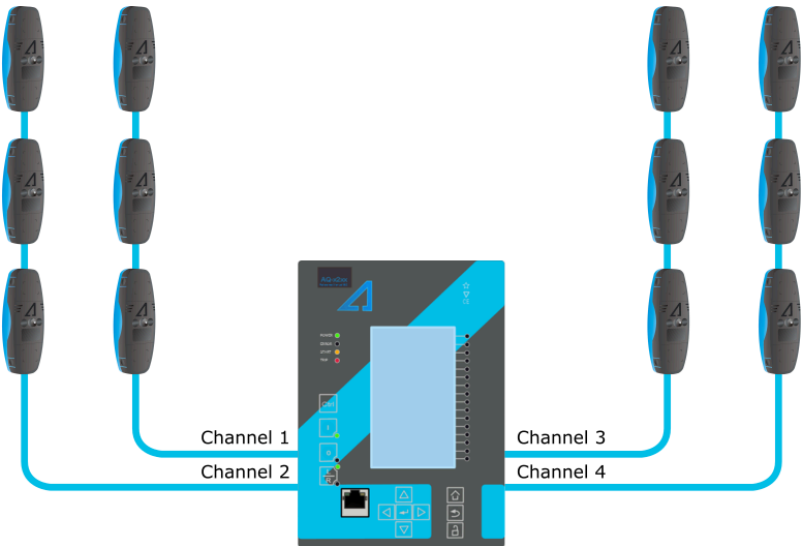
| Register | Description |
|---------------|--|
| Date and time | dd.mm.yyyy hh:mm:ss.mss |
| Event | Event name |
| >/< Mag# | The numerical value of the magnitude |
| Mag#/Set# | Ratio between the measured magnitude and the pick-up setting |

| Register | Description |
|----------------------|----------------------------|
| Trip time remaining | 0 ms...1800s |
| Setting group in use | Setting group 1...8 active |

4.4.11 Arc fault protection (IArc>/IOArc>; 50Arc/50NArc)

Arc faults occur for a multitude of reasons: e.g. insulation failure, incorrect operation of the protected device, corrosion, overvoltage, dirt, moisture, incorrect wiring, or even because of aging caused by electric load. It is important to detect the arc as fast as possible in order to minimize its effects. Using arc sensors to detect arc faults is much faster than merely measuring currents and voltages. In busbar protection devices with normal protection can be too slow to disconnect arcs within a safe time frame. For example, it may be necessary to delay operation time for hundreds of milliseconds when setting up an overcurrent protection relay to control the feeder breakers to achieve selectivity. This delay can be avoided by using arc protection. The arc protection card has a high-speed output to trip signals faster as well as to extend the speed of arc protection.

Figure. 4.4.11 - 114. Protection device equipped with arc protection.



The arc protection card has four (4) sensor channels, and up to three (3) arc point sensors can be connected to each channel. The sensor channels support Arcteq AQ-01 (light sensing) and AQ-02 (pressure and light sensing) units. Optionally, the protection function can also be applied with a phase current or a residual current condition: the function trips only if the light and overcurrent conditions are met.

Table. 4.4.11 - 99. Output signals of the IArc>/IOArc> function.

| Outputs | Activation condition |
|--|---|
| Channel 1 Light In Channel 2 Light In Channel 3 Light In Channel 4 Light In | The arc protection card's sensor channel detects light. |

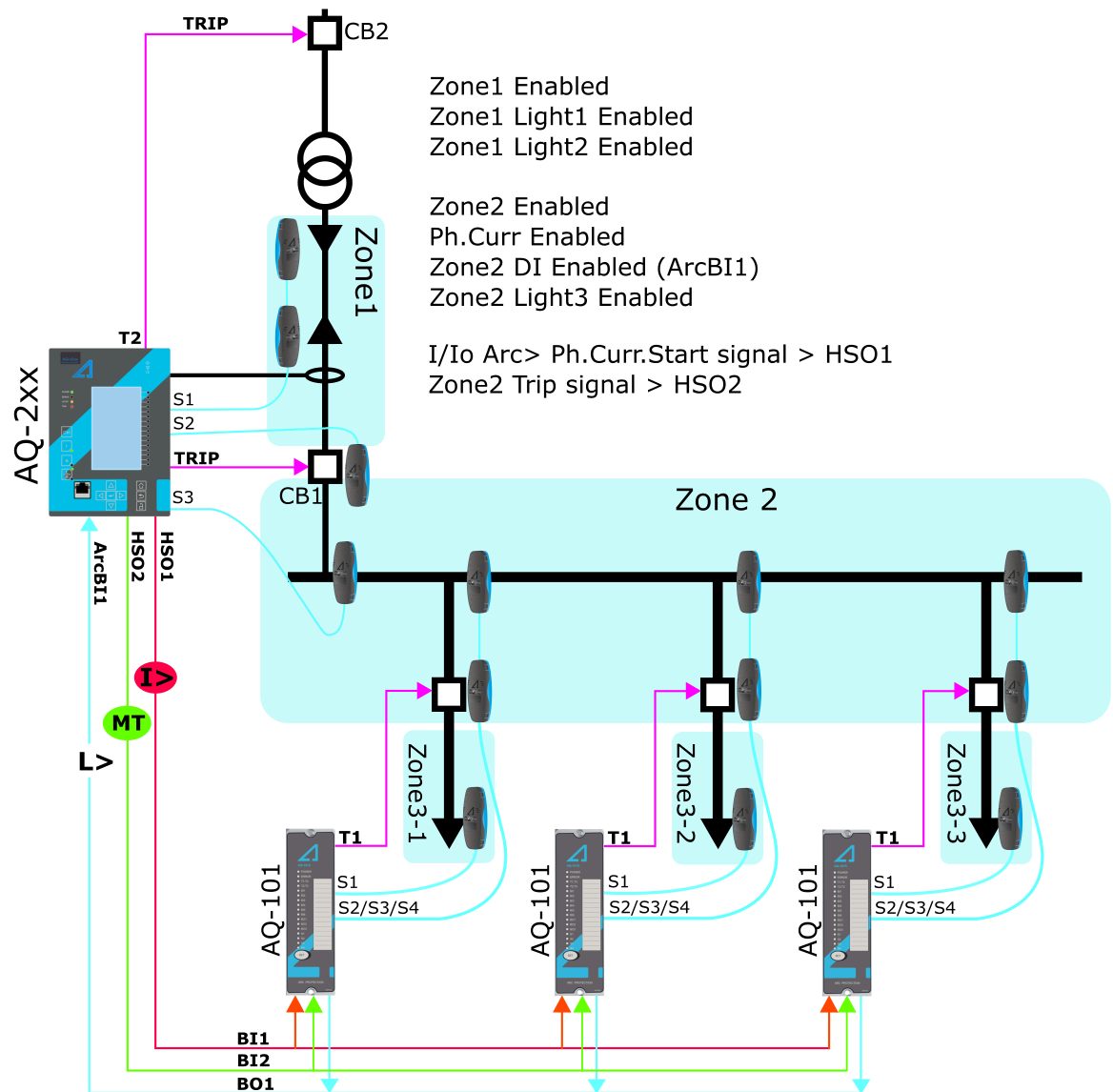
| Outputs | Activation condition |
|--|---|
| Channel 1 Pressure In Channel 2 Pressure In Channel 3 Pressure In Channel 4 Pressure In | The arc protection card's sensor channel detects pressure. |
| ARC Binary input signal | The arc protection card's binary input is energized. |
| I/O Arc> Ph. curr. START I/O Arc> Res. curr. START | The measured phase current or the residual current is over the set limit. |
| I/O Arc> Ph. curr. BLOCKED I/O Arc> Res. curr. BLOCKED | The phase current or the residual current measurement is blocked by an input. |
| I/O Arc> Zone 1 TRIP I/O Arc> Zone 2 TRIP I/O Arc> Zone 3 TRIP I/O Arc> Zone 4 TRIP | All required conditions for tripping the zone are met (light OR light and current). |
| I/O Arc> Zone 1 BLOCKED I/O Arc> Zone 2 BLOCKED I/O Arc> Zone 3 BLOCKED I/O Arc> Zone 4 BLOCKED | All required conditions for tripping the zone are met (light OR light and current) but the tripping is blocked by an input. |
| I/O Arc> S1 Sensor fault I/O Arc> S2 Sensor fault I/O Arc> S3 Sensor fault I/O Arc> S4 Sensor fault | The detected number of sensors in the channel does not match the settings. |
| I/O Arc> IO unit fault | The number of connected AQ-100 series units does not match the number of units set in the settings. |

Example of scheme setting

The following examples help the user better understand how the arc protection function is set. In the examples AQ-101 models are used to extend the protection of Zone 2 and to protect each outgoing feeder (Zone 3).

This scheme is a single-line diagram with AQ-200 series devices and with AQ-101 arc protection relays. The settings are for an incoming feeder AQ-200 device.

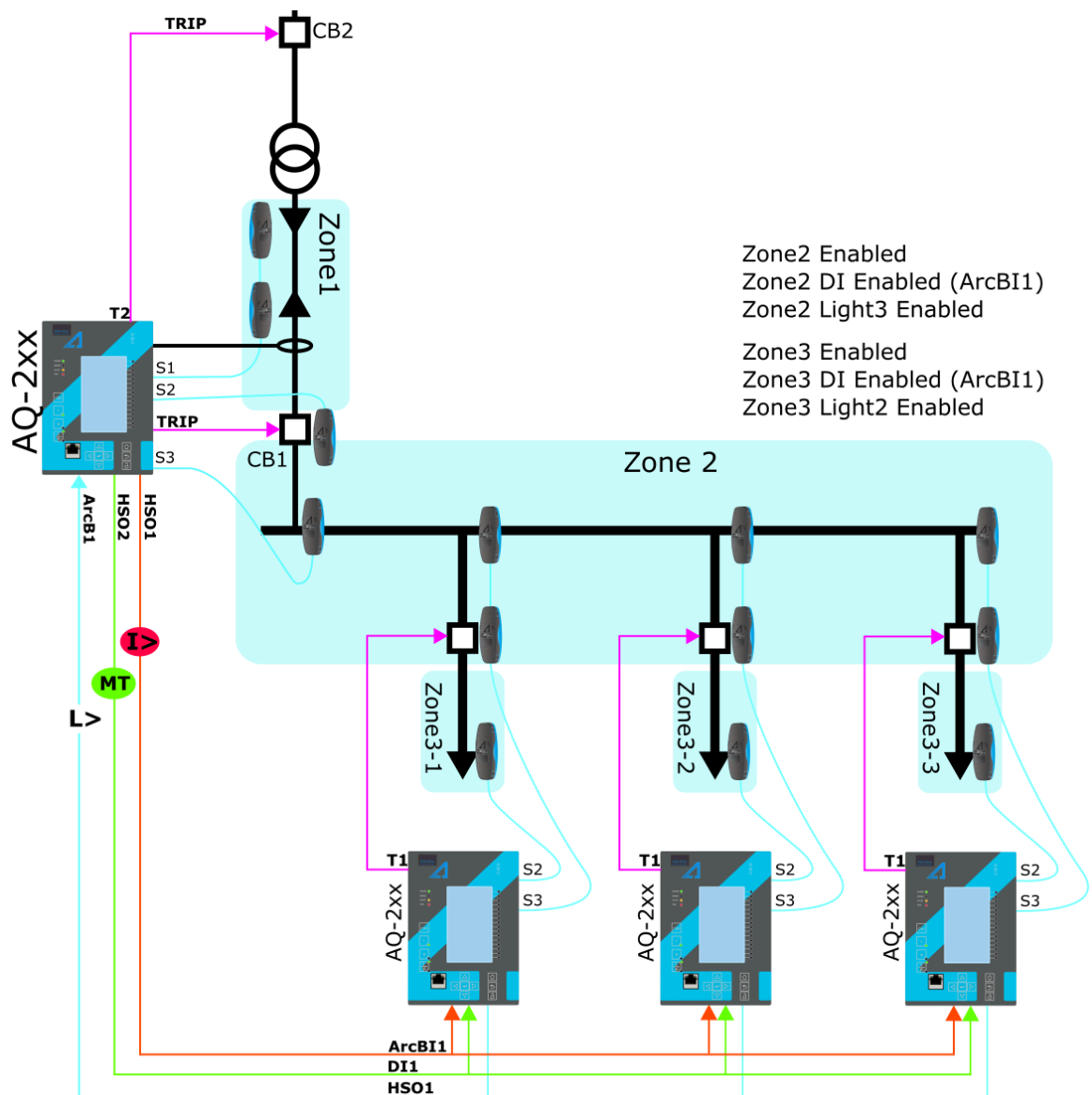
Figure. 4.4.11 - 115. Scheme with AQ-101 arc protection relays.



To set the zones for the AQ-200 models sensor channels start by enabling the protected zones (in this case, Zones 1 and 2). Then define which sensor channels are sensing which zones (in this case, sensor channels S1 and S2 are protecting Zone 1). Enable Light 1 of Zone 1 as well as Light 2 of Zone 2. The sensor channel S3 deals with Zone 2. Enable Light 3 of Zone 2. The high-speed output contacts HSO1 and HSO2 have been set to send overcurrent and master trip signals to the AQ-101 arc protection relays. The AQ-100 series units send out test pulses in specific intervals to check the health of the wiring between the AQ-100 series units. The parameter *I/Io Arc > Self supervision test pulse* should be activated when connecting the AQ-100 series units to the AQ-200 series arc protection card to prevent the pulses from activating ArcBI1.

The next example is almost like the previous one: it is also a single-line diagram with AQ 200 series devices. However, this time each outgoing feeder has an AQ-200 protection device instead of an AQ-101 arc protection relay.

Figure. 4.4.11 - 116. Scheme with AQ-200 protection devices.



The settings for the device supervising the incoming feeder are the same as in the first example. The devices supervising the busbar and the outgoing feeder, however, have a different setting. Both Zones 2 and 3 need to be enabled as there are sensors connected to both Zone 2 and 3 starts. Sensors connected to the channel S3 are in Zone 2. Then enable Light 3 of Zone 2. The sensor connected to the channel S2 is in Zone 3. Then enable Light 2 of Zone 3.

If any of the channels have a pressure sensing sensor, enable it the same way as the regular light sensors. If either phase overcurrent or residual overcurrent is needed for the tripping decision, they can be enabled in the same way as light sensors in the zone. When a current channel is enabled, the measured current needs to be above the set current limit in addition to light sensing.

Measured input

Arc protection uses samples based on current measurements. If the required number of samples is found to be above the setting limit, the current condition activates. The arc protection can use either phase currents, residual currents or both.

Table. 4.4.11 - 100. Measurement inputs of the U1/U2>/< function.

| Signal | Description | Time base |
|-------------------------|---|-----------|
| I _{L1} samples | Samples received by I _{L1} current measurement channel | 5ms |
| I _{L2} samples | Samples received by I _{L2} current measurement channel | 5ms |
| I _{L3} samples | Samples received by I _{L3} current measurement channel | 5ms |
| I ₀₁ samples | Samples received by I ₀₁ current measurement channel | 5ms |
| I ₀₂ samples | Samples received by I ₀₂ current measurement channel | 5ms |

General settings

The following general settings define the general behavior of the function. These settings are static i.e. it is not possible to change them by editing the setting group.

Table. 4.4.11 - 101. General settings of the function.

| Name | Range | Default | Description |
|--------------------------|---|------------|--|
| I/O Arc> force status to | <ul style="list-style-type: none"> Normal PH curr blocked PH curr Start ResCurr Blocked ResCurr Start Zone 1 Trip Zone1 Blocked Zone2 Trip Zone2 Blocked Zone3 Trip Zone3 Blocked Zone4 Trip Zone4 Blocked | Normal | Force the status of the function. Visible only when <i>Enable stage forcing</i> parameter is enabled in <i>General</i> menu. |
| Channel 1 sensors | <ul style="list-style-type: none"> No sensors 1 sensor 2 sensors 3 sensors | No sensors | Defines the number of sensors connected to the channel (channels 1/2/3/4). |
| Channel 2 sensors | | | |
| Channel 3 sensors | | | |
| Channel 4 sensors | | | |

| Name | Range | Default | Description |
|-------------------------|---|---------|--|
| Channel 1 sensor status | <ul style="list-style-type: none"> Sensors OK Configuration fault state | - | Displays the status of the sensor channel. If the number of sensors connected to the channel does not match with the set "Channel 1/2/3/4 sensors" setting, this parameter will go to the "Configuration fault" state. |
| Channel 2 sensor status | | | |
| Channel 3 sensor status | | | |
| Channel 4 sensor status | | | |

Pick-up settings

The pick-up of each zone of the `larc>/I0arc>` function is controlled by one of the following: the phase current pick-up setting, the residual current pick-up setting, or the sensor channels. The pick-up setting depends on which of these are activated in the zone.

Setting group selection controls the operating characteristics of the function, i.e. the user or user-defined logic can change function parameters while the function is running.

Table. 4.4.11 - 102. Enabled Zone pick-up settings.

| Name | Range | Step | Default | Description |
|--------------------------------|--|-------------------------|---------------------|--|
| Phase current pick-up | 0.05...40.00 $\times I_n$ | 0.01 $\times I_n$ | 1.2 $\times I_n$ | The phase current measurement's pick-up value (in p.u.). |
| I0 input selection | <ul style="list-style-type: none"> None I01 I02 | - | None | Selects the residual current channel (I01 or I02). |
| Res.current pick-up | 0.05...40.00 $\times I_{0n}$ | 0.01 $\times I_{0n}$ | 1.2 $\times I_{0n}$ | The residual current measurement's pick-up value (in p.u.). |
| Zone1/2/3/4 Enabled | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Enables the chosen zone. Up to 4 zones can be enabled. |
| Zone1/2/3/4 Ph. curr. Enabled | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | The phase overcurrent allows the zone to trip when light is detected. |
| Zone1/2/3/4 Res. curr. Enabled | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | The residual overcurrent allows the zone to trip when light is detected. |

| Name | Range | Step | Default | Description |
|------------------------------------|--|------|----------|--|
| Zone1/2/ 3/4 Light 1 Enabled | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Light detected in sensor channel 1 trips the zone. |
| Zone1/2/ 3/4 Light 2 Enabled | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Light detected in sensor channel 2 trips the zone. |
| Zone1/2/ 3/4 Light 3 Enabled | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Light detected in sensor channel 3 trips the zone. |
| Zone1/2/ 3/4 Light 4 Enabled | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Light detected in sensor channel 4 trips the zone. |
| Zone1/2/ 3/4 Pres. 1 Enabled | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Pressure detected in sensor channel 1 trips the zone. |
| Zone1/2/ 3/4 Pres. 2 Enabled | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Pressure detected in sensor channel 2 trips the zone. |
| Zone1/2/ 3/4 Pres. 3 Enabled | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Pressure detected in sensor channel 3 trips the zone. |
| Zone1/2/ 3/4 Pres. 4 Enabled | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Pressure detected in sensor channel 4 trips the zone. |
| Zone1/2/ 3/4 DI Enabled | <ul style="list-style-type: none"> Disabled Light In Current In | - | Disabled | Arc protection option card digital input function selection. "Light In" mode trips the zone when digital input is active. In "Current In" mode digital input must be active at the same time as any of the sensor channels for the zone to trip. |

Read-only parameters

The function's *Info* page displays useful, real-time information on the state of the protection function. It is accessed either through the device's HMI display, or through the setting tool software when it is connected to the device and its Live Edit mode is active.

Table. 4.4.11 - 103. Information displayed by the function.

| Name | Range | Description |
|--------------------|--|---|
| I/O Arc> condition | <ul style="list-style-type: none"> Z1 Trip Z1 Blocked Z2 Trip Z2 Blocked Z3 Trip Z3 Blocked Z4 Trip Z4 Blocked | Displays status of the protection function. |

| | | |
|---------------|---|---|
| Sensor status | <ul style="list-style-type: none"> • Ph Curr Blocked • Ph Curr Start • Res Curr Blocked • Res Curr Start • Channel1 Light • Channel1 Pressure • Channel2 Light • Channel2 Pressure • Channel3 Light • Channel3 Pressure • Channel4 Light • Channel4 Pressure • Digital input • I/O Arc> Sensor 1 Fault • I/O Arc> Sensor 2 Fault • I/O Arc> Sensor 3 Fault • I/O Arc> Sensor 4 Fault • I/O Arc> I/O-unit Fault | Displays the general status of sensors. |
|---------------|---|---|

Function blocking

The block signal is checked in the beginning of each program cycle. The blocking signal is received from the blocking matrix in the function's dedicated input. If the blocking signal is not activated when the pick-up element activates, a TRIP signal is generated.

If the blocking signal is active when the pick-up element activates, a BLOCKED signal is generated and the function does not process the situation further.

The variables the user can set are binary signals from the system. The blocking signal needs to reach the device minimum of 5 ms before the set operating delay has passed in order for the blocking to activate in time.

Events and registers

The arc fault protection function (abbreviated "ARC" in event block names) generates events and registers from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

The function's outputs can be used for direct I/O controlling and user logic programming. The function also provides a resettable cumulative counter for the events.

Table. 4.4.11 - 104. Event messages.

| Event block name | Event names |
|------------------|---------------------------|
| ARC1 | Zone 1...4 Trip ON |
| ARC1 | Zone 1...4 Trip OFF |
| ARC1 | Zone 1...4 Block ON |
| ARC1 | Zone 1...4 Block OFF |
| ARC1 | Phase current Blocked ON |
| ARC1 | Phase current Blocked OFF |
| ARC1 | Phase current Start ON |

| Event block name | Event names |
|------------------|---------------------------------|
| ARC1 | Phase current Start OFF |
| ARC1 | Residual current Blocked ON |
| ARC1 | Residual current Blocked OFF |
| ARC1 | Residual current Start ON |
| ARC1 | Residual current Start OFF |
| ARC1 | Channel 1...4 Light ON |
| ARC1 | Channel 1...4 Light OFF |
| ARC1 | Channel 1...4 Pressure ON |
| ARC1 | Channel 1...4 Pressure OFF |
| ARC1 | DI Signal ON |
| ARC1 | DI Signal OFF |
| ARC1 | I/O Arc> Sensor 1...4 Fault ON |
| ARC1 | I/O Arc> Sensor 1...4 Fault OFF |
| ARC1 | I/O Arc> I/O-unit Fault ON |
| ARC1 | I/O Arc> I/O-unit Fault OFF |

The function registers its operation into the last twelve (12) time-stamped registers. The table below presents the structure of the function's register content.

Table. 4.4.11 - 105. Register content.

| Register | Description |
|----------------------|----------------------------|
| Date and time | dd.mm.yyyy hh:mm:ss.mss |
| Event | Event name |
| Phase A current | Trip current |
| Phase B current | |
| Phase C current | |
| Residual current | |
| Active sensors | 1...4 |
| Setting group in use | Setting group 1...8 active |

4.5 Control functions

4.5.1 Common signals

Common signals function has all protection function start and trip signals internally connected to Common START and TRIP output signals. When any of the activated protection functions generate a START or a TRIP signal, Common signals function will also generate the same signal.

General settings

The following general settings define the general behavior of the function. These settings are static i.e. it is not possible to change them by editing the setting group.

Table. 4.5.1 - 106. General settings of the function.

| Name | Range | Default | Description |
|------------------------|---|---------|--|
| Common force status to | <ul style="list-style-type: none"> Normal Start Trip | Normal | Force the status of the function. Visible only when <i>Enable stage forcing</i> parameter is enabled in <i>General</i> menu. |

Common signals function has all START and TRIP signals of protection functions internally connected to Common START and TRIP output signals. But it is also possible to assign extra signals to activate Common START and TRIP.

Table. 4.5.1 - 107. Common signals extra inputs.

| Name | Description |
|-----------------|---|
| Common Start In | Assign extra signals to activate common START signal. Please note that all protection function START signals are already assigned internally to Common START. |
| Common Trip In | Assign extra signals to activate common TRIP signal. Please note that all protection function TRIP signals are already assigned internally to Common TRIP. |

Read-only parameters

The function's *Info* page displays useful, real-time information on the state of the protection function. It is accessed either through the device's HMI display, or through the setting tool software when it is connected to the device and its Live Edit mode is active.

Table. 4.5.1 - 108. Information displayed by the function.

| Name | Range | Description |
|--------------------------|---|----------------------------------|
| Common signals condition | <ul style="list-style-type: none"> Normal Start Trip | Displays status of the function. |

Function blocking

Common signals function itself doesn't have blocking input signals. Blocking of tripping should be done in each protection function settings.

Events

The common signals function (abbreviated "GNSIG" in event block names) generates events from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both.

The function's outputs can be used for direct I/O controlling and user logic programming. The function also provides a resettable cumulative counter for the START and TRIP events.

The events triggered by the function are recorded with a time stamp.

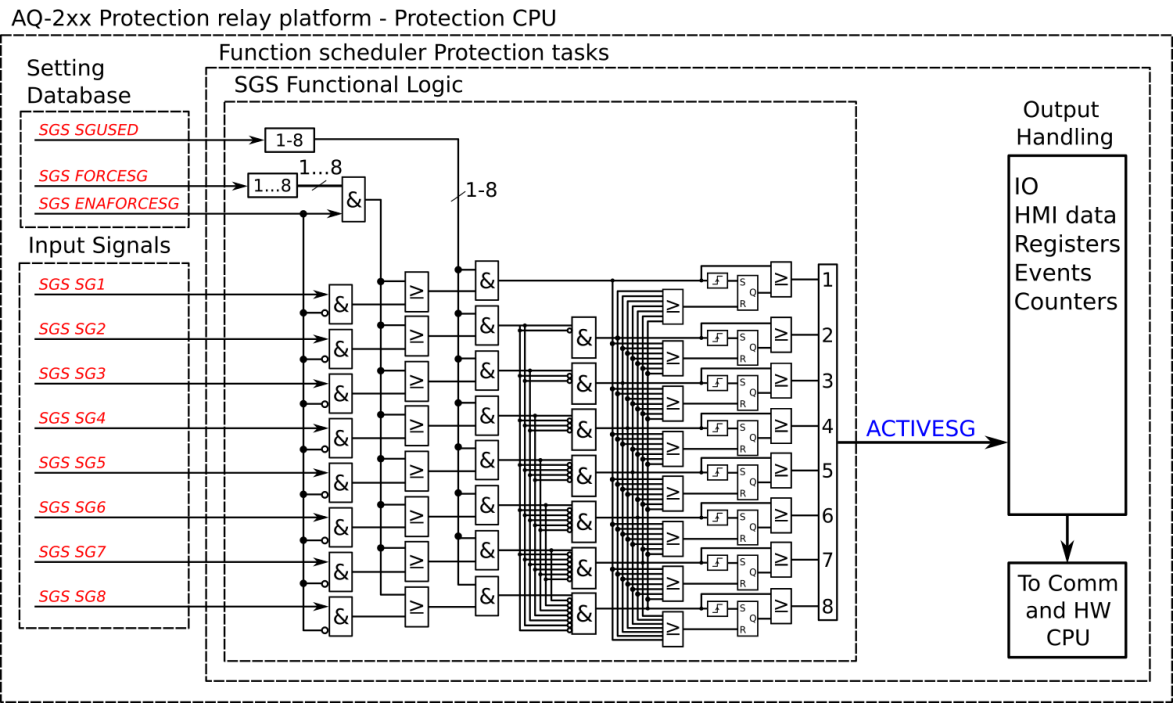
Table. 4.5.1 - 109. Event messages.

| Event block name | Event names |
|------------------|------------------|
| GNSIG | Common Start ON |
| GNSIG | Common Start OFF |
| GNSIG | Common Trip ON |
| GNSIG | Common Trip OFF |

4.5.2 Setting group selection

All device types support up to eight (8) separate setting groups. The Setting group selection function block controls the availability and selection of the setting groups. By default, only Setting group 1 (SG1) is active and therefore the selection logic is idle. When more than one setting group is enabled, the setting group selector logic takes control of the setting group activations based on the logic and conditions the user has programmed.

Figure. 4.5.2 - 117. Simplified function block diagram of the setting group selection function.

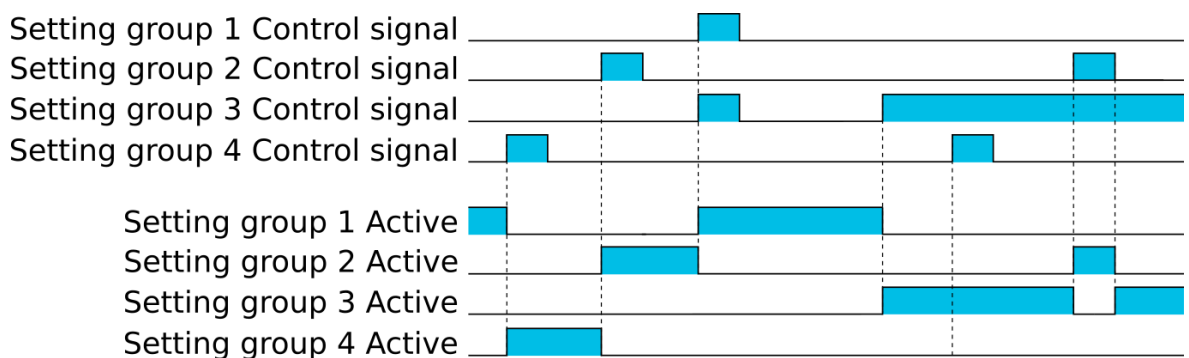


Setting group selection can be applied to each of the setting groups individually by activating one of the various internal logic inputs and connected digital inputs. The user can also force any of the setting groups on when the "Force SG change" setting is enabled by giving the wanted quantity of setting groups as a number in the communication bus or in the local HMI, or by selecting the wanted setting group from *Control* → *Setting groups*. When the forcing parameter is enabled, the automatic control of the local device is overridden and the full control of the setting groups is given to the user until the "Force SG change" is disabled again.

Setting groups can be controlled either by pulses or by signal levels. The setting group controller block gives setting groups priority values for situations when more than one setting group is controlled at the same time: the request from a higher-priority setting group is taken into use.

Setting groups follow a hierarchy in which setting group 1 has the highest priority, setting group 2 has second highest priority etc. If a static activation signal is given for two setting groups, the setting group with higher priority will be active. If setting groups are controlled by pulses, the setting group activated by pulse will stay active until another setting groups receives an activation signal.

Figure. 4.5.2 - 118. Example sequences of group changing (control with pulse only, or with both pulses and static signals).



Settings and signals

The settings of the setting group control function include the active setting group selection, the forced setting group selection, the enabling (or disabling) of the forced change, the selection of the number of active setting groups in the application, as well as the selection of the setting group changed remotely. If the setting group is forced to change, the corresponding setting group must be enabled and the force change must be enabled. Then, the setting group can be set from communications or from HMI to any available group. If the setting group control is applied with static signals right after the "Force SG" parameter is released, the application takes control of the setting group selection.

Table. 4.5.2 - 110. Settings of the setting group selection function.

| Name | Range | Default | Description |
|----------------------|--|---------|---|
| Active setting group | <ul style="list-style-type: none"> • SG1 • SG2 • SG3 • SG4 • SG5 • SG6 • SG7 • SG8 | SG1 | Displays which setting group is active. |

| Name | Range | Default | Description |
|-----------------------------|--|----------|---|
| Force setting group | <ul style="list-style-type: none"> None SG1 SG2 SG3 SG4 SG5 SG6 SG7 SG8 | None | The selection of the overriding setting group. After "Force SG change" is enabled, any of the configured setting groups in the device can be overridden. This control is always based on the pulse operating mode. It also requires that the selected setting group is specifically controlled to ON after "Force SG" is disabled. If there are no other controls, the last set setting group remains active. |
| Force setting group change | <ul style="list-style-type: none"> Disabled Enabled | Disabled | The selection of whether the setting group forcing is enabled or disabled. This setting has to be active before the setting group can be changed remotely or from a local HMI. This parameter overrides the local control of the setting groups and it remains on until the user disables it. |
| Used setting groups | <ul style="list-style-type: none"> SG1 SG1...2 SG1...3 SG1...4 SG1...5 SG1...6 SG1...7 SG1...8 | SG1 | The selection of the activated setting groups in the application. Newly-enabled setting groups use default parameter values. |
| Remote setting group change | <ul style="list-style-type: none"> None SG1 SG2 SG3 SG4 SG5 SG6 SG7 SG8 | None | This parameter can be controlled through SCADA to change the setting group remotely. Please note that if a higher priority setting group is being controlled by a signal, a lower priority setting group cannot be activated with this parameter. |

Table. 4.5.2 - 111. Signals of the setting group selection function.

| Name | Description |
|-----------------|--|
| Setting group 1 | The selection of Setting group 1 ("SG1"). Has the highest priority input in setting group control. Can be controlled with pulses or static signals. If static signal control is applied, no other SG requests will be processed. |
| Setting group 2 | The selection of Setting group 2 ("SG2"). Has the second highest priority input in setting group control. Can be controlled with pulses or static signals. If static signal control is applied, no requests with a lower priority than SG1 will be processed. |
| Setting group 3 | The selection of Setting group 3 ("SG3"). Has the third highest priority input in setting group control. Can be controlled with pulses or static signals. If static signal control is applied, no requests with a lower priority than SG1 and SG2 will be processed. |
| Setting group 4 | The selection of Setting group 4 ("SG4"). Has the fourth highest priority input in setting group control. Can be controlled with pulses or static signals. If static signal control is applied, no requests with a lower priority than SG1, SG2 and SG3 will be processed. |
| Setting group 5 | The selection of Setting group 5 ("SG5"). Has the fourth lowest priority input in setting group control. Can be controlled with pulses or static signals. If static signal control is applied, SG6, SG7 and SG8 requests will not be processed. |

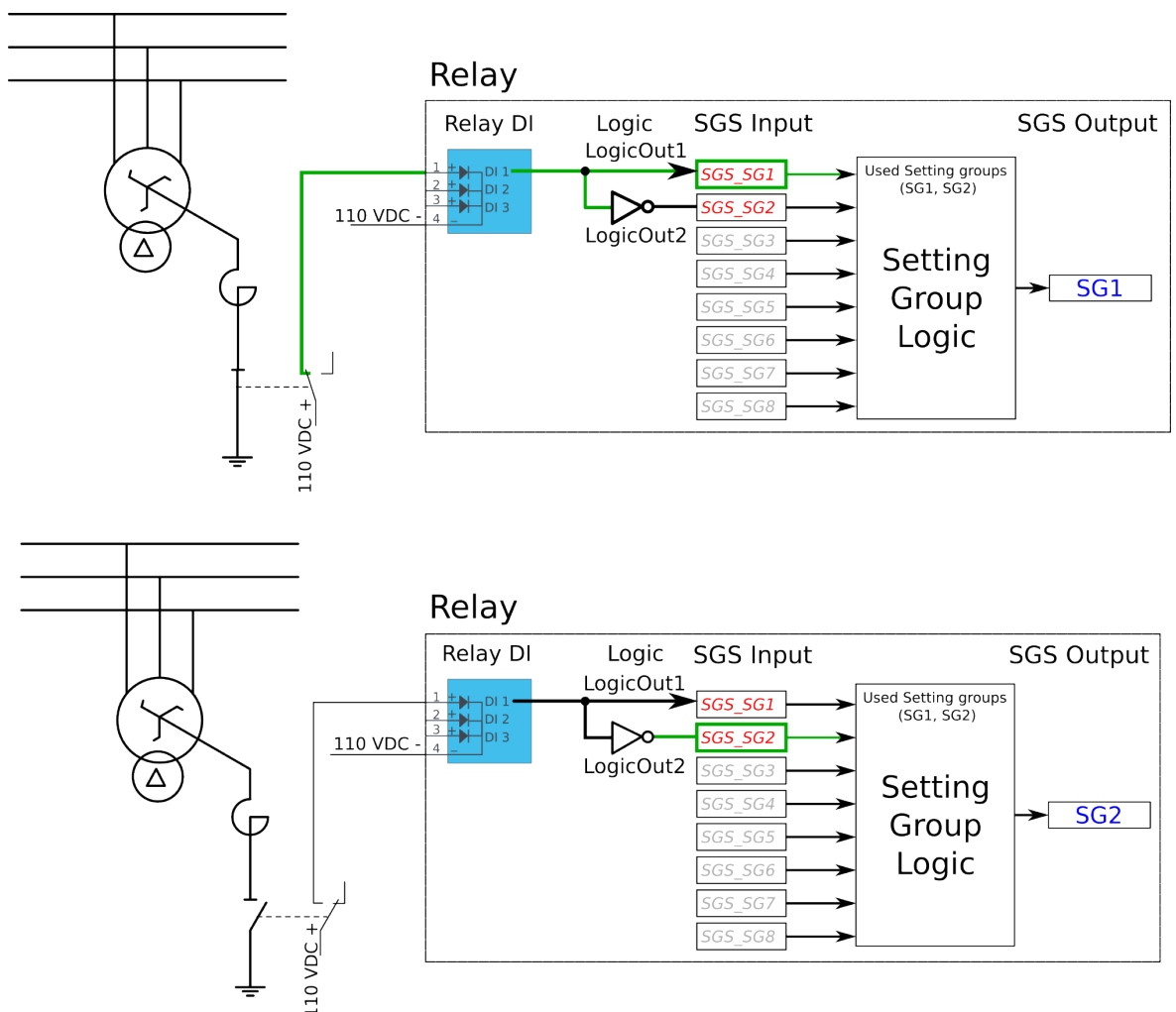
| Name | Description |
|-----------------|--|
| Setting group 6 | The selection of Setting group 6 ("SG6"). Has the third lowest priority input in setting group control. Can be controlled with pulses or static signals. If static signal control is applied, SG7 and SG8 requests will not be processed. |
| Setting group 7 | The selection of Setting group 7 ("SG7"). Has the second lowest priority input in setting group control. Can be controlled with pulses or static signals. If static signal control is applied, only SG8 requests will not be processed. |
| Setting group 8 | The selection of Setting group 8 ("SG8"). Has the lowest priority input in setting group control. Can be controlled with pulses or static signals. If static signal control is applied, all other SG requests will be processed regardless of the signal status of this setting group. |

Example applications for setting group control

This chapter presents some of the most common applications for setting group changing requirements.

A Petersen coil compensated network usually uses directional sensitive earth fault protection. The user needs to control its characteristics between varmetric and wattmetric; the selection is based on whether the Petersen coil is connected when the network is compensated, or whether it is open when the network is unearthed.

Figure. 4.5.2 - 119. Setting group control – one-wire connection from Petersen coil status.



Depending on the application's requirements, the setting group control can be applied either with a one-wire connection or with a two-wire connection by monitoring the state of the Petersen coil connection.

When the connection is done with one wire, the setting group change logic can be applied as shown in the figure above. The status of the Petersen coil controls whether Setting group 1 is active. If the coil is disconnected, Setting group 2 is active. This way, if the wire is broken for some reason, the setting group is always controlled to SG2.

Figure. 4.5.2 - 120. Setting group control – two-wire connection from Petersen coil status.

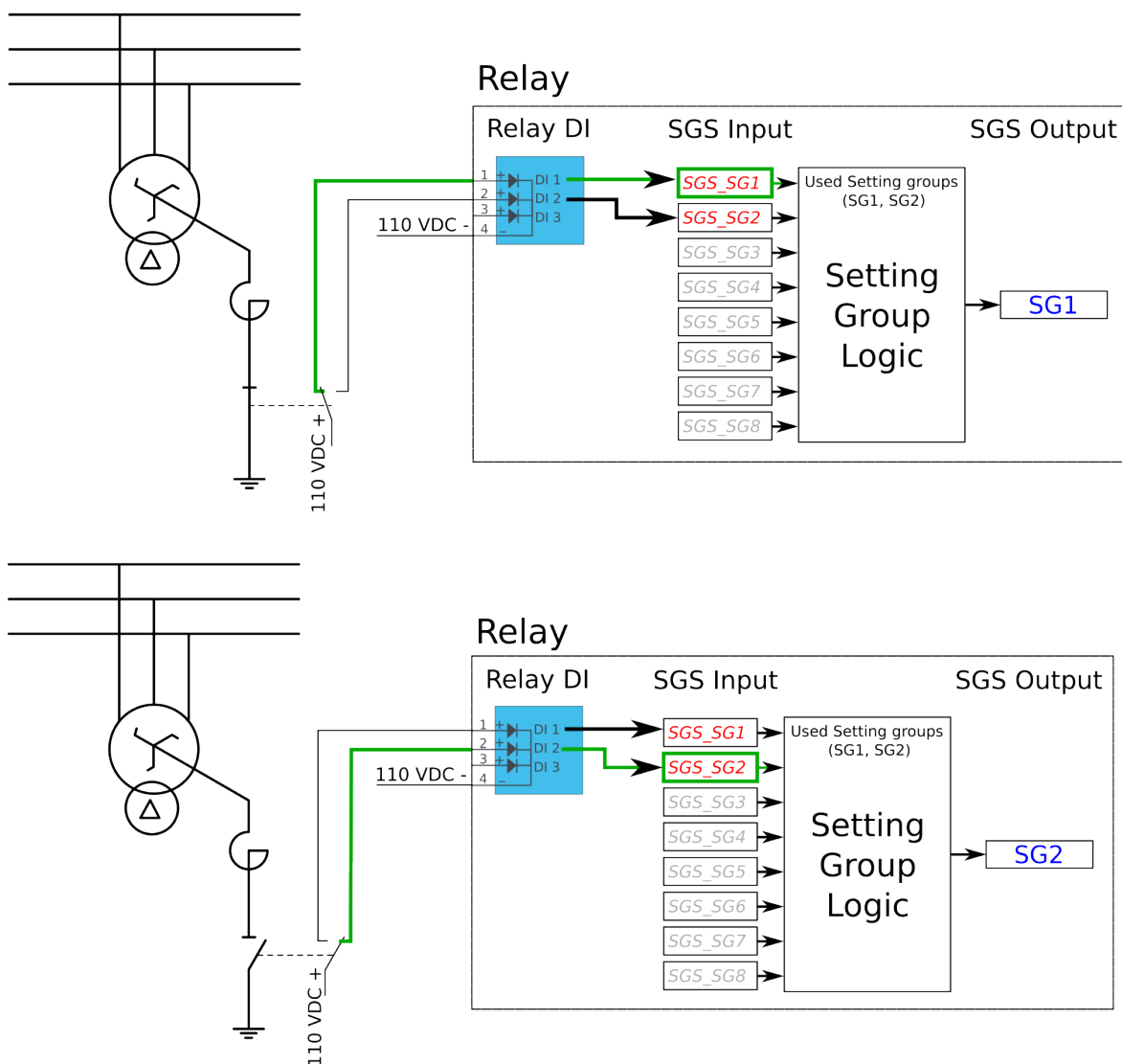
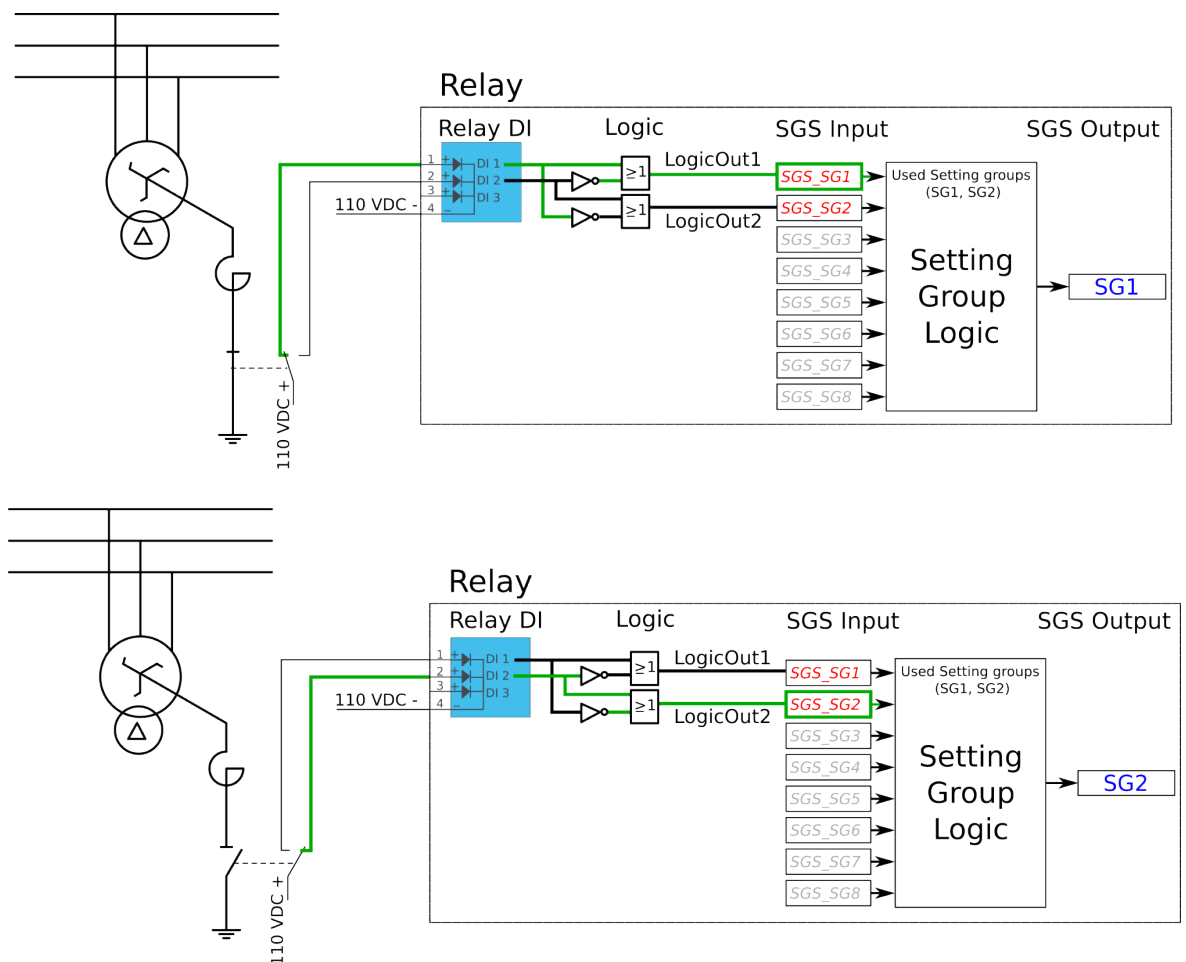


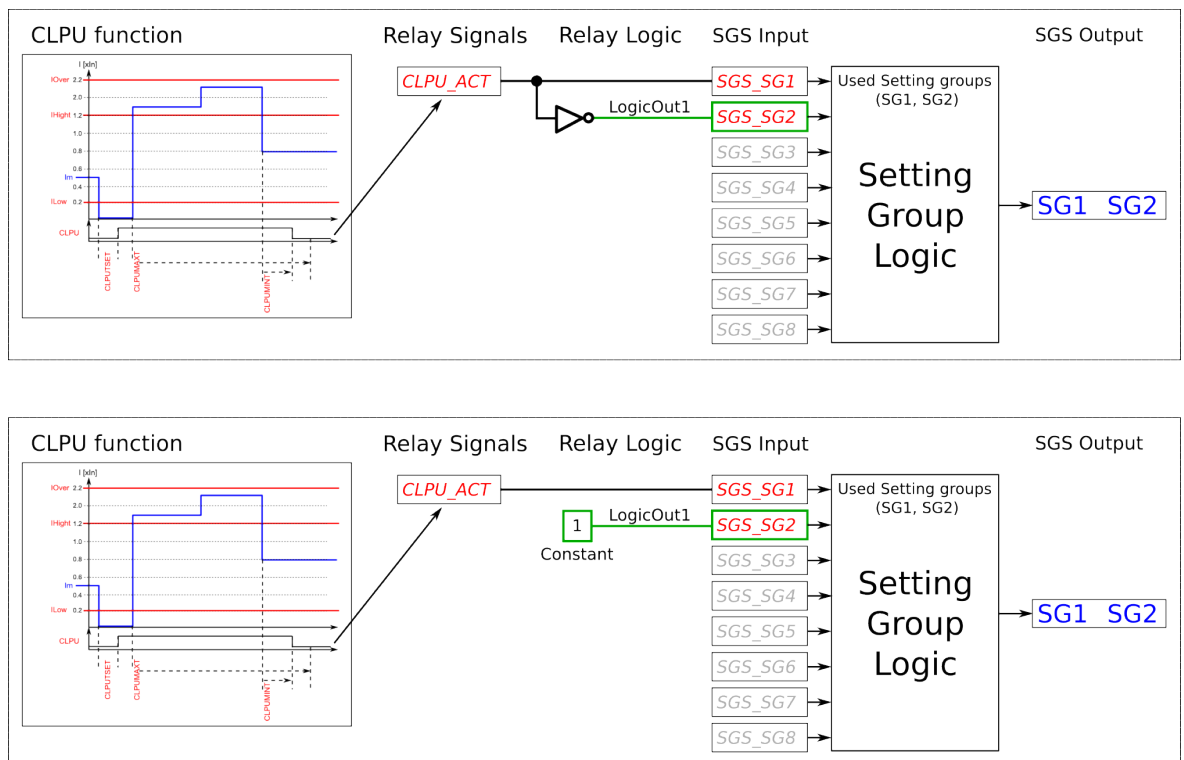
Figure. 4.5.2 - 121. Setting group control – two-wire connection from Petersen coil status with additional logic.



The images above depict a two-wire connection from the Petersen coil: the two images at the top show a direct connection, while the two images on the bottom include additional logic. With a two-wire connection the state of the Petersen coil can be monitored more securely. The additional logic ensures that a single wire loss will not affect the correct setting group selection.

The application-controlled setting group change can also be applied entirely from the device's internal logics. For example, the setting group change can be based on the cold load pick-up function (see the image below).

Figure. 4.5.2 - 122. Entirely application-controlled setting group change with the cold load pick-up function.



In these examples the cold load pick-up function's output is used for the automatic setting group change. Similarly to this application, any combination of the signals available in the device's database can be programmed to be used in the setting group selection logic.

As all these examples show, setting group selection with application control has to be built fully before they can be used for setting group control. The setting group does not change back to SG1 unless it is controlled back to SG1 by this application; this explains the inverted signal NOT as well as the use of logics in setting group control. One could also have SG2 be the primary SG, while the ON signal would be controlled by the higher priority SG1; this way the setting group would automatically return to SG2 after the automatic control is over.

Events

The setting group selection function block (abbreviated "SGS" in event block names) generates events from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

Table. 4.5.2 - 112. Event messages.

| Event block name | Event names |
|------------------|-----------------------------|
| SGS | SG2...8 Enabled |
| SGS | SG2...8 Disabled |
| SGS | SG1...8 Request ON |
| SGS | SG1...8 Request OFF |
| SGS | Remote Change SG Request ON |

| Event block name | Event names |
|------------------|---|
| SGS | Remote Change SG Request OFF |
| SGS | Local Change SG Request ON |
| SGS | Local Change SG Request OFF |
| SGS | Force Change SG ON |
| SGS | Force Change SG OFF |
| SGS | SG Request Fail Not configured SG ON |
| SGS | SG Request Fail Not configured SG OFF |
| SGS | Force Request Fail Force ON |
| SGS | Force Request Fail Force OFF |
| SGS | SG Req. Fail Lower priority Request ON |
| SGS | SG Req. Fail Lower priority Request OFF |
| SGS | SG1...8 Active ON |
| SGS | SG1...8 Active OFF |

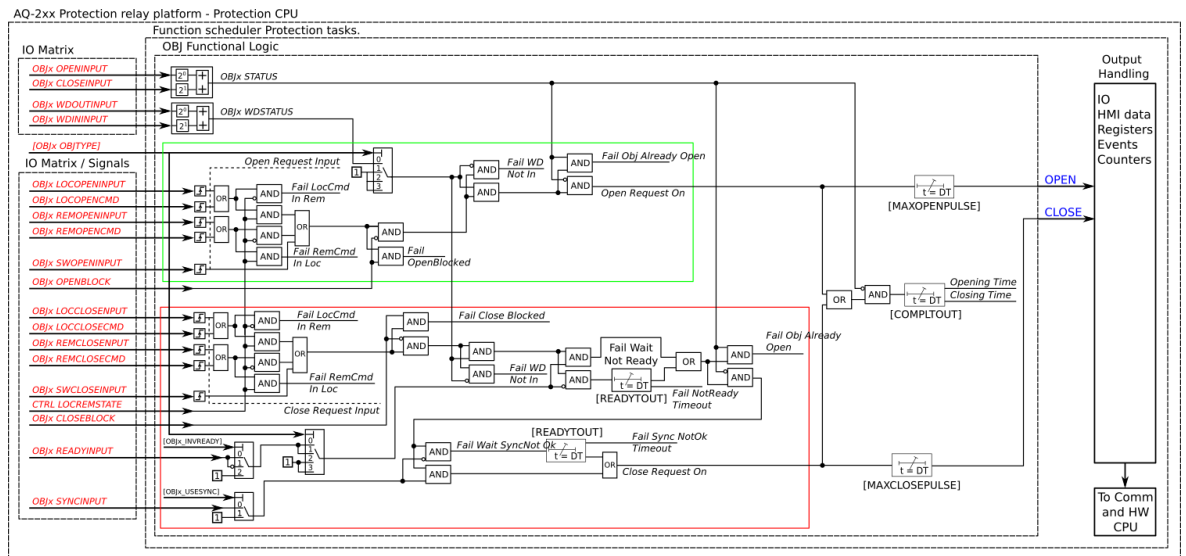
4.5.3 Object control and monitoring

The object control and monitoring function takes care of both for circuit breakers and disconnectors. The monitoring and controlling are based on the statuses of the device's configured digital inputs and outputs. The number of controllable and monitored objects in each device depends on the device type and amount of digital inputs. One controllable object requires a minimum of two (2) output contacts. The status monitoring of one monitored object usually requires two (2) digital inputs. Alternatively, object status monitoring can be performed with a single digital input: the input's active state and its zero state (switched to 1 with a NOT gate in the Logic editor).

An object can be controlled manually or automatically. Manual control can be done by local control, or by remote control. Local manual control can be done by devices front panel (HMI) or by external push buttons connected to devices digital inputs. Manual remote control can be done through one of the various communication protocols available (Modbus, IEC101/103/104 etc.). The function supports the modes "Direct control" and "Select before execute" while controlled remotely. Automatic controlling can be done with functions like auto-reclosing function (ANSI 79).

The main outputs of the function are the OBJECT OPEN and OBJECT CLOSE control signals. Additionally, the function reports the monitored object's status and applied operations. The setting parameters are static inputs for the function, which can only be changed by the user in the function's setup phase.

Figure. 4.5.3 - 123. Simplified function block diagram of the object control and monitoring function.



Settings

The following parameters help the user to define the object. The operation of the function varies based on these settings and the selected object type. The selected object type determines how much control is needed and which setting parameters are required to meet those needs.

Table. 4.5.3 - 113. Object settings and status parameters.

| Name | Range | Default | Description |
|------------------------|--|---------|--|
| Local/Remote status | <ul style="list-style-type: none"> Local Remote | Remote | Displays the status of the device's "local/remote" switch. Local controls cannot override the open and close commands while device is in "Remote" status. The remote controls cannot override the open and close commands while device is in "Local" status. |
| Object status force to | <ul style="list-style-type: none"> Normal Openreq On Closereq On Opensignal On Closesignal On WaitNoRdy On WaitNoSnc On NotrdyFail On NosyncFail On Opentout On Clotout On OpenreqUSR On CloreqUSR On | Normal | Force the status of the function. Visible only when <i>Enable stage forcing</i> parameter is enabled in <i>General</i> menu. |
| Object name | - | Objectx | The user-set name of the object, at maximum 32 characters long. |

| Name | Range | Default | Description |
|-------------------------------|--|-----------------|--|
| Object type | <ul style="list-style-type: none"> • Withdrawable circuit breaker • Circuit breaker • Disconnecter (MC) • Disconnecter (GND) | Circuit breaker | The selection of the object type. This selection defines the number of required digital inputs for the monitored object. This affects the symbol displayed in the HMI and the monitoring of the circuit breaker. It also affects whether the withdrawable cart is in/out status is monitored. See the next table ("Object types") for a more detailed look at which functionalities each of the object types have. |
| Objectx Breaker status | <ul style="list-style-type: none"> • Intermediate • Open • Closed • Bad | - | Displays the status of breaker. Intermediate is displayed when neither of the status signals (open or close) are active. Bad status is displayed when both status signals (open and close) are active. |
| Objectx Withdraw status | <ul style="list-style-type: none"> • WDIntermediate • WDCartOut • WDCart In • WDBad • Not in use | - | Displays the status of circuit breaker cart. WDIntermediate is displayed when neither of the status signals (in or out) are active. WDBad status is displayed when both status signals (in and out) are active. If the selected object type is not set to "Withdrawable circuit breaker", this setting displays the "No in use" option. |
| Additional status information | <ul style="list-style-type: none"> • Open Blocked • Open Allowed • Close Blocked • Close Allowed • Object Ready • Object Not Ready • Sync Ok • Sync Not Ok | - | Displays additional information about the status of the object. |
| Use Synchrocheck | <ul style="list-style-type: none"> • Not in use • Synchrocheck in use | Not in use | Selects whether the "Synchrocheck" condition is in use for the circuit breaker close command. If "In use" is selected the input chosen to "Sync.check status in" has to be active to be able to close circuit breaker. Synchrocheck status can be either an internal signal generated by synchrocheck function or digital input activation with an external synchrocheck device. |
| Use Object ready | <ul style="list-style-type: none"> • Ready High • Ready Low • Not in use | Not in use | Selects whether the "Object ready" condition is in use for the circuit breaker close command. If in use the signal connected to "Object ready status In" has to be high or low to be able to close the breaker (depending on "Ready High or Low" selection). |
| Open requests | $0 \dots 2^{32} - 1$ | - | Displays the number of successful "Open" requests. |
| Close requests | $0 \dots 2^{32} - 1$ | - | Displays the number of successful "Close" requests. |
| Open requests failed | $0 \dots 2^{32} - 1$ | - | Displays the number of failed "Open" requests. |
| Close requests failed | $0 \dots 2^{32} - 1$ | - | Displays the number of failed "Close" requests. |
| Clear statistics | <ul style="list-style-type: none"> • - • Clear | - | Clears the request statistics, setting them back to zero (0). Automatically returns to "-" after the clearing is finished. |

Table. 4.5.3 - 114. Object types.

| Name | Functionalities | Description |
|------------------------------|---|--|
| Withdrawable circuit breaker | Breaker cart position Circuit breaker position Circuit breaker control Object ready check before closing breaker Synchrochecking before closing breaker Interlocks | The monitor and control configuration of the withdrawable circuit breaker. |
| Circuit breaker | Position indication Control Object ready check before closing breaker Synchrochecking before closing breaker Interlocks | The monitor and control configuration of the circuit breaker. |
| Disconnecter (MC) | Position indication Control | The position monitoring and control of the disconnector. |
| Disconnecter (GND) | Position indication | The position indication of the earth switch. |

Table. 4.5.3 - 115. I/O.

| Signal | Range | Description |
|--|--|--|
| Objectx Open input ("Objectx Open Status In") | Digital input or other logical signal selected by the user (SWx) | A link to a physical digital input. The monitored object's OPEN status. "1" refers to the active open state of the monitored object. |
| Objectx Close input ("Objectx Close Status In") | | A link to a physical digital input. The monitored object's CLOSE status. "1" refers to the active close state of the monitored object. |
| WD Object In ("Withdrw.CartIn.Status In") | | A link to a physical digital input. The monitored withdrawable object's position is IN. "1" means that the withdrawable object cart is in. |
| WD Object Out ("Withdrw.CartOut.Status In") | | A link to a physical digital input. The monitored withdrawable object's position is OUT. "1" means that the withdrawable object cart is pulled out. |
| Object Ready (Objectx Ready status In") | | A link to a physical digital input. Indicates that status of the monitored object. "1" means that the object is ready and the spring is charged for a close command. |
| Synchrocheck permission ("Sync.Check status In") | | A link to a physical digital input or a synchrocheck function. "1" means that the synchrocheck conditions are met and the object can be closed. |
| Objectx Open command ("Objectx Open Command") | OUT1...OUTx | The physical "Open" command pulse to the device's output relay. |
| Objectx Close command ("Objectx Close Command") | | The physical "Close" command pulse to the device's output relay. |

Table. 4.5.3 - 116. Operation settings.

| Name | Range | Step | Default | Description |
|------------------------------------|-----------------|--------|---------|--|
| Breaker traverse time | 0.02...500.00 s | 0.02 s | 0.2 s | Determines the maximum time between open and close statuses when the breaker switches. If this set time is exceeded and both open and closed status inputs are active, the status "Bad" is activated in the "Objectx Breaker status" setting. If neither of the status inputs are active after this delay, the status "Intermediate" is activated. |
| Maximum Close command pulse length | 0.02...500.00 s | 0.02 s | 0.2 s | Determines the maximum length for a Close pulse from the output relay to the controlled object. If the object operates faster than this set time, the control pulse is reset and a status change is detected. |
| Maximum Open command pulse length | 0.02...500.00 s | 0.02 s | 0.2 s | Determines the maximum length for a Open pulse from the output relay to the controlled object. If the object operates faster than this set time, the control pulse is reset and a status change is detected. |
| Control termination timeout | 0.02...500.00 s | 0.02 s | 10 s | Determines the control pulse termination timeout. If the object has not changed its status in this given time the function will issue error event and the control is ended. This parameter is common for both open and close commands. |
| Final trip pulse length | 0.00...500.00 s | 0.02 s | 0.2 s | Determines the length of the final trip pulse length. When the object has executed the final trip, this signal activates. If set to 0 s, the signal is continuous. If auto-recloser function controls the object, "final trip" signal is activated only when there are no automatic reclosings expected after opening the breaker. |

Table. 4.5.3 - 117. Control settings (DI and Application).

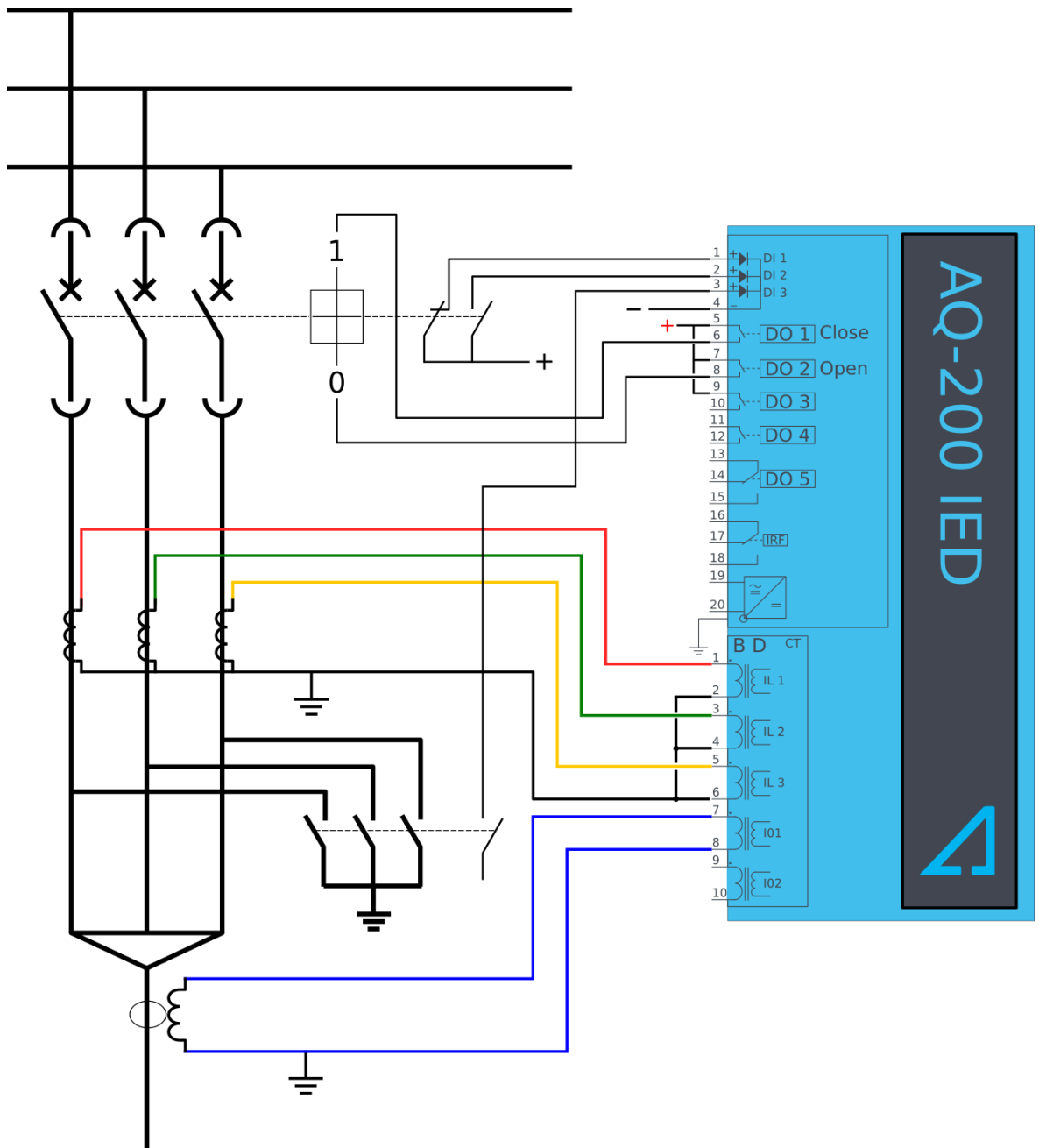
| Signal | Range | Description |
|------------------------------------|--|--|
| Access level for MIMIC control | <ul style="list-style-type: none"> User Operator Configurator Super user | Defines what level of access is required for MIMIC control. The default is the "Configurator" level. |
| Objectx LOCAL Close control input | Digital input or other logical signal selected by the user | The local Close command from a physical digital input (e.g. a push button). |
| Objectx LOCAL Open control input | | The local Open command from a physical digital input (e.g. a push button). |
| Objectx REMOTE Close control input | | The remote Close command from a physical digital input (e.g. RTU). |
| Objectx REMOTE Open control input | | The remote Open command from a physical digital input (e.g. RTU). |
| Objectx Application Close | | The Close command from the application. Can be any logical signal. |
| Objectx Application Open | | The Open command from the application. Can be any logical signal. |

Blocking and interlocking

The interlocking and blocking conditions can be set for each controllable object, with Open and Close set separately. Blocking and interlocking can be based on any of the following: other object statuses, a software function or a digital input.

The image below presents an example of an interlock application, where the closed earthing switch interlocks the circuit breaker close command.

Figure. 4.5.3 - 124. Example of an interlock application.



In order for the blocking signal to be received on time, it has to reach the function 5 ms before the control command.

Events and registers

The object control and monitoring function (abbreviated "OBJ" in event block names) generates events and registers from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

The function also provides a resettable cumulative counter for OPEN, CLOSE, OPEN FAILED, and CLOSE FAILED events.

Table. 4.5.3 - 118. Event messages of the OBJ function instances 1 – 5.

| Event block name | Description |
|------------------|---------------------|
| OBJ1...OBJ5 | Object Intermediate |
| OBJ1...OBJ5 | Object Open |
| OBJ1...OBJ5 | Object Close |
| OBJ1...OBJ5 | Object Bad |
| OBJ1...OBJ5 | WD Intermediate |
| OBJ1...OBJ5 | WD Out |
| OBJ1...OBJ5 | WD in |
| OBJ1...OBJ5 | WD Bad |
| OBJ1...OBJ5 | Open Request On |
| OBJ1...OBJ5 | Open Request Off |
| OBJ1...OBJ5 | Open Command On |
| OBJ1...OBJ5 | Open Command Off |
| OBJ1...OBJ5 | Close Request On |
| OBJ1...OBJ5 | Close Request Off |
| OBJ1...OBJ5 | Close Command On |
| OBJ1...OBJ5 | Close Command Off |
| OBJ1...OBJ5 | Open Blocked On |
| OBJ1...OBJ5 | Open Blocked Off |
| OBJ1...OBJ5 | Close Blocked On |
| OBJ1...OBJ5 | Close Blocked Off |
| OBJ1...OBJ5 | Object Ready |
| OBJ1...OBJ5 | Object Not Ready |
| OBJ1...OBJ5 | Sync Ok |
| OBJ1...OBJ5 | Sync Not Ok |

| Event block name | Description |
|------------------|------------------------------------|
| OBJ1...OBJ5 | Open Command Fail |
| OBJ1...OBJ5 | Close Command Fail |
| OBJ1...OBJ5 | Final trip On |
| OBJ1...OBJ5 | Final trip Off |
| OBJ1...OBJ5 | Contact Abrasion Alarm On |
| OBJ1...OBJ5 | Contact Abrasion Alarm Off |
| OBJ1...OBJ5 | Switch Operating Time Exceeded On |
| OBJ1...OBJ5 | Switch Operating Time Exceeded Off |
| OBJ1...OBJ5 | XCBR Loc On |
| OBJ1...OBJ5 | XCBR Loc Off |
| OBJ1...OBJ5 | XSWI Loc On |
| OBJ1...OBJ5 | XSWI LOC Off |

The function registers its operation into the last twelve (12) time-stamped registers. The table below presents the structure of the function's register content.

Table. 4.5.3 - 119. Register content.

| Name | Description |
|------------------------------|--|
| Date and time | dd.mm.yyyy hh:mm:ss.mss |
| Event | Event name |
| Recorded Object opening time | Time difference between the object receiving an "Open" command and the object receiving the "Open" status. |
| Recorded Object closing time | Time difference between the object receiving a "Close" command and object receiving the "Closed" status. |
| Object status | The status of the object. |
| WD status | The status of the withdrawable circuit breaker. |
| Open fail | The cause of an "Open" command's failure. |
| Close fail | The cause of a "Close" command's failure. |
| Open command | The source of an "Open" command. |
| Close command | The source of an "Open" command. |
| General status | The general status of the function. |

4.5.4 Indicator object monitoring

The indicator object monitoring function takes care of the status monitoring of disconnectors. The function's sole purpose is indication and does not therefore have any control functionality. To control circuit breakers and/or disconnectors, please use the Object control and monitoring function. The monitoring is based on the statuses of the configured device's digital inputs. The number of monitored indicators in a device depends on the device type and available inputs. The status monitoring of one monitored object usually requires two (2) digital inputs. Alternatively, object status monitoring can be performed with a single digital input: the input's active state and its zero state (switched to 1 with a NOT gate in the Logic editor).

The outputs of the function are the monitored indicator statuses (Open, Close, Intermediate and Bad). The setting parameters are static inputs for the function, which can only be changed by the use in the function's setup phase.

The inputs of the function are the binary status indications. The function generates general time stamped ON/OFF events to the common event buffer from each of the following signals: OPEN, CLOSE, BAD and INTERMEDIATE event signals. The time stamp resolution is 1 ms.

Settings

Function uses available hardware and software digital signal statuses. These input signals are also setting parameters for the function.

Table. 4.5.4 - 120. Indicator status.

| Name | Range | Default | Description |
|--|---|---------|---|
| Indicator name ("Ind. Name") | - | IndX | The user-set name of the object, at maximum 32 characters long. |
| IndicatorX Object status ("Ind.X Object Status") | <ul style="list-style-type: none"> Intermediate Open Closed Bad | - | Displays the status of the indicator object. Intermediate status is displayed when neither of the status conditions (open or close) are active. Bad status is displayed when both of the status conditions (open and close) are active. |

Table. 4.5.4 - 121. Indicator I/O.

| Signal | Range | Description |
|--|--|--|
| IndicatorX Open input ("Ind.X Open Status In") | Digital input or other logical signal selected by the user (SWx) | A link to a physical digital input. The monitored indicator's OPEN status. "1" refers to the active "Open" state of the monitored indicator. |
| IndicatorX Close input ("Ind.X Close Status In") | Digital input or other logical signal selected by the user (SWx) | A link to a physical digital input. The monitored indicator's CLOSE status. "1" refers to the active "Close" state of the monitored indicator. |

Events

The indicator object monitoring function (abbreviated "CIN" in event block names) generates events from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

Table. 4.5.4 - 122. Event messages (instances 1 – 5).

| Event block name | Event names |
|------------------|--------------|
| CIN1...5 | Intermediate |
| CIN1...5 | Open |
| CIN1...5 | Close |
| CIN1...5 | Bad |

4.5.5 Auto-recloser (79)

Auto-reclosing means a coordinated de-energization and re-energization of overhead lines (both transmission and distribution). Its purpose is to clear transient and semi-permanent fault causes from the line and automatically restore the supply to the line. These types of faults account for approximately 80...95 % of all faults found in transmission and distribution networks. The majority of these fault types can be cleared with high-speed auto-reclosing, while the rest can be cleared with delayed auto-reclosing by de-energizing the faulty line for a longer period of time.

Only a minority of overhead line faults are of the permanent type which require maintenance or repair in the actual fault location. This type of fault include lightning striking the line, a tree branch touching the line, an arc caused by animals, and a short-circuit caused by some other object touching the line. If the fault is permanent (e.g. a broken insulator or a fallen tree leaning on the overhead line), the auto-recloser cannot clear the fault and the faulty feeder is locked and prevented from closing until the cause of the fault is repaired in the actual fault location. Also, when a fault cannot be cleared by auto-reclosing the line, any close-distance short-circuits should avoid initiating the auto-recloser because that would only cause unnecessary stress for the lines and the circuit breakers. Similar situations also rise in mixed networks since cable network faults cannot be cleared with the auto-recloser. The function must therefore be aware of the fault location before applying the auto-recloser to the faulty line.

Auto-recloser as application

The main principle of the auto-recloser is to de-energize the faulty line and the fault location so the cause of the fault can drop out from the line. When the line is energized and an object either touches the line or drops onto the line, the current starts to flow through the object either to the ground or between the phases. This causes the surrounding air to heat and ionize, and it starts to operate as a conductor between the energized phase(s) and the ground causing an arc to ignite.

When the breaker is opened (either by an auto-recloser command or by a protection function), the voltage in the line goes to zero. This extinguishes the arc and lets the fault-causing object to drop from the line, thus clearing the cause of the fault. Auto-reclosing closes the breaker after a set time (called 'dead time' during which the line is not energized) and the supply is restored to the line. If the fault is not cleared by the first auto-recloser cycle (called 'shot'), more shots can be applied to the line.

Alternatively, the function can be set to initiate the final trip, locking the feeder closing. The decision between a single-shot and a multi-shot auto-recloser depends on the following: protection type, switchgear, circuit breaker, stability requirements, network type, consumer loads as well as local utility knowledge and network practices.

The user can select whether there is a set time delay (called 'arcing time') between shots to burn the fault-causing object from the line, or whether normal protection operating times are applied. When a fault is not present when the breaker is closed but reappears soon after (called 'discrimination time' and 'reclaim time'), the auto-recloser function can either arm another shot or give the final trip command and the feeder becomes locked. The user can select the preferred method in the function's settings.

It is difficult to define a typical auto-recloser scheme because the above-mentioned parameters (and thus the main parameters of a scheme) vary greatly in distribution and transmission networks. This is why there are no universally applicable answers from the number of shots and the duration of the dead times to which protection functions should trigger the auto-recloser.

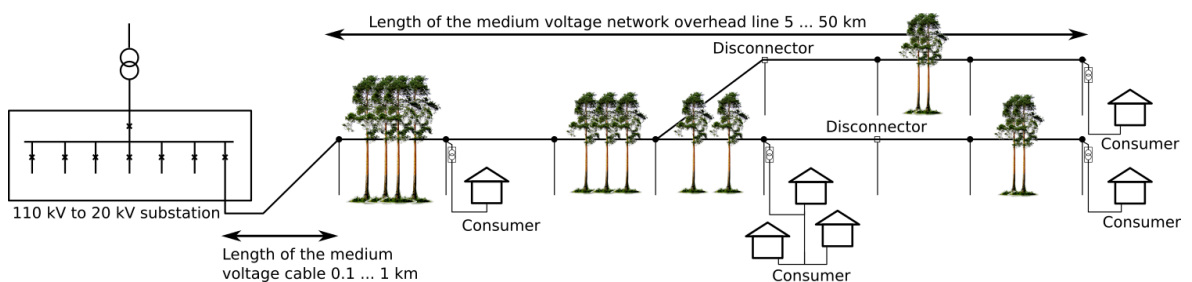
The minimum times for the "Dead time" setting is mostly dependent on the voltage level of the protected network: the air needs enough time to de-ionize before the circuit breaker is opened. For medium-voltage networks (20...75 kV) a 200 ms dead time should be sufficient. High-voltage networks require a longer dead time: a 110 kV network needs 300 ms and a 400 kV network needs 400...500 ms. This minimum time is not, however, less straightforward than this as it is affected by other parameters as well (such as conductor spacing, wind speed, fault type, fault duration, etc.). The main purpose of the "Dead time" setting is to give enough time for the air surrounding the fault location to return to its isolating state before the line is re-energized and therefore prevent the arc from reignite due to the heated and ionized air. The circuit breaker's open-close-open cycle capacity is another restricting factor for the minimum "Dead time" setting in low-voltage networks. In high-voltage networks, the time de-ionizing requires puts additional limitations on the minimum "Dead time" setting.

The user can build different schemes for evolving faults (such as transient earth faults that become multi-phase short-circuits or overcurrent faults) by changing the priorities and behaviors requests have. The auto-recloser function has five (5) independent priority requests for reclosing: REQ1 has the highest priority and REQ5 the lowest. The function also has one (1) critical request which halts the reclosing in any position when the request is received.

Auto-recloser scheme in radial networks

A typical medium-voltage overhead network is usually radial in structure. This does not cause any additional requirements for the auto-recloser scheme apart from the above-mentioned limitations from the required air de-ionization time and the capacity of the circuit breaker. Also, a typical medium-voltage overhead line consists only of consumers and has no power generation; thus, the main objective of the structure is to provide a stable and continuous supply of electricity.

Figure. 4.5.5 - 125. Diagram of a typical radial medium-voltage network in rural areas.



Usually, a radially built medium-voltage network in rural areas consists of a short cable connection from the substation to the overhead line, followed by a relatively long overhead line that normally ends with the consumer. The consumer (residence, farm, etc.) can connect to basically any point in the overhead line with a 20 kV/0.4 kV distribution transformer. The overhead line can have many branches, and it is not uncommon (especially in rural areas) that there are multiple forest areas the line runs through between the consumer connections. In longer lines in sparsely populated areas it is possible to isolate areas of the overhead line by dividing it up with disconnectors (at least in branches).

This type of application normally uses an auto-recloser with two shots (one high-speed and one delayed) which are triggered by earth fault protection or overcurrent protection. Short-circuit protection is used for interlocking the auto-recloser in case a clear short-circuit fault occurs in the line.

Figure. 4.5.5 - 126. Example of assigning request signals.

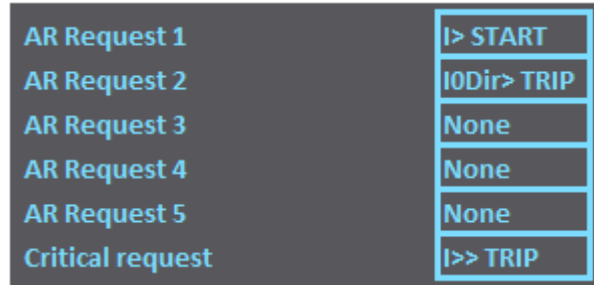
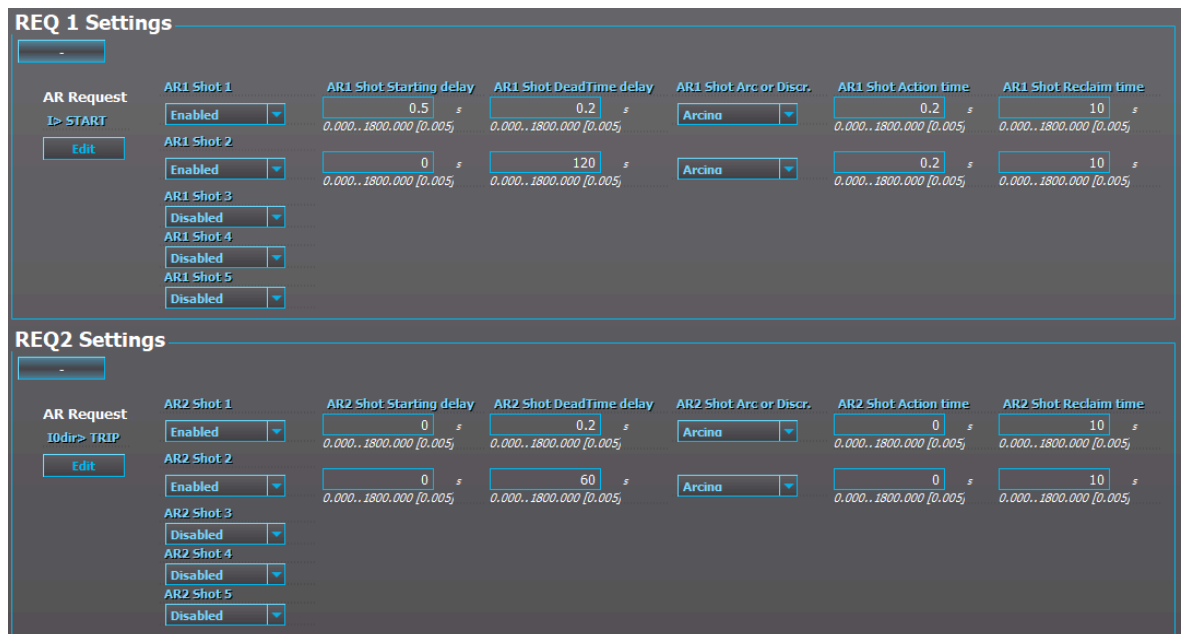


Figure. 4.5.5 - 127. Example of shot settings (two requests and two initialized shots).



In this example, earth fault (REQ2) uses its own operating time settings, whereas the time delay for overcurrent (REQ1) comes from the auto-recloser's own settings. Both fault types can initialize both of the shots with different settings. If the fault evolves from earth fault into a multi-phase fault, the auto-recloser uses the AR1 settings for the reclosing. In this example, the dead time between the first and the second shot in REQ1 differs from the dead time in REQ2 because the air needs more time to cool and de-ionize after an overcurrent or a multi-phase fault than it does after an earth fault. If the high-set overcurrent stage activates in any situation, the auto-reclosing sequence is stopped, the final trip is issued and the feeder closing is locked by the auto-recloser. A manual reset of the auto-recloser's lock is required before one can attempt to close the breaker. A manual reset can be applied from SCADA or locally from the device's HMI.

Based on the example above, the following six (6) sections present the principle signaling of the auto-recloser function. These are the auto-recloser sequence variations that can occur with this setup:

- from Trip with two shots (both fail)
- from Trip with two shots (high-speed fails, time-delayed succeeds)
- from Trip with two shots (high-speed succeeds)
- from Start with two shots (both fail)
- from Start with two shots (high-speed fails, time-delayed succeeds)

- from Start with two shots (high-speed succeeds).

The signal status graphs describe the statuses of available requests, the statuses of the auto-recloser's internal signals, the statuses of the timers, the breaker controls from the auto-recloser function as well as the breaker status signals.

The auto-recloser function operates closely with the object control and monitoring function, and all breaker status and monitor signals are forwarded from the selected object to the auto-recloser function. The circuit breaker's "Open" and "Close" signals are also controlled through the dedicated object. When the breaker cannot be closed (because it is not ready or the closing is waiting for a Synchrocheck allowance), the wait state is forwarded to the auto-recloser function to wait for the object's acknowledgement either of a successful closing or of a failure time-out. A similar situation can arise in the circuit breaker's "Open" command, for example, if the command is blocked because of an SF₆ gas leakage. In failure acknowledgement situations the auto-recloser function is always put to a lock-out state with a requirement for resetting once the cause of the lock-out is cleared. Resetting is done by an external input to the function or by closing the breaker.

Auto-recloser sequence from Trip with two shots (both fail).

In this auto-recloser scheme, the TRIP signal from the directional earth fault protection function (I0dir> TRIP) was set up as the operation starter for Request 2 (REQ2). REQ2 has two shots (Shots 1 and 2) enabled with the setting detailed in the image below; the first one is a high-speed shot (0.2 s) that is then followed by a time-delayed shot (60 s).

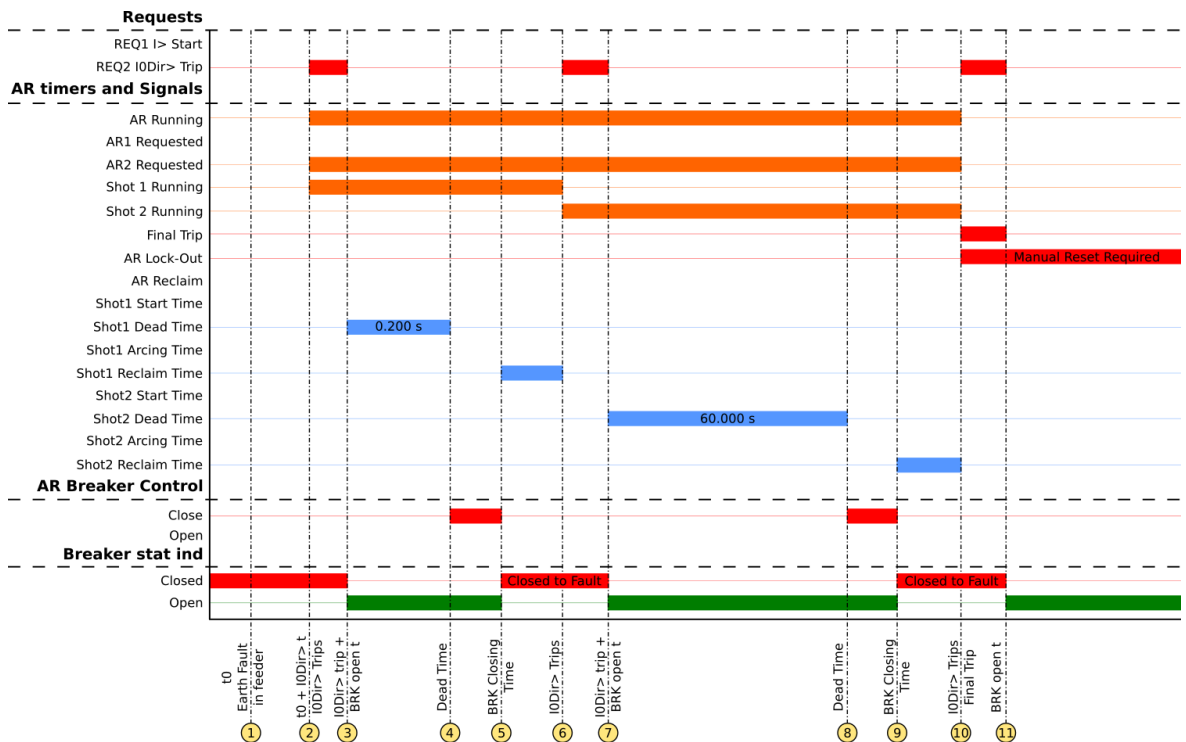
Figure. 4.5.5 - 128. Settings for I0dir> with two shots.

The screenshot displays the 'REQ2 Settings' window. On the left, 'AR Request' is set to 'I0dir> TRIP' with an 'Edit' button below it. The main area contains settings for six shots (AR2 Shot 1 to AR2 Shot 6). Shots 1 and 2 are 'Enabled', while Shots 3 through 6 are 'Disabled'. For each enabled shot, the 'AR2 Shot Starting delay' is 0 s, 'AR2 Shot DeadTime delay' is 0.2 s for Shot 1 and 60 s for Shot 2, 'AR2 Shot Arc or Discr.' is set to 'Arcino', 'AR2 Shot Action time' is 0 s, and 'AR2 Shot Reclaim time' is 10 s. Each numerical field has a range indicator below it: 0.000..1800.000 [0.005] s.

| AR Shot | AR Shot Starting delay | AR2 Shot DeadTime delay | AR2 Shot Arc or Discr. | AR2 Shot Action time | AR2 Shot Reclaim time |
|------------|------------------------|-------------------------|------------------------|----------------------|-----------------------|
| AR2 Shot 1 | 0 s | 0.2 s | Arcino | 0 s | 10 s |
| AR2 Shot 2 | 0 s | 60 s | Arcino | 0 s | 10 s |
| AR2 Shot 3 | Disabled | | | | |
| AR2 Shot 4 | Disabled | | | | |
| AR2 Shot 5 | Disabled | | | | |
| AR2 Shot 6 | Disabled | | | | |

When the TRIP signal is used to initiate the auto-recloser sequence, no additional starting or discrimination times are needed as the protection stage's own operation takes care of the breaker opening timings directly. Therefore, the auto-recloser function only monitors the status of the directional earth fault stage's tripping before initiating requests and shots.

Figure. 4.5.5 - 129. Signal status graph of the permanent earth fault auto-recloser cycle.



1. An earth fault is found in the protected line causing the I0Dir> protection to start calculating the operating time for a trip.
2. The I0Dir> trips and gives the "Open" command to the breaker's open coil. The auto-recloser function is initiated and the AR Running, AR2 Requested and Shot 1 Running signals are activated.
3. The circuit breaker is opened and the I0Dir> TRIP signal is released and simultaneously the REQ2 trip signal for the auto-recloser is released. The recloser starts calculating the Shot1 Dead Time to close the breaker.
4. The Shot1 Dead Time (200 ms) is exceeded and the function sends a "Close" request to the object breaker (AR Breaker): the conditions are met and the breaker's "Close" command is sent to the breaker's close coil.
5. The circuit breaker is closed towards the fault as it was not cleared by Shot 1 given the non-energized time. The I0dir> stage picks up and starts calculating the operating time for a trip. A "Close" command is dropped after the breaker's "Closed" indication is received and the auto-recloser function starts calculating Shot1 Reclaim Time.
6. The I0Dir> stage trips a second time and gives the REQ2 request to the function. However, as the function is in the process of calculating the Shot1 Reclaim Time when it receives this request, the function moves on to the next available shot (Shot 2) for the request. The Shot2 Running signal is set to active and the Shot1 Running is terminated.
7. The circuit breaker is opened and the I0Dir> TRIP signal is released and simultaneously REQ2 trip signal for auto-recloser is released. The recloser starts calculating the Shot2 Dead Time to close the breaker.
8. The Shot2 Dead Time (60 s) is exceeded and the function sends a "Close" request to the object breaker: the conditions are met and the breaker's "Close" command is sent to the breaker's close coil.
9. The circuit breaker is closed towards the fault since it was not cleared by Shot 2. The I0dir> stage picks up and starts calculating the operating time for a trip. A "Close" command is dropped after the breaker's "Closed" indication is received and the auto-recloser function starts calculating Shot2 Reclaim Time.

- 10. The I0Dir> stage trips a third time and gives the REQ2 request to the function. However, as the function is in the process of calculating the **Shot2 Reclaim Time** when it receives this request, the function tries to move on to the next available shot. Alas, this scheme does not have any more available shots and so the function begins the **Final Trip** state and drops the **AR Running**, **Shot2 Running** and **AR2 Requested** signals. The function enters the **AR Lock-out** state to prevent any further requests for reclosing.
- 11. The circuit breaker is opened and the I0Dir> TRIP signal is released, and simultaneously the REQ2 trip signal for the auto-recloser is released. The function is now in a steady lock-out state and waits for the user to manually reset and re-initialize the function by closing the breaker.

Auto-recloser sequence from Trip with two shots (high-speed fails, time-delayed succeeds).

This auto-recloser scheme has the same starters and shots as the previous example. The setting and signals are also the same. However, in this example the fault persists the high-speed shot but is cleared by the time-delayed shot.

Figure. 4.5.5 - 130. Settings for I0dir> with two shots.

REQ2 Settings

AR Request

I0dir> TRIP

Edit

AR2 Shot 1

Enabled

AR2 Shot 2

Enabled

AR2 Shot 3

Disabled

AR2 Shot 4

Disabled

AR2 Shot 5

Disabled

AR2 Shot Starting delay

0 s

0.000..1800.000 [0.005]

AR2 Shot DeadTime delay

0.2 s

0.000..1800.000 [0.005]

AR2 Shot Arc or Discr.

Arcing

AR2 Shot Action time

0 s

0.000..1800.000 [0.005]

AR2 Shot Reclaim time

10 s

0.000..1800.000 [0.005]

AR2 Shot Starting delay

0 s

0.000..1800.000 [0.005]

AR2 Shot DeadTime delay

60 s

0.000..1800.000 [0.005]

AR2 Shot Arc or Discr.

Arcing

AR2 Shot Action time

0 s

0.000..1800.000 [0.005]

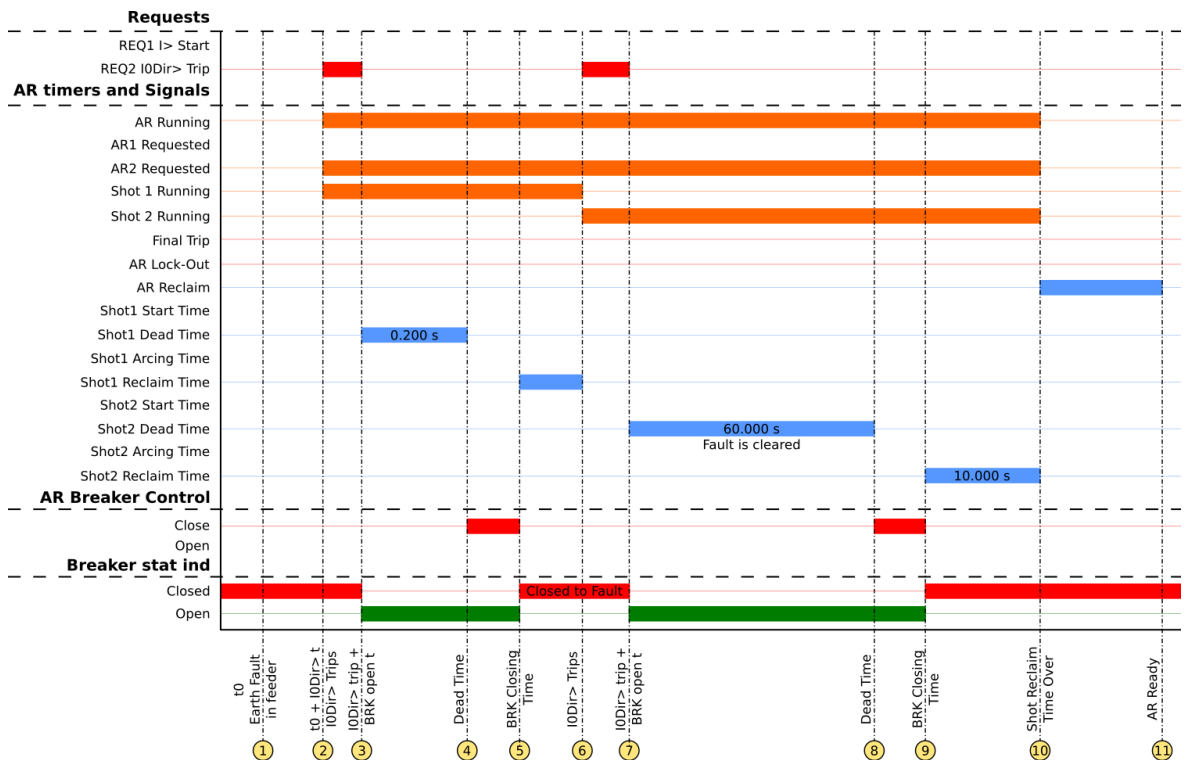
AR2 Shot Reclaim time

10 s

0.000..1800.000 [0.005]

This type of sequence (i.e. two shots required to clear the fault) represents 10...15 % of all faults that occur in MV overhead line networks.

Figure. 4.5.5 - 131. Signal status graph of the semi-permanent earth fault auto-recloser cycle.



1. An earth fault is found in the protected line causing the I0Dir> protection to start calculating the operating time for a trip.
2. The I0Dir> trips and gives the "Open" command to the breaker's open coil. The auto-recloser function is initiated and the AR Running, AR2 Requested and Shot 1 Running signals are activated.
3. The circuit breaker is opened and the I0Dir> TRIP signal is released and simultaneously the REQ2 trip signal for the auto-recloser is released. The recloser starts calculating the Shot1 Dead Time to close the breaker.
4. The Shot1 Dead Time (200 ms) is exceeded and the function sends a "Close" request to the object breaker: the conditions are met and the breaker's "Close" command is sent to the breaker's close coil.
5. The circuit breaker is closed towards the fault as it was not cleared by Shot 1. The I0dir> stage picks up and starts calculating the operating time for a trip. A "Close" command is dropped after the breaker's "Closed" indication is received and the auto-recloser function starts calculating Shot1 Reclaim Time.
6. The I0Dir> stage trips a second time and gives the REQ2 request to the function. However, as the function is in the process of calculating the Shot1 Reclaim Time when it receives this request, the function moves on to the next available shot (Shot 2) for the request. The Shot2 Running signal is set to active and the Shot1 Running is terminated.
7. The circuit breaker is opened and the I0Dir> TRIP signal is released and simultaneously REQ2 trip signal for the auto-recloser is released. The recloser starts calculating the Shot2 Dead Time to close the breaker.
8. The fault is cleared during Shot2 Dead Time. After that time (60 s) is exceeded, the function sends a "Close" request to the object breaker: the conditions are met and the breaker's "Close" command is sent to the breaker's close coil.
9. The circuit breaker is closed and since the fault has been cleared, no pick-ups are detected. The "Close" command is dropped after the breaker's "Closed" indication is received and the auto-recloser function starts calculating Shot2 Reclaim Time.

10. The Shot2 Reclaim Time (10 s) is exceeded, and so the AR Running, Shot 2 Running and AR2 Requested signals are terminated, and the AR Reclaim calculation begins. The difference between auto-reclosing and shot-specific reclaim times is that the function jumps to the next available shot should the fault return. If a fault returns after a successful cycle and the function's AR Reclaim signal is active, the function jumps directly to the Final Trip state and then enters the lock-out state. The user can control this behavior through the function settings. Both reclaim times can be set to 0 s when they are not needed, and the function skips all timers that are set to zero.
11. The AR Reclaim time is exceeded and the function is set to "Ready" to wait for the next request.

Auto-recloser sequence from Trip with two shots (high-speed succeeds).

This auto-recloser scheme has the same starters and shots as the two previous examples. The setting and signals are also the same. However, in this example the fault is cleared by the high-speed shot.

Figure. 4.5.5 - 132. Settings for I0dir> with two shots.

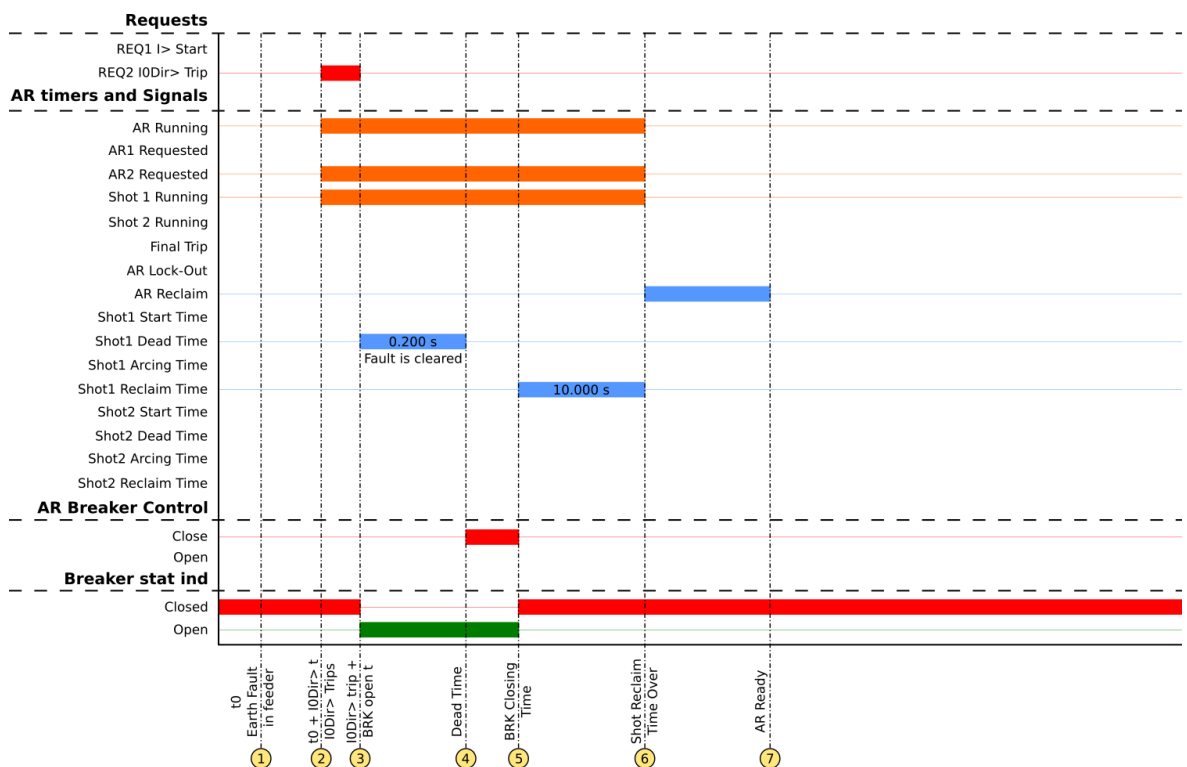
REQ2 Settings

AR Request: I0dir> TRIP

| AR2 Shot | AR2 Shot Starting delay | AR2 Shot DeadTime delay | AR2 Shot Arc or Discr. | AR2 Shot Action time | AR2 Shot Reclaim time |
|------------|-------------------------|-------------------------|------------------------|----------------------|-----------------------|
| AR2 Shot 1 | 0 s | 0.2 s | Arcing | 0 s | 10 s |
| AR2 Shot 2 | 0 s | 60 s | Arcing | 0 s | 10 s |
| AR2 Shot 3 | Disabled | | | | |
| AR2 Shot 4 | Disabled | | | | |
| AR2 Shot 5 | Disabled | | | | |

This type of sequence (i.e. the first shot clears the fault) represents 75...85 % of all faults that occur in MV overhead line networks.

Figure. 4.5.5 - 133. Signal status graph of the transient earth fault auto-recloser cycle.



1. An earth fault is found in the protected line causing the I0Dir> protection to start calculating the operating time for a trip.
2. The I0Dir> trips and gives the "Open" command to the breaker's open coil. The auto-recloser function is initiated and the **AR Running**, **AR2 Requested** and **Shot 1 Running** signals are activated.
3. The circuit breaker is opened and the I0Dir> TRIP signal is released and simultaneously the REQ2 trip signal for the auto-recloser is released. The recloser starts calculating the **Shot1 Dead Time** to close the breaker.
4. The fault is cleared during **Shot1 Dead Time** calculation. When that time (200 ms) is exceeded and the function sends a "Close" request to the object breaker: the conditions are met and the breaker's "Close" command is sent to the breaker's close coil.
5. The circuit breaker is closed and since the fault was cleared, no pick-ups are detected. The "Close" command is dropped after the breaker's "Closed" indication is received and the auto-recloser function starts calculating **Shot1 Reclaim Time**.
6. The **Shot1 Reclaim Time** (10 s) is exceeded, and so the **AR Running**, **Shot 2 Running** and **AR2 Requested** signals are terminated, and the **AR Reclaim** calculation begins. The difference between auto-reclosing and shot-specific reclaim times is that the function jumps to the next available shot should the fault returns. If a fault returns after a successful cycle and the function's AR Reclaim signal is active, the function jumps directly to the Final Trip state and then enters the lock-out state. The user can control this behavior through the function settings. Both reclaim times can be set to 0 s when they are not needed, and the function skips all timers that are set to zero. The user can also set it so that AR Reclaim is not used at all after a successful reclosing cycle.
7. The **AR Reclaim** time is exceeded and the function is set to "Ready" to wait for the next request.

Auto-recloser sequence from Start with two shots (both fail).

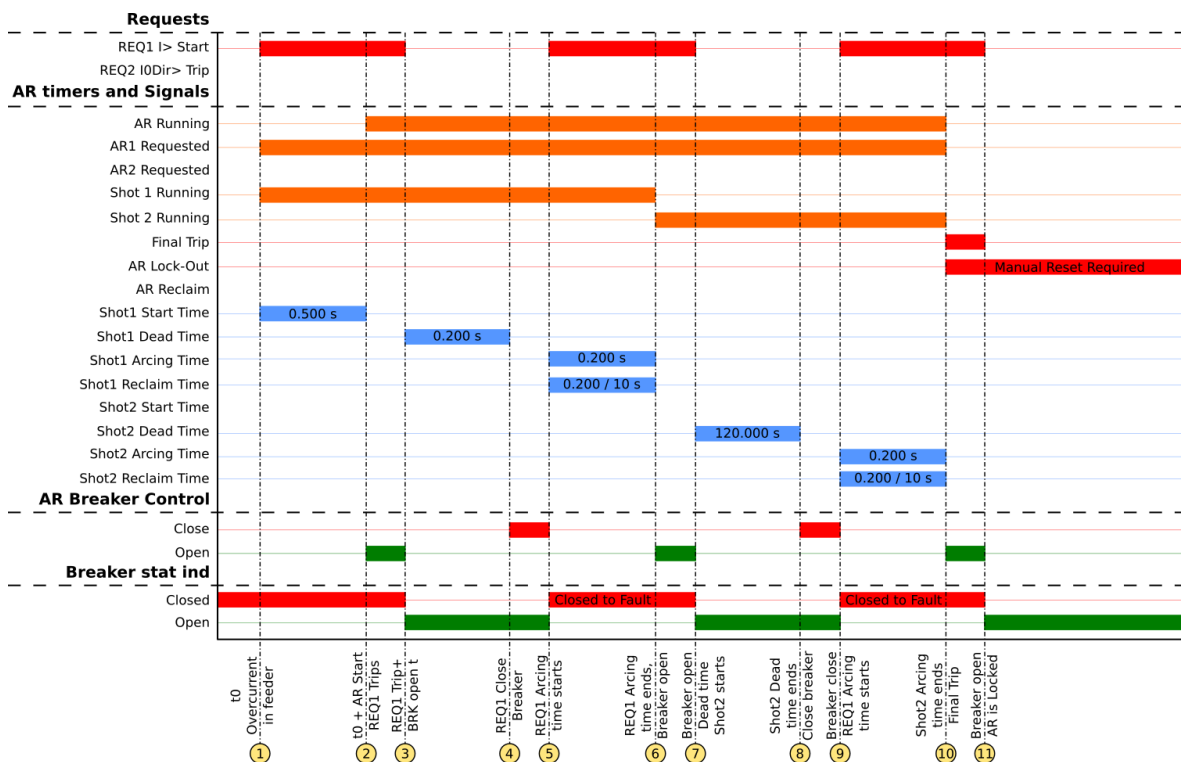
In this auto-recloser scheme, the START signal from the non-directional overcurrent protection function (I> START) was set up as the operation starter for Request 1 (REQ1). REQ1 has two shots (Shots 1 and 2) enabled with the setting detailed in the image below; the first one is a high-speed shot (0.2 s) that is then followed by a time-delayed shot (120 s). In this scheme the starting delay time is longer than in REQ2's high-speed shot. The shot action time is also longer in REQ1. If the fault persists after both shots, the time determining how long the breaker stays closed is reduced.

Figure. 4.5.5 - 134. Settings for I> with two shots.

| REQ 1 Settings | |
|-------------------------|----------|
| AR Request | I> START |
| AR1 Shot 1 | Enabled |
| AR1 Shot Starting delay | 0.5 s |
| AR1 Shot DeadTime delay | 0.2 s |
| AR1 Shot Arc or Discr. | Arcino |
| AR1 Shot Action time | 0.2 s |
| AR1 Shot Reclaim time | 10 s |
| AR1 Shot 2 | Enabled |
| AR1 Shot Starting delay | 0 s |
| AR1 Shot DeadTime delay | 120 s |
| AR1 Shot Arc or Discr. | Arcino |
| AR1 Shot Action time | 0.2 s |
| AR1 Shot Reclaim time | 10 s |
| AR1 Shot 3 | Disabled |
| AR1 Shot 4 | Disabled |
| AR1 Shot 5 | Disabled |

When the START signal is used to initiate the auto-recloser sequence, the fault duration timings are overseen by the auto-recloser function and thus both the starting time and the arcing time need to be set accordingly. The protection's main operating time settings should be longer than the values set to the auto-recloser function; this way the state changes work properly with this function.

Figure. 4.5.5 - 135. Signal status graph of the permanent overcurrent auto-recloser cycle.



1. An overcurrent is found in the protected line causing the I> protection to pick up. This activates the AR1 Requested signal to begin to calculate the Shot1 Start Time. This activates the Shot 1 Running signal even though the auto-recloser function is not yet running.
2. The Shot1 Start Time (500 ms) has elapsed and the auto-recloser function starts running (AR Running). This sends an "Open" command to the breaker.
3. The circuit breaker is opened and the I> stage's START signal is released and simultaneously REQ1 trip signal for auto-reclosing is released. The auto-recloser function starts calculating the Shot1 Dead Time to close the breaker.
4. The Shot1 Dead Time (200 ms) is exceeded and the auto-recloser function sends a "Close" request to the object breaker: the conditions are met and the breaker's "Close" command is sent to the breaker's close coil.
5. The circuit breaker is closed and since fault was not cleared, a new pick-up of I> is detected. A "Close" command is dropped after the breaker's "Closed" indication is received and the auto-recloser function starts calculating the Shot1 Reclaim Time simultaneously with the Shot1 Arcing Time.
6. The Shot1 Arcing Time (200 ms) is exceeded which means that the fault is not cleared and the function sends an "Open" command to the breaker. The function deactivates the Shot1 Running signal and instead activates the Shot2 Running signal.
7. The circuit breaker opens and the Shot2 Dead Time calculation begins.
8. The Shot2 Dead Time (120 s) is exceeded and the auto-recloser function sends a "Close" command to the breaker.
9. The circuit breaker is closed towards the fault since it was not cleared by Shot 2. The I> stage picks up and starts calculating the Shot2 Arcing Time for the Final Trip. The "Close" command is dropped after the the breaker's "Closed" indication is received. The auto-recloser function also starts calculating the Shot2 Reclaim Time.
10. The Shot2 Arcing Time (200 ms) is exceeded and the REQ1 request is given to the function. However, as the function is in the process of calculating the Shot2 Reclaim Time when it receives this request, the function tries to move on to the next available shot. Alas, this scheme does not have any more available shots and so the function begins the Final Trip state and drops the AR Running, Shot2 Running and AR1 Requested signals. The function enters the AR Lock-out state to prevent any further requests for reclosing.

11. The circuit breaker is opened and the I> function's START signal is released, and simultaneously the REQ1 trip signal for auto-reclosing is released. The function is now in a steady lock-out state and waits for the user to manually reset and re-initialize the function by closing the breaker.

Auto-recloser sequence from Start with two shots (high-speed fails, time-delayed succeeds).

This auto-recloser scheme has the same starters and shots as the previous example. The setting and signals are also the same. However, in this example the fault persists the high-speed shot but is cleared by the time-delayed shot.

Figure. 4.5.5 - 136. Settings for I> with two shots.

REQ 1 Settings

AR Request: I> START [Edit]

AR1 Shot 1: Enabled, Starting delay: 0.5 s, DeadTime delay: 0.2 s, Arc or Discr.: Arcing, Action time: 0.2 s, Reclaim time: 10 s

AR1 Shot 2: Enabled, Starting delay: 0 s, DeadTime delay: 120 s, Arc or Discr.: Arcing, Action time: 0.2 s, Reclaim time: 10 s

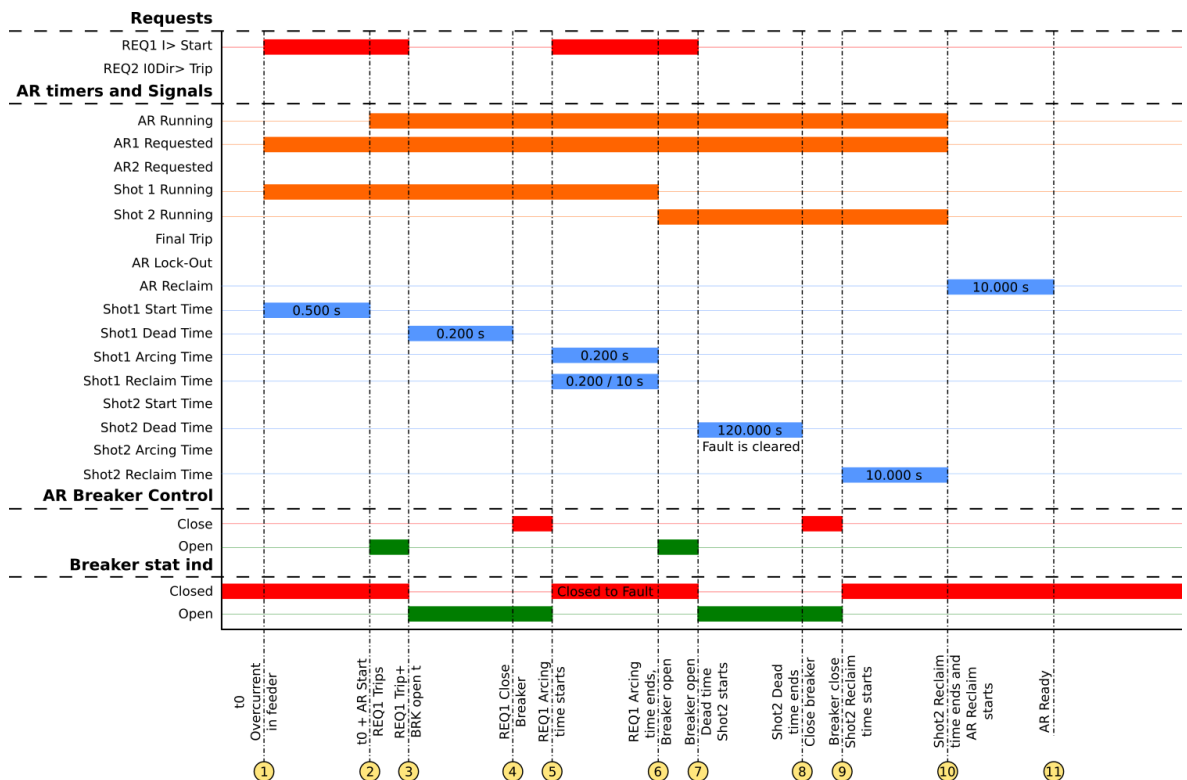
AR1 Shot 3: Disabled

AR1 Shot 4: Disabled

AR1 Shot 5: Disabled

This type of sequence (i.e. two shots required to clear the fault) represents 10...15 % of all faults that occur in MV overhead line networks.

Figure. 4.5.5 - 137. Signal status graph of the semi-permanent overcurrent auto-recloser cycle.



1. An overcurrent is found in the protected line causing the I> protection to pick up. This activates the AR1 Requested signal to begin to calculate the Shot1 Start Time. This activates the Shot 1 Running signal eventhough the auto-recloser function is not yet running.

2. The **Shot1 Start Time** (500 ms) for has elapsed and the auto-recloser function starts running (**AR Running**). This sends an "Open" command to the breaker.
3. The circuit breaker is opened and the I> stage's **START** signal is released and simultaneously **REQ1** trip signal for auto-reclosing is released. The auto-recloser function starts calculating the **Shot1 Dead Time** to close the breaker.
4. The **Shot1 Dead Time** (200 ms) is exceeded and the auto-recloser function sends a "Close" request to the object breaker: the conditions are met and the breaker's "Close" command is sent to the breaker's close coil.
5. The circuit breaker is closed and since fault was not cleared, a new pick-up of I> is detected. A "Close" command is dropped after the breaker's "Closed" indication is received and the auto-recloser function starts calculating the **Shot1 Reclaim Time** simultaneously with the **Shot1 Arcing Time**.
6. The **Shot1 Arcing Time** (200 ms) is exceeded which means that the fault is not cleared and the function sends an "Open" command to the breaker. The function deactivates the **Shot1 Running** signal and instead activates the **Shot2 Running** signal.
7. The circuit breaker opens and the **Shot2 Dead Time** calculation begins.
8. The fault is cleared during the **Shot2 Dead Time** (120 s). When that time is exceeded, the auto-recloser function sends a "Close" command to the breaker.
9. The circuit breaker is closed and since the fault was cleared by Shot 2, no more pick-ups are detected. The "Close" command is dropped after the the breaker's "Closed" indication is received. The auto-recloser function also starts calculating the **Shot2 Reclaim Time**.
10. The **Shot2 Reclaim Time** (10 s) is exceeded, and so the **AR Running**, **Shot2 Running** and **AR1 Requested** signals are terminated and the **AR Reclaim** calculation begins. The difference between auto-reclosing and shot-specific reclaim times is that the function jumps to the next available shot should the fault returns. If a fault returns after a successful cycle and the function's **AR Reclaim** signal is active, the function jumps directly to the Final Trip state and then enters the lock-out state. The user can control this behavior through the function settings. Both reclaim times can be set to 0 s when they are not needed, and the function skips all timers that are set to zero. The user can also set is so that **AR Reclaim** is not used at all after a successful recloser cycle.
11. The **AR Reclaim** time is exceeded and the function is set to "Ready" to wait for the next request.

Auto-recloser sequence from Start with two shots (high-speed succeeds).

This auto-recloser scheme has the same starters and shots as the two previous examples. The setting and signals are also the same. However, in this example the fault is cleared by the high-speed shot.

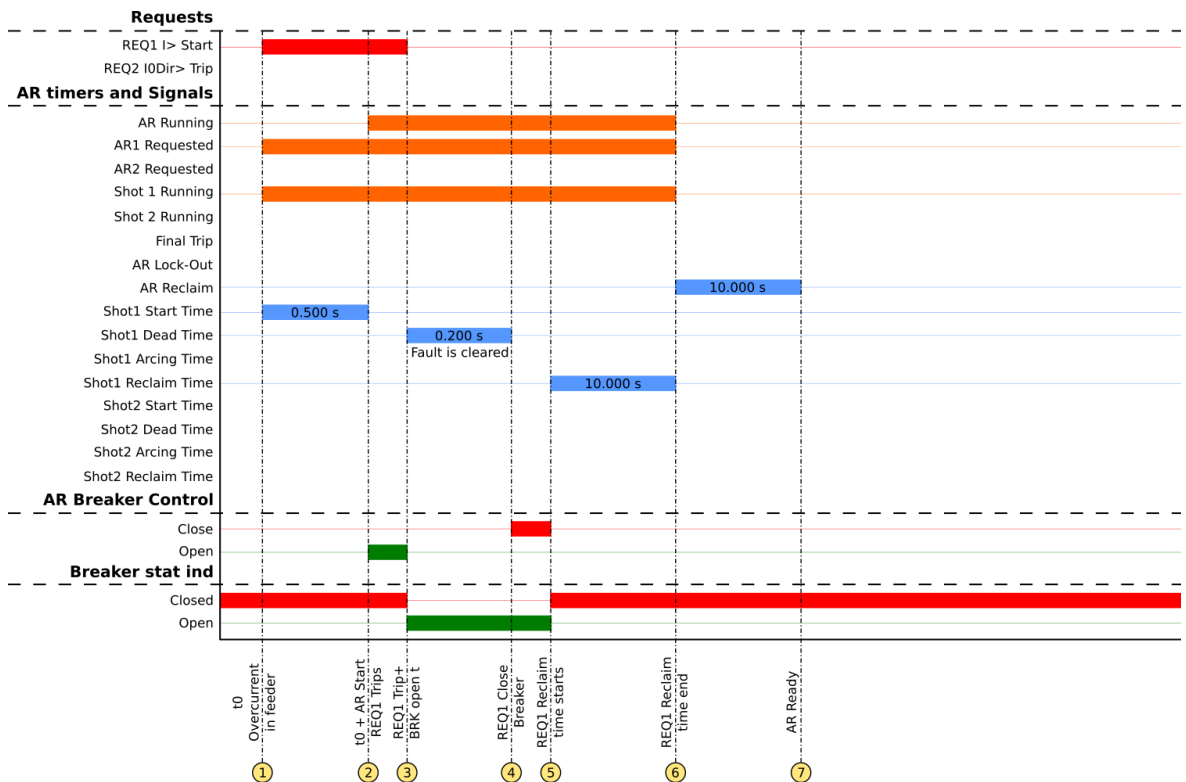
Figure. 4.5.5 - 138. Settings for I> with two shots.

The screenshot displays the 'REQ 1 Settings' window. On the left, under 'AR Request', 'I> START' is selected and an 'Edit' button is visible. The main area is divided into columns for various settings:

| Shot | Shot Status | Starting delay | DeadTime delay | Arc or Discr. | Action time | Reclaim time |
|------------|-------------|----------------------------------|----------------------------------|---------------|----------------------------------|---------------------------------|
| AR1 Shot 1 | Enabled | 0.5 s 0.000..1800.000 [0.005] | 0.2 s 0.000..1800.000 [0.005] | Arcino | 0.2 s 0.000..1800.000 [0.005] | 10 s 0.000..1800.000 [0.005] |
| AR1 Shot 2 | Enabled | 0 s 0.000..1800.000 [0.005] | 120 s 0.000..1800.000 [0.005] | Arcino | 0.2 s 0.000..1800.000 [0.005] | 10 s 0.000..1800.000 [0.005] |
| AR1 Shot 3 | Disabled | | | | | |
| AR1 Shot 4 | Disabled | | | | | |
| AR1 Shot 5 | Disabled | | | | | |

This type of sequence (i.e. the first shot clears the fault) represents 75...85 % of all faults that occur in MV overhead line networks.

Figure. 4.5.5 - 139. Signal status graph of the transient overcurrent auto-recloser cycle.

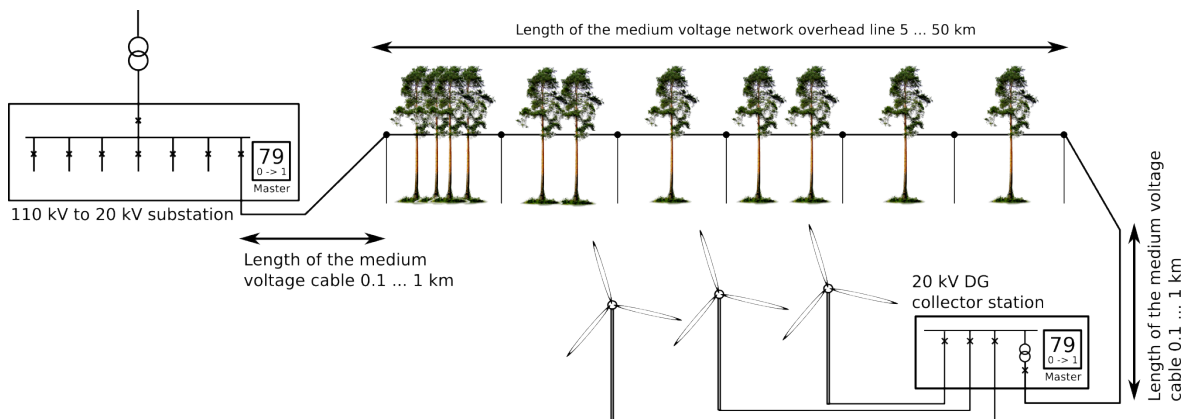


1. An overcurrent is found in the protected line causing the I> protection to pick up. This activates the AR1 Requested signal to begin to calculate the Shot1 Start Time. This activates the Shot 1 Running signal even though the auto-recloser function is not yet running.
2. The Shot1 Start Time (500 ms) has elapsed and the auto-recloser function starts running (AR Running). This sends an "Open" command to the breaker.
3. The circuit breaker is opened and the I> stage's START signal is released and simultaneously REQ1 trip signal for auto-reclosing is released. The auto-recloser function starts calculating the Shot1 Dead Time to close the breaker.
4. The fault is cleared during the Shot1 Dead Time (200 ms). When this time is exceeded, the auto-recloser function sends a "Close" request to the object breaker: the conditions are met and the breaker's "Close" command is sent to the breaker's close coil.
5. The circuit breaker is closed and since the fault was cleared, no pick-ups are detected. A "Close" command is dropped after the breaker's "Closed" indication is received and the auto-recloser function starts calculating the Shot1 Reclaim Time.
6. The Shot1 Reclaim Time (10 s) is exceeded, and so the AR Running, AR1 Requested and Shot 1 Running signals are terminated and the AR Reclaim calculation begins. The difference between auto-reclosing and shot-specific reclaim times is that the function jumps to the next available shot should the fault returns. If a fault returns after a successful cycle and the function's AR Reclaim signal is active, the function jumps directly to the Final Trip state and then enters the lock-out state. The user can control this behavior through the function settings. Both reclaim times can be set to 0 s when they are not needed, and the function skips all timers that are set to zero. The user can also set it so that AR Reclaim is not used at all after a successful recloser cycle.
7. The AR Reclaim time is exceeded and the function is set to "Ready" to wait for the next request.

Auto-recloser in meshed or ring networks

A typical auto-recloser scheme cannot be applied directly to an overhead line network that has a distributed generation (DG) component; this situation will become more common as renewable power sources become more widespread. Instead, this requires a two-end auto-recloser scheme where the two relays at both ends of the line function in a master–follower operation. The DG power plant must be disconnected from the rest of the network before the breaker's "Close" command is applied; otherwise the plant keeps the fault on during the auto-recloser's dead time and thus fails the reclosing. Additionally, when the main grid is disconnected from the DG power plant, the closing of the breaker is likely to cause phase shifting issues during the dead time.

Figure. 4.5.5 - 140. Auto-reclosing with distributed generation in the line.



This operation requires a link between the 110/20 kV substation's master relay and the 20 kV collector substation's follower relay. When the auto-recloser function is initiated, the collector station's breaker is opened and remains open until the auto-recloser sequence is over as there is no reason to close the breaker until the auto-recloser cycle has successfully cleared the fault. When the sequence is successful, the collector substation's breaker is given permission to close after the reclaim time; the breaker should be closed with the Synchrocheck function.

Once the collector substation is disconnected, the previously described basic principles of auto-reclosing apply. This method applies to all meshed or ring networks where the same line is fed power from multiple directions. This problem does not exist for typical consumer (radial) networks.

Arcing time and discrimination time

Generally, after the dead time has elapsed and the breaker is closed by the auto-recloser, this happens: the reclaim time starts calculating and if the process is interrupted by a new reclosing request, the function continues to the next state (the next available shot, or the Final Trip if no more shots are available). However, the user can use the "Shot action time" setting to control this behavior. The two settings are mutually exclusive: when "Arcing" is selected for a shot, "Discrimination" cannot be selected for the same shot.

The "Arcing" setting is used to control the auto-recloser when the START signal of a stage makes the requests. If the request (e.g. $I > \text{START}$) activates during the reclaim time, an arcing time calculation begins. If the fault persists, the function continues to the next state. If an arcing time calculation begins but stops before the set time has passed, the reclaim calculation continues normally. When that time has elapsed, the auto-recloser function returns either to the general reclaim time or to the Ready mode; the shot is considered successful. The arcing time counter does not reset when the reclaim calculation continues: every time it activates, it continues from where it left off. This means that the time set to the "ARx Shot action time" parameter is a cumulative counter of time allowed before deciding whether a shot is failed or successful.

The auto-recloser is sometimes used in time-coordinated, IDMT-protected networks that have old mechanical relays with current-dependent release times. In these cases the operation of the protection selectivity must be guaranteed by allowing all relay timing devices to completely reset during dead time to maintain the correct time discrimination after reclosing to the fault. Some mechanical IDMT relays can require up to ten seconds (10 s) to reset. When short dead times are required, the relays should reset almost immediately for the current-dependent time grading to operate as expected, and set the discrimination time (instead of the arcing time) to start simultaneously with the reclaim time. If new reclosing requests are made during this discrimination time, the function halts and lets the protection devices operate based on their own settings, and does not interfere with the protection functions' or the breaker's operation. However, this means that the auto-recloser has to be manually reset and the breaker manually closed before further reclosing requests can be made.

Auto-recloser I/O

The main outputs of the auto-recloser function are the control signals OBJECT OPEN and OBJECT CLOSE. The function also reports the recloser status information which is used in the logics, LED indications, and applied operations.

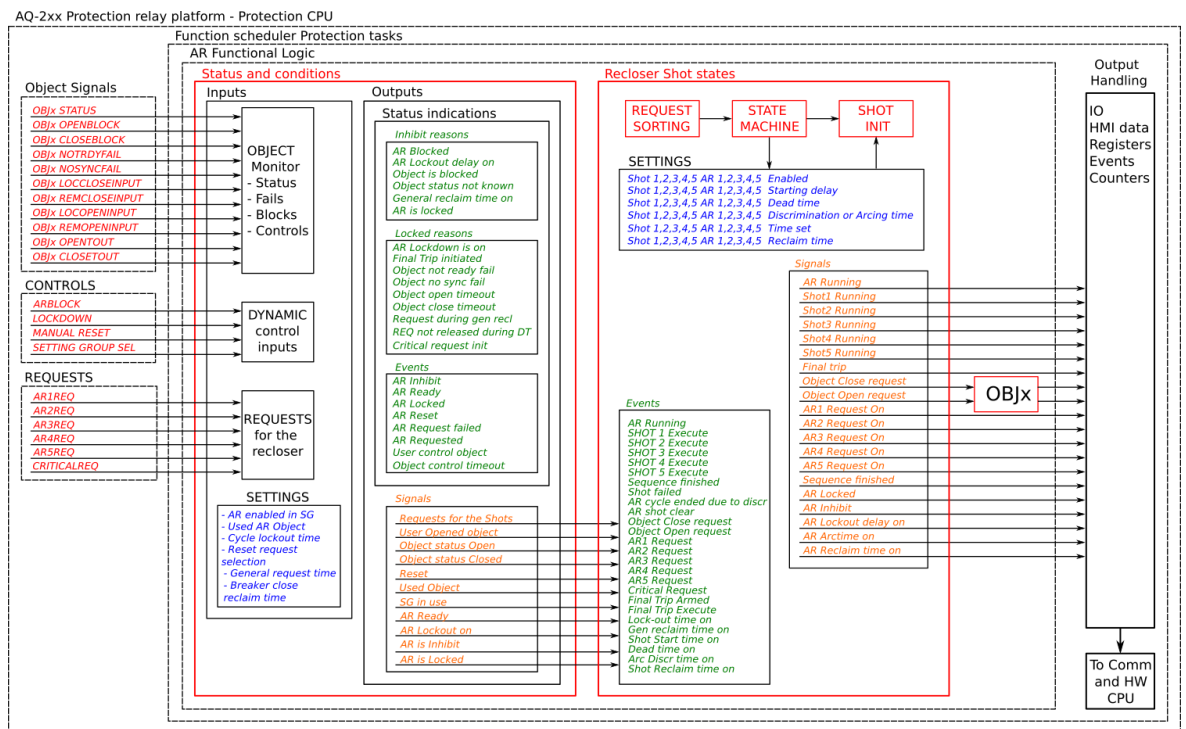
The inputs of the function are the following:

- binary recloser request signals
- blockings
- controlling signals
- the controlled object's monitoring and status signals.

The function generates general time-stamped ON/OFF events to the common event buffer from each of the two (2) output signal as well as from several operational event signals. The time stamp resolution is 1 ms. The function also a resettable cumulative counter for each of the applied reclosing events and requests.

The auto-recloser function can be divided into the starter, shot selector state machine, sorter and shot blocks which operate dynamically during the recloser sequences according to the given settings and input signal monitoring. The behavior of the function can be changed even during sequences that are based on programmed reclosing schemes and on active requests.

Figure. 4.5.5 - 141. Simplified function block diagram of the auto-recloser function.



As the diagram above shows, the auto-recloser function is tied to and dependent on the block status information and configuration of the object control and monitoring function. This is why the controlled object must be configured before the auto-recloser function can be used. In AQ-2xx protection systems the object control block supervises all breaker operations: this means that breaker-related functionalities (e.g. synchrocheck, breaker status monitoring) are not noted separately by the auto-recloser function. If any of these fail during the circuit breaker opening or closing, the object control function reports the event to the auto-recloser function which then takes the corresponding action.

In addition to the previously mentioned cases, the manual control of the breaker (whether open or close during the auto-recloser sequence) also always causes a reset of the auto-recloser. For example, if a breaker is closed manually during dead time towards a fault, the auto-recloser function enters the general reclaim mode and causes a lock-out of the function.

The auto-recloser function gives exhaustive information about its operations and statuses through online indications, events, registered data as well as output signals which can be configured to any output or logical input in the device. If the network configuration is altered during an auto-reclosing sequence, the operation of the auto-recloser function can also be modified accordingly by switching to a setting group that matches the changed network situation.

Input signals of the auto-recloser function

The required auto-recloser scheme determines how many and which setting parameters are needed. All status changes in the input signals (inc. the requests) always cause recorded events, also in the object's registers and the object's continuous status indications. Events can be enabled or disabled according to the application requirements.

Table. 4.5.5 - 123. AR input signals.

| Signal | Range | Description |
|---------------------|---------------------------------|---|
| AR On/Off | Any binary signal in the device | Enables or disables the auto-recloser function with any binary signal selected by the user. The parameter "Use AR On/Off signals" defines whether this input signal is in use or not. |
| AR Manual reset | Any binary signal in the device | Allows for the manual resetting of the recloser if locked (e.g. due to Final Trip). |
| AR Locking | Any binary signal in the device | Locks the auto-recloser so that it requires a manual reset before its operation can be set to "Ready". |
| AR Critical request | Any binary signal in the device | Defines the critical request for the function. If this signal is activated, the auto-recloser goes directly to the locked state the moment the request is received. |

Table. 4.5.5 - 124. Request signals.

| Signal | Range | Description |
|---------------------|---------------------------------|--|
| AR Request 1 (REQ1) | Any binary signal in the device | The request with the highest priority, it overrides all auto-reclosing requests with lower priorities. When this request signal is activated and other conditions for reclosing are met, a shot is applied. |
| AR Request 2 (REQ2) | Any binary signal in the device | The request with the second highest priority, it overrides all auto-reclosing requests with lower priorities. When this request signal is activated and other conditions for reclosing are met, a shot is applied. |
| AR Request 3 (REQ3) | Any binary signal in the device | The request with the third highest priority, it overrides all auto-reclosing requests with lower priorities. When this request signal is activated and other conditions for reclosing are met, a shot is applied. |
| AR Request 4 (REQ4) | Any binary signal in the device | The request with the fourth highest (and second lowest) priority, it overrides all auto-reclosing requests with lower priorities. When this request signal is activated and other conditions for reclosing are met, a shot is applied. |
| AR Request 5 (REQ5) | Any binary signal in the device | The request with the lowest priority, it is overridden by all other auto-reclosing requests. When this request signal is activated and other conditions for reclosing are met, a shot is applied. |

Output signals of the auto-recloser function

The outputs of the function are only indication signals (*Control* → *Control functions* → *Auto-recloser* → *I/O*). The breaker's "Open" and "Close" commands are controlled by the object control and monitoring function.

Table. 4.5.5 - 125. AR output signals.

| Signal | Description |
|----------------------|--|
| AR ON AR OFF | The signal "AR ON" is displayed when the auto-recloser function is enabled. The signal "AR OFF" is displayed if the "Use AR On/Off signals" is set to "Yes" and the input of the AR On/Off is inactive. |
| AR In progress | The signal "AR In progress" is activated and displayed when the function has opened the breaker and is calculating the time towards closing it. |
| AR1 Request ON | The signal "AR1 Request ON" is activated and displayed when the function is executing a shot requested by REQ1. |
| AR2 Request ON | The signal "AR2 Request ON" is activated and displayed when the function is executing a shot requested by REQ2. |
| AR3 Request ON | The signal "AR3 Request ON" is activated and displayed when the function is executing a shot requested by REQ3. |
| AR4 Request ON | The signal "AR4 Request ON" is activated and displayed when the function is executing a shot requested by REQ4. |
| AR5 Request ON | The signal "AR5 Request ON" is activated and displayed when the function is executing a shot requested by REQ5. |
| AR Running | The signal "AR Running" is activated and displayed when the function is in Running mode. |
| AR Shot 1 Running | The signal "AR Shot 1 Running" is activated and displayed when the function is executing Shot 1. |
| AR Shot 2 Running | The signal "AR Shot 2 Running" is activated and displayed when the function is executing Shot 2. |
| AR Shot 3 Running | The signal "AR Shot 3 Running" is activated and displayed when the function is executing Shot 3. |
| AR Shot 4 Running | The signal "AR Shot 4 Running" is activated and displayed when the function is executing Shot 4. |
| AR Shot 5 Running | The signal "AR Shot 5 Running" is activated and displayed when the function is executing Shot 5. |
| AR Sequence finished | The signal "AR Sequence finished" is activated and displayed when the function has closed the breaker after the last shot and is waiting for the Final Trip to occur or for the reclaim time to run out. |
| AR Final Trip | The signal "AR Final Trip" is activated and displayed when the function has executed the Final Trip command. |
| AR Dead time ON | The signal "AR Dead time ON" is activated and displayed when the function has opened the breaker and is calculating the time towards closing it. |
| AR Arcing time ON | The signal "AR Arcing time ON" is activated and displayed when the function is calculating the arcing time. |
| AR Reclaim time ON | The signal "AR Reclaim time ON" is activated and displayed when the function is calculating the reclaim time. |

| Signal | Description |
|--------------------------------------|---|
| AR Ready | The signal "AR Ready" is activated and displayed when the function is ready to execute the auto-reclosing sequence if a fault is detected. |
| AR Lockout after successful sequence | The signal "AR Reclaim time ON" is activated and displayed when the auto-recloser sequence has been successful but a new fault was detected before the lock-out time was depleted. No new sequence will be started while this signal is active, instead the function goes into the locked mode. |
| AR Operation inhibit | The signal "AR Operation inhibit" is activated and displayed when the function is in Inhibit mode. |
| AR Locked | The signal "AR Locked" is activated and displayed when the function is in Locked mode. |

Setting parameters

The auto-recloser function has settings that the user can freely configure. The setting cover all areas of the function so that the user can control the operational details of the function as needed. The function's operation can be static or dynamic depending on the setting group that is in use. The function has both general settings and active settings concerning requests and shots. The general settings control the desired object selection as well as the general behavior of the function in different operating schemes.

Table. 4.5.5 - 126. AR Status and basic settings.

| Setting | Range | Default | Description |
|-----------------------|---|----------|---|
| AR Mode | <ul style="list-style-type: none"> Disabled Enabled | Disabled | Enables and disables the auto-recloser function in the configuration. |
| Use AR On/Off signals | <ul style="list-style-type: none"> Yes No | No | Selects whether or not the AR ON and AR OFF signals are used. If set to "No" the auto-recloser is always in use. If set to "Yes" binary signal set to "AR ON/OFF" has to be active for the auto-recloser to be enabled. |

| Setting | Range | Default | Description |
|----------------|--|---------|---|
| AR Status | <ul style="list-style-type: none"> • AR is inhibit • AR is ready • AR is locked • AR is running • AR is not running • Lock out delay is running • Reclaim time counting • Start time counting • Dead time counting • Arcing or discr. time counting • Reclaim time counting • AR1 Requested • AR2 Requested • AR3 Requested • AR4 Requested • AR5 Requested • Executing Shot1 • Executing Shot2 • Executing Shot3 • Executing Shot4 • Executing Shot5 • Shot Clear | - | When clicked open, displays the status of the function. |
| Timer active | <ul style="list-style-type: none"> • - • AR Lockout • AR Reset Reclaim • AR Start Delay • AR Dead Time • AR Discrimination • AR Shot Reclaim | - | When the function is counting down towards any action, this parameter displays what is the next expected action when the "AR Timer value" reaches zero. |
| AR Timer value | 0...1800.00s | 0s | When the function is counting down towards any action, this parameter displays how much time is left until the action is executed. The "Timer active" setting displays what is the action when this timer reaches zero. |

Table. 4.5.5 - 127. AR General settings.

| Setting | Range | Step | Default | Description |
|---|--|--------|-------------------|--|
| Object for AR | <ul style="list-style-type: none"> Object 1 Object 2 Object 3 Object 4 Object 5 | - | Object 1 | Defines the monitored and/or controlled object, and the monitoring and/or controlling signals issued. This selection can be changed via the device's setting group selection in real time. |
| AR Enabled in SG | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Enables and disables the auto-recloser in the current setting group. Can be enabled and disabled in each setting group independently. This selection can be changed via the device's setting group selection in real time. |
| Require manual resetting | <ul style="list-style-type: none"> Required Obj Close CMD resets | - | Required | Defines the auto-recloser resetting after locking (Final trip, error condition). Resetting can be set to be only done manually with a user defined signal, or it can be reset by a general breaker "Close" command (from any source). This selection can be changed via the device's setting group selection in real time. |
| Successful reclose start general reclaim | <ul style="list-style-type: none"> Only shot reclaim Shot reclaim and general reclaim | - | Only shot reclaim | Defines whether the auto-recloser runs after a successful reclose (inc. shot reclaim time), or whether it enters the locked state after a request for auto-reclosing is applied. If "Shot reclaim and general reclaim" is selected, this selection defines the minimum time allowed between auto-reclosing cycles without changing the shot-specific reclaim times. This selection can be changed via the device's setting group selection in real time. |
| Lock-out time ("Lockout after successful AR") | 0.000...1800.000s | 0.005s | 0.000s | Defines the lock-out time after a successful reclosing. When set to 0.00 s, the recloser goes directly into the "Ready" state after a successful reclosing. If this time is running while a new reclosing request is applied, the auto-recloser opens the breaker and enters the locked state to prevent further reclosing attempts. This selection can be changed via the device's setting group selection in real time. |
| Object close reclaim time | 0.000...1800.000s | 0.005s | 10.000s | Defines the "Close" reclaim time of the object. This time starts when the object is manually closed or when the general reclaim time is selected after a successful auto-reclosing. If an auto-reclosing request is applied during this time, the auto-recloser enters the locked state to prevent further reclosing attempts. This selection can be changed via the device's setting group selection in real time. |

Table. 4.5.5 - 128. Auto-recloser shot settings.

| Setting | Range | Step | Default | Description |
|------------|---|------|----------|--|
| ARx Shot x | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Enables/disables Shot x for request ARx. If "Disabled", the ARx request skips Shot 1 and moves on to the next enabled shot. If "Enabled", the ARx request executes a shot according to Shot 1 settings. This selection can be changed via the device's setting group selection in real time. |

| Setting | Range | Step | Default | Description |
|--------------------------|--|---------|---------|--|
| ARx Shot starting delay | 0.000...1800.000s | 0.005s | 0.000s | Defines the starting delay of the shot, i.e. the minimum time an ARx request has to be active before opening the breaker and entering the dead time delay counting. This setting is used only when the ARx request comes from the function's START signal. If the function's TRIP request starting delay is not 0.000 s, the auto-recloser is prevented from starting. Whenever the shot is not the first one, this setting should be set to 0.000 s. This selection can be changed via the setting group selection in real time. |
| ARx Shot dead time delay | 0.000...1800.000s | 0.005s | 0.000s | Defines the dead time delay of the shot, i.e. the breaker's "Open" time before the auto-recloser closes the breaker. The time calculation starts from the breaker's "Open" signal. This selection can be changed via the device's setting group selection in real time. |
| ARx Shot Arc or Discr. | <ul style="list-style-type: none"> Arcing Discrimination | - | Arcing | Determines what happens when a fault persists after a dead time when the breaker is closed. Can be chosen between arcing and discrimination behavior; the selection depends on the application. When "Arcing" time is selected, the auto-recloser keeps the breaker closed until Action time is spent (also with Discrimination time). If a new request received during the Action time calculation, the auto-recloser locks out during the reclaim time. This selection can be changed via the device's setting group selection in real time. |
| ARx Shot action time | 0.000...1800.000s | 0.005s | 0.000s | Defines the action time for the shot after dead time and after the breaker is closed, i.e. the maximum arcing time or discrimination time when the reclaim time is running. When set to 0.000 s, the "Arcing" or "Discrimination" time is disabled in the auto-recloser scheme. This setting can be changed via the device's setting group selection in real time. |
| ARx Shot reclaim time | 0.000...1800.000s | 0.0005s | 0.000s | After the dead time has elapsed and the breaker is closed by the auto-recloser, the reclaim time starts calculating. If the process is interrupted by a new reclosing request, the function continues to the next shot. |

Figure. 4.5.5 - 142. Auto-recloser shot setting parameters.

| REQ 1 Settings | | | | | | |
|--|------------|----------------------------------|----------------------------------|------------------------|----------------------------------|---------------------------------|
| AR Request I> START <input type="button" value="Edit"/> | AR1 Shot 1 | AR1 Shot Starting delay | AR1 Shot DeadTime delay | AR1 Shot Arc or Discr. | AR1 Shot Action time | AR1 Shot Reclaim time |
| | Enabled | 0.5 s 0.000..1800.000 [0.005] | 0.2 s 0.000..1800.000 [0.005] | Arcina | 0.2 s 0.000..1800.000 [0.005] | 10 s 0.000..1800.000 [0.005] |
| | AR1 Shot 2 | 0 s 0.000..1800.000 [0.005] | 120 s 0.000..1800.000 [0.005] | Arcina | 0.2 s 0.000..1800.000 [0.005] | 10 s 0.000..1800.000 [0.005] |
| | AR1 Shot 3 | Disabled | | | | |
| | AR1 Shot 4 | Disabled | | | | |
| | AR1 Shot 5 | Disabled | | | | |
| REQ2 Settings | | | | | | |
| AR Request I> TRIP IOdir> TRIP <input type="button" value="Edit"/> | AR2 Shot 1 | AR2 Shot Starting delay | AR2 Shot DeadTime delay | AR2 Shot Arc or Discr. | AR2 Shot Action time | AR2 Shot Reclaim time |
| | Enabled | 0 s 0.000..1800.000 [0.005] | 0.2 s 0.000..1800.000 [0.005] | Arcina | 0 s 0.000..1800.000 [0.005] | 10 s 0.000..1800.000 [0.005] |
| | AR2 Shot 2 | 0 s 0.000..1800.000 [0.005] | 60 s 0.000..1800.000 [0.005] | Arcina | 0 s 0.000..1800.000 [0.005] | 10 s 0.000..1800.000 [0.005] |
| | AR2 Shot 3 | Disabled | | | | |
| | AR2 Shot 4 | Disabled | | | | |
| | AR2 Shot 5 | Disabled | | | | |
| REQ3 Settings | | | | | | |
| AR Request IOInt> TRIP <input type="button" value="Edit"/> | AR3 Shot 1 | AR3 Shot Starting delay | AR3 Shot DeadTime delay | AR3 Shot Arc or Discr. | AR3 Shot Action time | AR3 Shot Reclaim time |
| | Disabled | | | | | |
| | AR3 Shot 2 | 0 s 0.000..1800.000 [0.005] | 60 s 0.000..1800.000 [0.005] | Arcina | 0 s 0.000..1800.000 [0.005] | 30 s 0.000..1800.000 [0.005] |
| | AR3 Shot 3 | Disabled | | | | |
| | AR3 Shot 4 | Disabled | | | | |
| | AR3 Shot 5 | Disabled | | | | |
| REQ4 Settings | | | | | | |
| AR Request <input type="button" value="Edit"/> | AR4 Shot 1 | AR4 Shot Starting delay | AR4 Shot DeadTime delay | AR4 Shot Arc or Discr. | AR4 Shot Action time | AR4 Shot Reclaim time |
| | Disabled | | | | | |
| | AR4 Shot 2 | Disabled | | | | |
| | AR4 Shot 3 | Disabled | | | | |
| | AR4 Shot 4 | Disabled | | | | |
| | AR4 Shot 5 | Disabled | | | | |
| REQ5 Settings | | | | | | |
| AR Request <input type="button" value="Edit"/> | AR5 Shot 1 | AR5 Shot Starting delay | AR5 Shot DeadTime delay | AR5 Shot Arc or Discr. | AR5 Shot Action time | AR5 Shot Reclaim time |
| | Disabled | | | | | |
| | AR5 Shot 2 | Disabled | | | | |
| | AR5 Shot 3 | Disabled | | | | |
| | AR5 Shot 4 | Disabled | | | | |
| | AR5 Shot 5 | Disabled | | | | |

The auto-recloser function's shot settings are grouped into corresponding rows to make the setting of each shot straightforward. From the settings the user can see how the reclosing cycle is executed by each request, which functions initiate requests, and which shots and requests are in use.

The setting example in the image above presents a two-shot auto-recloser. One can see that the REQ1 is started by I> START signal. The starting delay is 500 ms, followed by a 200 ms dead time; after a 200 ms "Arcing" time and a 10 s reclaim time Shot 1 is executed. If Shot 1 fails, there is a 120 s dead time, a 200 ms "Arcing" time and a 10 s reclaim time before Shot 2 is executed. If Shot 2 fails, the auto-recloser initiates the Final Trip. In REQ2, the settings are otherwise the same, except I> TRIP and I0dir> TRIP are used to activate the request, Shot 1 does not have a starting delay, the dead time delay for Shot 2 is different and the action time for both shots is zero. REQ3 has just one shot with a 60 second dead time and a 30 ms shot reclaim. If REQ4 or REQ5 are activated, no shots are executed as none are set.

Inhibit and Locked states of the auto-recloser function

The auto-recloser function can have several reasons to go into "Lock-out" and "Inhibit" states where reclosing cannot be allowed for some reason. When the function enters the "Not ready" state, it gives an indication of the reason why it cannot be in the "Ready" state in order to quickly rectify whatever is causing the problem of the functions operation. The reason is indicated in the auto-recloser function's *Registers* menu.

The Inhibit reasons for the auto-recloser are the following:

- AR is blocked (from Blocking input)
- AR is not enabled (signal connected to "AR ON/OFF" is not active)
- AR is calculating the lock-out delay
- The object "Open" or "Close" command is blocked
- The object status is not known ("intermediate" or "bad" status)
- General reclaim time is running
- AR is locked

When the auto-recloser function is in the "Inhibit" state, it returns to the "Ready" state when the reason for the inhibition is removed.

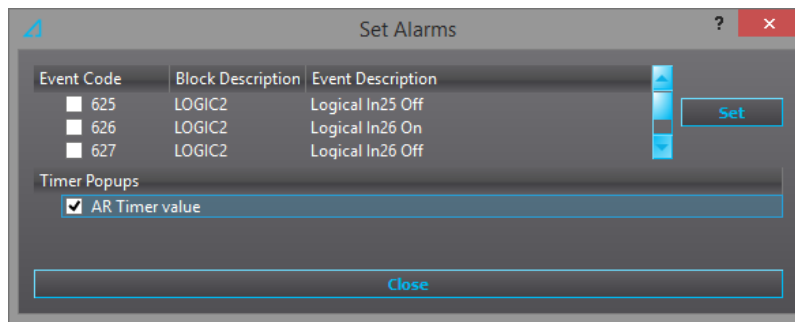
The Lock-out reasons for the auto-recloser are the following:

- The "AR Locked" signal is initiated (from "AR Locking" input)
- The Final Trip signal is given
- The "object not ready" failed within a given time (from Object)
- The "object no sync" failed within a given time (from Object)
- The object's "Open" timeout (from Object)
- The object's "Close" timeout (from Object)
- AR request initiated during General reclaim time
- AR request was not released during Dead Time
- Critical request initiated in any state of the auto-reclosing cycle

When the auto-recloser function is in the "Locked" state, it can be recovered only through by reset input, or by manually resetting the breaker. This depends on what the "Require manual resetting" parameter's setting is.

Displaying auto-reclosing timers in MIMIC view

The user can enable timers to be displayed in the MIMIC view. Enable the AR timer value at *Tools* → *Events and logs* → *Set alarm events* (see the image below). The timer displays the reclaim time and the dead time delay.



Events and registers

The auto-recloser function (abbreviated "AR" in event block names) generates events and registers from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

Table. 4.5.5 - 129. Event messages.

| Event block name | Event names |
|------------------|---|
| AR1 | AR Ready ON |
| AR1 | AR Ready OFF |
| AR1 | AR Locked reset |
| AR1 | AR Reclosing request rejected ON |
| AR1 | AR Reclosing request rejected OFF |
| AR1 | AR Reclosing request ON |
| AR1 | AR Reclosing request OFF |
| AR1 | User-operated Object AR halted and reset |
| AR1 | Object failure, AR locked |
| AR1 | Shot failed |
| AR1 | AR cycle ends due to a discrimination request |
| AR1 | AR Shot clear |
| AR1 | Object "Close" request |
| AR1 | Object "Open" request |
| AR1 | Inhibit condition ON |
| AR1 | Inhibit condition OFF |
| AR1 | Locking condition ON |
| AR1 | Locking condition OFF |
| AR1 | Reserved |
| AR1 | AR1 Request ON |

| Event block name | Event names |
|------------------|--|
| AR1 | AR1 Request OFF |
| AR1 | AR2 Request ON |
| AR1 | AR2 Request OFF |
| AR1 | AR3 Request ON |
| AR1 | AR3 Request OFF |
| AR1 | AR4 Request ON |
| AR1 | AR4 Request OFF |
| AR1 | AR5 Request ON |
| AR1 | AR5 Request OFF |
| AR1 | Critical request ON |
| AR1 | Critical request OFF |
| AR1 | AR Running ON |
| AR1 | AR Running OFF |
| AR1 | Shot 1 Execute ON |
| AR1 | Shot 1 Execute OFF |
| AR1 | Shot 2 Execute ON |
| AR1 | Shot 2 Execute OFF |
| AR1 | Shot 3 Execute ON |
| AR1 | Shot 3 Execute OFF |
| AR1 | Shot 4 Execute ON |
| AR1 | Shot 4 Execute OFF |
| AR1 | Shot 5 Execute ON |
| AR1 | Shot 5 Execute OFF |
| AR1 | Sequeunce finished, the Final trip armed |
| AR1 | Final trip executed |
| AR1 | Lock-out time ON |
| AR1 | Lock-out time OFF |
| AR1 | General reclaim time ON |
| AR1 | General reclaim time OFF |
| AR1 | Shot start time ON |
| AR1 | Shot start time OFF |

| Event block name | Event names |
|------------------|----------------------------|
| AR1 | Dead time ON |
| AR1 | Dead time OFF |
| AR1 | Arc Discr time ON |
| AR1 | Arc Discr time OFF |
| AR1 | Shot reclaim time ON |
| AR1 | Shot reclaim time OFF |
| AR1 | Sequence finished OFF |
| AR1 | Final trip executed OFF |
| AR1 | Object "Close" request OFF |
| AR1 | AR ON |
| AR1 | AR OFF |
| AR1 | AR Running (DT) ON |
| AR1 | AR Running (DT) OFF |

The function registers its operation into the last twelve (12) time-stamped registers. The register of the function records the ON event process data from statuses, commands, etc.

The table below presents the structure of the auto-recloser function's register content.

Table. 4.5.5 - 130. Register content.

| Register | Description |
|---------------------------|---|
| Date and time | dd.mm.yyyy hh:mm:ss.mss |
| Event | Event name |
| Setting group in use | 1...8 |
| Inhibit condition active | Inhibit reason ON |
| Inhibit condition release | Inhibit reason OFF |
| Locked condition active | Locked reason ON |
| Locked condition release | Locked reason OFF |
| AR status | The status code of the auto-recloser function |
| Active timer | Timer ON |
| Active time | The value of the timer |

The auto-recloser function's registers are treated differently than the registers of other functions.

Below is an exhaustive example of how the registers work based on a partial auto-recloser sequence. First is how the register list is displayed:

| Date and time | Registers |
|----------------------------|---|
| dd.mm.yyyy hh:mm:ss.mss | AR Status: AR is ready, AR is not running, AR2 Requested, Executing Shot 1 AR Timers: No timers running 0.000 s |
| dd.mm.yyyy hh:mm:ss.mss | AR Status: AR is ready, AR is not running, Start time counting, AR2 Requested, Executing Shot 1 AR Timers: Start Delay 0.000 s |
| dd.mm.yyyy hh:mm:ss.mss | AR Status: AR is ready, AR is running, Start time counting, AR2 Requested, Executing Shot 1 AR Timers: Start Delay 0.000 s |
| dd.mm.yyyy hh:mm:ss.mss | AR Status: AR is ready, AR is running, Dead time counting, AR2 Requested, Executing Shot 1 AR Timers: Dead Time 0.195 s |
| dd.mm.yyyy hh:mm:ss.mss | AR Status: AR is ready, AR is running, Dead time counting, Reclaim time counting, AR2 Requested, Executing Shot1 AR Timers: Dead Time -0.270 s |

The corresponding event list is as presented below (inc. object and protection events):

| | | |
|-------------------------|------|------------------------------|
| dd.mm.yyyy hh:mm:ss.mss | 1664 | NEF1 Start ON |
| dd.mm.yyyy hh:mm:ss.mss | 1666 | NEF1 Trip ON |
| dd.mm.yyyy hh:mm:ss.mss | 4065 | AR1 Shot 1 Execute ON |
| dd.mm.yyyy hh:mm:ss.mss | 4037 | AR1 AR Reclosing request ON |
| dd.mm.yyyy hh:mm:ss.mss | 4053 | AR1 AR2 Request ON |
| dd.mm.yyyy hh:mm:ss.mss | 4081 | AR1 Shot start time ON |
| dd.mm.yyyy hh:mm:ss.mss | 4045 | AR1 Object "Open" request |
| dd.mm.yyyy hh:mm:ss.mss | 2944 | OBJ1 Object Intermediate |
| dd.mm.yyyy hh:mm:ss.mss | 2952 | OBJ1 Open request ON |
| dd.mm.yyyy hh:mm:ss.mss | 2955 | OBJ1 Open command ON |
| dd.mm.yyyy hh:mm:ss.mss | 4063 | AR1 AR Running ON |
| dd.mm.yyyy hh:mm:ss.mss | 2954 | OBJ1 Open request OFF |
| dd.mm.yyyy hh:mm:ss.mss | 1665 | NEF1 Start OFF |
| dd.mm.yyyy hh:mm:ss.mss | 1667 | NEF1 Trip OFF |
| dd.mm.yyyy hh:mm:ss.mss | 4038 | AR1 AR Reclosing request OFF |
| dd.mm.yyyy hh:mm:ss.mss | 2945 | OBJ1 Open request |
| dd.mm.yyyy hh:mm:ss.mss | 2956 | OBJ1 Open command OFF |
| dd.mm.yyyy hh:mm:ss.mss | 4082 | AR1 Shot start time OFF |
| dd.mm.yyyy hh:mm:ss.mss | 4083 | AR1 Dead time ON |
| dd.mm.yyyy hh:mm:ss.mss | 2963 | OBJ1 Status change OFF |

| | | |
|-------------------------|------|----------------------------|
| dd.mm.yyyy hh:mm:ss.mss | 4044 | AR1 Object "Close" request |
| dd.mm.yyyy hh:mm:ss.mss | 2957 | OBJ1 Close request ON |
| dd.mm.yyyy hh:mm:ss.mss | 2958 | OBJ1 Close Fail |
| dd.mm.yyyy hh:mm:ss.mss | 2959 | OBJ1 Close request OFF |
| dd.mm.yyyy hh:mm:ss.mss | 2960 | OBJ1 Close command ON |
| dd.mm.yyyy hh:mm:ss.mss | 2962 | OBJ1 Status change ON |
| dd.mm.yyyy hh:mm:ss.mss | 2944 | OBJ1 Object Intermediate |
| dd.mm.yyyy hh:mm:ss.mss | 2946 | OBJ1 Object Close |
| dd.mm.yyyy hh:mm:ss.mss | 2961 | OBJ1 Close command OFF |
| dd.mm.yyyy hh:mm:ss.mss | 4087 | AR1 Shot reclaim time ON |

As these tables show, the register list complement the information from event lists when the control has encountered some unexpected behavior. The example above shows that the object had issues executing the "Close" command, which caused the dead time to be 270 ms longer than its set value. The reason for this behavior can be verified from the object control and monitoring function's registers.

The example below shows that the object was not ready when it received the closing request from the auto-recloser function and kept the request pending until it was ready to execute the "Close" command.

| | |
|----------------------------|--|
| dd.mm.yyyy hh:mm:ss.mss | Object Open, WD In, Open Allowed, Close Allowed, Object Ready, Sync Ok, Obj open time: 0.025 s |
| dd.mm.yyyy hh:mm:ss.mss | Object Open, WD In, Object not ready for Close request, Open Allowed, Close Allowed, Object Not Ready, Sync Ok |
| dd.mm.yyyy hh:mm:ss.mss | Object Open, WD In, Close request from Auto-recloser, Close pending due to: Close wait for Ready, Open Allowed, Close Allowed, Object Not Ready, Sync Ok |
| dd.mm.yyyy hh:mm:ss.mss | Object Open, WD In, Open Allowed, Close Allowed, Object Ready, Sync Ok |
| dd.mm.yyyy hh:mm:ss.mss | Object Closed, WD In, Open Allowed, Close Allowed, Object Ready, Sync Ok, Obj close time: 0.030 s |

Auto-recloser operation counters

The auto-recloser function keeps statistical track of the operated auto-reclosing cycles as well as of successful and failed shots.

The function records the following counters:

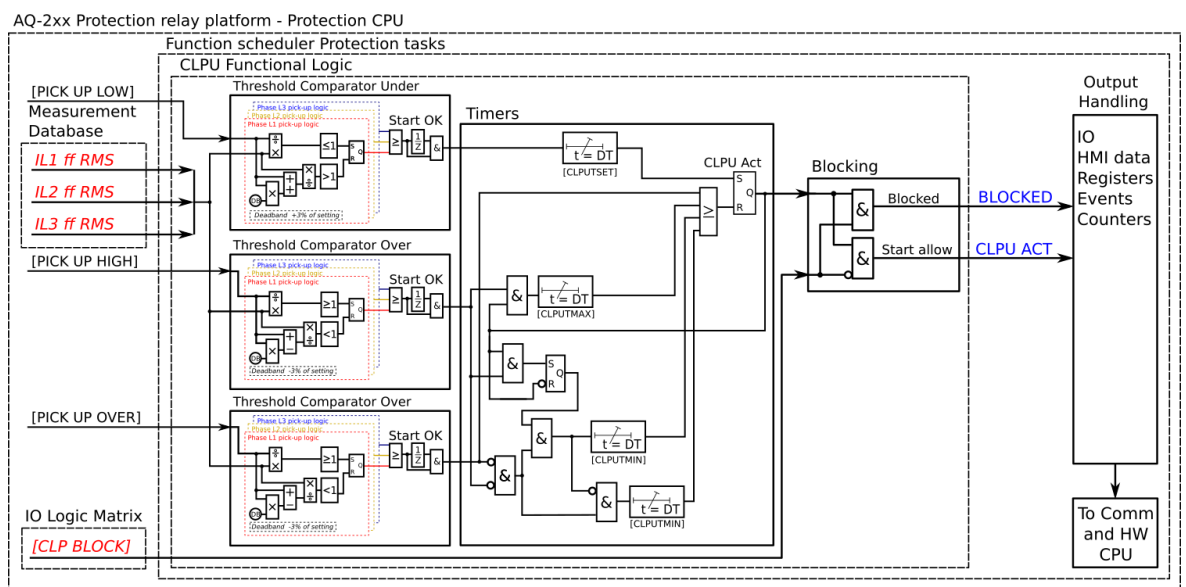
- Shot 1...5 started
- Shot 1...5 requested by AR1...5
- Shots failed
- Final trips
- Shots cleared
- AR started

The counters are cumulative and they update automatically according to the operations of the auto-recloser function. They can be found in the *Statistics* tab at *Control* → *Auto-recloser* → *Registers*.

4.5.6 Cold load pick-up (CLPU)

The cold load pick-up function is used for detecting so-called cold load situations, where a loss of load diversity has occurred after distribution has been re-energized. The characteristics of cold load situations vary according to the types of loads individual feeders have. This means that this function needs to be set specifically according to the load type of the feeder it is monitoring. For example, in residential areas there are relatively many thermostat-controlled devices (such as heating and cooling machinery) which normally run in asynchronous cycles. When restoring power after a longer power outage, these devices demand the full start-up power which can cause the inrush current to be significantly higher than what the load current was before the outage. This is uncommon in industrial environments since the restoring of the production process takes several hours, or even days, and the power level goes back to the level it was before the outage. However, some areas of the industrial network may find the cold load pick-up function useful.

Figure. 4.5.6 - 143. Simplified function block diagram of the cold load pick-up function.



Measured input

The function block uses fundamental frequency component of phase current measurement values.

Table. 4.5.6 - 131. Measurement inputs of the cold load pick-up function.

| Signal | Description | Time base |
|-------------|---|-----------|
| I_{L1RMS} | Fundamental frequency component of phase L1 (A) current | 5ms |
| I_{L2RMS} | Fundamental frequency component of phase L2 (B) current | 5ms |
| I_{L3RMS} | Fundamental frequency component of phase L3 (C) current | 5ms |

Pick-up settings

The I_{low} , I_{high} and I_{over} setting parameters control the the pick-up and activation of the cold load pick-up function. They define the maximum and minimum allowed measured current before action from the function. The function constantly calculates the ratio between the setting values and the measured magnitude (I_m) for each of the three phases. The reset ratio of 97 % is built into the function and is always relative to the setting value. The setting value is common for all measured phases. When the I_m exceeds the setting value (in single, dual or all phases) it triggers the pick-up operation of the function.

Setting group selection controls the operating characteristics of the function, i.e. the user or user-defined logic can change function parameters while the function is running.

Table. 4.5.6 - 132. Pick-up settings.

| Name | Range | Step | Default | Description |
|------------|-----------------|---------|---------|---|
| I_{low} | 0.01...40.00×In | 0.01×In | 0.20×In | The pick-up setting for low current detection. All measured currents must be below this setting in order for the cold load pick-up signal to be activated. |
| I_{high} | 0.01...40.00×In | 0.01×In | 1.20×In | The pick-up setting for high current detection. All measured currents must exceed this setting in order for the cold load pick-up signal to be activated. |
| I_{over} | 0.01...40.00×In | 0.01×In | 2.00×In | The pick-up setting for overcurrent detection. If this setting is exceeded by any of the measured currents, the cold load pick-up signal is released immediately. |

Read-only parameters

The function's *Info* page displays useful, real-time information on the state of the protection function. It is accessed either through the device's HMI display, or through the setting tool software when it is connected to the device and its Live Edit mode is active.

Table. 4.5.6 - 133. Information displayed by the function.

| Name | Range | Description |
|---------------|---|--|
| CLP condition | <ul style="list-style-type: none"> • Normal • Curr low • Overcurrent On • CLPU On • CLPU blocked | Displays status of the control function. |

Function blocking

The block signal is checked in the beginning of each program cycle. The blocking signal is received from the blocking matrix in the function's dedicated input. If the blocking signal is not activated when the pick-up element activates, a CLPU ACT signal is generated and the function proceeds to the time characteristics calculation.

If the blocking signal is active when the pick-up element activates, a BLOCKED signal is generated and the function does not process the situation further. If the CLPU ACT function has been activated before the blocking signal, it resets and processes the release time characteristics similarly to when the pick-up signal is reset.

The variables the user can set are binary signals from the system. The blocking signal needs to reach the device minimum of 5 ms before the set operating delay has passed in order for the blocking to activate in time.

Operating time characteristics

The behavior of the function's operating timers can be set for activation as well as for the situation monitoring and release of the cold load pick-up.

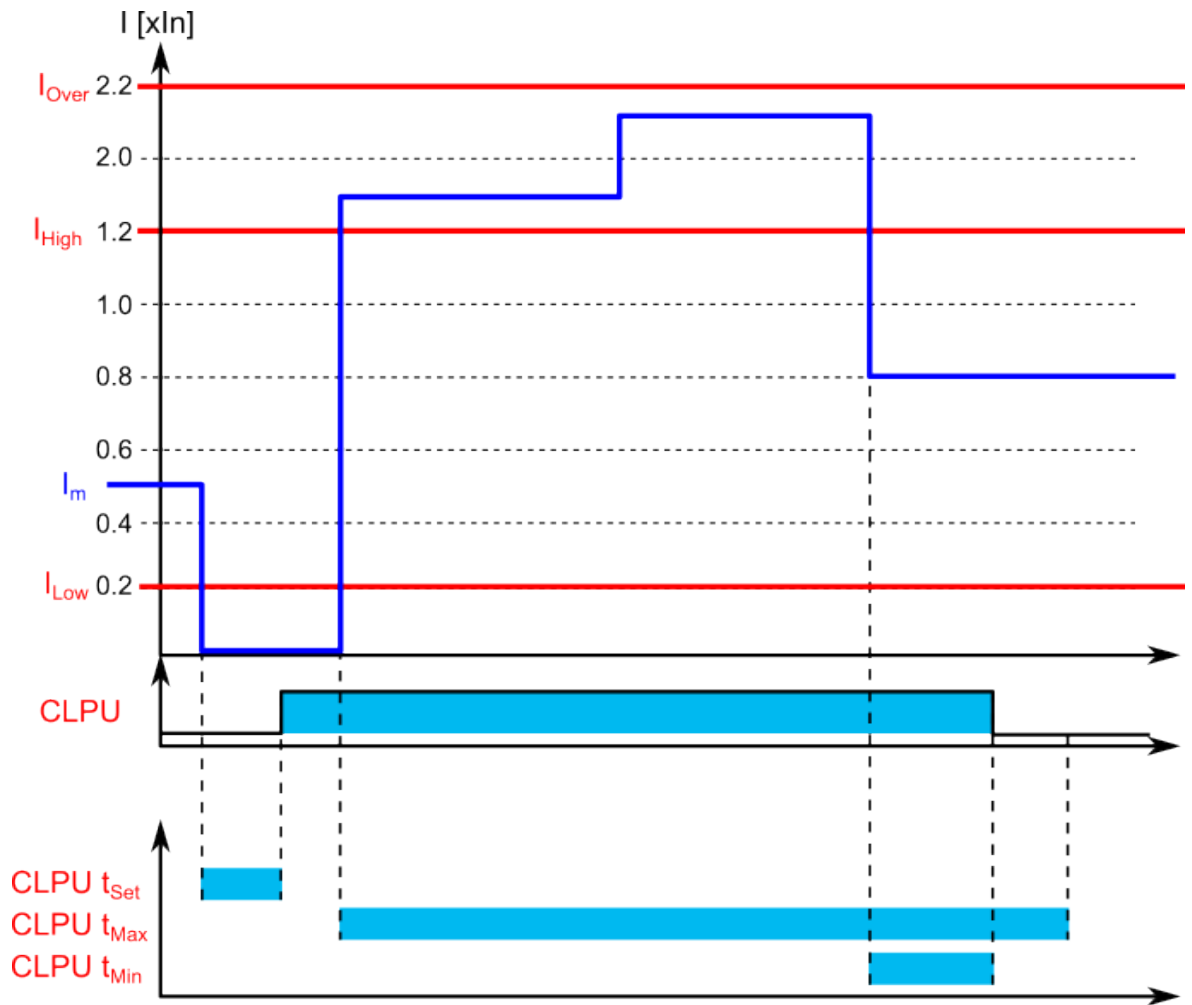
The table below presents the setting parameters for the function's time characteristics.

Table. 4.5.6 - 134. Setting parameters for operating time characteristics.

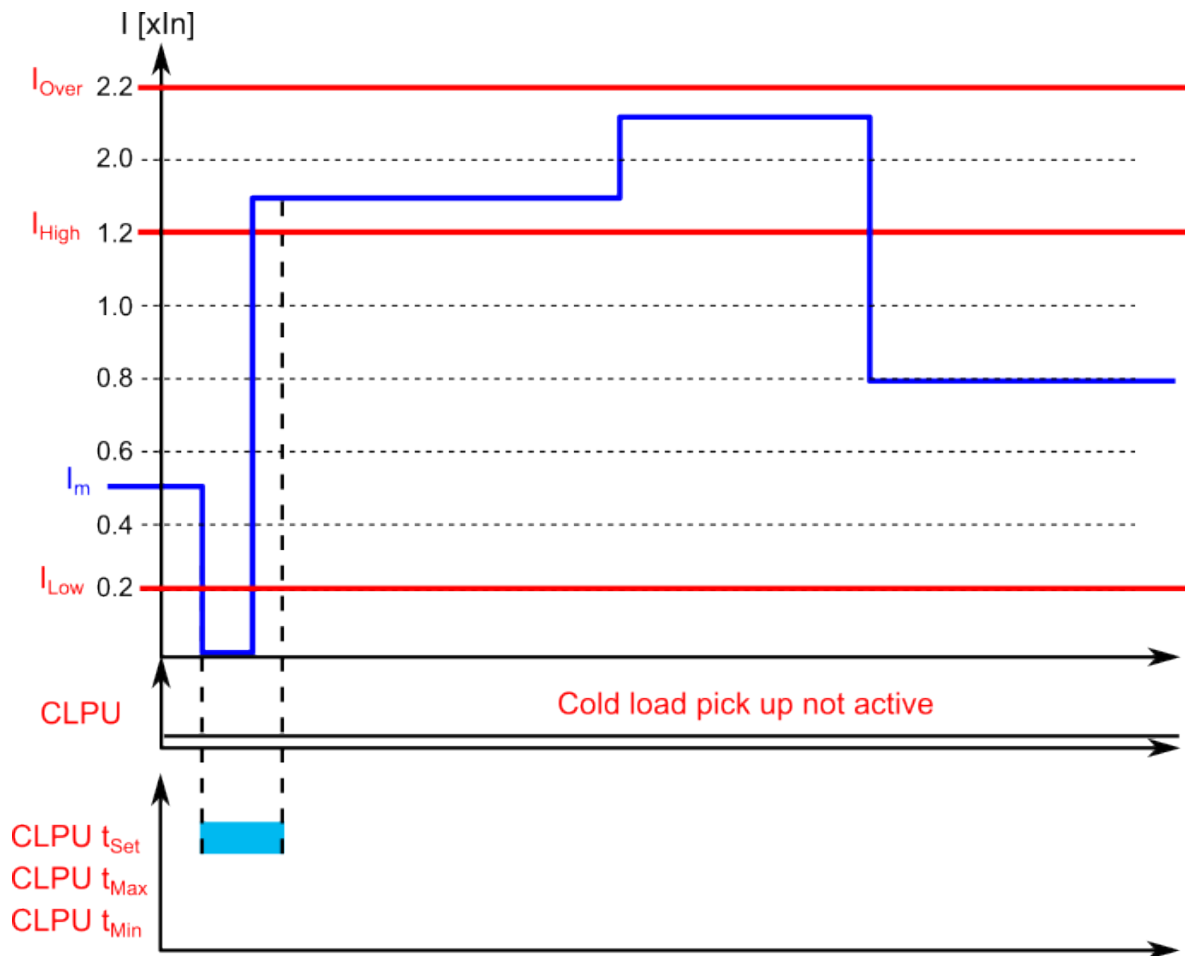
| Name | Range | Step | Default | Description |
|------------------|-------------------|--------|---------|---|
| T _{set} | 0.000...1800.000s | 0.005s | 10.000s | The function's start timer which defines how long the <i>I_{low}</i> condition has to last before the cold load pick-up is activated. |
| T _{max} | 0.000...1800.000s | 0.005s | 30.000s | The function's maximum timer which defines how long the starting condition can last and for how long the current is allowed to be over <i>I_{high}</i> . |
| T _{min} | 0.000...1800.000s | 0.005s | 0.040s | The function's minimum timer which defines how long the starting condition has to last at the minimum. If the start-up sequence includes more than one inrush situation, this parameter may be used to prolong the cold load pick-up time over the first inrush. Additionally, this parameter operates as the "reclaim" time for the function in case the inrush current is not immediately initiated in the start-up sequence. |

The six examples below showcase some typical cases with the cold load pick-up function.

Figure. 4.5.6 - 144. Example of timers and pick-up parameters (normal CLPU situation).

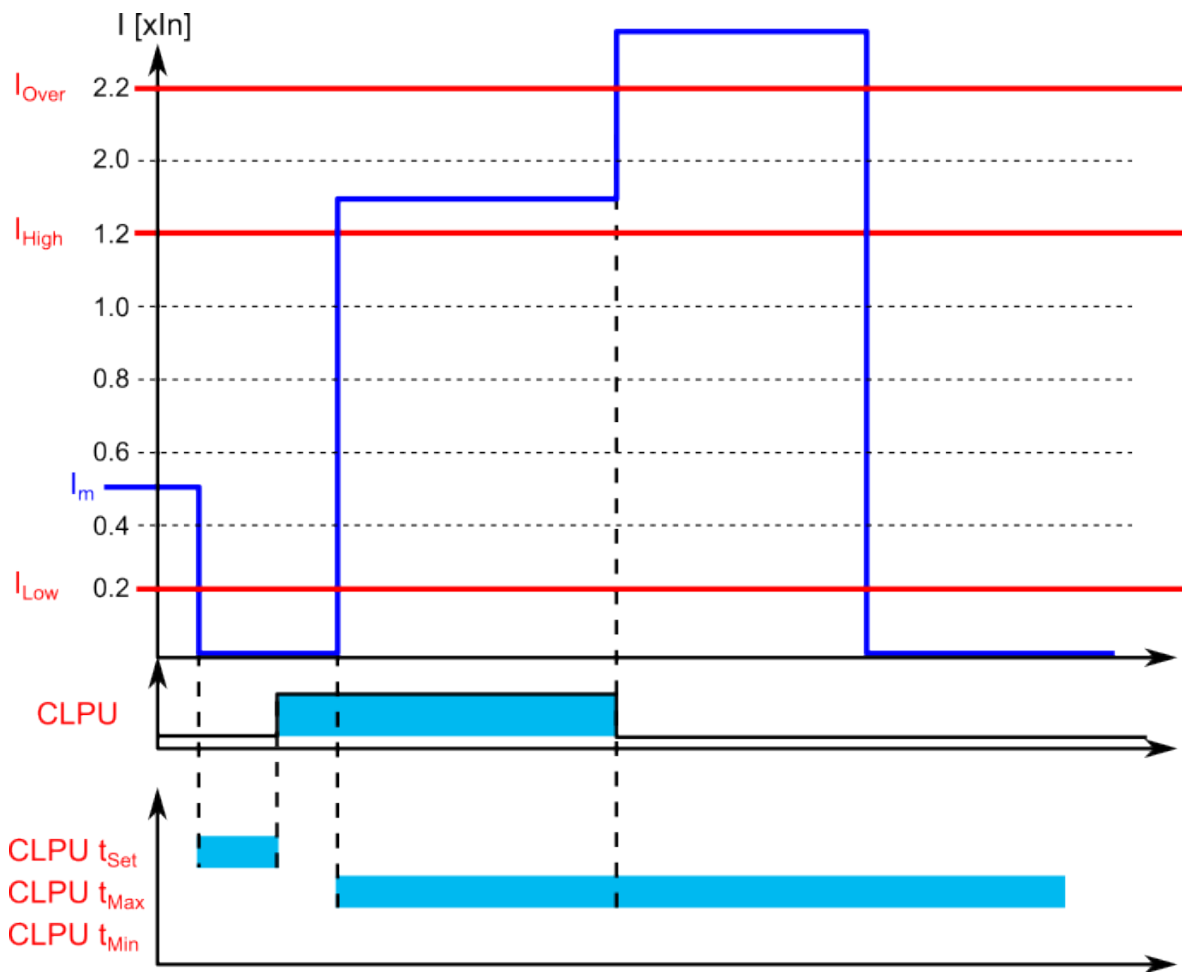


In the example above, the cold load pick-up function activates after the measured current dips below the I_{Low} setting and has been there for T_{Set} amount of time. When the current exceeds the I_{High} setting value, a timer starts counting towards the T_{Max} time. The pick-up current is cleared before the the counter reaches the T_{Max} time, when the measured current goes between of I_{Low} and the I_{High} . This is when the start-up condition is considered to be over. The cold load pick-up signal can be prolonged beyond this time by setting the T_{Min} to a value higher than 0.000 s.

Figure. 4.5.6 - 145. Example of timers and pick-up parameters (no cold load pick-up, I_{low} too short).

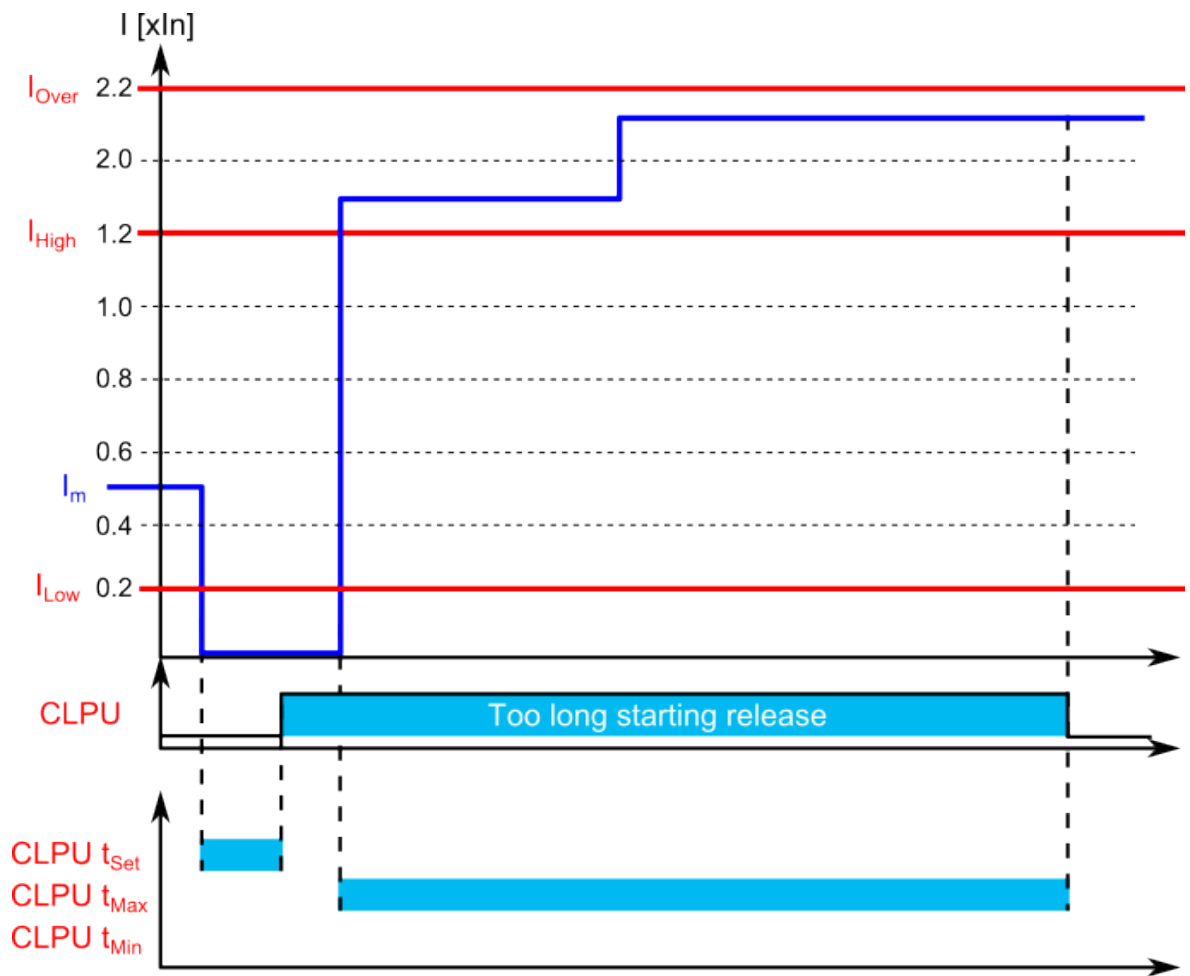
In the example above, the cold load pick-up function does not activate even when the measured current dips below the I_{low} setting, because the T_{set} is not exceeded and therefore no cold load pick-up signal is issued. If the user wants the function to activate within a shorter period of time, the T_{set} parameter can be set to a lower value. If the user wants no delay, the T_{set} can be zero seconds and the operation will be immediate.

Figure. 4.5.6 - 146. Example of timers and pick-up parameters (activated pick-up and instant release due to overcurrent).



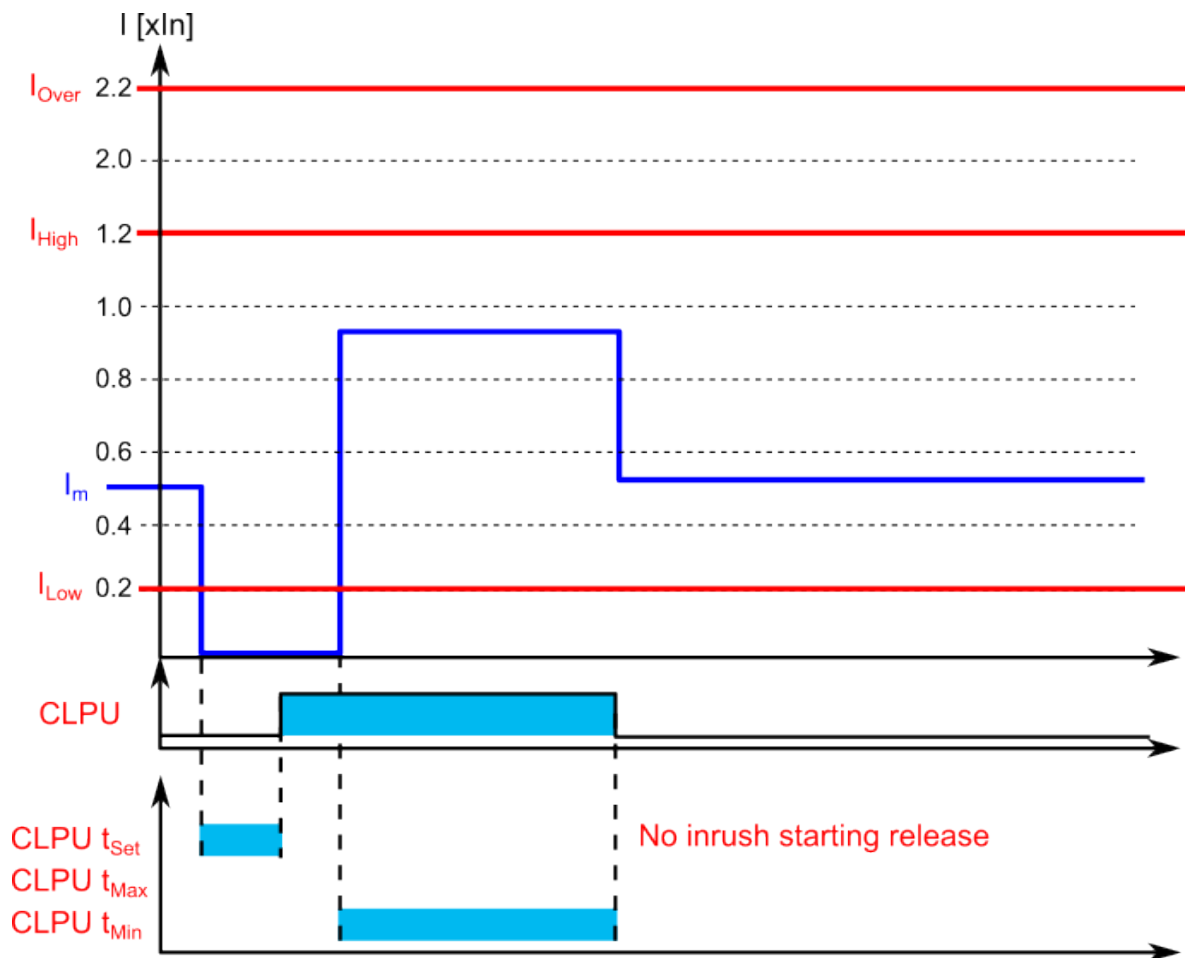
In the example above, the cold load pick-up function activates after the measured current dips below the I_{Low} setting and has been there for T_{Set} amount of time. When the I_m exceeds the I_{High} setting, a counter starts counting towards the T_{Max} time. The measured current exceeds the I_{Over} setting during the start-up situation and causes the cold load pick-up signal to be released immediately.

Figure. 4.5.6 - 147. Example of timers and pick-up parameters (activated pick-up and instant release due to too long starting).



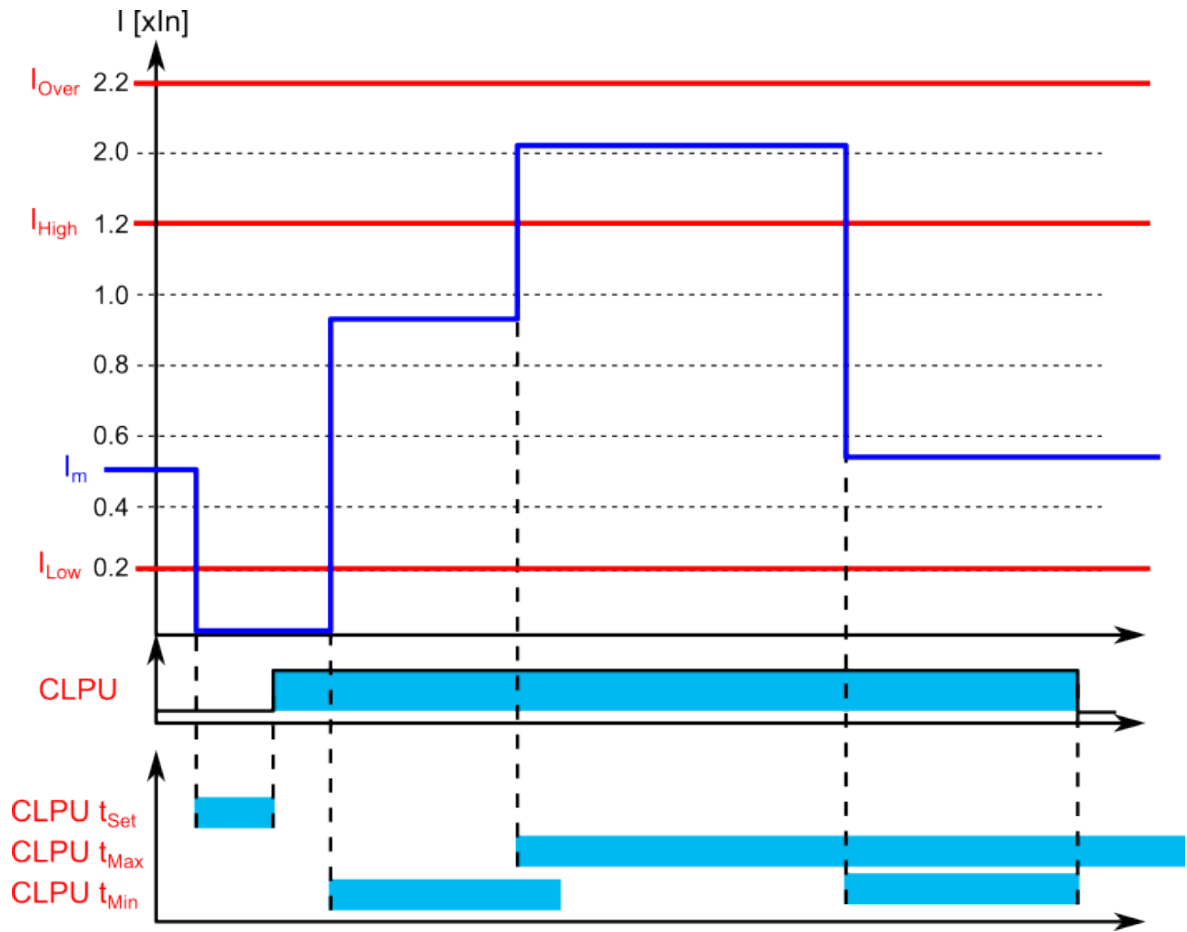
In the example above, the cold load pick-up function activates after the measured current has stayed below the I_{low} setting for a T_{set} amount of time. When the current exceeds the I_{high} setting, a timer starts counting towards the T_{max} time. The measured current stays above the I_{high} setting until the T_{max} is reached, which causes the release of the cold load pick-up signal.

Figure. 4.5.6 - 148. Example of timers and pick-up parameters (no inrush current detected in the starting).



In the example above, the cold load pick-up function activates after the measured current has stayed below the I_{Low} setting for a T_{set} amount of time. The current stays between the I_{Low} setting and the I_{High} setting, so the cold load pick-up signal is active for T_{min} time. As no inrush current is detected during that time, the signal is released.

Figure. 4.5.6 - 149. Example of timers and pick-up parameters (an inrush current detected during T_{min} time).



In the example above, the cold load pick-up function activates after the measured current has stayed below the I_{low} setting for a T_{set} amount of time. The current increases to between the I_{low} setting and the I_{high} setting, which causes a counter to start counting towards the T_{min} time. Before the counter reaches T_{min} , the current exceeds the I_{high} setting, which causes a counter to start counting towards the T_{max} time. The cold load pick-up signal remains active until the T_{max} has been reached, or until the start-up is over and the T_{min} time is over.

Events and registers

The cold load pick-up function (abbreviated "CLP" in event block names) generates events and registers from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

The function's outputs can be used for direct I/O controlling and user logic programming. The function also provides a resettable cumulative counter for the CLPU ACT and BLOCKED events.

Table. 4.5.6 - 135. Event messages.

| Event block name | Event names |
|------------------|--------------|
| CLP1 | LowStart ON |
| CLP1 | LowStart OFF |
| CLP1 | HighStart ON |

| Event block name | Event names |
|------------------|-------------------|
| CLP1 | HighStart OFF |
| CLP1 | LoadNormal ON |
| CLP1 | LoadNormal OFF |
| CLP1 | Overcurrent ON |
| CLP1 | Overcurrent OFF |
| CLP1 | CLPUActivated ON |
| CLP1 | CLPUActivated OFF |
| CLP1 | Block ON |
| CLP1 | Block OFF |

The function registers its operation into the last twelve (12) time-stamped registers. The register of the function records the ON event process data for ACTIVATED, BLOCKED, etc. The table below presents the structure of the function's register content.

Table. 4.5.6 - 136. Register content.

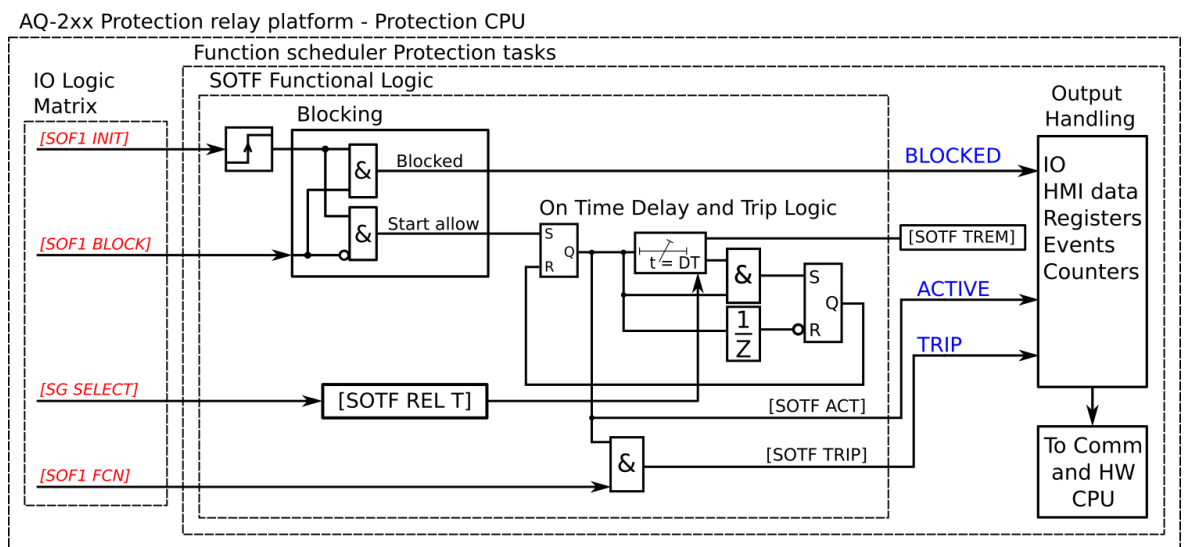
| Register | Description |
|------------------------|---|
| Date and time | dd.mm.yyyy hh:mm:ss.mss |
| Event | Event name |
| L1/L2/L3 current | Phase currents on trigger time |
| Time to CLPUact | Time remaining before the function is active |
| CLPU active time | The time the function has been active before starting |
| Start-up time | Recorded starting time |
| Releasing time of CLPU | Reclaim time counter |
| Setting group in use | Setting group 1...8 active |

4.5.7 Switch-on-to-fault (SOTF)

The switch-on-to-fault (SOTF) function is used for speeding up the tripping when the breaker is closed towards a fault or forgotten earthing to reduce the damage in the fault location. The function can be used to control protection functions, or it can be used to directly trip a breaker if any of the connected protection functions starts during the set SOTF time. The operation of the function is instant after the conditions are met and any one signal connected to the "*Function input*" input activates.

The function can be initiated by a digital input, or by a circuit breaker "Close" command connected to the "*SOTF activate input*" input. The duration of the SOTF-armed condition can be set by the "Release time for SOTF" setting parameter; it can be changed if the application so requires through setting group selection.

Figure. 4.5.7 - 150. Simplified function block diagram of the switch-on-to-fault function.



Input signals

The function block does not use analog measurement inputs. Instead, its operation is based entirely on binary signal statuses.

Table. 4.5.7 - 137. Input signals.

| Input | Description |
|----------------|--|
| Activate input | The digital input or logic signal for the function to arm and start calculating the SOTF time. Any binary signal can be used to activate the function and start the calculation. The rising edge of the signal is considered as the start of the function. |
| Block input | The input for blocking the function. Any binary signal can be used to block the function from starting. |
| Function input | The function input activates the function's instant trip if applied when the function is calculating the SOTF time. |

Settings

The switch-on-to-fault function has one setting and it determines how long the function remains active after it has been triggered. If the inputs receive any of the set signals during this time, the function's trip is activated.

Setting group selection controls the operating characteristics of the function, i.e. the user or user-defined logic can change function parameters while the function is running.

Table. 4.5.7 - 138. Settings of the function.

| Name | Range | Default | Description |
|----------------------|---|---------|--|
| SOTF force status to | <ul style="list-style-type: none"> Normal Blocked Active Trip | Normal | Force the status of the function. Visible only when <i>Enable stage forcing</i> parameter is enabled in <i>General</i> menu. |

| Name | Range | Default | Description |
|-----------------------|-------------------|---------|---|
| Release time for SOTF | 0.000...1800.000s | 1.000s | The time the function is active after triggering. |

Read-only parameters

The function's *Info* page displays useful, real-time information on the state of the protection function. It is accessed either through the device's HMI display, or through the setting tool software when it is connected to the device and its Live Edit mode is active.

Table. 4.5.7 - 139. Information displayed by the function.

| Name | Range | Description |
|----------------|---|--|
| SOTF condition | <ul style="list-style-type: none"> • Normal • Init • Active • Trip • Blocked | Displays status of the control function. |

Function blocking

The function can be blocked by activating the BLOCK input. This prevents the function's active time from starting.

Events and registers

The switch-on-to-fault function (abbreviated "SOF" in event block names) generates events and registers from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

The function's outputs can be used for direct I/O controlling and user logic programming. The function also provides a resettable cumulative counter for the INIT, BLOCKED, ACTIVE and TRIP events.

Table. 4.5.7 - 140. Event messages.

| Event block name | Event names |
|------------------|-----------------|
| SOF1 | SOTF Init ON |
| SOF1 | SOTF Init OFF |
| SOF1 | SOTF Block ON |
| SOF1 | SOTF Block OFF |
| SOF1 | SOTF Active ON |
| SOF1 | SOTF Active OFF |
| SOF1 | SOTF Trip ON |
| SOF1 | SOTF Trip OFF |

The function registers its operation into the last twelve (12) time-stamped registers. The register of the function records the ON process data of ACTIVATED events. The table below presents the structure of the function's register content.

Table. 4.5.7 - 141. Register content.

| Register | Description |
|-----------------------|---|
| Date and time | dd.mm.yyyy hh:mm:ss.mss |
| Event | Event name |
| Used SG | Setting group 1...8 active |
| SOTF remaining time | The time remaining of the set release time. |
| SOTF been active time | The time the function has been active. |

4.5.8 Milliampere output control

The milliamp current loop is the prevailing process control signal in many industries. It is an ideal method of transferring process information because a current does not change as it travels from a transmitter to a receiver. It is also much more simple and cost-effective.

The benefits of 4...20 mA loops:

- the dominant standard in many industries
- the simplest option to connect and configure
- uses less wiring and connections than other signals, thus greatly reducing initial setup costs
- good for travelling long distances, as current does not degrade over long connections like voltage does
- less sensitive to background electrical noise
- detects a fault in the system incredibly easily since 4 mA is equal to 0 % output.

Milliampere (mA) outputs

AQ-200 series supports up to two (2) independent mA option cards. Each card has four (4) mA output channels and one (1) mA input channel. If the device has an mA option card, enable mA outputs at *Control* → *Device IO* → *mA outputs*. The outputs are activated in groups of two: channels 1 and 2 are activated together, as are channels 3 and 4.

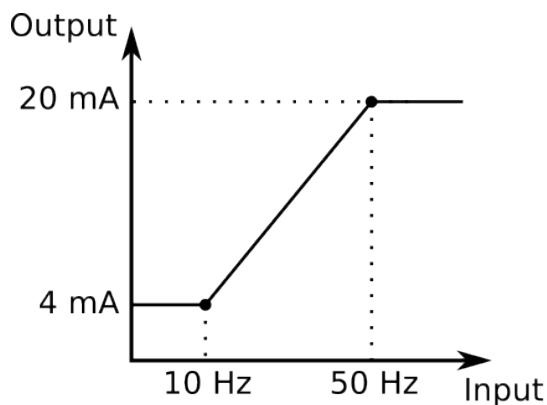
Table. 4.5.8 - 142. Main settings (output channels).

| Name | | Range | Default | Description |
|------------------|-----------------------------------|---|----------|---|
| mA option card 1 | Enable mA output channels 1 and 2 | <ul style="list-style-type: none"> • Disabled • Enabled | Disabled | Enables and disables the outputs of the mA output card 1. |
| | Enable mA output channels 3 and 4 | | | |
| mA option card 2 | Enable mA output channels 5 and 6 | <ul style="list-style-type: none"> • Disabled • Enabled | Disabled | Enables and disables the outputs of the mA output card 2. |
| | Enable mA output channels 7 and 8 | | | |

Table. 4.5.8 - 143. Settings for mA output channels.

| Name | Range | Step | Default | Description |
|---|---|----------|---|--|
| Enable mA output channel | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Enables and disables the selected mA output channel. If the channel is disabled, the channel settings are hidden. |
| Magnitude selection for mA output channel | <ul style="list-style-type: none"> Currents Voltages Powers Impedance and admittance Other | - | Currents | Defines the measurement category that is used for mA output control. |
| Magnitude of mA output channel | (dependent on the measurement category selection) | - | (dependent on the measurement category selection) | Defines the measurement magnitude used for mA output control. The available measurements depend on the selection of the "Magnitude selection for mA output channel" parameter. |
| Input value 1 | $-10^7 \dots 10^7$ | 0.001 | 0 | The first input point in the mA output control curve. |
| Scaled mA output value 1 | 0.0000...24.0000mA | 0.0001mA | 0mA | The mA output value when the measured value is equal to or less than Input value 1. |
| Input value 2 | $-10^7 \dots 10^7$ | 0.001 | 1 | The second input point in the mA output control curve. |
| Scaled mA output value 2 | 0.0000...24.0000mA | 0.0001mA | 0mA | The mA output value when the measured value is equal to or greater than Input value 2. |

Figure. 4.5.8 - 151. Example of the effects of mA output channel settings.



The screenshot shows the configuration for mA Output Channel 1. The settings are as follows:

- Enable mA Out Channel 1:** Enabled
- mA Out Channel 1 Magnitude selection:** Others
- mA Out Channel 1 Magnitude (Others):** System f.
- Input value 1:** 10
- Scaled mA output value 1:** 4 mA
- Input value 2:** 50
- Scaled mA output value 2:** 20 mA
- mA Out Channel 1 Input Magnitude now:** 0
- mA Out Channel 1 Outputs now:** 0 mA

Table. 4.5.8 - 144. Hardware indications.

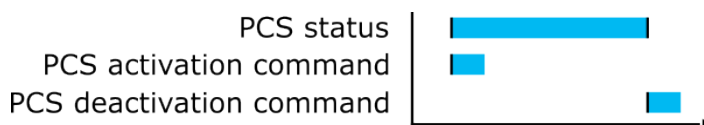
| Name | Range | Description |
|--------------------------------------|--|---|
| Hardware in mA output channels 1...4 | <ul style="list-style-type: none"> • None • Slot A • Slot B • Slot C • Slot D • Slot E • Slot F | Indicates the option card slot where the mA output card is located. |
| Hardware in mA output channels 5...8 | | |

Table. 4.5.8 - 145. Measurement values reported by mA output cards.

| Name | Range | Step | Description |
|------------------------------------|--------------------|----------|---|
| mA in Channel 1 | 0.0000...24.0000mA | 0.0001mA | Displays the measured mA value of the selected input channel. |
| mA in Channel 2 | | | |
| mA Out Channel Input Magnitude now | $-10^7 \dots 10^7$ | 0.001 | Displays the input value of the selected mA output channel at that moment. |
| mA Out Channel Outputs now | 0.0000...24.0000mA | 0.0001mA | Displays the output value of the selected mA output channel at that moment. |

4.5.9 Programmable control switch

The programmable control switch is a control function that controls its binary output signal. This output signal can be controlled locally from the device's mimic (displayed as a box in the mimic) or remotely from the RTU. The main purpose of programmable control switches is to block or enable function and to change function properties by changing the setting group. However, this binary signal can also be used for any number of other purposes, just like all other binary signals. Once a programmable control switch has been activated or disabled, it remains in that state until given a new command to switch to the opposite state (see the image below). The switch cannot be controlled by an auxiliary input, such as digital inputs or logic signals; it can only be controlled locally (mimic) or remotely (RTU).



Settings.

These settings can be accessed at *Control* → *Device I/O* → *Programmable control switch*.

Table. 4.5.9 - 146. Settings.

| Name | Range | Default | Description |
|--------------------------------|--|--------------|--|
| Switch name | - | Switchx | The user-settable name of the selected switch. The name can be up to 32 characters long. |
| Access level for Mimic control | <ul style="list-style-type: none"> User Operator Configurator Super user | Configurator | Determines which access level is required to be able to control the programmable control switch via the Mimic. |

Events

The programmable control switch function (abbreviated "PCS" in event block names) generates events from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp. The function offers five (5) independent switches. The function's output signals can be used for direct I/O controlling and user logic programming.

Table. 4.5.9 - 147. Event messages.

| Event block name | Event names |
|------------------|--------------|
| PCS | Switch 1 ON |
| PCS | Switch 1 OFF |
| PCS | Switch 2 ON |
| PCS | Switch 2 OFF |
| PCS | Switch 3 ON |
| PCS | Switch 3 OFF |
| PCS | Switch 4 ON |
| PCS | Switch 4 OFF |
| PCS | Switch 5 ON |
| PCS | Switch 5 OFF |

4.5.10 Analog input scaling curves

Sometimes when measuring with RTD inputs, milliampere inputs and digital inputs the measurement might be inaccurate because the signal coming from the source is inaccurate. One common example of this is tap changer location indication signal not changing linearly from step to step. If the output difference between the steps are not equal to each other, measuring the incoming signal accurately is not enough. "Analog input scaling curves" menu can be used to take these inaccuracies into account.

Analog input scaling curve settings can be found at *Measurement* → *AI(mA, DI volt) scaling* menu.

Currently following measurements can be scaled with analog input scaling curves:

- RTD inputs and mA inputs in "RTD & mA input" option cards
- mA inputs in "4x mA output & 1x mA input" option cards

- mA input in "4x mA input & 1x mA output" option cards
- Digital input voltages

Table. 4.5.10 - 148. Main settings (input channel).

| Name | Range | Step | Default | Description |
|--|---|---------|-------------|--|
| Analog input scaling | <ul style="list-style-type: none"> • Disabled • Activated | - | Disabled | Enables and disables the input. |
| Scaling curve 1...10 | <ul style="list-style-type: none"> • Disabled • Activated | - | Disabled | Enables and disables the scaling curve and the input measurement. |
| Curve 1...10 input signal select | <ul style="list-style-type: none"> • S7 mA Input • S8 mA Input • S15 mA Input • S16 mA Input • DI1...DI20 Voltage • RTD S1...S16 Resistance • mA In 1 (I card 1) • mA In 2 (I card 2) • mA In 1 (T card 1) • mA In 2 (T card 1) • mA In 3 (T card 1) • mA In 4 (T card 1) • mA In 1 (T card 2) • mA In 2 (T card 2) • mA In 3 (T card 2) • mA In 4 (T card 2) | - | S7 mA Input | Defines the measurement used by scaling curve. |
| Curve 1...10 input signal filtering | <ul style="list-style-type: none"> • No • Yes | - | No | Enables calculation of the average of received signal. |
| Curve 1...10 input signal filter time constant | 0.005...3800.000 s | 0.005 s | 1 s | Time constant for input signal filtering. This parameter is visible when "Curve 1...4 input signal filtering" has been set to "Yes". |
| Curve 1...10 input signal out of range set | <ul style="list-style-type: none"> • No • Yes | - | No | Enables out of range signals. If input signal is out of minimum and maximum limits, "ASC1...4 input out of range" signal is activated. |
| Curve1...10 input minimum | -1 000 000.00...1 000 000.00 | 0.00001 | 0 | Defines the minimum input of the curve. If input is below the set limit, "ASC1...4 input out of range" is activated. |

| Name | Range | Step | Default | Description |
|---------------------------|------------------------------------|---------|---------|--|
| Curve 1...10 input | -1 000 000.00...1 000 000.00 | 0.00001 | - | Displays the input measurement received by the curve. |
| Curve1...10 input maximum | -1 000 000.00...1 000 000.00 | 0.00001 | 0 | Defines the maximum input of the curve. If input is above the set limit, "ASC1...4 input out of range" is activated. |
| Curve1...10 output | -1 000 000.00...1 000 000.00 | 0.00001 | - | Displays the output of the curve. |

The input signal filtering parameter calculates the average of received signals according to the set time constant. This is why rapid changes and disturbances (such as fast spikes) are smothered. The Nyquist rate states that the filter time constant must be at least double the period time of the disturbance process signal. For example, the value for the filter time constant is 2 seconds for a 1 second period time of a disturbance oscillation.

$$H(s) = \frac{Wc}{s+Wc} = \frac{1}{1+s/Wc}$$

When the curve signal is out of range, it activates the "ASC1...10 input out of range" signal, which can be used inside logic or with other functions of the device. The signal can be assigned directly to an output relay or to an LED in the I/O matrix. The "Out of range" signal is activated, when the measured signal falls below the set input minimum limit, or when it exceeds the input maximum limit.

If for some reason the input signal is lost, the value is fixed to the last actual measured cycle value. The value does not go down to the minimum if it has been something else at the time of the signal breaking.

Table. 4.5.10 - 149. Output settings and indications.

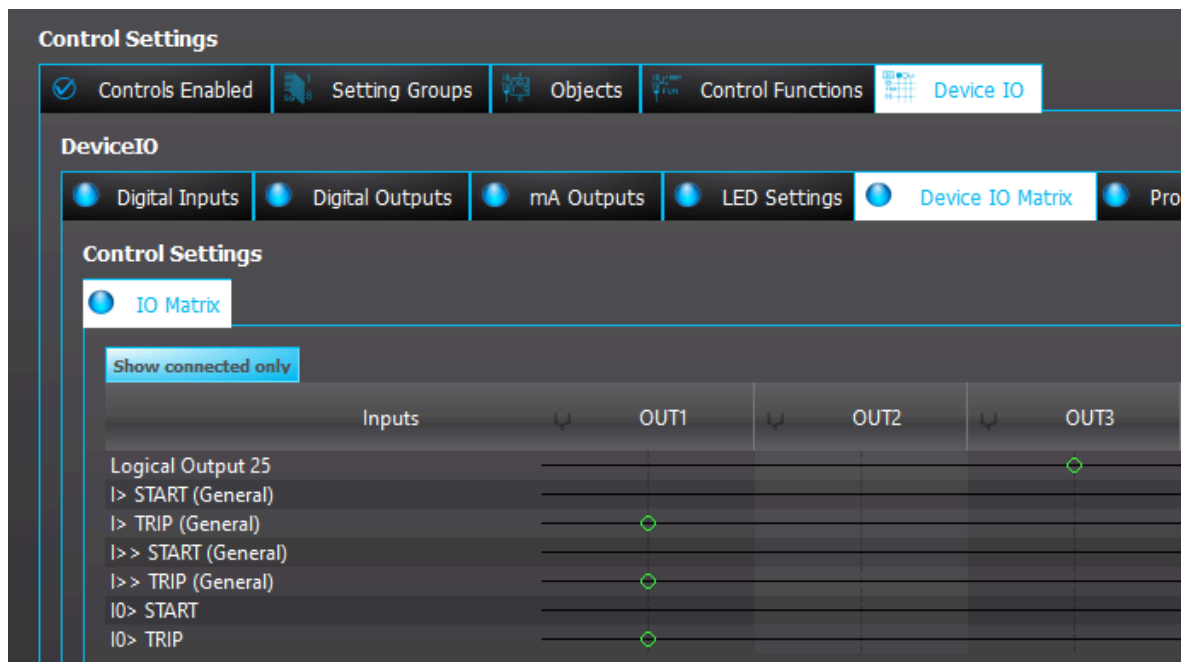
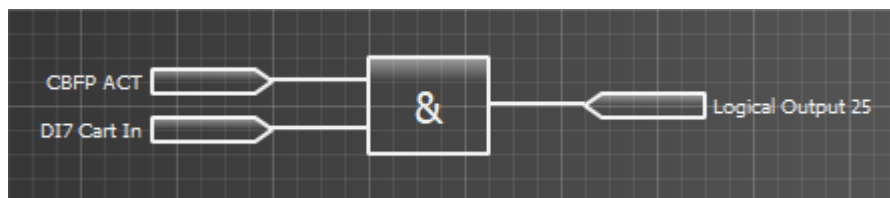
| Name | Range | Step | Default | Description |
|---------------------------|---|----------|----------------|--|
| Curve 1...10 update cycle | 5...10 000ms | 5ms | 150ms | Defines the length of the input measurement update cycle. If the user wants a fast operation, this setting should be fairly low. |
| Scaled value handling | <ul style="list-style-type: none"> Floating point Integer out (Floor) Integer (Ceiling) Integer (Nearest) | - | Floating point | Rounds the milliampere signal output as selected. |
| Input value 1 | 0...4000 | 0.000 01 | 0 | The measured input value at Curve Point 1. |
| Scaled output value 1 | $-10^7 \dots 10^7$ | 0.000 01 | 0 | Scales the measured milliampere signal at Point 1. |
| Input value 2 | 0...4000 | 0.000 01 | 1 | The measured input value at Curve Point 2. |

| Name | Range | Step | Default | Description |
|-----------------------|--|---------|----------|--|
| Scaled output value 1 | $-10^7 \dots 10^7$ | 0.00001 | 0 | Scales the measured milliamper signal at Point 2. |
| Add curvepoint 3...20 | <ul style="list-style-type: none"> Not used Used | - | Not used | Allows the user to create their own curve with up to twenty (20) curve points, instead of using a linear curve between two points. |

4.5.11 Logical outputs

Logical outputs are used for sending binary signals out from a logic that has been built in the logic editor. Logical signals can be used for blocking functions, changing setting groups, controlling digital outputs, activating LEDs, etc. The status of logical outputs can also be reported to a SCADA system. 32 logical outputs are available. The figure below presents a logic output example where a signal from the circuit breaker failure protection function controls the digital output relay number 3 ("OUT3") when the circuit breaker's cart status is "In".

Figure. 4.5.11 - 152. Logic output example. Logical output is connected to an output relay in matrix.



Logical output descriptions

Logical outputs can be given a description. The user defined description are displayed in most of the menus:

- logic editor
- matrix
- block settings
-

-
- etc.

Table. 4.5.11 - 150. Logical output user description.

| Name | Range | Default | Description |
|---------------------------------------|----------------------|-----------------------------|--|
| User editable description LO1...32 | 1...31 characters | Logical output 1...32 | Description of the logical output. This description is used in several menu types for easier identification. |

Events

The logical outputs (abbreviated "LOGIC" in event block names) generates events from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp. The function's output signals can be used for direct I/O controlling and user logic programming.

Table. 4.5.11 - 151. Event messages.

| Event block name | Event names |
|------------------|------------------------|
| LOGIC1 | Logical out 1...32 ON |
| LOGIC1 | Logical out 1...32 OFF |

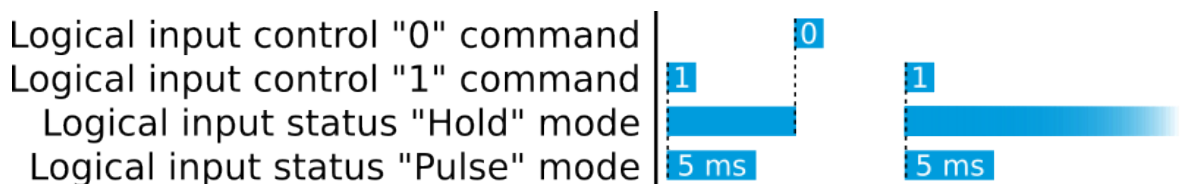
4.5.12 Logical inputs

Logical inputs are binary signals that a user can control manually to change the behavior of the AQ-200 unit or to give direct control commands. Logical inputs can be controlled with a virtual switch built in the mimic and from a SCADA system. Logical inputs are volatile signals: their status will always return to "0" when the AQ-200 device is rebooted. 32 logical inputs are available.

Logical inputs have two modes available: Hold and Pulse. When a logical input which has been set to "Hold" mode is controlled to "1", the input will switch to status "1" and it stays in that status until it is given a control command to go to status "0" or until the device is rebooted. When a logical input which has been set to "Pulse" mode is controlled to "1", the input will switch to status "1" and return back to "0" after 5 ms.

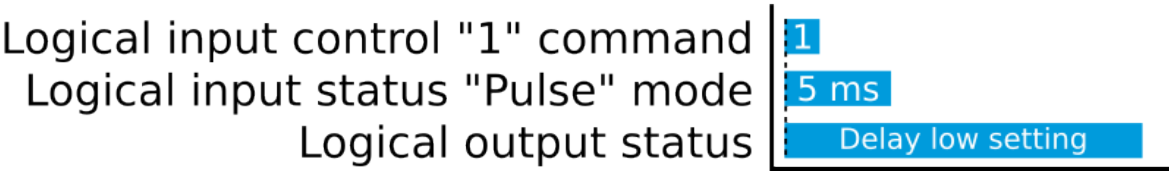
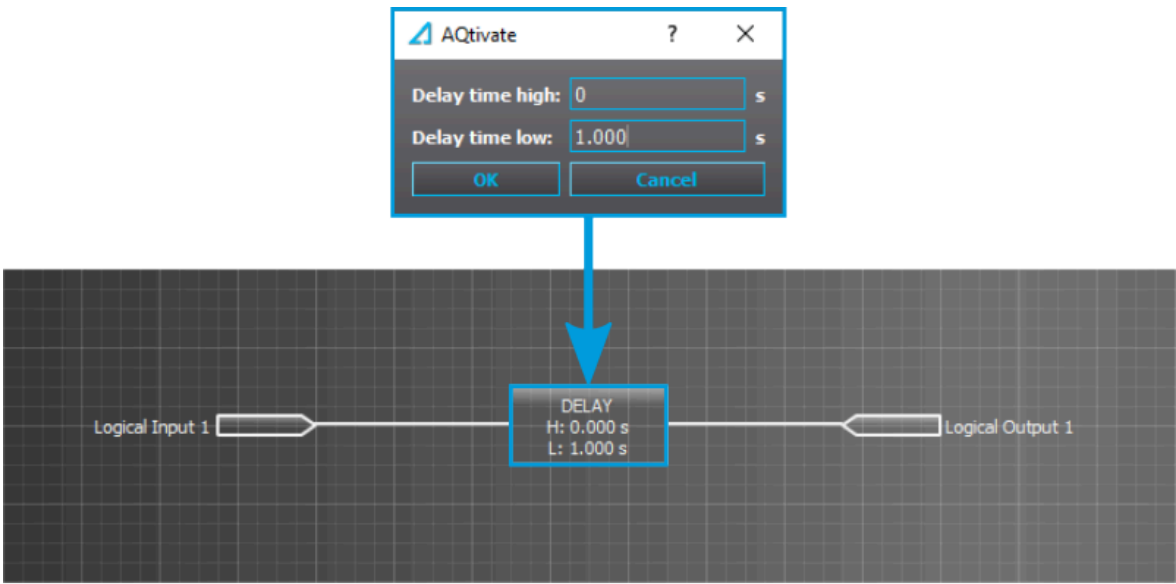
The figure below presents the operation of a logical input in Hold mode and in Pulse mode.

Figure. 4.5.12 - 153. Operation of logical input in "Hold" and "Pulse" modes.



A logical input pulse can also be extended by connecting a DELAY-low gate to a logical output, as has been done in the example figure below.

Figure. 4.5.12 - 154. Extending a logical input pulse.



Logical input descriptions

Logical inputs can be given a description. The user defined description are displayed in most of the menus:

- logic editor
- matrix
- block settings
-
-
- etc.

Table. 4.5.12 - 152. Logical input user description.

| Name | Range | Default | Description |
|------------------------------------|-------------------|----------------------|---|
| User editable description LI1...32 | 1...31 characters | Logical input 1...32 | Description of the logical input. This description is used in several menu types for easier identification. |

Events

The logical outputs (abbreviated "LOGIC" in event block names) generates events from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp. The function's output signals can be used for direct I/O controlling and user logic programming.

Table. 4.5.12 - 153. Event messages.

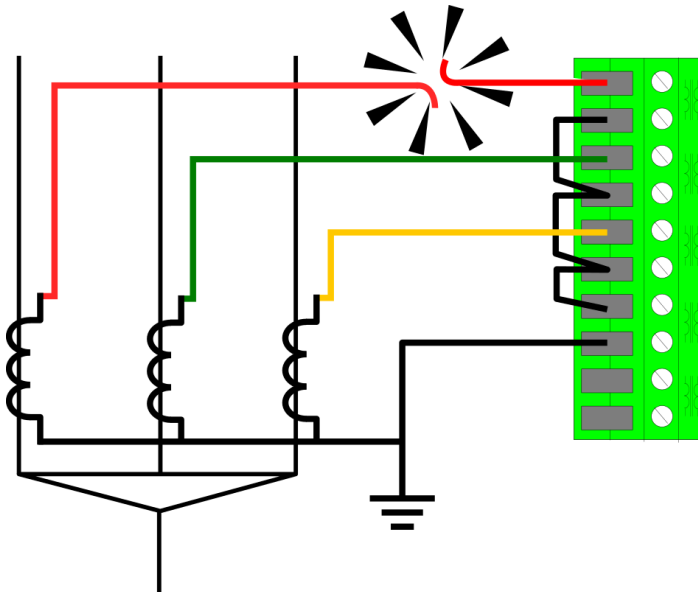
| Event block name | Event names |
|------------------|-----------------------|
| LOGIC2 | Logical in 1...32 ON |
| LOGIC2 | Logical in 1...32 OFF |

4.6 Monitoring functions

4.6.1 Current transformer supervision

The current transformer supervision function (abbreviated CTS in this document) is used for monitoring the CTs as well as the wirings between the device and the CT inputs for malfunctions and wire breaks. An open CT circuit can generate dangerously high voltages into the CT secondary side, and cause unintended activations of current balance monitoring functions.

Figure. 4.6.1 - 155. Secondary circuit fault in phase L1 wiring.

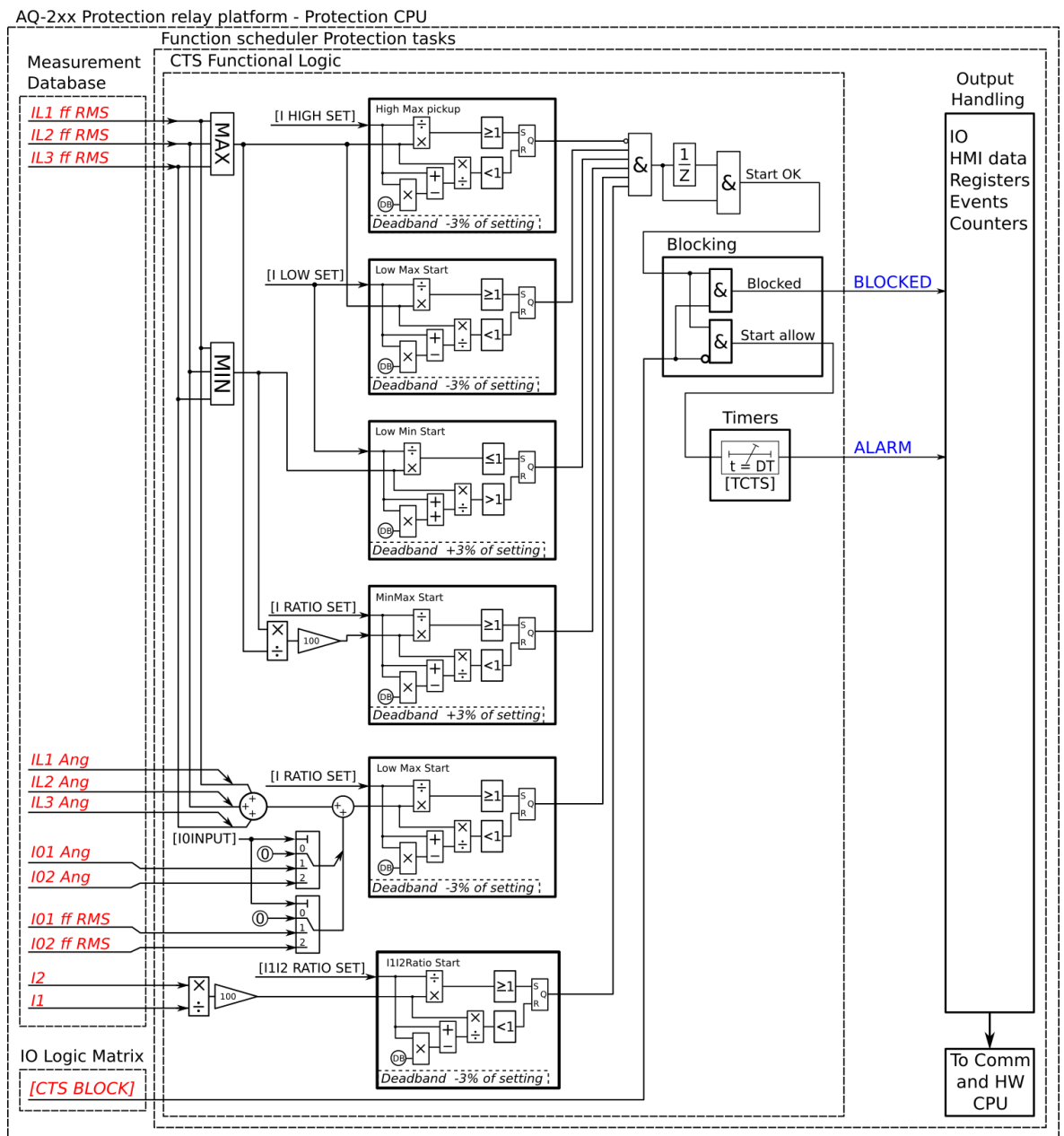


The function constantly monitors the instant values and the key calculated magnitudes of the phase currents. Additionally, the residual current circuit can be monitored if the residual current is measured from a dedicated residual current CT. The user can enable and disable the residual circuit monitoring at will.

The following conditions have to met simultaneously for the function alarm to activate:

- None of the three-phase currents exceeds the $I_{set\ high\ limit}$ setting.
- At least one of the three-phase currents exceeds the $I_{set\ low\ limit}$ setting.
- At least one of the three-phase currents are below the $I_{set\ low\ limit}$ setting.
- The ratio between the calculated minum and maximum of the three-phase currents is below the $I_{set\ ratio}$ setting.
- The ratio between the negative sequence and the positive sequence exceeds the $I2/I1\ ratio$ setting.
- The calculated difference ($IL1+IL2+IL3+I0$) exceeds the $I_{sum\ difference}$ setting (optional).
- The above-mentioned condition is met until the set time delay for alarm.

Figure. 4.6.1 - 156. Simplified function block diagram of the CTS function.



Measured input

The function block uses fundamental frequency component of phase current measurement values and residual current measurement values. The function supervises the angle of each current measurement channel. Positive sequence current and negative sequence currents are calculated from the phase currents. The user can select what is used for the residual current measurement: nothing, the I01 channel, or the I02 channel.

Table. 4.6.1 - 154. Measured inputs of the CTS function.

| Signal | Description | Time base |
|--------|---|-----------|
| IL1RMS | Fundamental frequency component of phase L1 (A) current | 5ms |
| IL2RMS | Fundamental frequency component of phase L2 (B) current | 5ms |

| Signal | Description | Time base |
|-------------|---|-----------|
| I_{L3RMS} | Fundamental frequency component of phase L3 (C) current | 5ms |
| I_{01RMS} | Fundamental frequency component of residual input I01 | 5ms |
| I_{02RMS} | Fundamental frequency component of residual input I02 | 5ms |

General settings

The following general settings define the general behavior of the function. These settings are static i.e. it is not possible to change them by editing the setting group.

Table. 4.6.1 - 155. General settings of the function.

| Name | Range | Default | Description |
|------------------------------|--|------------|---|
| CTS force status to | <ul style="list-style-type: none"> Normal Alarm Blocked | Normal | Force the status of the function. Visible only when <i>Enable stage forcing</i> parameter is enabled in <i>General</i> menu. |
| I0 input selection | <ul style="list-style-type: none"> Not in use I01 I02 | Not in use | Selects the measurement input for the residual current. If the residual current is measured with a separate CT, the residual current circuit can be monitored with the CTS function as well. However, this does not apply to summing connections (Holmgren, etc.). If the phase current CT is summed with I01 or I02, this selection should be set to "Not in use". |
| I0 direction | <ul style="list-style-type: none"> Add Subtract | Add | Defines the polarity of residual current channel connection. |
| Compensate natural unbalance | <ul style="list-style-type: none"> - Comp | - | When activated while the line is energized, the currently present calculated residual current is compensated to 0. |

Pick-up settings

The I_{set} and I_{0set} setting parameters control the current-dependent pick-up and activation of the current transformer supervision function. They define the minimum and maximum allowed measured current before action from the function. The function constantly calculates the ratio between the setting values and the measured magnitude (I_m) for each of the three phases and for the selected residual current input. The reset ratio of 97 % and 103% are built into the function and is always relative to the I_{set} value. The setting value is common for all measured amplitudes, and when the I_m exceeds the I_{set} value (in single, dual or all currents) it triggers the pick-up operation of the function.

Setting group selection controls the operating characteristics of the function, i.e. the user or user-defined logic can change function parameters while the function is running.

Table. 4.6.1 - 156. Pick-up settings.

| Name | Range | Step | Default | Description |
|----------------------|-------------------------------|-------------------|-------------------|--|
| I_{set} high limit | $0.01 \dots 40.00 \times I_N$ | $0.01 \times I_N$ | $1.20 \times I_N$ | Determines the pick-up threshold for phase current measurement. This setting limit defines the upper limit for the phase current's pick-up element. If this condition is met, it is considered as fault and the function is not activated. |

| Name | Range | Step | Default | Description |
|-----------------------------|---------------------|-------------|-------------|--|
| $I_{\text{set low limit}}$ | 0.01...40.00× I_n | 0.01× I_n | 0.10× I_n | Determines the pick-up threshold for phase current measurement. This setting limit defines the lower limit for the phase current's pick-up element. This condition has to be met for the function to activate. |
| $I_{\text{set ratio}}$ | 0.01...100.00% | 0.01% | 10.00% | Determines the pick-up ratio threshold between the minimum and maximum values of the phase current. This condition has to be met for the function to activate. |
| $I_{2/I1 \text{ ratio}}$ | 0.01...100.00% | 0.01% | 49.00% | Determines the pick-up ratio threshold for the negative and positive sequence currents calculated from the phase currents. This condition has to be met for the function to activate. The ratio is 50 % for a full single-phasing fault (i.e. when one of the phases is lost entirely). Setting this at 49 % allows a current of $0.01 \times I_n$ to flow in one phase, while the other two are at nominal current. |
| $I_{\text{sum difference}}$ | 0.01...40.00× I_n | 0.01× I_n | 0.10× I_n | Determines the pick-up ratio threshold for the calculated residual phase current and the measured residual current. If the measurement circuit is healthy, the sum of these two currents should be 0. |
| Time delay for alarm | 0.000...1800.000s | 0.005s | 0.5s | Determines the delay between the activation of the function and the alarm. |

Read-only parameters

The function's *Info* page displays useful, real-time information on the state of the protection function. It is accessed either through the device's HMI display, or through the setting tool software when it is connected to the device and its Live Edit mode is active.

Table. 4.6.1 - 157. Information displayed by the function.

| Name | Range | Step | Description |
|--|--|--------------|---|
| Uncompensated residual unbalance Pri | <ul style="list-style-type: none"> Normal Start Trip Blocked | - | Displays the natural unbalance of current after compensating it with <i>Compensate natural unbalance</i> parameter. |
| Natural unbalance ang | -360.00...360.00 deg | 0.01 deg | Displays the natural unbalance of angle after compensating it with <i>Compensate natural unbalance</i> parameter. |
| Measured current difference $I_{\text{sum, IO}}$ | 0.00...50.00 × I_n | 0.01 × I_n | Current difference between summed phases and residual current. |
| Measured angle difference $I_{\text{sum, IO}}$ | -360...360 deg | 0.01 deg | Angle difference between summed phases and residual current. |

Function blocking

The block signal is checked in the beginning of each program cycle. The blocking signal is received from the blocking matrix in the function's dedicated input. If the blocking signal is not activated when the pick-up element activates, a START signal is generated and the function proceeds to the time characteristics calculation.

If the blocking signal is active when the pick-up element activates, a BLOCKED signal is generated and the function does not process the situation further. If the START function has been activated before the blocking signal, it resets and the release time characteristics are processed similarly to when the pick-up signal is reset.

The variables the user can set are binary signals from the system. The blocking signal needs to reach the device minimum of 5 ms before the set operating delay has passed in order for the blocking to activate in time.

Operating time characteristics

This function supports definite time delay (DT). For detailed information on this delay type please refer to the chapter "[General properties of a protection function](#)" and its section "Operating time characteristics for trip and reset".

Typical cases of current transformer supervision

The following nine examples present some typical cases of the current transformer supervision and their setting effects.

Figure. 4.6.1 - 157. All works properly, no faults.

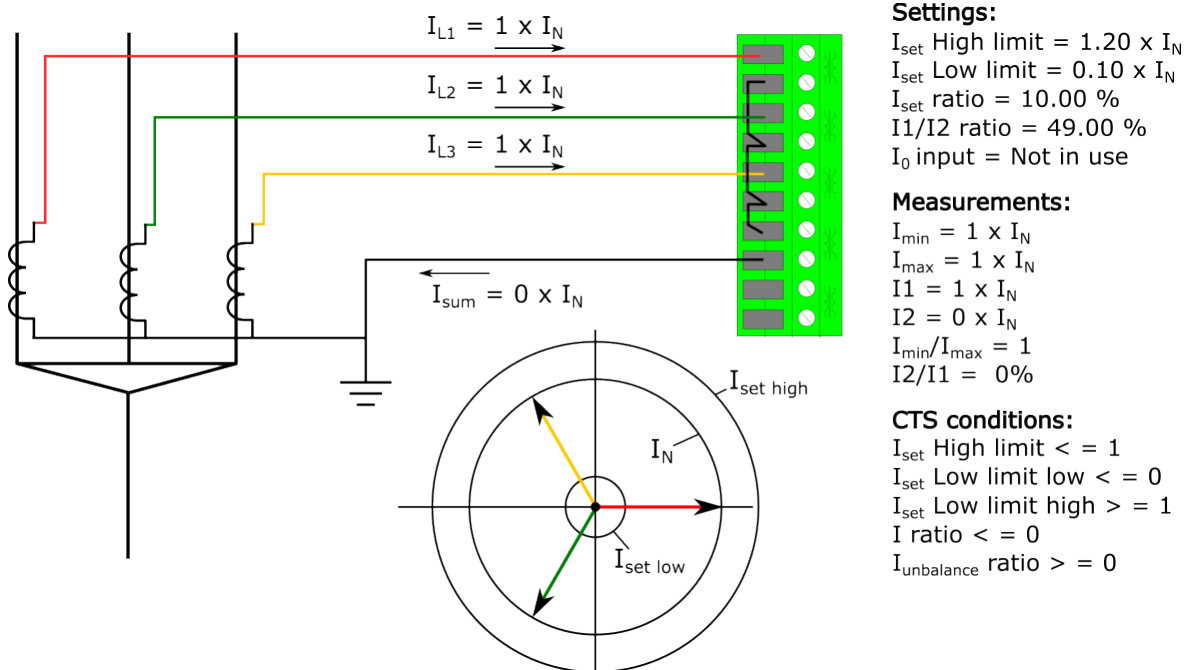
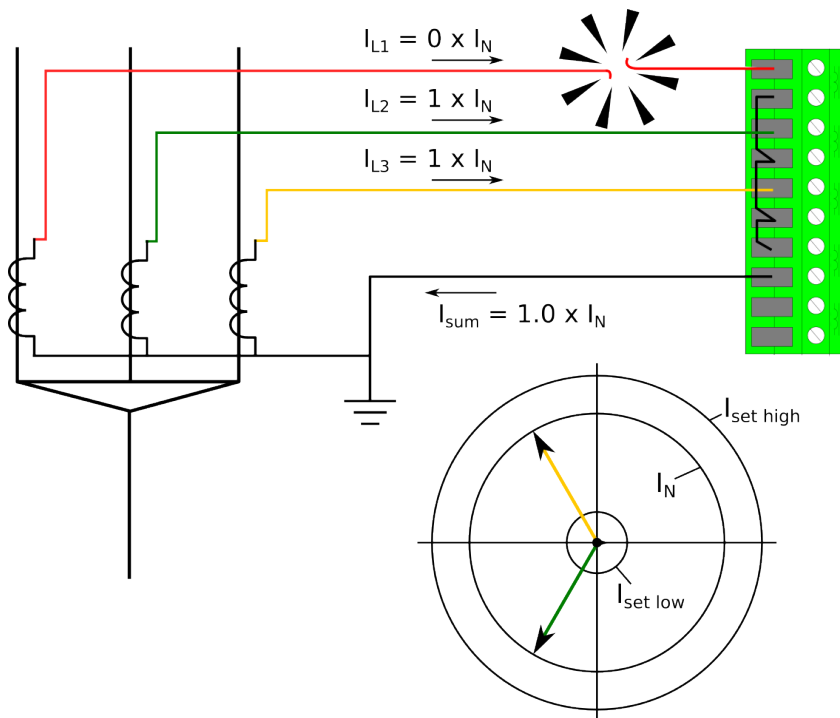


Figure. 4.6.1 - 158. Secondary circuit fault in phase L1 wiring.

**Settings:**

$I_{set\ High\ limit} = 1.20 \times I_N$
 $I_{set\ Low\ limit} = 0.10 \times I_N$
 $I_{set\ ratio} = 10.00\ \%$
 $I1/I2\ ratio = 49.00\ \%$
 $I_0\ input = \text{Not in use}$

Measurements:

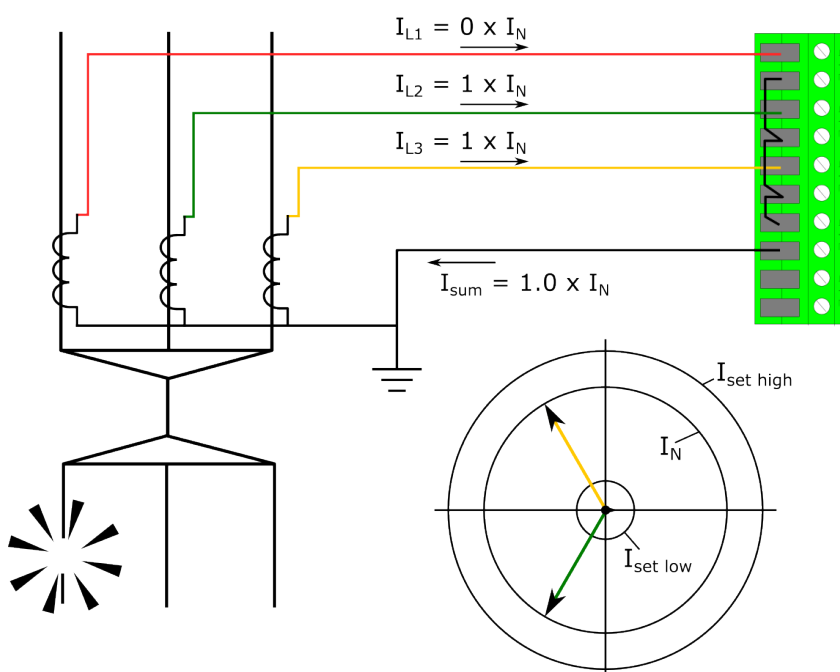
$I_{min} = 0 \times I_N$
 $I_{max} = 1 \times I_N$
 $I1 = 0.67 \times I_N$
 $I2 = 0.33 \times I_N$
 $I_{min}/I_{max} = 0$
 $I2/I1 = 50\%$

CTS conditions:

$I_{set\ High\ limit} < = 1$
 $I_{set\ Low\ limit\ low} < = 1$
 $I_{set\ Low\ limit\ high} > = 1$
 $I\ ratio < = 1$
 $I_{unbalance\ ratio} > = 1$

When a fault is detected and all conditions are met, the CTS timer starts counting. If the situation continues until the set time has passed, the function issues an alarm.

Figure. 4.6.1 - 159. Primary circuit fault in phase L1 wiring.

**Settings:**

$I_{set\ High\ limit} = 1.20 \times I_N$
 $I_{set\ Low\ limit} = 0.10 \times I_N$
 $I_{set\ ratio} = 10.00\ \%$
 $I1/I2\ ratio = 49.00\ \%$
 $I_0\ input = \text{Not in use}$

Measurements:

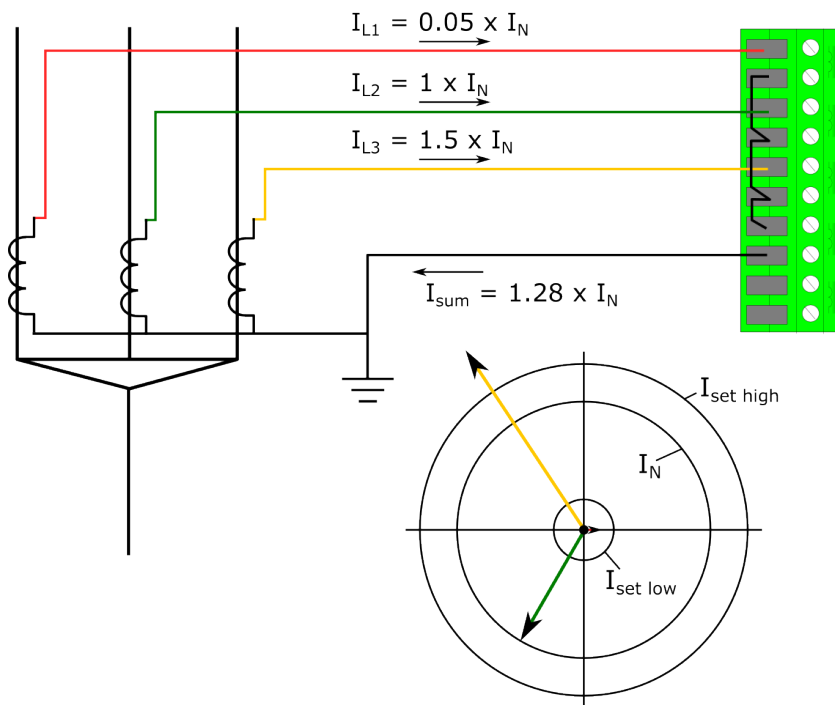
$I_{min} = 0 \times I_N$
 $I_{max} = 1 \times I_N$
 $I1 = 0.67 \times I_N$
 $I2 = 0.33 \times I_N$
 $I_{min}/I_{max} = 0$
 $I2/I1 = 50\%$

CTS conditions:

$I_{set\ High\ limit} < = 1$
 $I_{set\ Low\ limit\ low} < = 1$
 $I_{set\ Low\ limit\ high} > = 1$
 $I\ ratio < = 1$
 $I_{unbalance\ ratio} > = 1$

In this example, distinguishing between a primary fault and a secondary fault is impossible. However, the situation meets the function's activation conditions, and if this state (secondary circuit fault) continues until the set time has passed, the function issues an alarm. This means that the function supervises both the primary and the secondary circuit.

Figure. 4.6.1 - 160. No wiring fault but heavy unbalance.

**Settings:**

I_{set} High limit = $1.20 \times I_N$
 I_{set} Low limit = $0.10 \times I_N$
 I_{set} ratio = 10.00 %
 $I1/I2$ ratio = 49.00 %
 I_0 input = Not in use

Measurements:

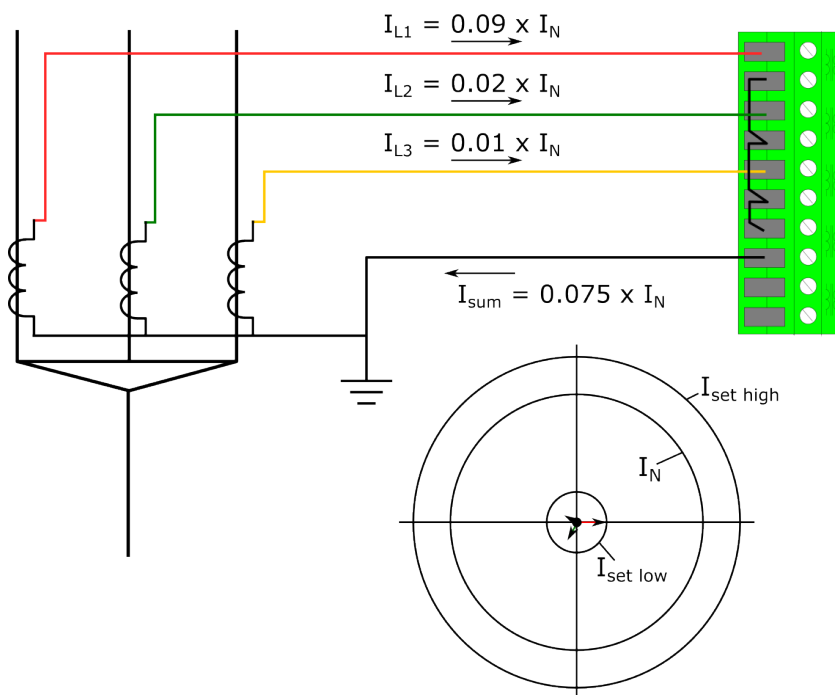
$I_{min} = 0.05 \times I_N$
 $I_{max} = 1.50 \times I_N$
 $I1 = 0.85 \times I_N$
 $I2 = 0.43 \times I_N$
 $I_{min}/I_{max} = 0.7 \%$
 $I2/I1 = 50.03 \%$

CTS conditions:

I_{set} High limit ≤ 0
 I_{set} Low limit low ≤ 1
 I_{set} Low limit high > 1
 I ratio ≤ 1
 $I_{unbalance}$ ratio > 1

If any of the phases exceed the $I_{set\ high\ limit}$ setting, the operation of the function is not activated. This behavior is applied to short-circuits and earth faults even when the fault current exceeds the $I_{set\ high\ limit}$ setting.

Figure. 4.6.1 - 161. Low current and heavy unbalance.

**Settings:**

I_{set} High limit = $1.20 \times I_N$
 I_{set} Low limit = $0.10 \times I_N$
 I_{set} ratio = 10.00 %
 $I1/I2$ ratio = 49.00 %
 I_0 input = Not in use

Measurements:

$I_{min} = 0.01 \times I_N$
 $I_{max} = 0.09 \times I_N$
 $I1 = 0.04 \times I_N$
 $I2 = 0.03 \times I_N$
 $I_{min}/I_{max} = 11.0 \%$
 $I2/I1 = 62.92 \%$

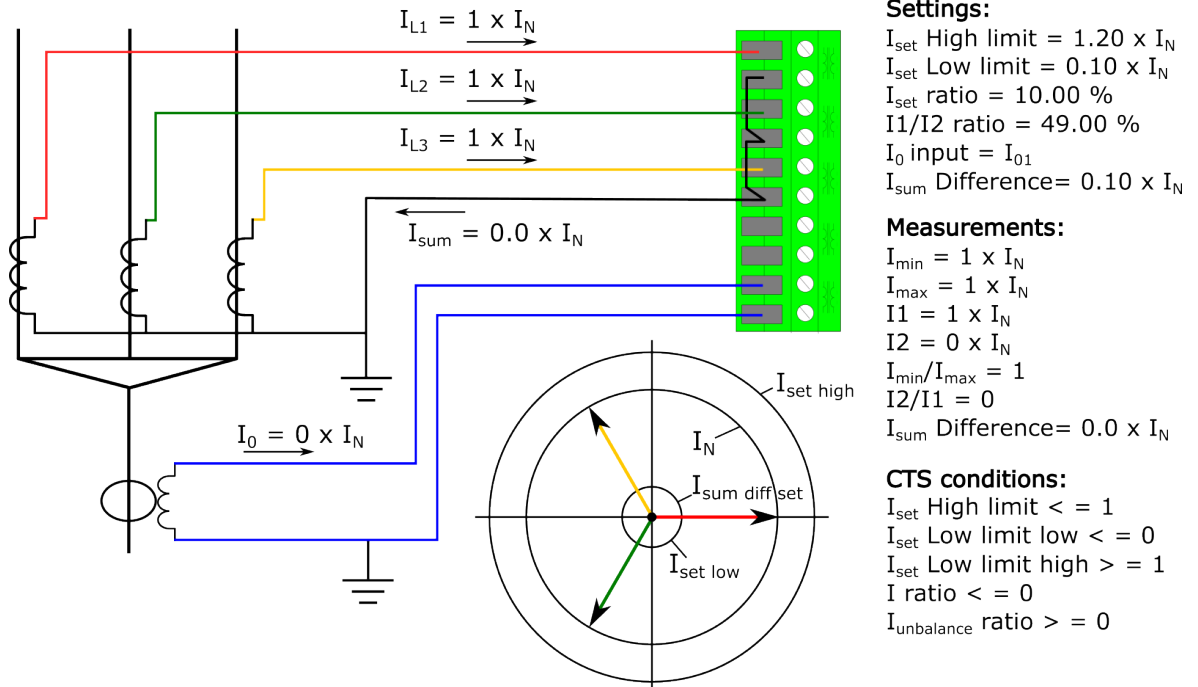
CTS conditions:

I_{set} High limit ≤ 1
 I_{set} Low limit low ≤ 1
 I_{set} Low limit high > 0
 I ratio ≤ 1
 $I_{unbalance}$ ratio > 1

If all of the measured phase magnitudes are below the $I_{set\ low\ limit}$ setting, the function is not activated even when the other conditions (inc. the unbalance condition) are met.

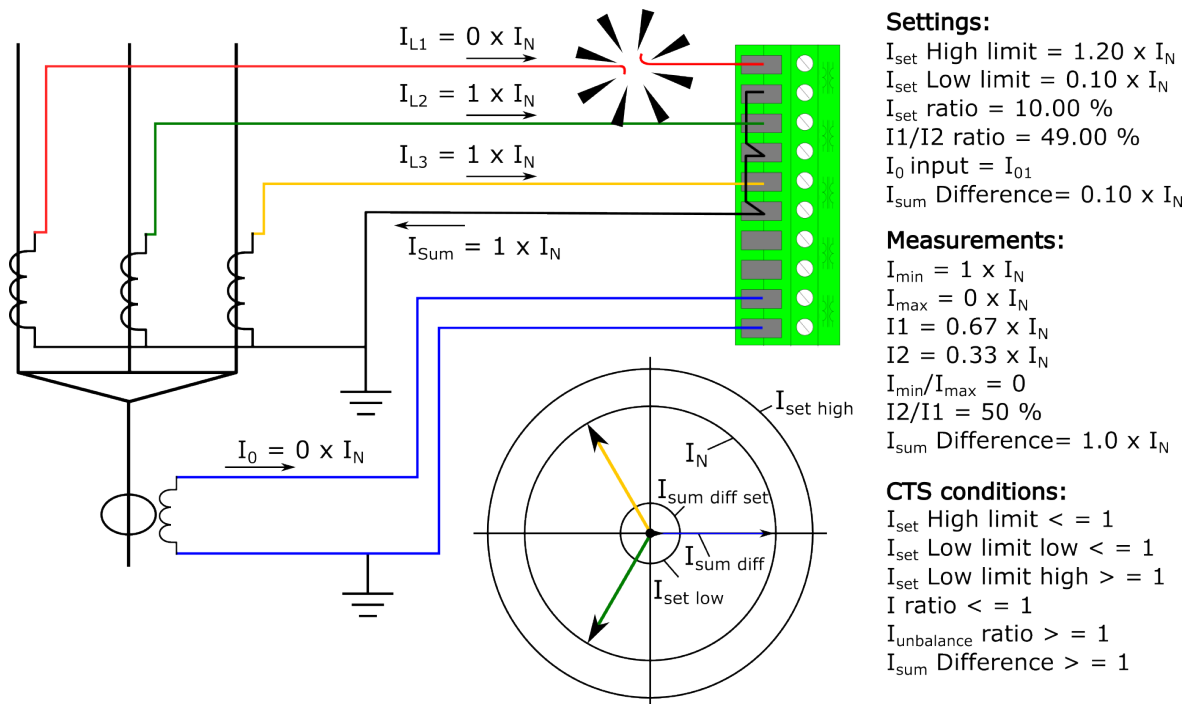
If the I_{set} high limit and I_{set} low limit setting parameters are adjusted according to the application's normal behavior, the operation of the function can be set to be very sensitive for broken circuit and conductor faults.

Figure. 4.6.1 - 162. Normal situation, residual current also measured.



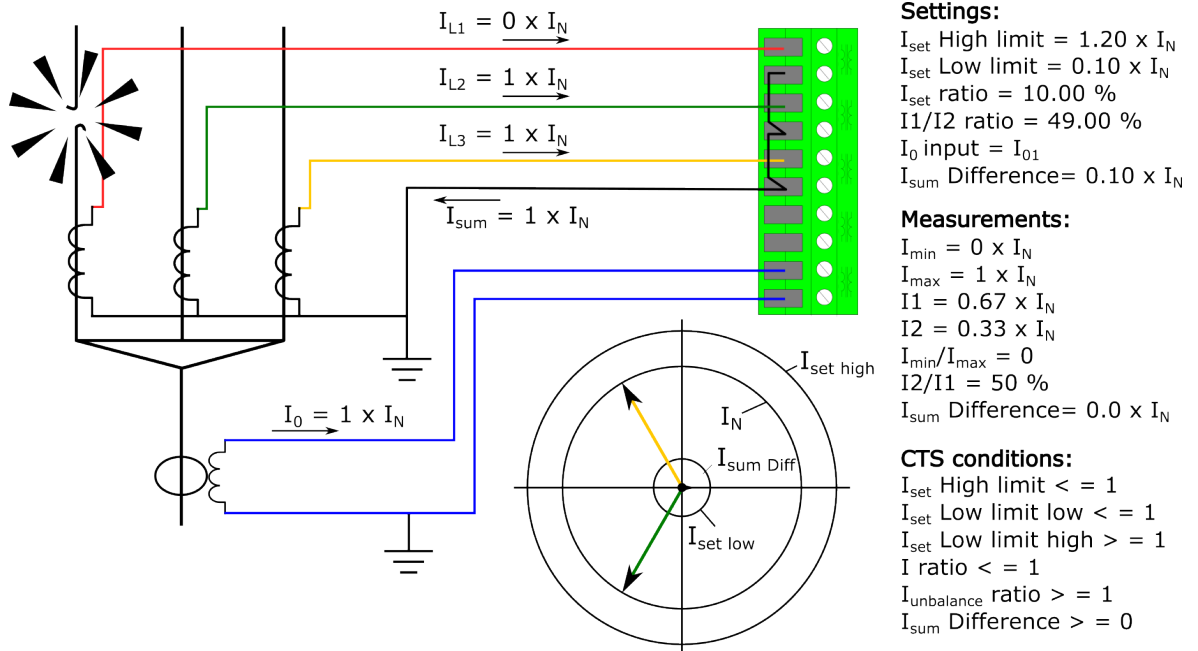
When the residual condition is added with the "I0 input selection", the sum of the current and the residual current are compared against each other to verify the wiring condition.

Figure. 4.6.1 - 163. Broken secondary phase current wiring.



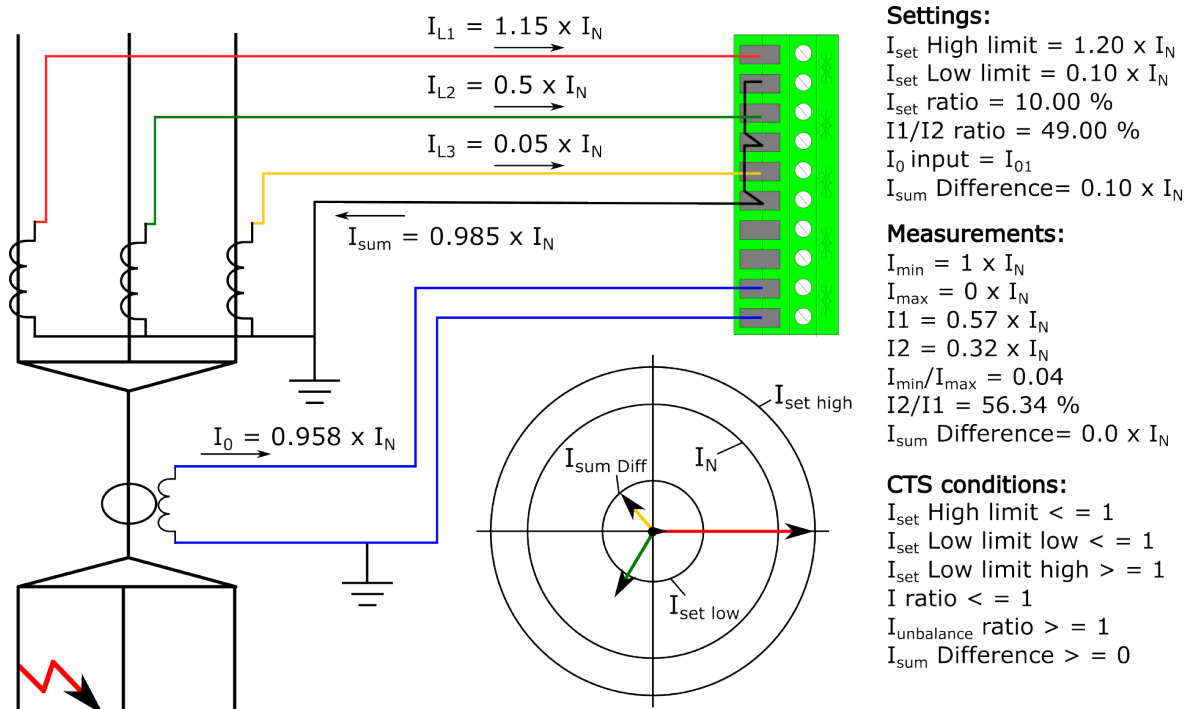
When phase current wire is broken all of the conditions are met in the CTS and alarm shall be issued in case if the situation continues until the set alarming time is met.

Figure. 4.6.1 - 164. Broken primary phase current wiring.



In this example, all other condition are met except the residual difference. That is now $0 \times I_N$, which indicates a primary side fault.

Figure. 4.6.1 - 165. Primary side high-impedance earth fault.



In this example there is a high-impedance earth fault. It does not activate the function, if the measurement conditions are met, while the calculated and measured residual current difference does not reach the limit. The I_{sum} difference setting should be set according to the application in order to reach maximum security and maximum sensitivity for the network earthing.

Events and registers

The current transformer supervision function (abbreviated "CTS" in event block names) generates events and registers from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

The function's outputs can be used for direct I/O controlling and user logic programming. The function also provides a resettable cumulative counter for the CTS ALARM and BLOCKED events.

Table. 4.6.1 - 158. Event messages.

| Event block name | Event names |
|------------------|-------------|
| CTS1 | Alarm ON |
| CTS1 | Alarm OFF |
| CTS1 | Block ON |
| CTS1 | Block OFF |

The function registers its operation into the last twelve (12) time-stamped registers; this information is available for all provided instances separately. The register of the function records the ON event process data for ACTIVATED, BLOCKED, etc. The table below presents the structure of the function's register content.

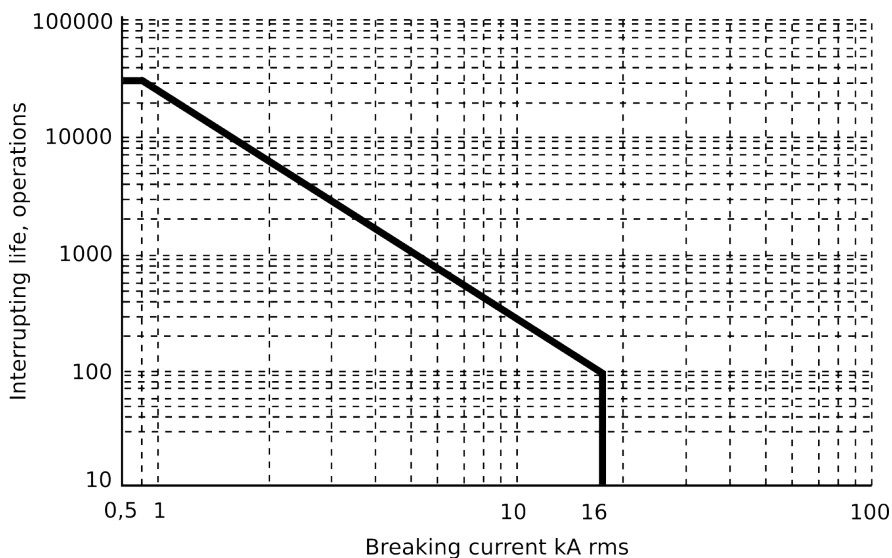
Table. 4.6.1 - 159. Register content.

| Register | Description |
|----------------------|---|
| Date and time | dd.mm.yyyy hh:mm:ss.mss |
| Event | Event name |
| Trigger currents | The phase currents (L1, L2 & L3), the residual currents (I01 & I02), and the sequence currents (I1 & I2) on trigger time. |
| Time to CTSact | Time remaining before alarm activation. |
| Fault type | The status code of the monitored current. |
| Setting group in use | Setting group 1...8 active |

4.6.2 Circuit breaker wear monitoring

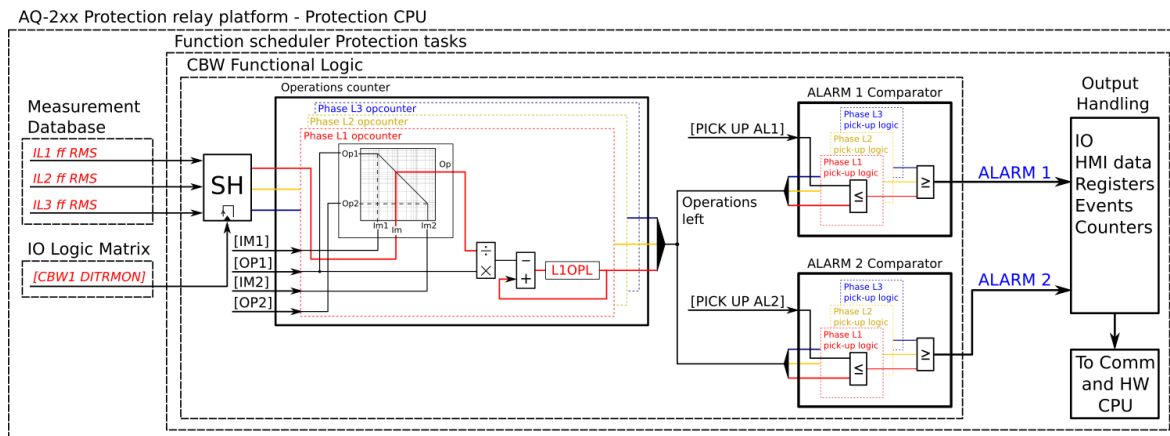
The circuit breaker wear function is used for monitoring the circuit breaker's lifetime and its maintenance needs caused by interrupting currents and mechanical wear. The function uses the circuit breaker's manufacturer-supplied data for the breaker operating cycles in relation to the interrupted current magnitudes.

Figure. 4.6.2 - 166. Example of the circuit breaker interrupting life operations.



The function is triggered from the circuit breaker's "Open" command output and it monitors the three-phase current values in both the tripping moment and the normal breaker opening moment. The maximum value of interrupting life operations for each phase is calculated from these currents. The value is cumulatively deducted from the starting operations starting value. The user can set up two separate alarm levels, which are activated when the value of interrupting life operations is below the setting limit. The "Trip contact" setting defines the output that triggers the current monitoring at the breaker's "Open" command.

Figure. 4.6.2 - 167. Simplified function block diagram of the circuit breaker wear function.



Measured input

The function block uses fundamental frequency component of phase current measurement values.

Table. 4.6.2 - 160. Measurement inputs of the circuit breaker wear function.

| Signal | Description | Time base |
|-------------|---|-----------|
| I_{L1RMS} | Fundamental frequency component of phase L1 (A) current | 5ms |
| I_{L2RMS} | Fundamental frequency component of phase L2 (B) current | 5ms |
| I_{L3RMS} | Fundamental frequency component of phase L3 (C) current | 5ms |

General settings

The following general settings define the general behavior of the function. These settings are static i.e. it is not possible to change them by switching the setting group.

Table. 4.6.2 - 161. General settings.

| Name | Range | Default | Description |
|---------------------|--|---------|--|
| CBW force status to | <ul style="list-style-type: none"> Normal Alarm1 On Alarm2 On | Normal | Force the status of the function. Visible only when <i>Enable stage forcing</i> parameter is enabled in <i>General</i> menu. |

Circuit breaker characteristics settings

The circuit breaker characteristics are set by two operating points, defined by the nominal breaking current, the maximum allowed breaking current and their respective operation settings. This data is provided by the circuit breaker's manufacturer.

Table. 4.6.2 - 162. Settings for circuit breaker characteristics.

| Name | Range | Step | Default | Description |
|-------------------------------|--------------|--------|---------|---|
| Operations 1 | 0...200 000 | 1 | 50 000 | The number of interrupting life operations at the nominal current (Close - Open). |
| Operations 2 | 0...200 000 | 1 | 100 | The number of interrupting life operations at the rated breaking current (Open). |
| Current 1 (I _{nom}) | 0...100.00kA | 0.01kA | 1kA | The rated normal current (RMS). |
| Current 2 (I _{max}) | 0...100.00kA | 0.01kA | 20kA | The rated short-circuit breaking current (RMS). |

Pick-up settings

For the alarm stages Alarm 1 and Alarm 2, the user can set the pick-up level for the number of operations left. The pick-up setting is common for all phases and the alarm stage picks up if any of the phases goes below this setting.

Table. 4.6.2 - 163. Pick-up settings.

| Name | Range | Default | Description |
|-------------|---|----------|---|
| Alarm 1 | <ul style="list-style-type: none"> Disabled Enabled | Disabled | Enable and disable the Alarm 1 stage. |
| Alarm 1 Set | 0...200 000 | 1 000 | Defines the pick-up threshold for remaining operations. When the number of remaining operations is below this setting, the ALARM 1 signal is activated. |
| Alarm 2 | <ul style="list-style-type: none"> Disabled Enabled | Disabled | Enable and disable the Alarm 2 stage. |

| Name | Range | Default | Description |
|-------------|-------------|---------|---|
| Alarm 2 Set | 0...200 000 | 100 | Defines the pick-up threshold for remaining operations. When the number of remaining operations is below this setting, the ALARM 2 signal is activated. |

Setting example

Let us examine the settings, using a low-duty vacuum circuit breaker as an example. The image below presents the technical specifications provided by the manufacturer, with the data relevant to our settings highlighted in red:

| | |
|---|------------|
| Rated voltage, kV | 24 |
| Rated current, A | 800 |
| Rated power frequency test voltage, kV | 50 |
| Rated frequency, Hz | 50/60 |
| Rated impulse test voltage, kV peak | 125 |
| Partial discharge level at 1,1 rated voltage kV, pC | <10 |
| Rated short-circuit breaking current, kA | 16 |
| Rated short-circuit making current, kA peak | 41.5 |
| Short time withstand current, 4s, kA | 16 |
| Mechanical life, CO cycles, not less than | 30,000 |
| Interrupting life operations, not less than | |
| at rated current | 30,000 |
| at breaking current | 100 |
| at other currents | see Fig.41 |
| Closing time, ms, not more than | 35 |
| Opening time, ms, not more than | 15 |
| Breaking time, ms, not more than | 25 |
| Main contact resistance, $\mu\Omega$ m, not more than | 40 |
| Maximum ambient temperature, C° | +55 |
| Minimum ambient temperature, C° | -40 |
| Design class (according to IEC 60932) | 1 |
| Electrical endurance class at rated IEEE/IEC duty | E2 |
| Mechanical endurance class at rated IEEE/IEC duty | M2 |
| Capacitive current switching class | C2 |
| "Mechanical vibration and shock withstand capability, IEC 60721, IEC 60068" | Class 4M4 |
| Maximum altitude above sea level, m | 3000* |
| Maximum humidity, non condensing | 98 % |
| Weight, kg - LD_1 | 35 |
| Weight, kg - LD_6 | 55 |

Now, we set the stage as follows:

| Parameter | Setting |
|-------------|-------------------|
| Current 1 | 0.80 kA |
| Operation 1 | 30 000 operations |

| Parameter | Setting |
|----------------|-----------------|
| Current 2 | 16.00 kA |
| Operations 2 | 100 operations |
| Enable Alarm 1 | Enabled |
| Alarm 1 Set | 1000 operations |
| Enable Alarm 2 | Enabled |
| Alarm 2 Set | 100 operations |

With these settings, Alarm 1 is issued when the cumulative interruption counter for any of the three phases dips below the set 1000 remaining operations ("Alarm 1 Set"). Similarly, when any of the counters dips below 100 remaining operations, Alarm 2 is issued.

Read-only parameters

The function's *Info* page displays useful, real-time information on the state of the protection function. It is accessed either through the device's HMI display, or through the setting tool software when it is connected to the device and its Live Edit mode is active.

Table. 4.6.2 - 164. Information displayed by the function.

| Name | Range | Description |
|--------------------|--|--|
| CBW condition | <ul style="list-style-type: none"> • Normal • Alarm1 On • Alarm2 On | Displays the status of the function. |
| Breaker operations | - | Cumulative counter of "open" operations. |
| Alarm 1 counter | - | Alarm 1 operation counter. |
| Alarm 2 counter | - | Alarm 2 operation counter. |
| L1 Operations left | - | Operations left for phase L1. |
| L2 Operations left | - | Operations left for phase L2. |
| L3 Operations left | - | Operations left for phase L3. |

Events and registers

The circuit breaker wear function (abbreviated "CBW" in event block names) generates events and registers from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The function's outputs can be used for direct I/O controlling and user logic programming. The events triggered by the function are recorded with a time stamp.

The function also provides a resettable cumulative counter for the "Open" operations as well as the ALARM 1 and ALARM 2 events.

Table. 4.6.2 - 165. Event messages.

| Event block name | Event names |
|------------------|---------------------|
| CBW1 | CBWEAR1 Triggered |
| CBW1 | CBWEAR1 Alarm 1 ON |
| CBW1 | CBWEAR1 Alarm 1 OFF |
| CBW1 | CBWEAR1 Alarm 2 ON |
| CBW1 | CBWEAR1 Alarm 2 OFF |

The function registers its operation into the last twelve (12) time-stamped registers. The register of the function records the ON event process data. The table below presents the structure of the function's register content.

Table. 4.6.2 - 166. Register content.

| Register | Description |
|-----------------|--|
| Date and time | dd.mm.yyyy hh:mm:ss.mss |
| Event | Event name |
| Trigger current | Phase currents on trigger time |
| Deducted Op | L1/L2/L3 Deducted operations from the cumulative sum |
| Operations left | L1/L2/L3 Operations left |

4.6.3 Current total harmonic distortion (THD)

The total harmonic distortion (THD) function is used for monitoring the content of the current harmonic. The THD is a measurement of the harmonic distortion present, and it is defined as the ratio between the sum of all harmonic components' powers and the power of the fundamental frequency (RMS).

Harmonics can be caused by different sources in electric networks such as electric machine drives, thyristor controls, etc. The function's monitoring of the currents can be used to alarm of the harmonic content rising too high; this can occur when there is an electric quality requirement in the protected unit, or when the harmonics generated by the process need to be monitored.

The function constantly measures the phase and residual current magnitudes as well as the harmonic content of the monitored signals up to the 31st harmonic component. When the function is activated, the measurements are also available for the mimic and the measurement views in the HMI carousel. The user can also set the alarming limits for each measured channel if the application so requires.

The monitoring of the measured signals can be selected to be based either on an amplitude ratio or on the above-mentioned power ratio. The difference is in the calculation formula (as shown below):

Figure. 4.6.3 - 168. THD calculation formulas.

$$THD_P = \frac{I_{x2}^2 + I_{x3}^2 + I_{x4}^2 \dots I_{x31}^2}{I_{x1}^2}$$

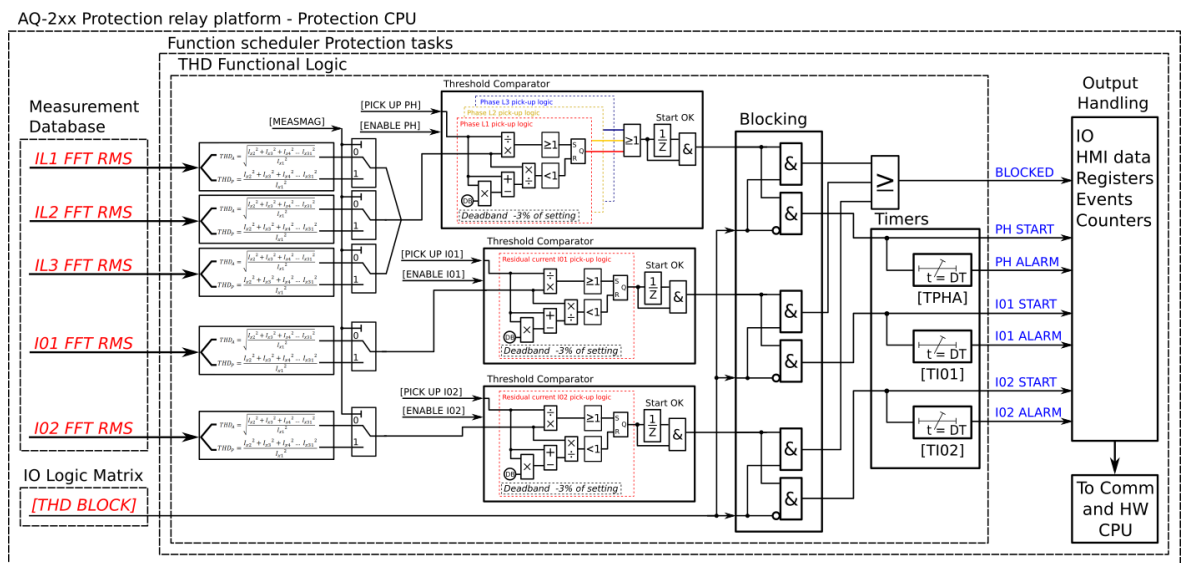
, where
I = measured current,
x = measurement input,
n = harmonic number

$$THD_A = \sqrt{\frac{I_{x2}^2 + I_{x3}^2 + I_{x4}^2 \dots I_{x31}^2}{I_{x1}^2}}$$

, where
I = measured current,
x = measurement input,
n = harmonic number

While both of these formulas exist, the power ratio (THD_P) is recognized by the IEEE, and the amplitude ratio (THD_A) is recognized by the IEC.

Figure. 4.6.3 - 169. Simplified function block diagram of the total harmonic distortion monitor function.



Measured input

The function block uses phase and residual current measurement channels. The function always uses FFT measurement of the whole harmonic spectrum of 32 components from each measured current channel. From these measurements the function calculates either the amplitude ratio or the power ratio.

Table. 4.6.3 - 167. Measurement inputs of the total harmonic distortion monitor function.

| Signal | Description | Time base |
|---------------------|---|-----------|
| I _{L1} FFT | FFT measurement of phase L1 (A) current | 5ms |
| I _{L2} FFT | FFT measurement of phase L2 (B) current | 5ms |
| I _{L3} FFT | FFT measurement of phase L3 (C) current | 5ms |
| I ₀₁ FFT | FFT measurement of residual I01 current | 5ms |
| I ₀₂ FFT | FFT measurement of residual I02 current | 5ms |

The selection of the calculation method is made with a setting parameter (common for all measurement channels).

General settings

The following general settings define the general behavior of the function. These settings are static i.e. it is not possible to change them by editing the setting group.

Table. 4.6.3 - 168. General settings.

| Name | Range | Default | Description |
|-----------------------|--|-----------|---|
| Measurement magnitude | <ul style="list-style-type: none"> Amplitude Power | Amplitude | Defines which available measured magnitude the function uses. |

Pick-up settings

The *PhaseTHD*, *I01THD* and *I02THD* setting parameters control the the pick-up and activation of the function. They define the maximum allowed measured current THD before action from the function. Before the function activates alarm signals, their corresponding pick-up elements need to be activated with the setting parameters *Enable phase THD alarm*, *Enable I01 THD alarm* and *Enable I02 THD alarm*. The function constantly calculates the ratio between the setting values and the calculated THD for each of the three phases. The reset ratio of 97 % is built into the function and is always relative to the setting value. The setting value is common for all measured phases. When the calculated THD exceeds the pick-up value (in single, dual or all phases), it triggers the pick-up operation of the function.

Setting group selection controls the operating characteristics of the function, i.e. the user or user-defined logic can change function parameters while the function is running.

Table. 4.6.3 - 169. Pick-up settings.

| Name | Range | Step | Default | Description |
|------------------------|---|-------|---------|---|
| Enable phase THD alarm | <ul style="list-style-type: none"> Enabled Disabled | - | Enabled | Enables and disables the THD alarm function from phase currents. |
| Enable I01 THD alarm | <ul style="list-style-type: none"> Enabled Disabled | - | Enabled | Enables and disables the THD alarm function from residual current input I01. |
| Enable I02 THD alarm | <ul style="list-style-type: none"> Enabled Disabled | - | Enabled | Enables and disables the THD alarm function from residual current input I02. |
| Phase THD pick-up | 0.10...100.00% | 0.01% | 10.00% | The pick-up setting for the THD alarm element from the phase currents. At least one of the phases' measured THD value has to exceed this setting in order for the alarm signal to activate. |
| I01 THD pick-up | 0.10...100.00% | 0.01% | 10.00% | The pick-up setting for the THD alarm element from the residual current I01. The measured THD value has to exceed this setting in order for the alarm signal to activate. |

| Name | Range | Step | Default | Description |
|-----------------|----------------|-------|---------|---|
| I02 THD pick-up | 0.10...100.00% | 0.01% | 10.00% | The pick-up setting for the THD alarm element from the residual current I02. The measured THD value has to exceed this setting in order for the alarm signal to activate. |

Read-only parameters

The function's *Info* page displays useful, real-time information on the state of the protection function. It is accessed either through the device's HMI display, or through the setting tool software when it is connected to the device and its Live Edit mode is active.

Table. 4.6.3 - 170. Information displayed by the function.

| Name | Range | Description |
|---------------|---|---|
| THD condition | <ul style="list-style-type: none"> • Normal • Start • Alarm • Blocked | Displays status of the monitoring function. |

Function blocking

The block signal is checked in the beginning of each program cycle. The blocking signal is received from the blocking matrix in the function's dedicated input. If the blocking signal is not activated when the pick-up element activates, a START signal is generated and the function proceeds to the time characteristics calculation.

If the blocking signal is active when the pick-up element activates, a BLOCKED signal is generated and the function does not process the situation further. If the START function has been activated before the blocking signal, it resets and the release time characteristics are processed similarly to when the pick-up signal is reset.

The variables the user can set are binary signals from the system. The blocking signal needs to reach the device minimum of 5 ms before the set operating delay has passed in order for the blocking to activate in time.

Operating time characteristics for activation and reset

This function supports definite time delay (DT). The following table presents the setting parameters for the function's time characteristics.

Table. 4.6.3 - 171. Settings for operating time characteristics.

| Name | Range | Step | Default | Description |
|-----------------------|-------------------|--------|---------|---|
| Phase THD alarm delay | 0.000...1800.000s | 0.005s | 10.000s | Defines the delay for the alarm timer from the phase currents' measured THD. |
| I01 THD alarm delay | 0.000...1800.000s | 0.005s | 10.000s | Defines the delay for the alarm timer from the residual current I01's measured THD. |
| I02 THD alarm delay | 0.000...1800.000s | 0.005s | 10.000s | Defines the delay for the alarm timer from the residual current I02's measured THD. |

Events and registers

The total harmonic distortion monitor function (abbreviated "THD" in event block names) generates events and registers from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

The function's outputs can be used for direct I/O controlling and user logic programming. The function also provides a resettable cumulative counter for the START, ALARM and BLOCKED events.

Table. 4.6.3 - 172. Event messages.

| Event block name | Event names |
|------------------|---------------------|
| THD1 | THD Start Phase ON |
| THD1 | THD Start Phase OFF |
| THD1 | THD Start I01 ON |
| THD1 | THD Start I01 OFF |
| THD1 | THD Start I02 ON |
| THD1 | THD Start I02 OFF |
| THD1 | THD Alarm Phase ON |
| THD1 | THD Alarm Phase OFF |
| THD1 | THD Alarm I01 ON |
| THD1 | THD Alarm I01 OFF |
| THD1 | THD Alarm I02 ON |
| THD1 | THD Alarm I02 OFF |
| THD1 | Blocked ON |
| THD1 | Blocked OFF |

The function registers its operation into the last twelve (12) time-stamped registers. The register of the function records the ON event process data for START, ALARM and BLOCKED. The table below presents the structure of the function's register content.

Table. 4.6.3 - 173. Register content.

| Register | Description |
|-------------------------|--------------------------------|
| Date and time | dd.mm.yyyy hh:mm:ss.mss |
| Event | Event name |
| L1h, L2h, L3h Fault THD | Start/Alarm THD of each phase. |
| Setting group in use | Setting group 1...8 active. |

4.6.4 Disturbance recorder (DR)

The disturbance recorder is a high-capacity (64 MB permanent flash memory) and fully digital recorder integrated to the protection relay. The maximum sample rate of the recorder's analog channels is 64 samples per cycle. The recorder also supports 95 digital channels simultaneously with the twenty (20) measured analog channels. Maximum capacity of recordings is 100.

The recorder provides a great tool to analyze the performance of the power system during network disturbance situations. The recorder's output is in general COMTRADE format and it is compatible with most viewers and injection devices. The files are based on the IEEE standard C37.111-1999. Captured recordings can be injected as playback with secondary testing tools that support the COMTRADE file format. Playback of files might help to analyze the fault, or can be simply used for educational purposes.

Analog and digital recording channels

Up to 20 analog recording channels and 95 digital channels are supported.

Table. 4.6.4 - 174. Analog recording channels.

| Signal | Description |
|-------------|--|
| IL1 | Phase current I_{L1} |
| IL2 | Phase current I_{L2} |
| IL3 | Phase current I_{L3} |
| I01c | Residual current I_{01} coarse* |
| I01f | Residual current I_{01} fine* |
| I02c | Residual current I_{02} coarse* |
| I02f | Residual current I_{02} fine* |
| IL1" | Phase current I_{L1} (CT card 2) |
| IL2" | Phase current I_{L2} (CT card 2) |
| IL3" | Phase current I_{L3} (CT card 2) |
| I01"c | Residual current I_{01} coarse* (CT card 2) |
| I01"f | Residual current I_{01} fine* (CT card 2) |
| I02"c | Residual current I_{02} coarse* (CT card 2) |
| I02"f | Residual current I_{02} fine* (CT card 2) |
| U1(2)VT1 | Line-to-neutral U_{L1} or line-to-line voltage U_{L12} (VT card 1) |
| U2(3)VT1 | Line-to-neutral U_{L2} or line-to-line voltage U_{L23} (VT card 1) |
| U3(1)VT1 | Line-to-neutral U_{L3} or line-to-line voltage U_{L31} (VT card 1) |
| U0(ss)VT1 | Zero sequence voltage U_0 or synchrocheck voltage U_{SS} (VT card 1) |
| F tracked 1 | Tracked frequency of reference 1 |

| Signal | Description |
|-------------|--|
| F tracked 2 | Tracked frequency of reference 2 |
| F tracked 3 | Tracked frequency of reference 3 |
| ISup | Current measurement module voltage supply supervision (CT card 1) |
| ISup" | Current measurement module voltage supply supervision (CT card 2) |
| USup | Voltage measurement module voltage supply supervision (VT card 1) |
| IL1" | Phase current I_{L1} (CT card 3) |
| IL2" | Phase current I_{L2} (CT card 3) |
| IL3" | Phase current I_{L3} (CT card 3) |
| I01" c | Residual current I_{01} coarse* (CT card 3) |
| I01" f | Residual current I_{01} fine* (CT card 3) |
| I02" c | Residual current I_{02} coarse* (CT card 3) |
| I02" f | Residual current I_{02} fine* (CT card 3) |
| ISup_3 | Current measurement module voltage supply supervision (CT card 3) |
| UL1(2)VT2 | Line-to-neutral U_{L1} or line-to-line voltage U_{L12} (VT card 2) |
| UL2(3)VT2 | Line-to-neutral U_{L2} or line-to-line voltage U_{L23} (VT card 2) |
| UL3(1)VT2 | Line-to-neutral U_{L3} or line-to-line voltage U_{L31} (VT card 2) |
| U0(SS)VT2 | Zero sequence voltage U_0 or synchrocheck voltage U_{ss} (VT card 2) |
| USup_2 | Voltage measurement module voltage supply supervision (VT card 2) |

***NOTE:** There are two signals for each residual current channel in the disturbance recorder: coarse and fine. A coarse signal is capable of sampling in the full range of the current channel but suffers a loss of accuracy at very low currents. A fine signal is capable of sampling at very low currents and with high accuracy but cuts off at higher currents. Table below lists performance of both channels with fine and coarse gain.

Table. 4.6.4 - 175. Residual current channel performance with coarse or residual gain.

| Channel | Coarse gain range | Fine gain range | Fine gain peak |
|---------|-------------------|-----------------|----------------|
| I01 | 0...150 A | 0...10 A | 15 A |
| I02 | 0...75 A | 0...5 A | 8 A |

Table. 4.6.4 - 176. Digital recording channels – Measurements.

| Signal | Description | Signal | Description |
|----------|-------------|--------|-------------|
| Currents | | | |

| Signal | Description | Signal | Description |
|-----------------------|---|-------------------------------|--|
| Pri.Pha.curr.ILx | Primary phase current ILx (IL1, IL2, IL3) | Pha.curr.ILx TRMS Pri | Primary phase current TRMS (IL1, IL2, IL3) |
| Pha.angle ILx | Phase angle ILx (IL1, IL2, IL3) | Pos./Neg./Zero seq.curr. | Positive/Negative/Zero sequence current |
| Pha.curr.ILx | Phase current ILx (IL1, IL2, IL3) | Sec.Pos./Neg./Zero seq.curr. | Secondary positive/negative/zero sequence current |
| Sec.Pha.curr.ILx | Secondary phase current ILx (IL1, IL2, IL3) | Pri.Pos./Neg./Zero seq.curr. | Primary positive/negative/zero sequence current |
| Pri.Res.curr.I0x | Primary residual current I0x (I01, I02) | Pos./Neg./Zero seq.curr.angle | Positive/Negative/Zero sequence current angle |
| Res.curr.angle I0x | Residual current angle I0x (I01, I02) | Res.curr.I0x TRMS | Residual current TRMS I0x (I01, I02) |
| Res.curr.I0x | Residual current I0x (I01, I02) | Res.curr.I0x TRMS Sec | Secondary residual current TRMS I0x (I01, I02) |
| Sec.Res.curr.I0x | Secondary residual current I0x (I01, I02) | Res.curr.I0x TRMS Pri | Primary residual current TRMS I0x (I01, I02) |
| Pri.cal.I0 | Primary calculated I0 | Pha.Lx ampl. THD | Phase Lx amplitude THD (L1, L2, L3) |
| Sec.calc.I0 | Secondary calculated I0 | Pha.Lx pow. THD | Phase Lx power THD (L1, L2, L3) |
| calc.I0 | Calculated I0 | Res.I0x ampl. THD | Residual I0x amplitude THD (I01, I02) |
| calc.I0 Pha.angle | Calculated I0 phase angle | Res.I0x pow. THD | Residual I0x power THD (I01, I02) |
| Pha.curr.ILx TRMS | Phase current TRMS ILx (IL1, IL2, IL3) | P-P curr.ILx | Phase-to-phase current ILx (IL1, IL2, IL3) |
| Pha.curr.ILx TRMS Sec | Secondary phase current TRMS (IL1, IL2, IL3) | P-P curr.I0x | Phase-to-phase current I0x (I01, I02) |
| Voltages | | | |
| Ux Volt p.u. | Ux voltage in per-unit values (U1, U2, U3, U4) | System volt ULxx mag | Magnitude of the system voltage ULxx (UL12, UL23, UL31) |
| Ux Volt pri | Primary Ux voltage (U1, U2, U3, U4) | System volt ULxx mag(kV) | Magnitude of the system voltage ULxx in kilovolts (UL12, UL23, UL31) |
| Ux Volt sec | Secondary Ux voltage (U1, U2, U3, U4) | System volt ULxx ang | Angle of the system voltage ULxx (UL12, UL23, UL31) |
| Ux Volt TRMS p.u. | Ux voltage TRMS in per-unit values (U1, U2, U3, U4) | System volt ULx mag | Magnitude of the system voltage ULx (U1, U2, U3, U4) |

| Signal | Description | Signal | Description |
|-------------------------------------|--|-------------------------------------|---|
| Ux Volt TRMS pri | Primary Ux voltage TRMS (U1, U2, U3, U4) | System volt ULx mag(kV) | Magnitude of the system voltage ULx in kilovolts (U1, U2, U3, U4) |
| Ux Volt TRMS sec | Secondary Ux voltage TRMS (U1, U2, U3, U4) | System volt ULx ang | Angle of the system voltage ULx (U1, U2, U3, U4) |
| Pos./Neg./Zero seq.Volt.p.u. | Positive/Negative/Zero sequence voltage in per-unit values | System volt U0 mag | Magnitude of the system voltage U0 |
| Pos./Neg./Zero seq.Volt.pri | Primary positive/negative/zero sequence voltage | System volt U0 mag(kV) | Magnitude of the system voltage U0 in kilovolts |
| Pos./Neg./Zero seq.Volt.sec | Secondary positive/negative/zero sequence voltage | System volt U0 mag(%) | Magnitude of the system voltage U0 in percentages |
| Ux Angle | Ux angle (U1, U2, U3, U4) | System volt U0 ang | Angle of the system voltage U0 |
| Pos./Neg./Zero Seq volt.Angle | Positive/Negative/Zero sequence voltage angle | Ux Angle difference | Ux angle difference (U1, U2, U3) |
| Resistive and reactive currents | | | |
| ILx Resistive Current p.u. | ILx resistive current in per-unit values (IL1, IL2, IL3) | Pos.seq. Resistive Current Pri. | Primary positive sequence resistive current |
| ILx Reactive Current p.u. | ILx reactive current in per-unit values (IL1, IL2, IL3) | Pos.seq. Reactive Current Pri. | Primary positive sequence reactive current |
| Pos.Seq. Resistive Current p.u. | Positive sequence resistive current in per-unit values | I0x Residual Resistive Current Pri. | Primary residual resistive current I0x (I01, I02) |
| Pos.Seq. Reactive Current p.u. | Positive sequence reactive current in per-unit values | I0x Residual Reactive Current Pri. | Primary residual reactive current I0x (I01, I02) |
| I0x Residual Resistive Current p.u. | I0x residual resistive current in per-unit values (I01, I02) | ILx Resistive Current Sec. | Secondary resistive current ILx (IL1, IL2, IL3) |
| I0x Residual Reactive Current p.u. | I0x residual ractive current in per-unit values (I01, I02) | ILx Reactive Current Sec. | Secondary reactive current ILx (IL1, IL2, IL3) |
| ILx Resistive Current Pri. | Primary resistive current ILx (IL1, IL2, IL3) | I0x Residual Resistive Current Sec. | Secondary residual resistive current I0x (I01, I02) |
| ILx Reactive Current Pri. | Primary reactive current ILx (IL1, IL2, IL3) | I0x Residual Reactive Current Sec. | Secondary residual reactive current I0x (I01, I02) |

| Signal | Description | Signal | Description |
|----------------------------------|--|---|--|
| Power, GYB, frequency | | | |
| Lx PF | Lx power factor (L1, L2, L3) | Curve x Input | Input of Curve x (1, 2, 3, 4) |
| POW1 3PH Apparent power (S) | Three-phase apparent power | Curve x Output | Output of Curve x (1, 2, 3, 4) |
| POW1 3PH Apparent power (S MVA) | Three-phase apparent power in megavolt-amperes | Enablefbasedfunctions(VT1) | Enable frequency-based functions |
| POW1 3PH Active power (P) | Three-phase active power | Track.sys.f. | Tracked system frequency |
| POW1 3PH Active power (P MW) | Three-phase active power in megawatts | Sampl.f. used | Used sample frequency |
| POW1 3PH Reactive power (Q) | Three-phase reactive power | Tr f CH x | Tracked frequency (channels A, B, C) |
| POW1 3PH Reactive power (Q MVar) | Three-phase reactive power in megavars | Alg f Fast | Fast frequency algorithm |
| POW1 3PH Tan(phi) | Three-phase tangent phi | Alg f avg | Average frequency algorithm |
| POW1 3PH Cos(phi) | Three-phase cosine phi | Frequency based protections blocked | When true ("1"), all frequency-based protections are blocked. |
| 3PH PF | Three-phase power factor | f atm. Protections (when not measurable returns to nominal) | Frequency at the moment. If the system nominal is set to 50 Hz, this will show "50 Hz". |
| Neutral conductance G (Pri) | Primary neutral conductance | f atm. Display (when not measurable is 0 Hz) | Frequency at the moment. If the frequency is not measurable, this will show "0 Hz". |
| Neutral susceptance B (Pri) | Primary neutral susceptance | f meas qlty | Quality of tracked frequency |
| Neutral admittance Y (Pri) | Primary neutral admittance | f meas from | Indicates which of the three voltage or current channel frequencies is used by the device. |
| Neutral admittance Y (Ang) | Neutral admittance angle | SS1.meas.frqs | Synchrocheck – the measured frequency from voltage channel 1 |
| I01 Resistive component (Pri) | Primary resistive component I01 | SS2.meas.frqs | Synchrocheck – the measured frequency from voltage channel 2 |
| I01 Capacitive component (Pri) | Primary capacitive component I01 | Enable f based functions | Status of this signal is active when frequency-based protection functions are enabled. |

Table. 4.6.4 - 177. Digital recording channels – Binary signals.

| Signal | Description | Signal | Description |
|----------------------------|---|--|--|
| Dlx | Digital input 1...11 | Timer x Output | Output of Timer 1...10 |
| Open/close control buttons | Active if buttons I or O in the unit's front panel are pressed. | Internal Relay Fault active | If the unit has an internal fault, this signal is active. |
| Status PushButton x On | Status of Push Button 1...12 is ON | (Protection, control and monitoring event signals) | (see the individual function description for the specific outputs) |
| Status PushButton x Off | Status of Push Button 1...12 is OFF | Always True/False | "Always false" is always "0". Always true is always "1". |
| Forced SG in use | Stage forcing in use | OUTx | Output contact statuses |
| SGx Active | Setting group 1...8 active | GOOSE INx | GOOSE input 1...64 |
| Double Ethernet LinkA down | Double ethernet communication card link A connection is down. | GOOSE INx quality | Quality of GOOSE input 1...64 |
| Double Ethernet LinkB down | Double ethernet communication card link B connection is down. | Logical Input x | Logical input 1...32 |
| MBIO ModA Ch x Invalid | Channel 1...8 of MBIO Mod A is invalid | Logical Output x | Logical output 1...64 |
| MBIO ModB Ch x Invalid | Channel 1...8 of MBIO Mod B is invalid | NTP sync alarm | If NTP time synchronization is lost, this signal will be active. |
| MBIO ModB Ch x Invalid | Channel 1...8 of MBIO Mod C is invalid | Ph.Rotating Logic control 0=A-B-C, 1=A-C-B | Phase rotating order at the moment. If true ("1") the phase order is reversed. |

**NOTICE!**

Digital channels are measured every 5 ms.

Recording settings and triggering

Disturbance recorder can be triggered manually or automatically by using the dedicated triggers. Every signal listed in "Digital recording channels" can be selected to trigger the recorder.

The device has a maximum limit of 100 for the number of recordings. Even when the recordings are very small, their number cannot exceed 100. The number of analog and digital channels together with the sample rate and the time setting affect the recording size. See calculation examples below in the section titled "Estimating the maximum length of total recording time".

Table. 4.6.4 - 178. Recorder control settings.

| Name | Range | Description |
|----------------------------------|--|--|
| Recorder enabled | <ul style="list-style-type: none"> • Enabled • Disabled | Enables and disables the disturbance recorder function. |
| Recorder status | <ul style="list-style-type: none"> • Recorder ready • Recording triggered • Recording and storing • Storing recording • Recorder full • Wrong config | Indicates the status of recorder. |
| Clear record+ | $0 \dots 2^{32} - 1$ | Clears selected recording. If "1" is inserted, first recording will be cleared from memory. If "10" is inserted, tenth (10th) recording will be cleared from memory. |
| Manual trigger | <ul style="list-style-type: none"> • - • Trig | Triggers disturbance recording manually. This parameter will return back to "-" automatically. |
| Clear all records | <ul style="list-style-type: none"> • - • Clear | Clears all disturbance recordings. |
| Clear newest record | <ul style="list-style-type: none"> • - • Clear | Clears the newest stored disturbance recording. |
| Clear oldest record | <ul style="list-style-type: none"> • - • Clear | Clears the oldest stored disturbance recording. |
| Max. number of recordings | $0 \dots 100$ | Displays the maximum number of recordings that can be stored in the device's memory with settings currently in use. The maximum number of recordings can go up to 100. |
| Max. length of a recording | $0.000 \dots 1800.000\text{s}$ | Displays the maximum length of a single recording. |
| Max. location of the pre-trigger | $0.000 \dots 1800.000\text{s}$ | Displays the highest pre-triggering time that can be set with the settings currently in use. |
| Recordings in memory | $0 \dots 100$ | Displays how many recordings are stored in the memory. |

Table. 4.6.4 - 179. Recorder trigger setting.

| Name | Description |
|------------------|--|
| Recorder trigger | Selects the trigger input(s). Clicking the "Edit" button brings up a pop-up window, and checking the boxes enable the selected triggers. |

Table. 4.6.4 - 180. Recorder settings.

| Name | Range | Default | Description |
|------------------------------|---|-------------|--|
| Recording length | 0.100...1800.000s | 1s | Sets the length of a recording. |
| Recording mode | <ul style="list-style-type: none"> FIFO Keep olds | FIFO | Selects what happens when the memory is full. "FIFO" (= first in, first out) replaces the oldest stored recording with the latest one. "Keep olds" does not accept new recordings. |
| Analog channel samples | <ul style="list-style-type: none"> 64s/c 32s/c 16s/c 8s/c | 64s/c | Selects the sample rate of the disturbance recorder in samples per cycle. The samples are saved from the measured wave according to this setting. |
| Digital channel samples | 5ms (fixed) | 5 ms(fixed) | The fixed sample rate of the recorded digital channels. |
| Pretriggering time | 0.2...15.0s | 0.2s | Sets the recording length before the trigger. |
| Analog recording CH1...CH20 | 0...8 freely selectable channels | - | Selects the analog channel for recording. Please see the list of all available analog channels in the section titled "Analog and digital recording channels". |
| Automatically get recordings | <ul style="list-style-type: none"> Disabled Enabled | Disabled | <p>Enables and disables the automatic transfer of recordings. The recordings are taken from the device's protection CPU and transferred to the device's FTP directory in the communication CPU; the FTP client then automatically loads the recordings from the device and transfers them further to the SCADA system.</p> <p>Please note that when this setting is enabled, all new disturbance recordings will be pushed to the FTP server of the device. Up to six (6) recordings can be stored in the FTP at once. Once those six recordings have been retrieved and removed, more recordings will then be pushed to the FTP.</p> <p>When a recording has been sent to the FTP server of the device, it is no longer accessible through setting tools <i>Disturbance recorder</i> → <i>Get DR files</i> command.</p> |
| Recorder digital channels | 0...95 freely selectable channels | - | Selects the digital channel for recording. Please see the list of all available digital channels in the section titled "Analog and digital recording channels". |

NOTICE!

The disturbance recorder is not ready unless the "Max. length of a recording" parameter is showing some value other than zero. At least one trigger input has to be selected in the "Recorder Trigger" setting to fulfill this term.

Estimating the maximum length of total recording time

Once the disturbance recorder's settings have been made and loaded to the device, the device automatically calculates and displays the total length of recordings. However, if the user wishes to confirm this calculation, they can do so with the following formula. Please note that the formula assumes there are no other files in the FTP that share the 64 MB space.

$$\frac{\text{Total sample reserve}}{(f_n * (Ch_{an} + 1) * SR) + (200 \text{ Hz} * Ch_{dig})}$$

Where:

- total sample reserve = the number of samples available in the FTP when no other files are saved; calculated by dividing the total number of available bytes by 4 bytes (=the size of one sample); e.g. 64 306 588 bytes/4 bytes = 16 076 647 samples.
- f_n = the nominal frequency (Hz).
- Ch_{an} = the number of analog channels recorded; "+ 1" stands for the time stamp for each recorded sample.
- SR = the selected sample rate (s/c).
- 200 Hz = the rate at which digital channels are always recorded, i.e. 5 ms.
- Ch_{dig} = the number of digital channels recorded.

For example, let us say the nominal frequency is 50 Hz, the selected sample rate is 64 s/c, nine (9) analog channels and two (2) digital channels record. The calculation is as follows:

$$\frac{16\,076\,647 \text{ samples}}{(50 \text{ Hz} * (9 + 1) * 64) + (200 \text{ Hz} * 2)} \approx 496 \text{ s}$$

Therefore, the maximum recording length in our example is approximately 496 seconds.

Application example

This chapter presents an application example of how to set the disturbance recorder and analyze its output. The recorder is configured by using the setting tool software or device HMI, and the results are analyzed with the AQviewer software (is automatically downloaded and installed with AQtivate). Registered users can download the latest tools from the Arcteq website (arcteq.fi/downloads/).

In this example, we want the recordings to be made according to the following specifications:

- the recording length is 6.0 s
- the sample rate is 64 s/c (therefore, with a 50 Hz system frequency a sample is taken every 312.5 μ s)
- the analog channels 1...8 are used
- digital channels are tracked every 5 ms
- the first activation of the overcurrent stage trip ($I > \text{TRIP}$) triggers the recorder
- the pre-triggering time is 5 (ie. how long is recorded before the $I > \text{TRIP}$ signal) and the post-triggering time is 1 s

The image below shows how these settings are placed in the setting tool.

Figure. 4.6.4 - 170. Disturbance recorder settings.

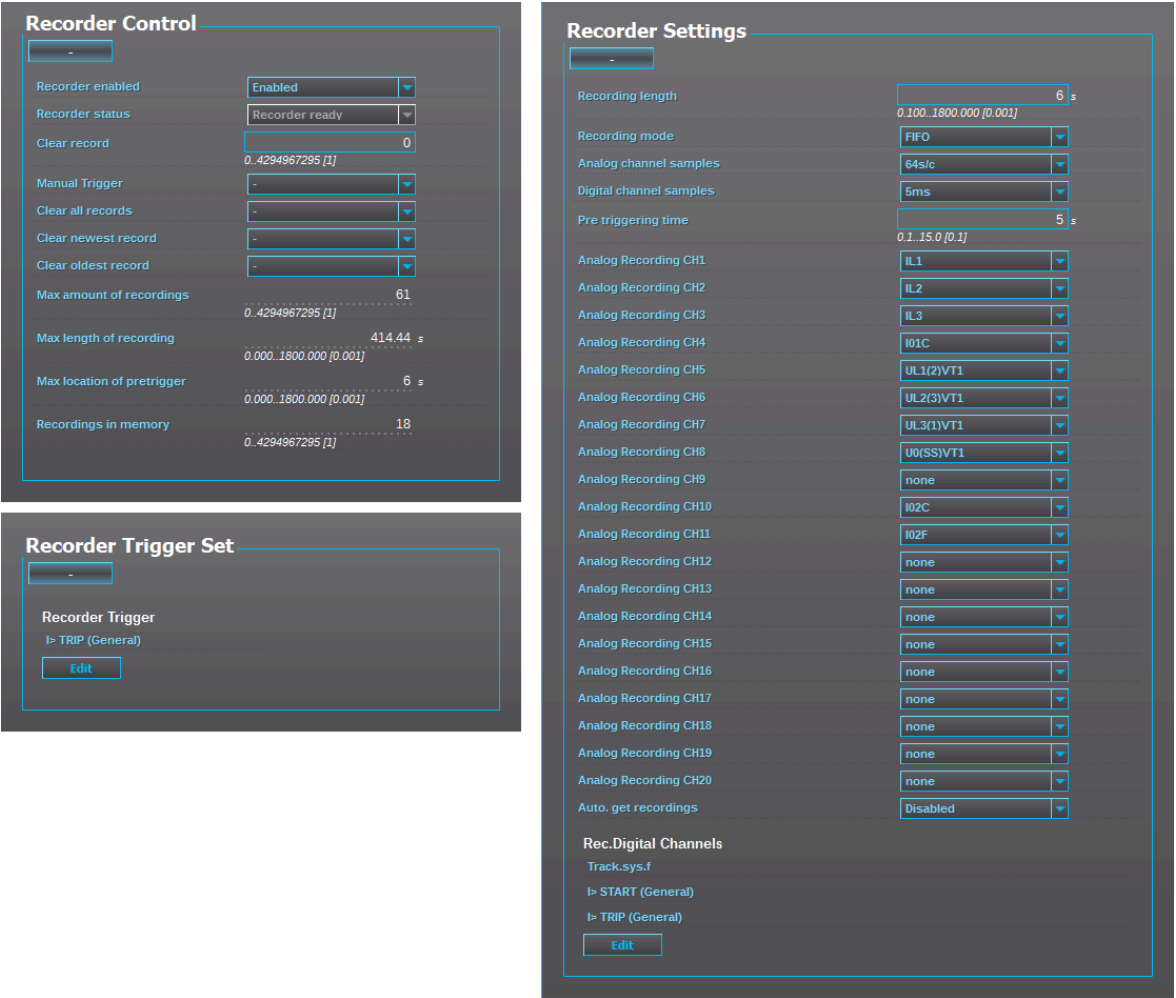
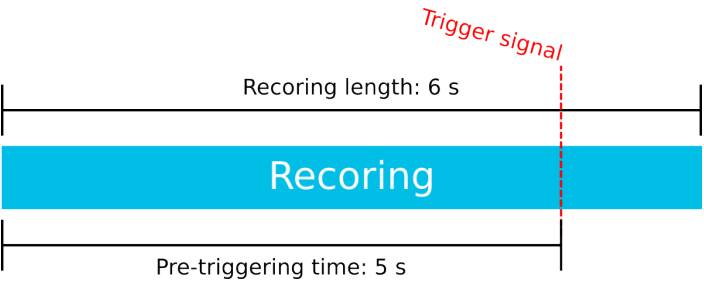
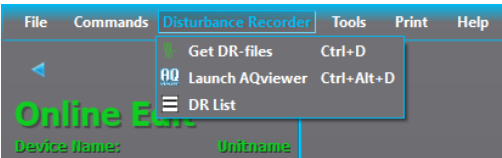


Figure. 4.6.4 - 171. Effects of recording length and pre-triggering time signals. This example is based on the settings shown above.



When there is at least one recording in the device's memory, that recording can be analyzed by using the AQviewer software (see the image below). However, the recording must first be made accessible to AQviewer. The user can read it from the device's memory (*Disturbance recorder* → *Get DR-files*). Alternatively, the user can load the recordings individually (*Disturbance recorder* → *DR List*) from a folder in the PC's hard disk drive; the exact location of the folder is described in *Tools* → *Settings* → *DR path*.



The user can also launch the AQviewer software from the *Disturbance recorder* menu. AQviewer software instructions can be found in AQtivate 200 Instruction manual (arcteq.fi/downloads/).

Events

The disturbance recorder function (abbreviated "DR" in event block names) generates events and registers from the status changes in the events listed below. Events cannot be masked off. The events triggered by the function are recorded with a time stamp.

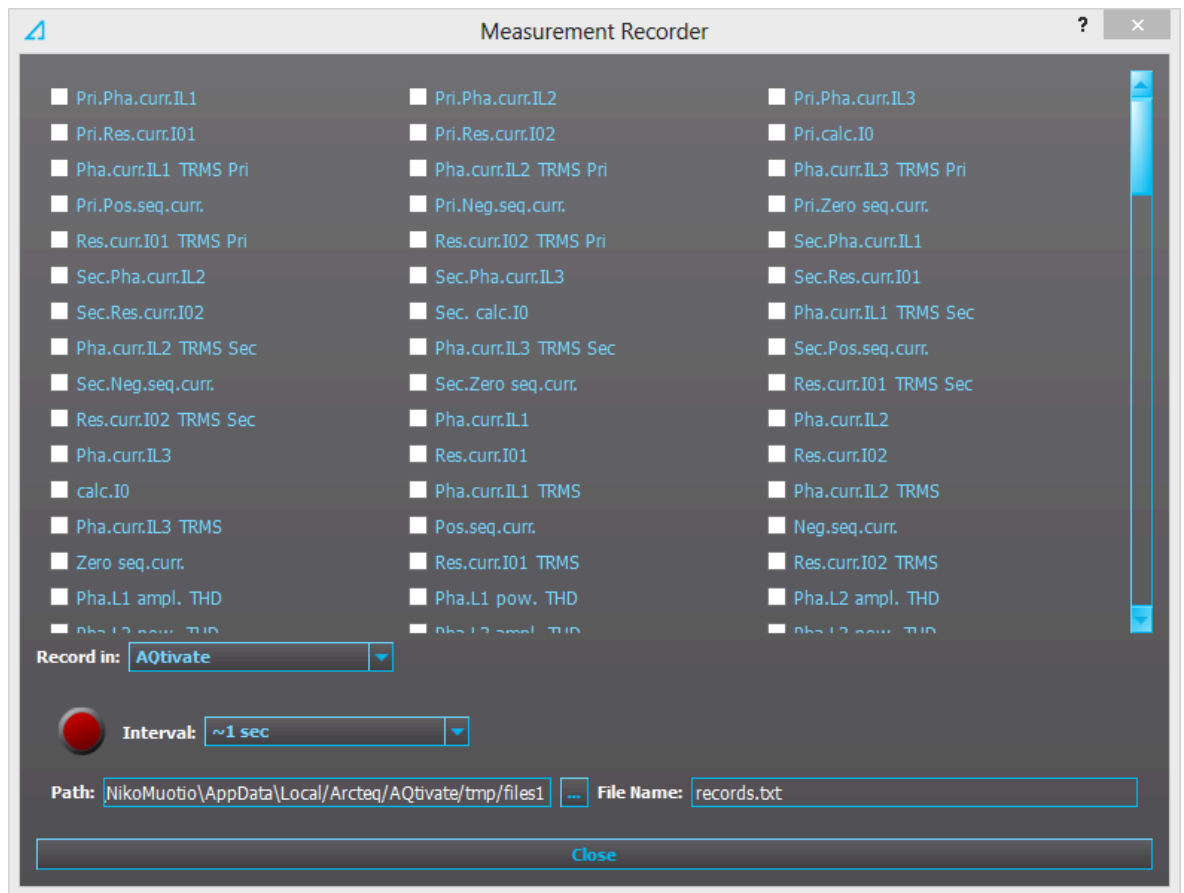
Table. 4.6.4 - 181. Event messages.

| Event block name | Event names |
|------------------|--------------------------|
| DR1 | Recorder triggered ON |
| DR1 | Recorder triggered OFF |
| DR1 | Recorder memory cleared |
| DR1 | Oldest record cleared |
| DR1 | Recorder memory full ON |
| DR1 | Recorder memory full OFF |
| DR1 | Recording ON |
| DR1 | Recording OFF |
| DR1 | Storing recording ON |
| DR1 | Storing recording OFF |
| DR1 | Newest record cleared |

4.6.5 Event logger

Event logger records status changes of protection functions, digital inputs, logical signals etc. Events are recorded with a timestamp. The time stamp resolution is 1 ms. Up to 15 000 events can be stored at once. When 15 000 events have been recorded, the event history will begin to remove the oldest events to make room for new events. You can find more information about event masks in the selected function's "Events" tab. Event masks determine what is recorded into the event history; they are configured in each function's individual settings in the *Protection, Control and Monitoring* menu. Event history is accessible with PC setting tool (*Tools → Events and Logs → Event history*) and from the device HMI if "Events" view has been configured with Carousel designer in PC setting tool.

4.6.6 Measurement recorder



Measurements can be recorded to a file with the measurement recorder. The chosen measurements are recorded at selected intervals. In the "Measurement recorder" window, the measurements the user wants to be recorded can be selected by checking their respective check boxes. In order for the measurement recorder to activate, a connection to a device must be established via the setting tool software and its Live Edit mode must be enabled (see the AQtivate 200 manual for more information). Navigate to the measurement recorder through *Tools* → *Miscellaneous tools* → *Measurement recorder*. The recording interval can be changed from the "Interval" drop-down menu. From the "Record in" drop-down menu the user can also choose whether the measurements are recorded in the setting tool or in the device.

If the recording is done in the setting tool, both the setting tool software and its Live Edit mode have to be activated. The user can change the recording file location by editing the "Path" field. File names can also be changed with the "File name" field. Hitting the "Record" button (the big red circle) starts the recorder. Please note that closing the "Measurement recorder" window does not stop the recording; that can only be done by hitting the "Stop" button (the big blue circle).

If the recording is done in the device, only the recording interval needs to be set before recording can be started. The setting tool estimates the maximum recording time, which depends on the recording interval. When the measurement recorder is running, the measurements can be viewed in graph form with the AQtivate PRO software (see the image below).

Figure. 4.6.6 - 172. Measurement recorder values viewed with AQtivate PRO.



Table. 4.6.6 - 182. Available analog signals.

| | | |
|-----------------------|-----------------------------|----------------------------------|
| Current measurements | P-P Curr.I" L3 | L1 Imp.React.Ind.E.Mvarh |
| Pri.Pha.Curr.IL1 | P-P Curr.I" 01 | L1 Imp.React.Ind.E.kvarh |
| Pri.Pha.Curr.IL2 | P-P Curr.I" 02 | L1 Exp/Imp React.Ind.E.bal.Mvarh |
| Pri.Pha.Curr.IL3 | Pha.angle I" L1 | L1 Exp/Imp React.Ind.E.bal.kvarh |
| Pri.Res.Curr.I01 | Pha.angle I" L2 | L2 Exp.Active Energy MWh |
| Pri.Res.Curr.I02 | Pha.angle I" L3 | L2 Exp.Active Energy kWh |
| Pri.Calc.I0 | Res.Curr.angle I" 01 | L2 Imp.Active Energy MWh |
| Pha.Curr.IL1 TRMS Pri | Res.Curr.angle I" 02 | L2 Imp.Active Energy kWh |
| Pha.Curr.IL2 TRMS Pri | Calc.I" 0.angle | L2 Exp/Imp Act. E balance MWh |
| Pha.Curr.IL3 TRMS Pri | I" Pos.Seq.Curr.angle | L2 Exp/Imp Act. E balance kWh |
| Pri.Pos.Seq.Curr. | I" Neg.Seq.Curr.angle | L2 Exp.React.Cap.E.Mvarh |
| Pri.Neg.Seq.Curr. | I" Zero.Seq.Curr.angle | L2 Exp.React.Cap.E.kvarh |
| Pri.Zero.Seq.Curr. | Voltage measurements | L2 Imp.React.Cap.E.Mvarh |
| Res.Curr.I01 TRMS Pri | U1Volt Pri | L2 Imp.React.Cap.E.kvarh |
| Res.Curr.I02 TRMS Pri | U2Volt Pri | L2 Exp/Imp React.Cap.E.bal.Mvarh |
| Sec.Pha.Curr.IL1 | U3Volt Pri | L2 Exp/Imp React.Cap.E.bal.kvarh |
| Sec.Pha.Curr.IL2 | U4Volt Pri | L2 Exp.React.Ind.E.Mvarh |

| | | |
|-----------------------|---------------------|----------------------------------|
| Sec.Pha.Curr.IL3 | U1Volt Pri TRMS | L2 Exp.React.Ind.E.kvarh |
| Sec.Res.Curr.I01 | U2Volt Pri TRMS | L2 Imp.React.Ind.E.Mvarh |
| Sec.Res.Curr.I02 | U3Volt Pri TRMS | L2 Imp.React.Ind.E.kvarh |
| Sec.Calc.I0 | U4Volt Pri TRMS | L2 Exp/Imp React.Ind.E.bal.Mvarh |
| Pha.Curr.IL1 TRMS Sec | Pos.Seq.Volt.Pri | L2 Exp/Imp React.Ind.E.bal.kvarh |
| Pha.Curr.IL2 TRMS Sec | Neg.Seq.Volt.Pri | L3 Exp.Active Energy MWh |
| Pha.Curr.IL3 TRMS Sec | Zero.Seq.Volt.Pri | L3 Exp.Active Energy kWh |
| Sec.Pos.Seq.Curr. | U1Volt Sec | L3 Imp.Active Energy MWh |
| Sec.Neg.Seq.Curr. | U2Volt Sec | L3 Imp.Active Energy kWh |
| Sec.Zero.Seq.Curr. | U3Volt Sec | L3 Exp/Imp Act. E balance MWh |
| Res.Curr.I01 TRMS Sec | U4Volt Sec | L3 Exp/Imp Act. E balance kWh |
| Res.Curr.I02 TRMS Sec | U1Volt Sec TRMS | L3 Exp.React.Cap.E.Mvarh |
| Pha.Curr.IL1 | U2Volt Sec TRMS | L3 Exp.React.Cap.E.kvarh |
| Pha.Curr.IL2 | U3Volt Sec TRMS | L3 Imp.React.Cap.E.Mvarh |
| Pha.Curr.IL3 | U4Volt Sec TRMS | L3 Imp.React.Cap.E.kvarh |
| Res.Curr.I01 | Pos.Seq.Volt.Sec | L3 Exp/Imp React.Cap.E.bal.Mvarh |
| Res.Curr.I02 | Neg.Seq.Volt.Sec | L3 Exp/Imp React.Cap.E.bal.kvarh |
| Calc.I0 | Zero.Seq.Volt.Sec | L3 Exp.React.Ind.E.Mvarh |
| Pha.Curr.IL1 TRMS | U1Volt p.u. | L3 Exp.React.Ind.E.kvarh |
| Pha.Curr.IL2 TRMS | U2Volt p.u. | L3 Imp.React.Ind.E.Mvarh |
| Pha.Curr.IL3 TRMS | U3Volt p.u. | L3 Imp.React.Ind.E.kvarh |
| Pos.Seq.Curr. | U4Volt p.u. | L3 Exp/Imp React.Ind.E.bal.Mvarh |
| Neg.Seq.Curr. | U1Volt TRMS p.u. | L3 Exp/Imp React.Ind.E.bal.kvarh |
| Zero.Seq.Curr. | U2Volt TRMS p.u. | Exp.Active Energy MWh |
| Res.Curr.I01 TRMS | U3Volt p.u. | Exp.Active Energy kWh |
| Res.Curr.I02 TRMS | U4Volt p.u. | Imp.Active Energy MWh |
| Pha.L1 ampl. THD | Pos.Seq.Volt. p.u. | Imp.Active Energy kWh |
| Pha.L2 ampl. THD | Neg.Seq.Volt. p.u. | Exp/Imp Act. E balance MWh |
| Pha.L3 ampl. THD | Zero.Seq.Volt. p.u. | Exp/Imp Act. E balance kWh |
| Pha.L1 pow. THD | U1Volt Angle | Exp.React.Cap.E.Mvarh |
| Pha.L2 pow. THD | U2Volt Angle | Exp.React.Cap.E.kvarh |
| Pha.L3 pow. THD | U3Volt Angle | Imp.React.Cap.E.Mvarh |

| | | |
|------------------------|---------------------------|-------------------------------|
| Res.I01 ampl. THD | U4Volt Angle | Imp.React.Cap.E.kvarh |
| Res.I01 pow. THD | Pos.Seq.Volt. Angle | Exp/Imp React.Cap.E.bal.Mvarh |
| Res.I02 ampl. THD | Neg.Seq.Volt. Angle | Exp/Imp React.Cap.E.bal.kvarh |
| Res.I02 pow. THD | Zero.Seq.Volt. Angle | Exp.React.Ind.E.Mvarh |
| P-P Curr.IL1 | System Volt UL12 mag | Exp.React.Ind.E.kvarh |
| P-P Curr.IL2 | System Volt UL12 mag (kV) | Imp.React.Ind.E.Mvarh |
| P-P Curr.IL3 | System Volt UL23 mag | Imp.React.Ind.E.kvarh |
| P-P Curr.I01 | System Volt UL23 mag (kV) | Exp/Imp React.Ind.E.bal.Mvarh |
| P-P Curr.I02 | System Volt UL31 mag | Exp/Imp React.Ind.E.bal.kvarh |
| Pha.angle IL1 | System Volt UL31 mag (kV) | Other measurements |
| Pha.angle IL2 | System Volt UL1 mag | TM> Trip expect mode |
| Pha.angle IL3 | System Volt UL1 mag (kV) | TM> Time to 100% T |
| Res.Curr.angle I01 | System Volt UL2 mag | TM> Reference T curr. |
| Res.Curr.angle I02 | System Volt UL2 mag (kV) | TM> Active meas curr. |
| Calc.I0.angle | System Volt UL3 mag | TM> T est.with act. curr. |
| Pos.Seq.Curr.angle | System Volt UL3 mag (kV) | TM> T at the moment |
| Neg.Seq.Curr.angle | System Volt U0 mag | TM> Max.Temp.Rise All. |
| Zero.Seq.Curr.angle | System Volt U0 mag (kV) | TM> Temp.Rise atm. |
| Pri.Pha.Curr.I"L1 | System Volt U1 mag | TM> Hot Spot estimate |
| Pri.Pha.Curr.I"L2 | System Volt U1 mag (kV) | TM> Hot Spot Max. All |
| Pri.Pha.Curr.I"L3 | System Volt U2 mag | TM> Used k for amb.temp |
| Pri.Res.Curr.I"01 | System Volt U2 mag (kV) | TM> Trip delay remaining |
| Pri.Res.Curr.I"02 | System Volt U3 mag | TM> Alarm 1 time to rel. |
| Pri.Calc.I"0 | System Volt U3 mag (kV) | TM> Alarm 2 time to rel. |
| Pha.Curr.I"L1 TRMS Pri | System Volt U4 mag | TM> Inhibit time to rel. |
| Pha.Curr.I"L2 TRMS Pri | System Volt U4 mag (kV) | TM> Trip time to rel. |
| Pha.Curr.I"L3 TRMS Pri | System Volt UL12 ang | S1 Measurement |
| I" Pri.Pos.Seq.Curr. | System Volt UL23 ang | S2 Measurement |
| I" Pri.Neg.Seq.Curr. | System Volt UL31 ang | S3 Measurement |
| I" Pri.Zero.Seq.Curr. | System Volt UL1 ang | S4 Measurement |
| Res.Curr.I"01 TRMS Pri | System Volt UL2 ang | S5 Measurement |
| Res.Curr.I"02 TRMS Pri | System Volt UL3 ang | S6 Measurement |

| | | |
|------------------------|-------------------------------|----------------------|
| Sec.Pha.Curr.I"L1 | System Volt U0 ang | S7 Measurement |
| Sec.Pha.Curr.I"L2 | System Volt U1 ang | S8 Measurement |
| Sec.Pha.Curr.I"L3 | System Volt U2 ang | S9 Measurement |
| Sec.Res.Curr.I"01 | System Volt U3 ang | S10 Measurement |
| Sec.Res.Curr.I"02 | System Volt U4 ang | S11 Measurement |
| Sec.Calc.I"0 | Power measurements | S12 Measurement |
| Pha.Curr.I"L1 TRMS Sec | L1 Apparent Power (S) | Sys.meas.frqs |
| Pha.Curr.I"L2 TRMS Sec | L1 Active Power (P) | f atm. |
| Pha.Curr.I"L3 TRMS Sec | L1 Reactive Power (Q) | f meas from |
| I" Sec.Pos.Seq.Curr. | L1 Tan(phi) | SS1.meas.frqs |
| I" Sec.Neg.Seq.Curr. | L1 Cos(phi) | SS1f meas from |
| I" Sec.Zero.Seq.Curr. | L2 Apparent Power (S) | SS2 meas.frqs |
| Res.Curr.I"01 TRMS Sec | L2 Active Power (P) | SS2f meas from |
| Res.Curr.I"02 TRMS Sec | L2 Reactive Power (Q) | L1 Bias current |
| Pha.Curr.I"L1 | L2 Tan(phi) | L1 Diff current |
| Pha.Curr.I"L2 | L2 Cos(phi) | L1 Char current |
| Pha.Curr.I"L3 | L3 Apparent Power (S) | L2 Bias current |
| Res.Curr.I"01 | L3 Active Power (P) | L2 Diff current |
| Res.Curr.I"02 | L3 Reactive Power (Q) | L2 Char current |
| Calc.I"0 | L3 Tan(phi) | L3 Bias current |
| Pha.Curr.I"L1 TRMS | L3 Cos(phi) | L3 Diff current |
| Pha.Curr.I"L2 TRMS | 3PH Apparent Power (S) | L3 Char current |
| Pha.Curr.I"L3 TRMS | 3PH Active Power (P) | HV I0d> Bias current |
| I" Pos.Seq.Curr. | 3PH Reactive Power (Q) | HV I0d> Diff current |
| I" Neg.Seq.Curr. | 3PH Tan(phi) | HV I0d> Char current |
| I" Zero.Seq.Curr. | 3PH Cos(phi) | LV I0d> Bias current |
| Res.Curr.I"01 TRMS | Energy measurements | LV I0d> Diff current |
| Res.Curr.I"02 TRMS | L1 Exp.Active Energy MWh | LV I0d> Char current |
| Pha.IL"1 ampl. THD | L1 Exp.Active Energy kWh | Curve1 Input |
| Pha.IL"2 ampl. THD | L1 Imp.Active Energy MWh | Curve1 Output |
| Pha.IL"3 ampl. THD | L1 Imp.Active Energy kWh | Curve2 Input |
| Pha.IL"1 pow. THD | L1 Exp/Imp Act. E balance MWh | Curve2 Output |

| | | |
|--------------------|----------------------------------|----------------------|
| Pha.IL"2 pow. THD | L1 Exp/Imp Act. E balance kWh | Curve3 Input |
| Pha.IL"3 pow. THD | L1 Exp.React.Cap.E.Mvarh | Curve3 Output |
| Res.I"01 ampl. THD | L1 Exp.React.Cap.E.kvarh | Curve4 Input |
| Res.I"01 pow. THD | L1 Imp.React.Cap.E.Mvarh | Curve4 Output |
| Res.I"02 ampl. THD | L1 Imp.React.Cap.E.kvarh | Control mode |
| Res.I"02 pow. THD | L1 Exp/Imp React.Cap.E.bal.Mvarh | Motor status |
| P-P Curr.I"L1 | L1 Exp/Imp React.Cap.E.bal.kvarh | Active setting group |
| P-P Curr.I"L2 | L1 Exp.React.Ind.E.Mvarh | |
| | L1 Exp.React.Ind.E.kvarh | |

4.6.7 Measurement value recorder

The measurement value recorder function records the value of the selected magnitudes at the time of a pre-defined trigger signal. A typical application is the recording of fault currents or voltages at the time of the breaker trips; it can also be used to record the values from any trigger signal set by the user. The user can select whether the function records per-unit values or primary values. Additionally, the user can set the function to record overcurrent fault types or voltage fault types. The function operates instantly from the trigger signal.

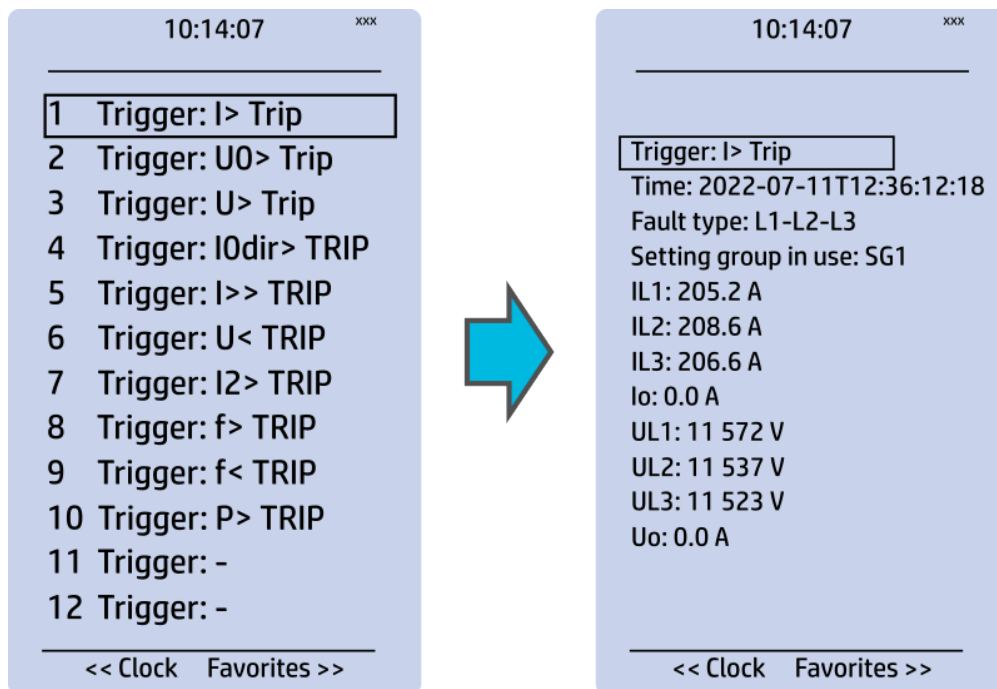
The measurement value recorder function has an integrated fault display which shows the current fault values when the tripped by one of the following functions:

- I> (non-directional overcurrent)
- I2> (current unbalance)
- Idir> (directional overcurrent)
- IO> (non-directional earth fault)
- IOdir> (directional earth fault)
- f<(underfrequency)
- f> (overfrequency)
- U< (undervoltage)
- U> (overvoltage)
- U1/U2 >/< (sequence voltage)
- U0> (residual voltage)
- P> (over power)
- P< (under power)
- Prev> (reverse power)
- T> (thermal overload)

When any of these functions trip, the fault values and the fault type are displayed in the Mimic view. The view can be enabled by activating the "VREC Trigger on" setting (*Tools → Events and logs → Set alarm events*). The resetting of the fault values is done by the input selected in the *General* menu.

Function keeps 12 latest recordings in memory. Recordings can be viewed in the HMI if "Fault registers" view has been added with "Carousel designer" tool.

Figure. 4.6.7 - 173. 12 latest recordings can be accessed from HMI if "Fault registers" view has been enabled in "Carousel designer" tool.



Measured input

The function block uses analog current and voltage measurement values. Based on these values, the device calculates the primary and secondary values of currents, voltages, powers, and impedances as well as other values.

The user can set up to eight (8) magnitudes to be recorded when the function is triggered. An overcurrent fault type, a voltage fault type, and a tripped stage can be recorded and reported straight to SCADA.

NOTICE!



The available measurement values depend on the device type. If only current analog measurements are available, the recorder can solely use signals which only use current. The same applies, if only voltage analog measurements are available.

| Currents | Description |
|---|--|
| IL1 (ff), IL2 (ff), IL3 (ff), I01 (ff), I02 (ff) | The fundamental frequency current measurement values (RMS) of phase currents and of residual currents. |
| IL1TRMS, IL2TRMS, IL3TRMS, I01TRMS, I02TRMS | The TRMS current measurement values of phase currents and of residual currents. |
| IL1,2,3 & I01/I02 2 nd h., 3 rd h., 4 th h., 5 th h., 7 th h., 9 th h., 11 th h., 13 th h., 15 th h., 17 th h., 19 th h. | The magnitudes of phase current components: Fundamental, 2 nd harmonic, 3 rd harmonic, 4 th harmonic, 5 th harmonic 7 th , harmonic 9 th , harmonic 11 th , harmonic 13 th , harmonic 15 th , harmonic 17 th , harmonic 19 th harmonic current. |
| I1, I2, I0Z | The positive sequence current, the negative sequence current and the zero sequence current. |
| I0CalcMag | The residual current calculated from phase currents. |

| Currents | Description |
|---|---|
| IL1Ang, IL2Ang, IL3Ang, I01Ang, I02Ang, I0CalcAng, I1Ang, I2Ang | The angles of each measured current. |
| Voltages | Description |
| UL1Mag, UL2Mag, UL3Mag, UL12Mag, UL23Mag, UL31Mag U0Mag, U0CalcMag | The magnitudes of phase voltages, of phase-to-phase voltages, and of residual voltages. |
| U1 Pos.seq V mag, U2 Neg.seq V mag | The positive sequence voltage and the negative sequence voltage. |
| UL1Ang, UL2Ang, UL3Ang, UL12Ang, UL23Ang, UL31Ang U0Ang, U0CalcAng | The angles of phase voltages, of phase-to-phase voltages, and of residual voltages. |
| U1 Pos.seq V Ang, U2 Neg.seq V Ang | The positive sequence angle and the negative sequence angle. |
| Powers | Description |
| S3PH, P3PH, Q3PH | The three-phase apparent, active and reactive powers. |
| SL1, SL2, SL3, PL1, PL2, PL3, QL1, QL2, QL3 | The phase apparent, active and reactive powers. |
| tanfi3PH, tanfiL1, tanfiL2, tanfiL3 | The tan (φ) of three-phase powers and phase powers. |
| cosfi3PH, cosfiL1, cosfiL2, cosfiL3 | The cos (φ) of three-phase powers and phase powers. |
| Impedances and admittances | Description |
| RL12, RL23, RL31 XL12, XL23, XL31, RL1, RL2, RL3 XL1, XL2, XL3 Z12, Z23, Z31 ZL1, ZL2, ZL3 | The phase-to-phase and phase-to-neutral resistances, reactances and impedances. |
| Z12Ang, Z23Ang, Z31Ang, ZL1Ang, ZL2Ang, ZL3Ang | The phase-to-phase and phase-to-neutral impedance angles. |
| Rseq, Xseq, Zseq RseqAng, XseqAng, ZseqAng | The positive sequence resistance, reactance and impedance values and angles. |
| GL1, GL2, GL3, G0 BL1, BL2, BL3, B0 YL1, YL2, YL3, Y0 | The conductances, susceptances and admittances. |
| YL1angle, YL2angle, YL3angle Y0angle | The admittance angles. |
| Others | Description |
| System f. | The tracking frequency in use at that moment. |
| Ref f1 | The reference frequency 1. |

| Currents | Description |
|--------------------|--|
| Ref f2 | The reference frequency 2. |
| M thermal T | The motor thermal temperature. |
| F thermal T | The feeder thermal temperature. |
| T thermal T | The transformer thermal temperature. |
| RTD meas 1...16 | The RTD measurement channels 1...16. |
| Ext RTD meas 1...8 | The external RTD measurement channels 1...8 (ADAM module). |

Reported values

When triggered, the function holds the recorded values of up to eight channels, as set. In addition to this tripped stage, the overcurrent fault type and the voltage fault types are reported to SCADA.

Table. 4.6.7 - 183. Reported values.

| Name | Range | Description |
|------------------------|--|-----------------------------|
| Tripped stage | <ul style="list-style-type: none"> • - • I> Trip • I>> Trip • I>>> Trip • I>>>> Trip • IDir> Trip • IDir>> Trip • IDir>>> Trip • IDir>>>> Trip • U> Trip • U>> Trip • U>>> Trip • U>>>> Trip • U< Trip • U<< Trip • U<<< Trip • U<<<< Trip • IO> TRIP • IO>> Trip • IO>>> Trip • IO>>>> Trip • IODir> Trip • IODir>> Trip • IODir>>> Trip • IODir>>>> Trip • f> Trip • f>> Trip • f>>> Trip • f>>>> Trip • f< Trip • f<< Trip • f<<< Trip • f<<<< Trip • P> Trip • P< Trip • Prev> Trip • T> Trip • I2> Trip • I2>> Trip • I2>>> Trip • I2>>>> Trip • U1/2 > Trip • U1/2 >> Trip • U1/2 >>> Trip • U1/2 >>>> Trip • U0> Trip • U0>> Trip • U0>>> Trip • U0>>>> Trip | The tripped stage. |
| Overcurrent fault type | <ul style="list-style-type: none"> • A-G • B-G • A-B • C-G • A-C • B-C • A-B-C | The overcurrent fault type. |

| Name | Range | Description |
|--------------------|---|--|
| Voltage fault type | <ul style="list-style-type: none"> • A(AB) • B(BC) • A-B(AB-BC) • C(CA) • A-C(AB-CA) • B-C(BC-CA) • A-B-C • Overfrequency • Underfrequency • Overpower • Underpower • Reversepower • Thermal overload • Unbalance • Harmonic overcurrent • Residual overvoltage | The voltage fault type. |
| Magnitude 1...8 | 0.000...1800.000 A/V/p.u. | The recorded value in one of the eight channels. |

Events

The measurement value recorder function (abbreviated "VREC" in event block names) generates events from the status changes in the events listed below. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp.

Table. 4.6.7 - 184. Event messages.

| Event block name | Event name |
|------------------|------------------------|
| VREC1 | Recorder triggered ON |
| VREC1 | Recorder triggered OFF |

5 Communication

5.1 Connections menu

"Connections" menu is found under "Communication" menu. It contains all basic settings of ethernet port and RS-485 serial port included with every AQ-200 device as well as settings of communication option cards.

Table. 5.1 - 185. Ethernet settings.

| Name | Range | Description |
|---|--|--|
| IP address | 0.0.0.0...255.255.255.255 | Set IP address of the ethernet port in the back of the AQ-200 series device. |
| Netmask | 0.0.0.0...255.255.255.255 | Set netmask of the ethernet port in the back of the AQ-200 series device. |
| Gateway | 0.0.0.0...255.255.255.255 | Set gateway of the ethernet port in the back of the AQ-200 series device. |
| MAC-Address | 00-00-00-00-00-00...FF-FF-FF-FF-FF-FF | Indication of MAC address of the AQ-200 series device. |
| Storm Protection | <ul style="list-style-type: none"> Disable Enable | When enabled, the Storm protection functionality of the internal switch in the device is enabled. This functionality aims to protect the device from excess ethernet traffic caused by storm situation. When enabled, the packet rate allowed to pass through on the ingress port towards the device, is limited to 150 packets per second. Multicast packets are also included in the packet limit. |
| Double Ethernet card mode | <ul style="list-style-type: none"> Switch HSR PRP | If the device has a double ethernet option card it is possible to choose its mode. |
| COM A and Ethernet option card connection | <ul style="list-style-type: none"> Block all Allow both directions Allow COM A to option card Allow option card to COM A | If the device has ethernet option card it is possible to determine the allowed direction of data. |
| Double Ethernet link events | <ul style="list-style-type: none"> Disable Enable | Disables or enables "Double Ethernet Link A down" and "Double Ethernet Link B down" logic signals and events. |
| Double Ethernet PRP ports | <ul style="list-style-type: none"> AB BA | LanA and LanB port assignment for communication cards that support PRP. |

Virtual Ethernet enables the device to be connected to multiple different networks simultaneously via one physical Ethernet connection. Virtual Ethernet has its own separate IP address and network configurations. All Ethernet-based protocol servers listen for client connections on the IP addresses of both the physical Ethernet and the Virtual Ethernet.

Table. 5.1 - 186. Virtual Ethernet settings.

| Name | Description |
|-----------------------------------|---|
| Enable virtual adapter (No / Yes) | Enable virtual adapter. Off by default. |
| IP address | Set IP address of the virtual adapter. |
| Netmask | Set netmask of the virtual adapter. |
| Gateway | Set gateway of the virtual adapter. |

AQ-200 series devices are always equipped with an RS-485 serial port. In the software it is identified as "Serial COM1" port.

Table. 5.1 - 187. Serial COM1 settings.

| Name | Range | Description |
|----------|--|---|
| Bitrate | <ul style="list-style-type: none"> 9600bps 19200bps 38400bps | Bitrate used by RS-485 port. |
| Databits | 7...8 | Databits used by RS-485 port. |
| Parity | <ul style="list-style-type: none"> None Even Odd | Paritybits used by RS-485 port. |
| Stopbits | 1...2 | Stopbits used by RS-485 port. |
| Protocol | <ul style="list-style-type: none"> None ModbusRTU ModbusIO IEC103 SPA DNP3 IEC101 | Communication protocol used by RS-485 port. |

AQ-200 series supports communication option card type that has serial fiber ports (Serial COM2) an RS-232 port (Serial COM3).

Table. 5.1 - 188. Serial COM2 settings.

| Name | Range | Description |
|----------|---|---|
| Bitrate | <ul style="list-style-type: none"> 9600bps 19200bps 38400bps | Bitrate used by serial fiber channels. |
| Databits | 7...8 | Databits used by serial fiber channels. |
| Parity | <ul style="list-style-type: none"> None Even Odd | Paritybits used by serial fiber channels. |
| Stopbits | 1...2 | Stopbits used by serial fiber channels. |

| Name | Range | Description |
|------------|--|---|
| Protocol | <ul style="list-style-type: none"> None ModbusRTU ModbusIO IEC103 SPA DNP3 IEC101 | Communication protocol used by serial fiber channels. |
| Echo | <ul style="list-style-type: none"> Off On | Enable or disable echo. |
| Idle Light | <ul style="list-style-type: none"> Off On | Idle light behaviour. |

Table. 5.1 - 189. Serial COM3 settings.

| Name | Range | Description |
|----------|--|---|
| Bitrate | <ul style="list-style-type: none"> 9600bps 19200bps 38400bps | Bitrate used by RS-232 port. |
| Databits | 7...8 | Databits used by RS-232 port. |
| Parity | <ul style="list-style-type: none"> None Even Odd | Paritybits used by RS-232 port. |
| Stopbits | 1...2 | Stopbits used by RS-232 port. |
| Protocol | <ul style="list-style-type: none"> None ModbusRTU ModbusIO IEC103 SPA DNP3 IEC101 | Communication protocol used by RS-232 port. |

5.2 Time synchronization

Time synchronization source can be selected with "Time synchronization" parameter in the "General" menu.

Table. 5.2 - 190. General time synchronization source settings.

| Name | Range | Description |
|-----------------------------|---|---|
| Time synchronization source | <ul style="list-style-type: none"> Internal External NTP External serial IRIG-B | Selection of time synchronization source. |

5.2.1 Internal

If no external time synchronization source is available the mode should be set to "internal". This means that the AQ-200 device clock runs completely on its own. Time can be set to the device with AQtivate setting tool with *Commands* → *Sync Time* command or in the clock view from the HMI. When using *Sync time* command AQtivate sets the time to device the connected computer is currently using. Please note that the clock doesn't run when the device is powered off.

5.2.2 NTP

When enabled, the NTP (Network Time Protocol) service can use external time sources to synchronize the device's system time. The NTP client service uses an Ethernet connection to connect to the NTP time server. NTP can be enabled by setting the primary time server and the secondary time server parameters to the address of the system's NTP time source(s).

Table. 5.2.2 - 191. Server settings.

| Name | Range | Description |
|-------------------------------|---------------------------|---|
| Primary time server address | 0.0.0.0...255.255.255.255 | Defines the address of the primary NTP server. Setting this parameter at "0.0.0.0" means that the server is not in use. |
| Secondary time server address | 0.0.0.0...255.255.255.255 | Defines the address of the secondary (or backup) NTP server. Setting this parameter at "0.0.0.0" means that the server is not in use. |

Table. 5.2.2 - 192. Client settings.

| Name | Range | Description |
|----------------|---|--|
| IP address | 0.0.0.0...255.255.255.255 | Defines the address of the NTP client. NOTE: This address must be different than the general IP address of the device. |
| Netmask | 0.0.0.0...255.255.255.255 | Defines the client's netmask. |
| Gateway | 0.0.0.0...255.255.255.255 | Defines the client's gateway. |
| MAC address | 00-00-00-00-00-00...FF-FF-FF-FF-FF-FF | Displays the MAC address of the client. |
| Network status | <ul style="list-style-type: none"> Running IP error NM error GW error | Displays the status or possible errors of the NTP (client) settings. |

Table. 5.2.2 - 193. Status.

| Name | Range | Description |
|------------------------|---|---|
| NTP quality for events | <ul style="list-style-type: none"> No sync Synchronized | Displays the status of the NTP time synchronization at the moment. NOTE: This indication is not valid if another time synchronization method is used (external serial). |

| Name | Range | Description |
|-----------------------------|----------------|--|
| NTP-processed message count | 0...4294967295 | Displays the number of messages processed by the NTP protocol. |

**NOTICE!**

A unique IP address must be reserved for the NTP client. The device's IP address cannot be used.

Additionally, the time zone of the device can be set by connecting to the device and the selecting the time zone at *Commands* → *Set time zone* in AQtivate setting tool.

5.3 Communication protocols

5.3.1 IEC 61850

The user can enable the IEC 61850 protocol in device models that support this protocol at *Communication* → *Protocols* → *IEC61850*. AQ-21x frame units support Edition 1 of IEC 61850. AQ-25x frame units support both Edition 1 and 2 of IEC 61850. The following services are supported by IEC 61850 in Arcteq devices:

- Up to six data sets (predefined data sets can be edited with the IEC 61850 tool in AQtivate)
- Report Control Blocks (both buffered and unbuffered reporting)
- Control ('Direct operate with normal security', 'Select before operate with normal security', 'Direct with enhanced security' and 'Select before operate with enhanced security' control sequences)
- Disturbance recording file transfer
- GOOSE
- Time synchronization

The device's current IEC 61850 setup can be viewed and edited with the IEC61850 tool (*Tools* → *Communication* → *IEC 61850*).

Settings

The general setting parameters for the IEC 61850 protocol are visible both in AQtivate and in the local HMI. The settings are described in the table below.

Table. 5.3.1 - 194. General settings.

| Name | Range | Step | Default | Description |
|-----------------------|---|------|----------|--|
| Enable IEC 61850 | <ul style="list-style-type: none"> • Disabled • Enabled | - | Disabled | Enables and disables the IEC 61850 communication protocol. |
| Reconfigure IEC 61850 | <ul style="list-style-type: none"> • - • Reconfigure | - | - | Reconfigures IEC 61850 settings. |
| IP port | 0...65 535 | 1 | 102 | Defines the IP port used by the IEC 61850 protocol. The standard (and default) port is 102. |

| Name | Range | Step | Default | Description |
|----------------------------|--|----------|----------------|---|
| Control Authority switch | <ul style="list-style-type: none"> Remote Control Station Level Control | - | Remote Control | The device can be set to allow object control via IEC 61850 only from clients that are of category Station level control. This would mean that other Remote control clients would not be allowed to control. In Remote control mode all IEC 61850 clients of both remote and station level category are allowed to control objects. |
| Ethernet port | <ul style="list-style-type: none"> All COM A Double ethernet card | - | All | Determines which ports use IEC61850. Parameter is visible if double ethernet option card is found in the device. |
| General deadband | 0.1...10.0 % | 0.1 % | 2 % | Determines the general data reporting deadband settings. |
| Active energy deadband | 0.1...1000.0 kWh | 0.1 kWh | 2 kWh | Determines the data reporting deadband settings for this measurement. |
| Reactive energy deadband | 0.1...1000.0 kVar | 0.1 kVar | 2 kVar | Determines the data reporting deadband settings for this measurement. |
| Active power deadband | 0.1...1000.0 kW | 0.1 kW | 2 kW | Determines the data reporting deadband settings for this measurement. |
| Reactive power deadband | 0.1...1000.0 kVar | 0.1 kVar | 2 kVar | Determines the data reporting deadband settings for this measurement. |
| Apparent power deadband | 0.1...1000.0 kVA | 0.1 kVA | 2 kVA | Determines the data reporting deadband settings for this measurement. |
| Power factor deadband | 0.01...0.99 | 0.01 | 0.05 | Determines the data reporting deadband settings for this measurement. |
| Frequency deadband | 0.01...1.00 Hz | 0.01 Hz | 0.1 Hz | Determines the data reporting deadband settings for this measurement. |
| Current deadband | 0.01...50.00 A | 0.01 A | 5 A | Determines the data reporting deadband settings for this measurement. |
| Residual current deadband | 0.01...50.00 A | 0.01 A | 0.2 A | Determines the data reporting deadband settings for this measurement. |
| Voltage deadband | 0.01...5000.00 V | 0.01 V | 200 V | Determines the data reporting deadband settings for this measurement. |
| Residual voltage deadband | 0.01...5000.00 V | 0.01 V | 200 V | Determines the data reporting deadband settings for this measurement. |
| Angle measurement deadband | 0.1...5.0 deg | 0.1 deg | 1 deg | Determines the data reporting deadband settings for this measurement. |
| Integration time | 0...10 000 ms | 1 ms | 0 ms | Determines the integration time of the protocol. If this parameter is set to "0 ms", no integration time is in use. |

| Name | Range | Step | Default | Description |
|---------------------|--|------|---------|--|
| GOOSE Ethernet port | <ul style="list-style-type: none"> All COM A Double ethernet card | - | All | Determines which ports can use GOOSE communication. Visible if double ethernet option card is found in the device. |

For more information on the IEC 61850 communication protocol support, please refer to the conformance statement documents (www.arcteq.fi/downloads/ → AQ 200 series → Resources).

5.3.1.1 GOOSE

Arcteq devices support both GOOSE publisher and GOOSE subscriber. GOOSE subscriber is enabled with the "GOOSE subscriber enable" parameter at *Communication* → *Protocols* → *IEC 61850/GOOSE*. The GOOSE inputs are configured using either the local HMI or the AQtivate software.

There are up to 64 GOOSE inputs available for use. Each of the GOOSE inputs also has a corresponding input quality signal which can also be used in internal logic. The quality is good, when the input quality status is "low" (that is, when the quality is marked as "0"). The value of the input quality can switch on as a result of a GOOSE time-out or a configuration error, for example. The status and quality of the various logical input signals can be viewed at the *GOOSE IN status* and *GOOSE IN quality* tabs at *Control* → *Device I/O* → *Logical signals*.

GOOSE input settings

The table below presents the different settings available for all 64 GOOSE inputs.

These settings can be found from *Communication* → *Protocols* → *IEC61850*.

Table. 5.3.1.1 - 195. GOOSE input settings.

| Name | Range | Description |
|------------------------------------|---|--|
| In use | <ul style="list-style-type: none"> No (Default) Yes | Enables and disables the GOOSE input in question. |
| Application ID ("AppID") | 0x0...0x3FFF | Defines the application ID that will be matched with the publisher's GOOSE control block. |
| Configuration revision ("ConfRev") | 1...2 ³² -1 | Defines the configuration revision that will be matched with the publisher's GOOSE control block. |
| Data index ("DataIdx") | 0...99 | Defines the data index of the value in the matched published frame. It is the status of the GOOSE input. |
| NextIdx is quality | <ul style="list-style-type: none"> No (Default) Yes | Selects whether or not the next received input is the quality bit of the GOOSE input. |

GOOSE input descriptions

Each of the GOOSE inputs can be given a description. The user defined description are displayed in most of the menus:

- logic editor
- matrix
- block settings
-
-
- etc.

These settings can be found from *Control* → *Device IO* → *Logical Signals* → *GOOSE IN Description*.

Table. 5.3.1.1 - 196. GOOSE input user description.

| Name | Range | Default | Description |
|--------------------------------|-------------------|------------|---|
| User editable description GI x | 1...31 characters | GOOSE IN x | Description of the GOOSE input. This description is used in several menu types for easier identification. |

GOOSE events

GOOSE signals generate events from status changes. The user can select which event messages are stored in the main event buffer: ON, OFF, or both. The events triggered by the function are recorded with a time stamp and with process data values. The time stamp resolution is 1 ms.

Table. 5.3.1.1 - 197. GOOSE event

| Event block name | Event name | Description |
|------------------|----------------------------------|--|
| GOOSE1...GOOSE2 | GOOSE IN 1...64 ON/OFF | Status change of GOOSE input. |
| GOOSE3...GOOSE4 | GOOSE IN 1...64 quality Bad/Good | Status change of GOOSE inputs quality. |

Setting the publisher

The configuration of the GOOSE publisher is done using the IEC 61850 tool in AQtivate (*Tools* → *Communication* → *IEC 61850*). Refer to *AQtivate-200 Instruction manual* for more information on how to set up GOOSE publisher.

5.3.2 Modbus/TCP and Modbus/RTU

The device supports both Modbus/TCP and Modbus/RTU communication. Modbus/TCP uses the Ethernet connection to communicate with Modbus/TCP clients. Modbus/RTU is a serial protocol that can be selected for the available serial ports.

The following Modbus function types are supported:

- Read multiple holding registers (function code 3)
- Write single holding register (function code 6)
- Write multiple holding registers (function code 16)
- Read/Write multiple registers (function code 23)

The following data can be accessed using both Modbus/TCP and Modbus/RTU:

- Device measurements
- Device I/O
- Commands
- Events

- Time

Once the configuration file has been loaded, the user can access the Modbus map of the device via the AQtivate software (*Tools* → *Communication* → *Modbus Map*). Please note that holding registers start from 1. Some masters might begin numbering holding register from 0 instead of 1; this will cause an offset of 1 between the device and the master. Modbus map can be edited with Modbus Configurator (*Tools* → *Communication* → *Modbus Configurator*).

Table. 5.3.2 - 198. Modbus/TCP settings.

| Parameter | Range | Description |
|-------------------|---|--|
| Enable Modbus/TCP | <ul style="list-style-type: none"> • Disabled • Enabled | Enables and disables the Modbus/TCP on the Ethernet port. |
| IP port | 0...65 535 | Defines the IP port used by Modbus/TCP. The standard port (and the default setting) is 502. |
| Event read mode | <ul style="list-style-type: none"> • Get oldest available • Continue previous connection • New events only | Get oldest event possible (Default) Continue with the event idx from previous connection Get only new events from connection time and forward. |

Table. 5.3.2 - 199. Modbus/RTU settings.

| Parameter | Range | Description |
|---------------|---------|--|
| Slave address | 1...247 | Defines the Modbus/RTU slave address for the unit. |

Reading events

Modbus protocol does not support time-stamped events by standard definition. This means that every vendor must come up with their own definition how to transfer events from the device to the client. In AQ-200 series devices events can be read from HR17...HR22 holding registers. HR17 contains the event-code, HR18...20 contains the time-stamp in UTC, HR21 contains a sequential index and HR22 is reserved for future expansion. See the Modbus Map for more information. The event-codes and their meaning can be found from Event list (*Tools* → *Events and Logs* → *Event list* in setting tool). The event-code in HR17 is 0 if no new events can be found in the device event-buffer. Every time HR17 is read from client the event in event-buffer is consumed and on following read operation the next un-read event information can be found from event registers. HR11...HR16 registers contains a back-up of last read event. This is because some users want to double-check that no events were lost

5.3.3 IEC 103

IEC 103 is the shortened form of the international standard IEC 60870-5-103. The AQ-200 series units are able to run as a secondary (slave) station. The IEC 103 protocol can be selected for the serial ports that are available in the device. A primary (master) station can then communicate with the AQ-200 device and receive information by polling from the slave device. The transfer of disturbance recordings is not supported.

NOTE: Once the configuration file has been loaded, the IEC 103 map of the device can be found in the AQtivate software (*Tools* → *IEC 103 map*).

The following table presents the setting parameters for the IEC 103 protocol.

| Name | Range | Step | Default | Description |
|----------------------|---------------|------|---------|---|
| Slave address | 1...254 | 1 | 1 | Defines the IEC 103 slave address for the unit. |
| Measurement interval | 0...60 000 ms | 1 ms | 2000 ms | Defines the interval for the measurements update. |

5.3.4 IEC 101/104

The standards IEC 60870-5-101 and IEC 60870-5-104 are closely related. Both are derived from the IEC 60870-5 standard. On the physical layer the IEC 101 protocol uses serial communication whereas the IEC 104 protocol uses Ethernet communication. The IEC 101/104 implementation works as a slave in the unbalanced mode.

For detailed information please refer to the IEC 101/104 interoperability document (www.arcteq.fi/downloads/ → AQ-200 series → Resources → "AQ-200 IEC101 & IEC104 interoperability").

IEC 101 settings

Table. 5.3.4 - 200. IEC 101 settings.

| Name | Range | Step | Default | Description |
|---------------------------------|------------|------|---------|--|
| Common address of ASDU | 0...65 534 | 1 | 1 | Defines the common address of the application service data unit (ASDU) for the IEC 101 communication protocol. |
| Common address of ASDU size | 1...2 | 1 | 2 | Defines the size of the common address of ASDU. |
| Link layer address | 0...65 534 | 1 | 1 | Defines the address for the link layer. |
| Link layer address size | 1...2 | 1 | 2 | Defines the address size of the link layer. |
| Information object address size | 2...3 | 1 | 3 | Defines the address size of the information object. |
| Cause of transmission size | 1...2 | 1 | 2 | Defines the cause of transmission size. |

IEC 104 settings

Table. 5.3.4 - 201. IEC 104 settings.

| Name | Range | Step | Default | Description |
|----------------|---|------|----------|--|
| IEC 104 enable | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Enables and disables the IEC 104 communication protocol. |
| IP port | 0...65 535 | 1 | 2404 | Defines the IP port used by the protocol. |

| Name | Range | Step | Default | Description |
|------------------------|------------|------|---------|---|
| Common address of ASDU | 0...65 534 | 1 | 1 | Defines the common address of the application service data unit (ASDU) for the IEC 104 communication protocol. |
| APDU timeout (t1) | 0...3600 s | 1 s | 0 s | The maximum amount of time the slave waits for a transmitted Application Protocol Data Unit (APDU) to be confirmed as received by the master. |
| Idle timeout (t3) | 0...3600 s | 1 s | 0 s | The slave outstation can use a test frame to determine if the channel is still available after a prolonged period of communications inactivity. Test frame is sent at an interval specified here. |

Measurement scaling coefficients

The measurement scaling coefficients are available for the following measurements, in addition to the general measurement scaling coefficient:

Table. 5.3.4 - 202. Measurements with scaling coefficient settings.

| Name | Range |
|------------------|--|
| Active energy | <ul style="list-style-type: none"> • No scaling • 1/10 • 1/100 • 1/1000 • 1/10 000 • 1/100 000 • 1/1 000 000 • 10 • 100 • 1000 • 10 000 • 100 000 • 1 000 000 |
| Reactive energy | |
| Active power | |
| Reactive power | |
| Apparent power | |
| Power factor | |
| Frequency | |
| Current | |
| Residual current | |
| Voltage | |
| Residual voltage | |
| Angle | |

Deadband settings.

Table. 5.3.4 - 203. Analog change deadband settings.

| Name | Range | Step | Default | Description |
|------------------------|-----------------|--------|---------|---|
| General deadband | 0.1...10.0% | 0.1% | 2% | Determines the general data reporting deadband settings. |
| Active energy deadband | 0.1...1000.0kWh | 0.1kWh | 2kWh | Determines the data reporting deadband settings for this measurement. |

| Name | Range | Step | Default | Description |
|----------------------------|------------------|---------|---------|---|
| Reactive energy deadband | 0.1...1000.0kVar | 0.1kVar | 2kVar | |
| Active power deadband | 0.1...1000.0kW | 0.1kW | 2kW | |
| Reactive power deadband | 0.1...1000.0kVar | 0.1kVar | 2kVar | |
| Apparent power deadband | 0.1...1000.0kVA | 0.1kVA | 2kVA | |
| Power factor deadband | 0.01...0.99 | 0.01 | 0.05 | |
| Frequency deadband | 0.01...1.00Hz | 0.01Hz | 0.1Hz | |
| Current deadband | 0.01...50.00A | 0.01A | 5A | |
| Residual current deadband | 0.01...50.00A | 0.01A | 0.2A | |
| Voltage deadband | 0.01...5000.00V | 0.01V | 200V | |
| Residual voltage deadband | 0.01...5000.00V | 0.01V | 200V | |
| Angle measurement deadband | 0.1...5.0deg | 0.1deg | 1deg | |
| Integration time | 0...10 000ms | 1ms | - | Determines the integration time of the protocol. If this parameter is set to "0 ms", no integration time is in use. |

5.3.5 SPA

The device can act as a SPA slave. SPA can be selected as the communication protocol for the RS-485 port (Serial COM1). When the device has a serial option card, the SPA protocol can also be selected as the communication protocol for the serial fiber (Serial COM2) ports or RS-232 (Serial COM3) port. Please refer to the chapter "[Construction and installation](#)" in the device manual to see the connections for these modules.

The data transfer rate of SPA is 9600 bps, but it can also be set to 19 200 bps or 38 400 bps. As a slave the device sends data on demand or by sequenced polling. The available data can be measurements, circuit breaker states, function starts, function trips, etc. The full SPA signal map can be found in AQtivate (*Tools* → *SPA map*).

The SPA event addresses can be found at *Tools* → *Events and logs* → *Event list*.

Table. 5.3.5 - 204. SPA setting parameters.

| Name | Range | Description |
|---------------|---|--|
| SPA address | 1...899 | SPA slave address. |
| UTC time sync | <ul style="list-style-type: none"> Disabled Enabled | Determines if UTC time is used when synchronizing time. When disabled it is assumed time synchronization uses local time. If enabled it is assumed that UTC time is used. When UTC time is used the timezone must be set at <i>Commands</i> → <i>Set time zone</i> . |

**NOTICE!**

To access SPA map and event list, an .aqs configuration file should be downloaded from the device.

5.3.6 DNP3

DNP3 is a protocol standard which is controlled by the DNP Users Group (www.dnp.org). The implementation of a DNP3 slave is compliant with the DNP3 subset (level) 2, but it also contains some functionalities of the higher levels. For detailed information please refer to the DNP3 Device Profile document (www.arcteq.fi/downloads/ → AQ-200 series → Resources).

Settings

The following table describes the DNP3 setting parameters.

Table. 5.3.6 - 205. Settings.

| Name | Range | Step | Default | Description |
|-----------------------------------|---|------|----------|--|
| Enable DNP3 TCP | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Enables and disables the DNP3 TCP communication protocol when the Ethernet port is used for DNP3. If a serial port is used, the DNP3 protocol can be enabled from <i>Communication</i> → <i>DNP3</i> . |
| IP port | 0...65 535 | 1 | 20 000 | Defines the IP port used by the protocol. |
| Slave address | 1...65 519 | 1 | 1 | Defines the DNP3 slave address of the unit. |
| Master address | 1...65 534 | 1 | 2 | Defines the address for the allowed master. |
| Link layer time-out | 0...60 000ms | 1ms | 0ms | Defines the length of the time-out for the link layer. |
| Link layer retries | 1...20 | 1 | 1 | Defines the number of retries for the link layer. |
| Diagnostic - Error counter | 0...2 ³² -1 | 1 | - | Counts the total number of errors in received and sent messages. |
| Diagnostic - Transmitted messages | 0...2 ³² -1 | 1 | - | Counts the total number of transmitted messages. |
| Diagnostic - Received messages | 0...2 ³² -1 | 1 | - | Counts the total number of received messages. |

Default variations

Table. 5.3.6 - 206. Default variations.

| Name | Range | Default | Description |
|----------------------------------|--|---------|---|
| Group 1 variation (BI) | <ul style="list-style-type: none"> Var 1 Var 2 | Var 1 | Selects the variation of the binary signal. |
| Group 2 variation (BI change) | <ul style="list-style-type: none"> Var 1 Var 2 | Var 2 | Selects the variation of the binary signal change. |
| Group 3 variation (DBI) | <ul style="list-style-type: none"> Var 1 Var 2 | Var 1 | Selects the variation of the double point signal. |
| Group 4 variation (DBI change) | <ul style="list-style-type: none"> Var 1 Var 2 | Var 2 | Selects the variation of the double point signal. |
| Group 20 variation (CNTR) | <ul style="list-style-type: none"> Var 1 Var 2 Var 5 Var 6 | Var 1 | Selects the variation of the control signal. |
| Group 22 variation (CNTR change) | <ul style="list-style-type: none"> Var 1 Var 2 Var 5 Var 6 | Var 5 | Selects the variation of the control signal change. |
| Group 30 variation (AI) | <ul style="list-style-type: none"> Var 1 Var 2 Var 3 Var 4 Var 5 | Var 5 | Selects the variation of the analog signal. |
| Group 32 variation (AI change) | <ul style="list-style-type: none"> Var 1 Var 2 Var 3 Var 4 Var 5 Var 7 | Var 5 | Selects the variation of the analog signal change. |

Setting the analog change deadbands

Table. 5.3.6 - 207. Analog change deadband settings.

| Name | Range | Step | Default | Description |
|--------------------------|------------------|---------|---------|---|
| General deadband | 0.1...10.0% | 0.1% | 2% | Determines the general data reporting deadband settings. |
| Active energy deadband | 0.1...1000.0kWh | 0.1kWh | 2kWh | Determines the data reporting deadband settings for this measurement. |
| Reactive energy deadband | 0.1...1000.0kVar | 0.1kVar | 2kVar | |
| Active power deadband | 0.1...1000.0kW | 0.1kW | 2kW | |

| Name | Range | Step | Default | Description |
|----------------------------|------------------|---------|---------|---|
| Reactive power deadband | 0.1...1000.0kVar | 0.1kVar | 2kVar | |
| Apparent power deadband | 0.1...1000.0kVA | 0.1kVA | 2kVA | |
| Power factor deadband | 0.01...0.99 | 0.01 | 0.05 | |
| Frequency deadband | 0.01...1.00Hz | 0.01Hz | 0.1Hz | |
| Current deadband | 0.01...50.00A | 0.01A | 5A | |
| Residual current deadband | 0.01...50.00A | 0.01A | 0.2A | |
| Voltage deadband | 0.01...5000.00V | 0.01V | 200V | |
| Residual voltage deadband | 0.01...5000.00V | 0.01V | 200V | |
| Angle measurement deadband | 0.1...5.0deg | 0.1deg | 1deg | |
| Integration time | 0...10 000ms | 1ms | 0ms | Determines the integration time of the protocol. If this parameter is set to "0 ms", no integration time is in use. |

5.3.7 Modbus I/O

The Modbus I/O protocol can be selected to communicate on the available serial ports. The Modbus I/O is actually a Modbus/RTU master implementation that is dedicated to communicating with serial Modbus/RTU slaves such as RTD input modules. Up to three (3) Modbus/RTU slaves can be connected to the same bus polled by the Modbus I/O implementation. These are named I/O Module A, I/O Module B and I/O Module C. Each of the modules can be configured using parameters in the following two tables.

Table. 5.3.7 - 208. Module settings.

| Name | Range | Description |
|----------------------|---|---|
| I/O module X address | 0...247 | Defines the Modbus unit address for the selected I/O Module (A, B, or C). If this setting is set to "0", the selected module is not in use. |
| Module x type | <ul style="list-style-type: none"> ADAM-4018+ ADAM-4015 | Selects the module type. |
| Channels in use | Channel 0...Channel 7 (or None) | Selects the number of channels to be used by the module. |

Table. 5.3.7 - 209. Channel settings.

| Name | Range | Step | Default | Description |
|-------------------|--|------|----------|---|
| Thermocouple type | <ul style="list-style-type: none"> +/- 20mA 4...20mA Type J Type K Type T Type E Type R Type S | - | 4...20mA | <p>Selects the thermocouple or the mA input connected to the I/O module.</p> <p>Types J, K, T and E are nickel-alloy thermocouples, while Types R and S are platinum/rhodium-alloy thermocouples.</p> |
| Input value | -101.0...2000.0 | 0.1 | - | Displays the input value of the selected channel. |
| Input status | <ul style="list-style-type: none"> Invalid OK | - | - | Displays the input status of the selected channel. |

5.4 Analog fault registers

At *Communication* → *General I/O* → *Analog fault registers* the user can set up to twelve (12) channels to record the measured value when a protection function starts or trips. These values can be read in two ways: locally from this same menu, or through a communication protocol if one is in use.

The following table presents the setting parameters available for the 12 channels.

Table. 5.4 - 210. Fault register settings.

| Name | Range | Step | Default | Description |
|-----------------------|---|------|-------------|---|
| Select record source | Not in use I>, I>>, I>>>, I>>>> (IL1, IL2, IL3) Id>, Id>>, Id>>>, Id>>>> (IL1, IL2, IL3) IO>, IO>>, IO>>>, IO>>>> (IO) IOd>, IOd>>, IOd>>>, IOd>>>> (IO) FLX (Fault locator) | - | Not in use | <p>Selects the protection function and its stage to be used as the source for the fault register recording.</p> <p>The user can choose between non-directional overcurrent, directional overcurrent, non-directional earth fault, directional earth fault, and fault locator functions.</p> |
| Select record trigger | <ul style="list-style-type: none"> TRIP signal START signal START and TRIP signals | - | TRIP signal | Selects what triggers the fault register recording: the selected function's TRIP signal, its START signal, or either one. |
| Recorded fault value | - 1000 000.00...1 000 000.00 | 0.01 | - | Displays the recorded measurement value at the time of the selected fault register trigger. |

5.5 Real-time measurements to communication

With the *Real-time signals to communication* menu the user can report measurements to SCADA in a faster interval. The real measurement update delay depends on the used communication protocol and equipment used. Up to ten (10) magnitudes can be selected. The recorded value can be either a per-unit value or a primary value (set by the user).

Measurable values

Function block uses analog current and voltage measurement values. The device uses these values as the basis when it calculates the primary and secondary values of currents, voltages, powers, impedances and other values.

Table. 5.5 - 211. Available measured values.

| Signals | Description |
|---|---|
| Currents | |
| IL1 (ff), IL2 (ff), IL3 (ff), I01 (ff), I02 (ff) | Fundamental frequency (RMS) current measurement values of phase currents and residual currents. |
| IL1 (TRMS), IL2 (TRMS), IL3 (TRMS), I01 (TRMS), I02 (TRMS) | TRMS current measurement values of phase currents and residual currents. |
| IL1, IL2, IL3, I01, I02 & 2 nd h., 3 rd h., 4 th h., 5 th h., 7 th h., 9 th h., 11 th h., 13 th h., 15 th h., 17 th h., 19 th h. | Magnitudes of the phase current components: 2 nd harmonic, 3 rd harmonic, 4 th harmonic, 5 th harmonic 7 th , harmonic 9 th , harmonic 11 th , harmonic 13 th , harmonic 15 th , harmonic 17 th , harmonic 19 th harmonic current. |
| I1, I2, I0Z | Positive sequence current, negative sequence current and zero sequence current. |
| I0CalcMag | Residual current calculated from phase currents. |
| IL1Ang, IL2Ang, IL3Ang, I01Ang, I02Ang, I0CalcAng I1Ang, I2Ang | Angles of each measured current. |
| Voltages | |
| UL1Mag, UL2Mag, UL3Mag, UL12Mag, UL23Mag, UL31Mag, U0Mag, U0CalcMag | Magnitudes of phase voltages, phase-to-phase voltages and residual voltages. |
| U1 Pos.seq V mag, U2 Neg.seq V mag | Positive and negative sequence voltages. |
| UL1Ang, UL2Ang, UL3Ang, UL12Ang, UL23Ang, UL31Ang, U0Ang, U0CalcAng | Angles of phase voltages, phase-to-phase voltages and residual voltages. |
| U1 Pos.seq V Ang, U2 Neg.seq V Ang | Positive and negative sequence angles. |
| Powers | |
| S3PH P3PH Q3PH | Three-phase apparent, active and reactive power. |
| SL1, SL2, SL3, PL1, PL2, PL3, QL1, QL2, QL3 | Phase apparent, active and reactive powers. |

| Signals | Description |
|--|---|
| tanfi3PH tanfiL1 tanfiL2 tanfiL3 | Tan (ϕ) of three-phase powers and phase powers. |
| cosfi3PH cosfiL1 cosfiL2 cosfiL3 | Cos (ϕ) of three-phase powers and phase powers. |
| Impedances and admittances | |
| RL12, RL23, RL31 XL12, XL23, XL31 RL1, RL2, RL3 XL1, XL2, XL3 Z12, Z23, Z31 ZL1, ZL2, ZL3 | Phase-to-phase and phase-to-neutral resistances, reactances and impedances. |
| Z12Ang, Z23Ang, Z31Ang, ZL1Ang, ZL2Ang, ZL3Ang | Phase-to-phase and phase-to-neutral impedance angles. |
| Rseq, Xseq, Zseq RseqAng, XseqAng, ZseqAng | Positive sequence resistance, reactance and impedance values and angles. |
| GL1, GL2, GL3, G0 BL1, BL2, BL3, B0 YL1, YL2, YL3, Y0 | Conductances, susceptances and admittances. |
| YL1angle, YL2angle, YL3angle, Y0angle | Admittance angles. |
| Others | |
| System f. | Used tracking frequency at the moment. |
| Ref f1 | Reference frequency 1. |
| Ref f2 | Reference frequency 2. |
| M thermal T | Motor thermal temperature. |
| F thermal T | Feeder thermal temperature. |
| T thermal T | Transformer thermal temperature. |
| RTD meas 1...16 | RTD measurement channels 1...16. |
| Ext RTD meas 1...8 | External RTD measurement channels 1...8 (ADAM module). |

Settings

Table. 5.5 - 212. Settings.

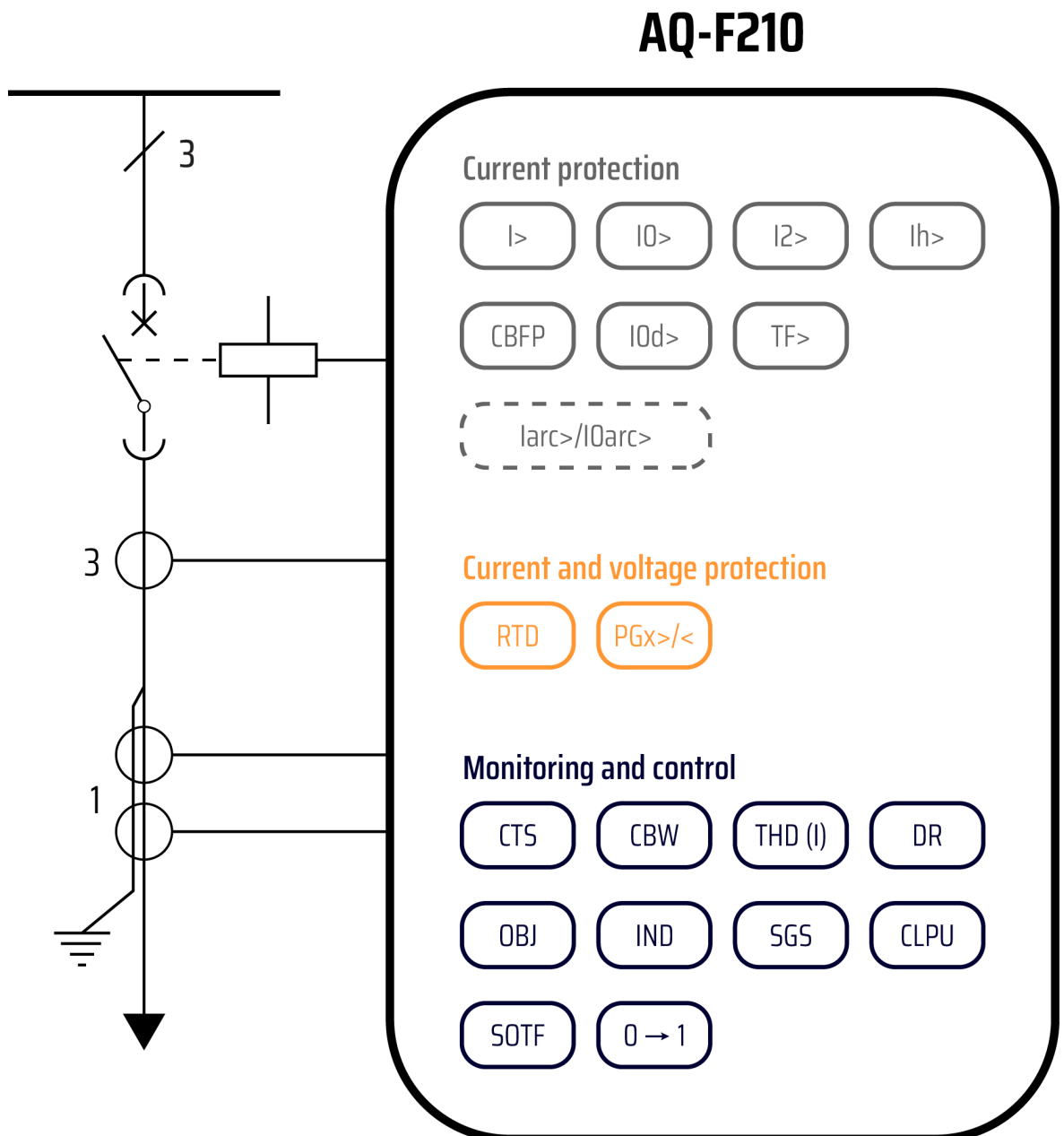
| Name | Range | Step | Default | Description |
|---------------------------------|---|------|----------|--|
| Measurement value recorder mode | <ul style="list-style-type: none"> Disabled Activated | - | Disabled | Activates and disables the real-time signals to communication. |

| Name | Range | Step | Default | Description |
|---------------------------------|--|-------|----------|--|
| Scale current values to primary | <ul style="list-style-type: none"> No Yes | - | No | Selects whether or not values are scaled to primary. |
| Slot X magnitude selection | <ul style="list-style-type: none"> Currents Voltages Powers Impedance (ZRX) and admittance (YGB) Others | - | Currents | Selects the measured magnitude category of the chosen slot. |
| Slot X magnitude | Described in table above ("Available measured values") | - | - | Selects the magnitude in the previously selected category. |
| Magnitude X | -10 000 000.000...10 000 000.000 | 0.001 | - | Displays the measured value of the selected magnitude of the selected slot. The unit depends on the selected magnitude (either amperes, volts, or per-unit values). |

6 Connections and application examples

6.1 Connections of AQ-F210

Figure. 6.1 - 174. AQ-F210 application example with function block diagram.

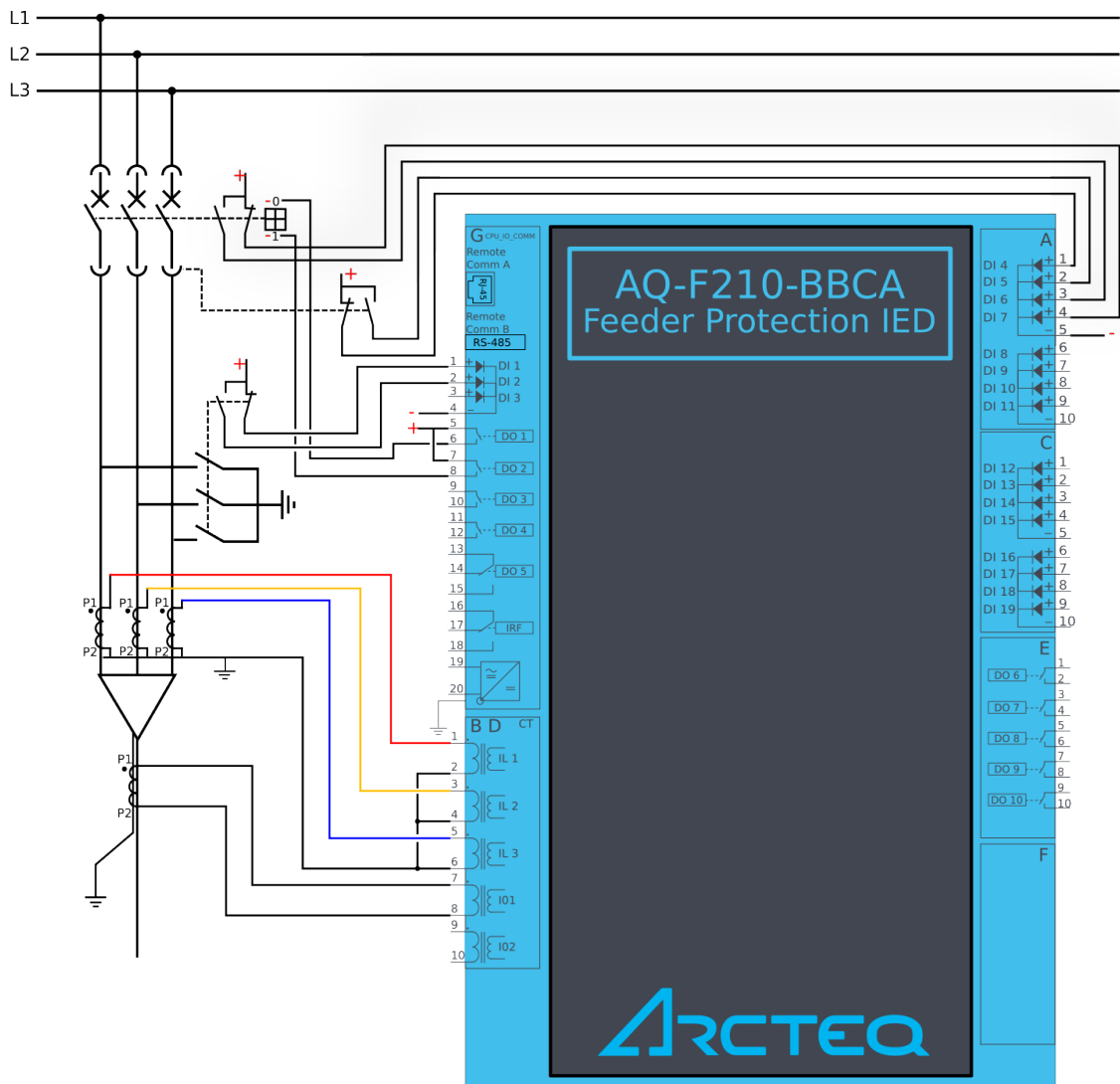


6.2 Application example and its connections

This chapter presents an application example for the feeder protection relay.

As can be seen in the image below, the example application has connected three phase currents and the residual current (I01). Additionally, the digital inputs are connected to indicate the breaker status, while the digital outputs are used for breaker control.

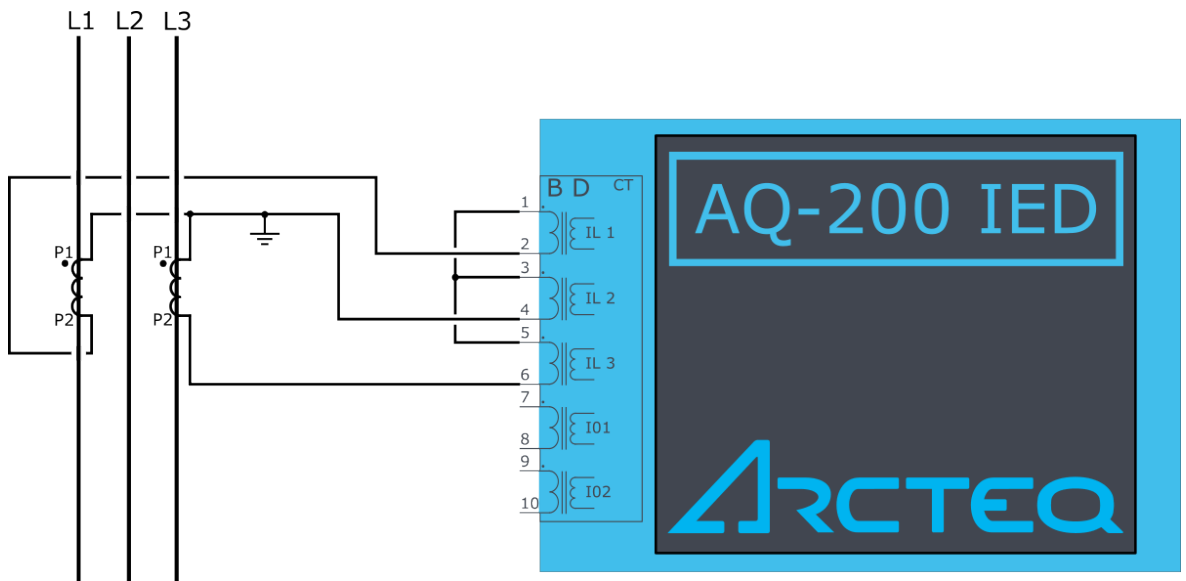
Figure. 6.2 - 175. Application example and its connections.



6.3 Two-phase, three-wire ARON input connection

This chapter presents the two-phase, three-wire ARON input connection for any AQ-200 series device with a current transformer. The example is for applications with protection CTs for just two phases. The connection is suitable for both motor and feeder applications.

Figure. 6.3 - 176. ARON connection.



The ARON input connection can measure the load symmetrically despite the fact that one of the CTs is missing from the installation. Normally, Phase 2 does not have a current transformer installed as an external fault is much more likely to appear on Lines 1 or 3.

A fault between Line 2 and the earth cannot be detected when the ARON input connection is used. In order to detect an earth fault in Phase 2, a cable core CT must be used.

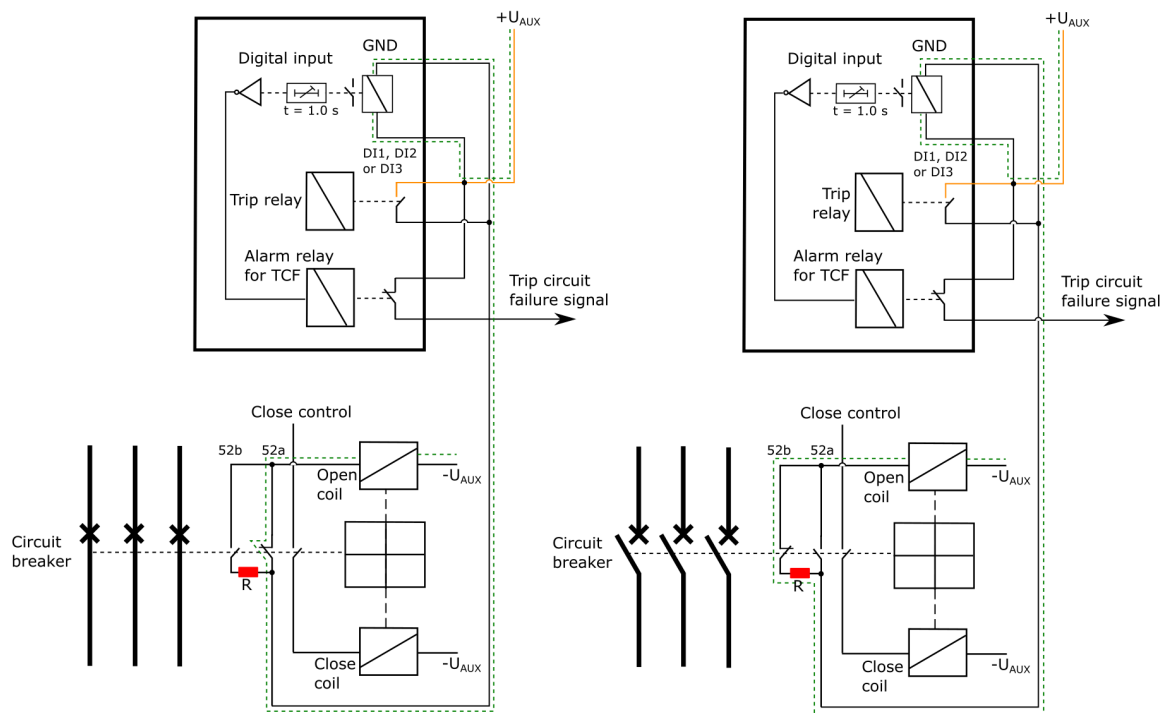
6.4 Trip circuit supervision (95)

Trip circuit supervision is used to monitor the wiring from auxiliary power supply, through the device's digital output, and all the way to the open coil of the breaker. It is recommended to supervise the health of the trip circuit when breaker is closed.

Trip circuit supervision with one digital input and one non-latched trip output

The figure below presents an application scheme for trip circuit supervision with one digital input and a non-latched trip output. With this connection the current keeps flowing to the open coil of the breaker via the breaker's closing auxiliary contacts (52b) even after the circuit breaker is opened. This requires a resistor which reduces the current: this way the coil is not energized and the relay output does not need to cut off the coil's inductive current.

Figure. 6.4 - 177. Trip circuit supervision with one DI and one non-latched trip output.

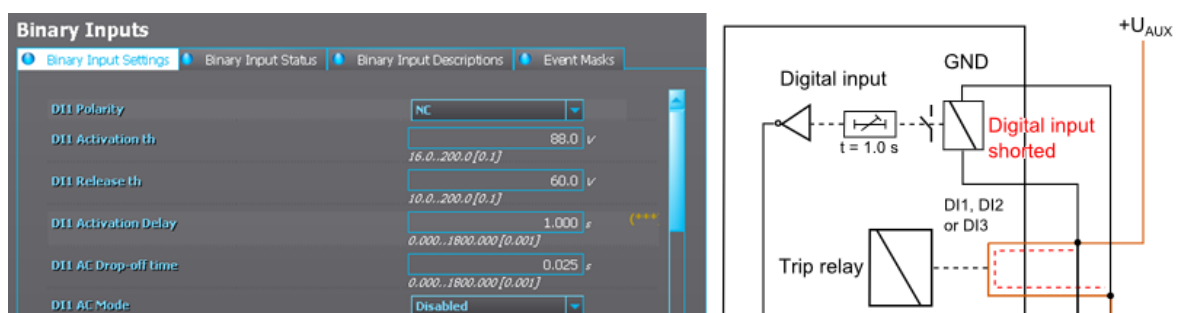


Note that the digital input that monitors the circuit is normally closed, and the same applies to the alarm relay if one is used. For monitoring and especially trip circuit supervision purposes it is recommended to use a normally closed contact to confirm the wiring's condition. An active digital input generates a less than 2 mA current to the circuit, which is usually small enough not to make the breaker's open coil operate.

When the trip relay is controlled and the circuit breaker is opening, the digital input is shorted by the trip contact as long as the breaker opens. Normally, this takes about 100 ms if the relay is non-latched. A one second activation delay should, therefore, be added to the digital input. An activation delay that is slightly longer than the circuit breaker's operations time should be enough. When circuit breaker failure protection (CBFP) is used, adding its operation time to the digital input activation time is useful. The whole digital input activation time is, therefore, $t_{DI} = t_{CB} + t_{IEDrelease} + t_{CBFP}$.

The image below presents the necessary settings when using a digital input for trip circuit supervision. The input's polarity must be NC (normally closed) and a one second delay is needed to avoid nuisance alarm while the circuit breaker is controlled open.

Figure. 6.4 - 178. Settings for a digital input used for trip circuit supervision.



Non-latched outputs are seen as hollow circles in the output matrix, whereas latched contacts are painted. See the image below of an output matrix where a non-latched trip contact is used to open the circuit breaker.

Figure. 6.4 - 179. Non-latched trip contact.

| Inputs | OUT1 | OUT2 | OUT3 | OUT4 | OUT5 |
|--------------------|------|------|------|------|------|
| I> START (General) | | | | | |
| I> START(A) | | | | | |
| I> START(B) | | | | | |
| I> START(C) | | | | | |
| I> TRIP (General) | | | | | |
| I> TRIP(A) | | | | | |
| I> TRIP(B) | | | | | |
| I> TRIP(C) | | | | | |
| I> BLOCKED | | | | | |

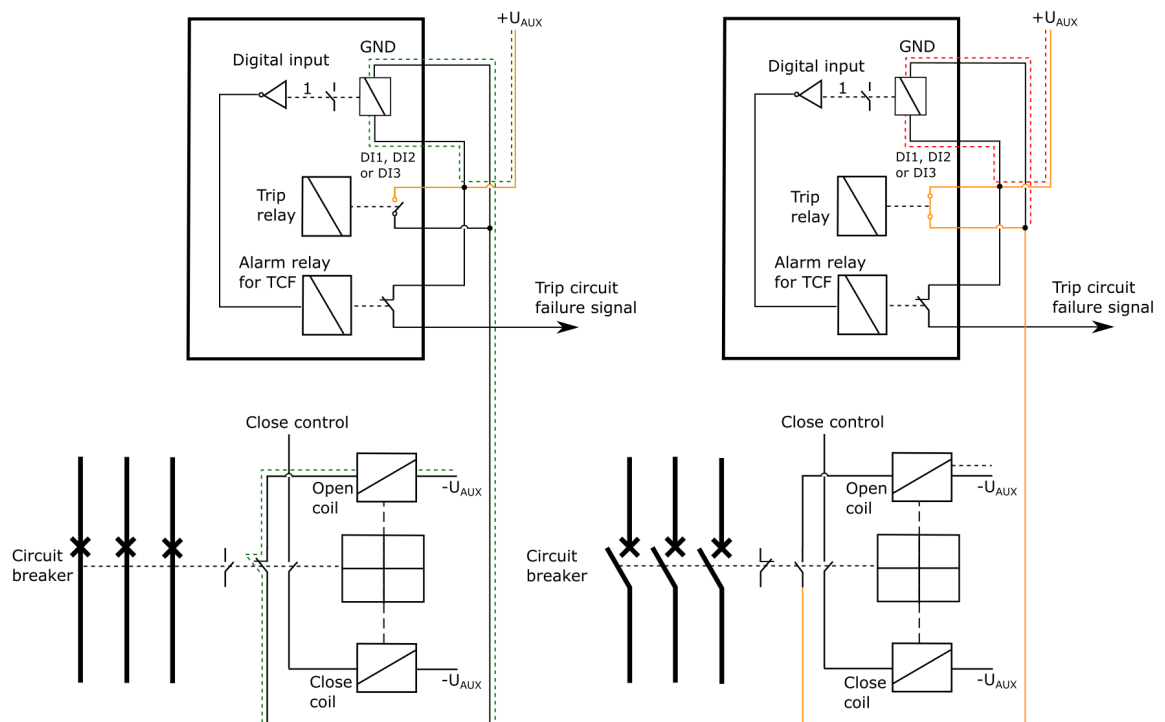
When the auto-reclosing function is used in feeder applications, the trip output contacts must be non-latched. Trip circuit supervision is generally easier and more reliable to build with non-latched outputs.

The open coil remains energized only as long as the circuit breaker is opened and the output releases. This takes approximately 100 ms depending on the size and type of the breaker. When the breaker opens, the auxiliary contacts open the inductive circuit; however, the trip contact does not open at the same time. The device's output relay contact opens in under 50 ms or after a set release delay that takes place after the breaker is opened. This means that the open coil is energized for a while after the breaker has already opened. The coil could even be energized a moment longer if the circuit breaker failure protection has to be used and the incomer performs the trip.

Trip circuit supervision with one digital input and one connected, non-latched trip output

There is one main difference between non-latched and latched control in trip circuit supervision: when using the latched control, the trip circuit (in an open state) cannot be monitored as the digital input is shorted by the device's trip output.

Figure. 6.4 - 180. Trip circuit supervision with one DI and one latched output contact.

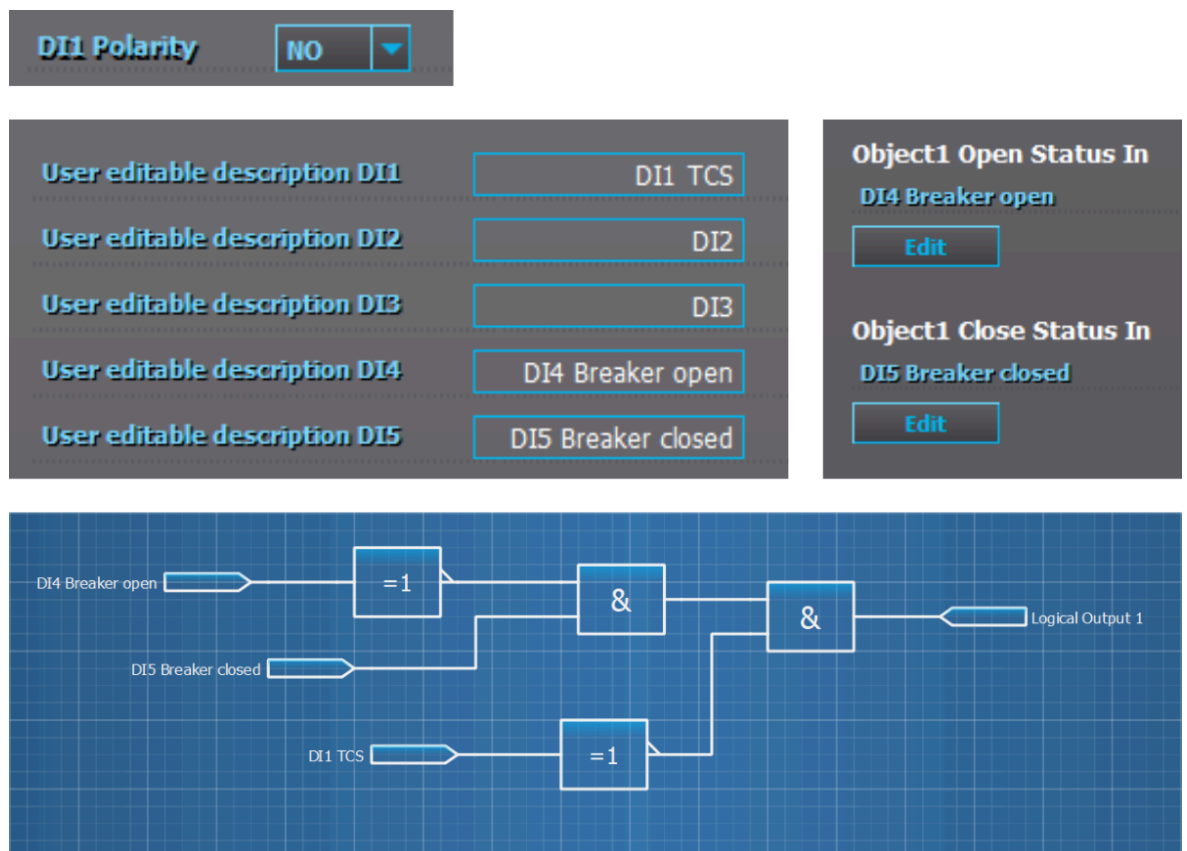


The trip circuit with a latched output contact can be monitored, but only when the circuit breaker's status is "Closed". Whenever the breaker is open, the supervision is blocked by an internal logic scheme. Its disadvantage is that the user does not know whether or not the trip circuit is intact when the breaker is closed again.

The following logic scheme (or similar) blocks the supervision alarm when the circuit breaker is open. The alarm is issued whenever the breaker is closed and whenever the inverted digital input signal ("TCS") activates. A normally closed digital input activates only when there is something wrong with the trip circuit and the auxiliary power goes off. Logical output can be used in the output matrix or in SCADA as the user wants.

The image below presents a block scheme when a non-latched trip output is not used.

Figure. 6.4 - 181. Example block scheme.



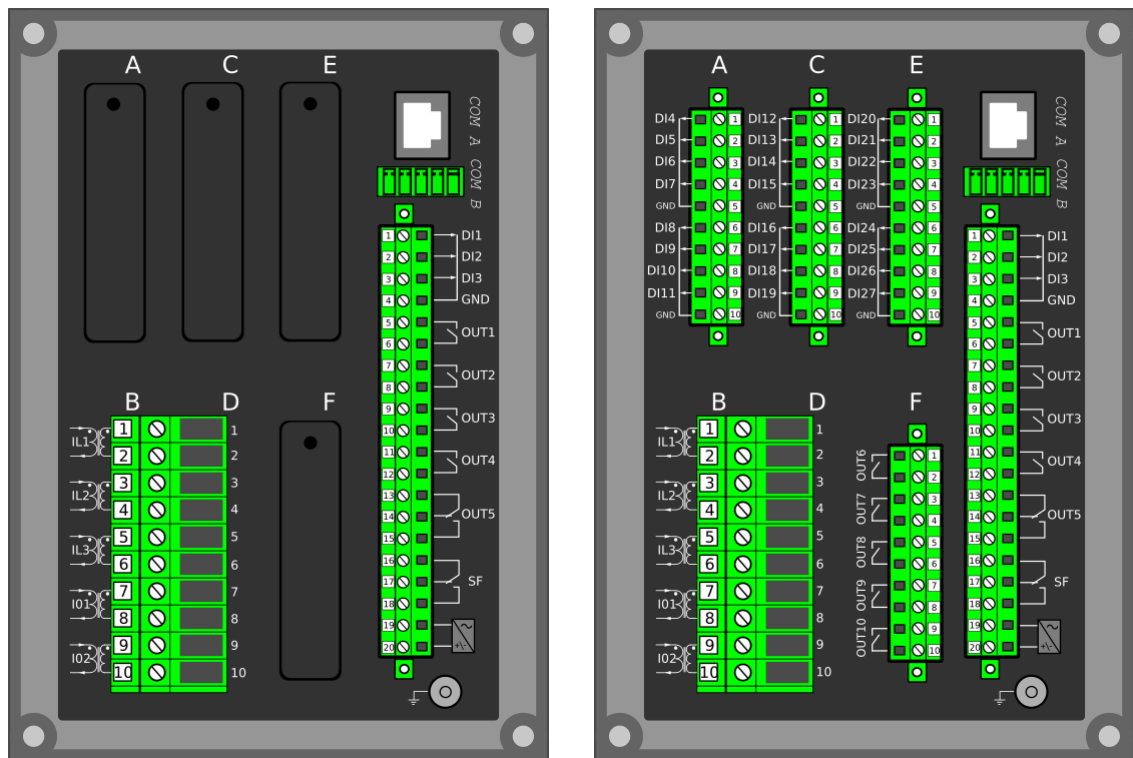
7 Construction and installation

7.1 Construction

AQ-X210 is a member of the modular and scalable AQ-200 series, and it includes four (4) configurable and modular add-on card slots. As a standard configuration the device includes the CPU module (which consists of the CPU, a number of inputs and outputs, and the power supply) as well as one separate current measurement module.

The images below present the modules of both the non-optioned model (AQ-X210-XXXXXXX-AAAA, on the left) and the fully optioned model (AQ-X210-XXXXXXX-BBBC, on the right).

Figure. 7.1 - 182. Modular construction of AQ-X210.



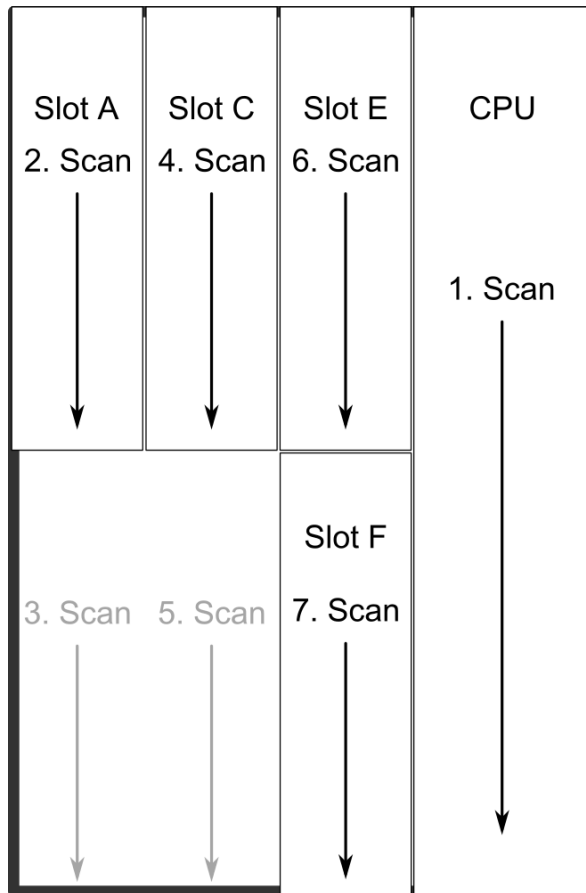
The modular structure of AQ-X210 allows for scalable solutions for different application requirements. In non-standard configurations Slots A, C, E and F accept all available add-on modules, such as digital I/O modules, integrated arc protection and other special modules. The only difference between the slots affecting device scalability is that Slots E and F also support communication options.

Start-up scan searches for modules according to their type designation code. If the module content is not what the device expects, the device issues a hardware configuration error message. In field upgrades, therefore, inserted add-on module must be ordered from Arcteq Relays Ltd. or its representative who can then provide the module with its corresponding unlocking code to allow the device to operate correctly once the hardware configuration has been upgraded.

When an I/O module is inserted into the device, the module location affects the naming of the I/O. The I/O scanning order in the start-up sequence is as follows: the CPU module I/O, Slot A, Slot C, Slot E, Slot F. This means that the digital input channels DI1, DI2 and DI3 as well as the digital output channels OUT1, OUT2, OUT3, OUT4 and OUT5 are always located in the CPU module. If additional I/O cards are installed, their location and card type affect the I/O naming.

The figure below presents the start-up hardware scan order of the device as well as the I/O naming principles.

Figure. 7.1 - 183. AQ-X210 hardware scanning and I/O naming principles.



1. Scan

The start-up system; detects and self-tests the CPU module, voltages, communication and the I/O; finds and assigns "DI1", "DI2", "DI3", "OUT1", "OUT2", "OUT3", "OUT4" and "OUT5".

2. Scan

Scans Slot A, and moves to the next slot if Slot A is empty. If the scan finds an 8DI module (that is, a module with eight digital inputs), it reserves the designations "DI4", "DI5", "DI6", "DI7", "DI8", "DI9", "DI10" and "DI11" to this slot. If the scan finds a DO5 module (that is, a module with five digital outputs), it reserves the designations "OUT6", "OUT7", "OUT8", "OUT9" and "OUT10" to this slot. The I/O is then added if the type designation code (e.g. AQ-P215-PH0AAAA-BBC) matches with the existing modules in the device. If the code and the modules do not match, the device issues an alarm. An alarm is also issued if the device expects to find a module here but does not find one.

3. Scan

Scans Slot B, which should always remain empty in AQ-X210 devices. If it is not empty, the device issues an alarm.

4. Scan

Scans Slot C, and moves to the next slot if Slot C is empty. If the scan finds an 8DI module, it reserves the designations "DI4", "DI5", "DI6", "DI7", "DI8", "DI9", "DI10" and "DI11" to this slot. If Slot A also has an 8DI module (and therefore has already reserved these designations), the device reserves the designations "DI12", "DI13", "DI14", "DI15", "DI16", "DI17", "DI18" and "DI19" to this slot. If the scan finds a 5DO module, it reserves the designations "OUT6", "OUT7", "OUT8", "OUT9" and "OUT10" to this slot. Again, if Slot A also has a 5DO and has therefore already reserved these designations, the device reserves the designations "OUT11", "OUT12", "OUT13", "OUT14" and "OUT15" to this slot.

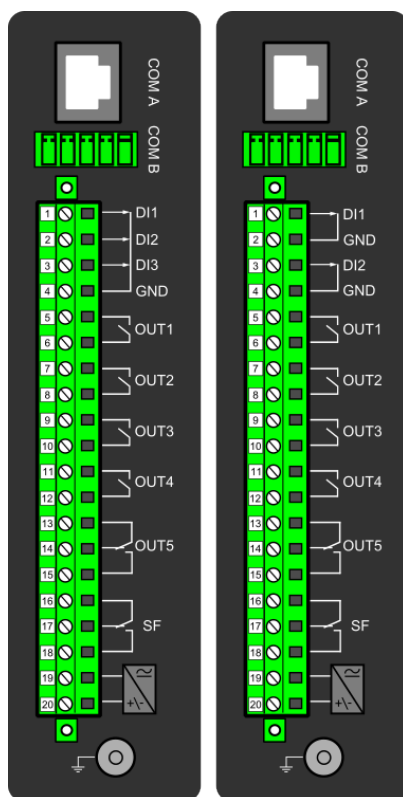
5. Scan
Scans Slot D and finds the five channels of the CT module (fixed for AQ-X210). If the CTM is not found, the device issues an alarm.
6. Scan
A similar operation to Scan 4 (checks which designations have been reserved by modules in previous slots and numbers the new ones accordingly).
7. Scan
A similar operation to Scan 4 (checks which designations have been reserved by modules in previous slots and numbers the new ones accordingly).

Thus far this chapter has only explained the installation of I/O add-on cards to the option module slots. This is because all other module types are treated in a same way. For example, when an additional communication port is installed into the upper port of the communication module, its designation is Communication port 3 or higher, as Communication ports 1 and 2 already exist in the CPU module (which is scanned, and thus designated, first). After a communication port is detected, it is added into the device's communication space and its corresponding settings are enabled.

The fully optioned example case of AQ-X210-XXXXXX-**BBBC** (the first image pair, on the right) has a total of 27 digital input channels available: three (DI1...DI3) in the CPU module, and the rest in Slots A, C and E in groups of eight. It also has a total of 10 digital output channels available: five (DO1...DO5) in the CPU module, and five (DO6...DO10) in Slot F. These same principles apply to all non-standard configurations in the AQ-X210 devices.

7.2 CPU module

Figure. 7.2 - 184. CPU module.



Module connectors

Table. 7.2 - 213. Module connector descriptions.

| Connector | Description | |
|------------|---|--|
| COM A | Communication port A, or the RJ-45 port. Used for the setting tool connection and for IEC 61850, Modbus/TCP, IEC 104, DNP3 and station bus communications. | |
| COM B | Communication port B, or the RS-485 port. Used for the SCADA communications for the following protocols: Modbus/RTU, Modbus I/O, SPA, DNP3, IEC 101 and IEC 103. The pins have the following designations: Pin 1 = DATA +, Pin 2 = DATA –, Pin 3 = GND, Pins 4 & 5 = Terminator resistor enabled by shorting. | |
| | Model with 3 digital inputs | Model with 2 digital inputs |
| X 1 | Digital input 1, nominal threshold voltage 24 V, 110 V or 220 V. | Digital input 1, nominal threshold voltage 24 V, 110 V or 220 V. |
| X 2 | Digital input 2, nominal threshold voltage 24 V, 110 V or 220 V. | GND for digital input 1. |
| X 3 | Digital input 3, nominal threshold voltage 24 V, 110 V or 220 V. | Digital input 2, nominal threshold voltage 24 V, 110 V or 220 V. |
| X 4 | Common GND for digital inputs 1, 2 and 3. | GND for digital input 2. |
| X 5:6 | Output relay 1, with a normally open (NO) contact. | |
| X 7:8 | Output relay 2, with a normally open (NO) contact. | |
| X 9:10 | Output relay 3, with a normally open (NO) contact. | |
| X 11:12 | Output relay 4, with a normally open (NO) contact. | |
| X 13:14:15 | Signaling relay 5, with a changeover contact. Not to be used in trip coil control. | |
| X 16:17:18 | System fault's signaling relay, with a changeover contact. Pins 16 and 17 are closed when the unit has a system fault or is powered OFF. Pins 16 and 18 are closed when the unit is powered ON and there is no system fault. | |
| X 19:20 | Power supply IN. Either 80...265 VAC/DC (model A; order code "H") or 18...75 DC (model B; order code "L"). Positive side (+) to Pin 20. | |
| GND | The device's earthing connector. | |

By default, the CPU module (combining the CPU, the I/O and the power supply) is included in all AQ-200 devices to provide two standard communication ports and the device's basic digital I/O. The module can be ordered to include 2 or 3 digital inputs.

The digital output controls are also set by the user with software. Digital outputs are controlled in 5 ms program cycles. All output contacts are mechanical. The rated voltage of the NO/NC outputs is 250 VAC/DC.

The auxiliary voltage is defined in the ordering code: the available power supply models available are A (80...265 VAC/DC) and B (18...75 DC). For further details, please refer to the "Auxiliary voltage" chapter in the "Technical data" section of this document.

Digital inputs

The current consumption of the digital inputs is 2 mA when activated, while the range of the operating voltage is 24 V/110 V/220 V depending on the ordered hardware. All digital inputs are scanned in 5 ms program cycles, and their pick-up and release delays as well as their NO/NC selection can be set with software.

The settings described in the table below can be found at *Control* → *Device I/O* → *Digital input settings* in the device settings.

Table. 7.2 - 214. Digital input settings.

| Name | Range | Step | Default | Description |
|----------------------|--|---------|----------|--|
| Dlx Polarity | <ul style="list-style-type: none"> NO (Normally open) NC (Normally closed) | - | NO | Selects whether the status of the digital input is 1 or 0 when the input is energized. |
| Dlx Activation delay | 0.000...1800.000 s | 0.001 s | 0.000 s | Defines the delay for the status change from 0 to 1. |
| Dlx Drop-off time | 0.000...1800.000 s | 0.001 s | 0.000 s | Defines the delay for the status change from 1 to 0. |
| Dlx AC mode | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Selects whether or not a 30-ms deactivation delay is added to account for alternating current. |

Digital input and output descriptions

CPU card digital inputs and outputs can be given a description. The user defined description are displayed in most of the menus:

- logic editor
- matrix
- block settings
-
-
- etc.

Table. 7.2 - 215. Digital input and output user description.

| Name | Range | Default | Description |
|--------------------------------|-------------------|---------|--|
| User editable description Dlx | 1...31 characters | Dlx | Description of the digital input. This description is used in several menu types for easier identification. |
| User editable description OUTx | | OUTx | Description of the digital output. This description is used in several menu types for easier identification. |

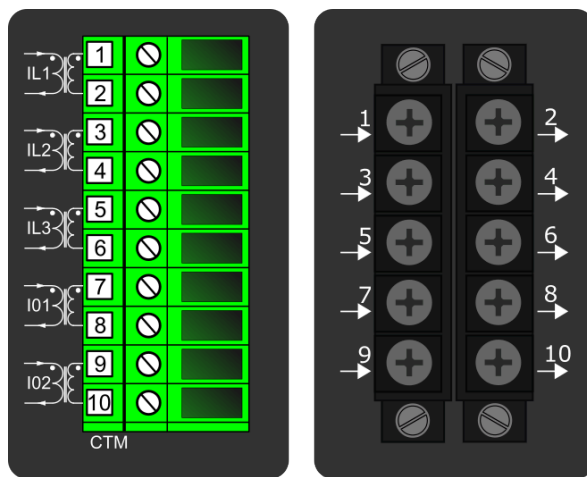
Scanning cycle

All digital inputs are scanned in a 5 ms cycle, meaning that the state of an input is updated every 0...5 milliseconds. When an input is used internally in the device (either in setting group change or logic), it takes additional 0...5 milliseconds to operate. Theoretically, therefore, it takes 0...10 milliseconds to change the group when a digital input is used for group control or a similar function. In practice, however, the delay is between 2...8 milliseconds about 95 % of the time. When a digital input is connected directly to a digital output (T1...Tx), it takes an additional 5 ms round. Therefore, when a digital input controls a digital output internally, it takes 0...15 milliseconds in theory and 2...13 milliseconds in practice.

Please note that the mechanical delay of the relay is not included in these approximations.

7.3 Current measurement module

Figure. 7.3 - 185. Module connections with standard and ring lug terminals.



| Connector | Description |
|-----------|---|
| CTM 1-2 | Phase current measurement for phase L1 (A). |
| CTM 3-4 | Phase current measurement for phase L2 (B). |
| CTM 5-6 | Phase current measurement for phase L3 (C). |
| CTM 7-8 | Coarse residual current measurement IO1. |
| CTM 9-10 | Fine residual current measurement IO2. |

A basic current measurement module with five channels includes three-phase current measurement inputs as well as coarse and fine residual current inputs. The CT module is available with either standard or ring lug connectors.

The current measurement module is connected to the secondary side of conventional current transformers (CTs). The nominal current for the phase current inputs is 5 A. The input nominal current can be scaled for secondary currents of 1...10 A. The secondary currents are calibrated to nominal currents of 1 A and 5 A, which provide $\pm 0.5\%$ inaccuracy when the range is $0.005...4 \times I_n$.

The measurement ranges are as follows:

- Phase currents 25 mA...250 A (RMS)
- Coarse residual current 5 mA...150 A (RMS)

- Fine residual current 1 mA...75 A (RMS)

The characteristics of phase current inputs are as follows:

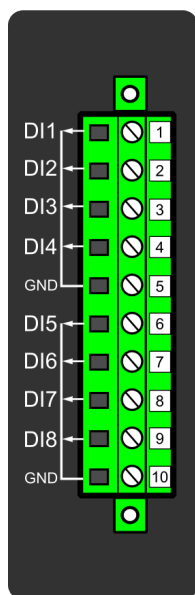
- The angle measurement inaccuracy is less than ± 0.2 degrees with nominal current.
- The frequency measurement range of the phase current inputs is 6...1800 Hz with standard hardware.
- The quantization of the measurement signal is applied with 18-bit AD converters, and the sample rate of the signal is 64 samples/cycle when the system frequency ranges from 6 Hz to 75 Hz.

For further details please refer to the "Current measurement" chapter in the "Technical data" section of this document.

7.4 Option cards

7.4.1 Digital input module (optional)

Figure. 7.4.1 - 186. Digital input module (DI8) with eight add-on digital inputs.



| Connector | Description (x = the number of digital inputs in other modules that precede this one in the configuration) |
|-----------|--|
| X 1 | DIx + 1 |
| X 2 | DIx + 2 |
| X 3 | DIx + 3 |
| X 4 | DIx + 4 |
| X 5 | Common earthing for the first four digital inputs. |
| X 6 | DIx + 5 |
| X 7 | DIx + 6 |
| X 8 | DIx + 7 |

| Connector | Description (x = the number of digital inputs in other modules that precede this one in the configuration) |
|-----------|--|
| X 9 | Dlx + 8 |
| X 10 | Common earthing for the other four digital inputs. |

The DI8 module is an add-on module with eight (8) galvanically isolated digital inputs. This module can be ordered directly to be installed into the device in the factory, or it can be upgraded in the field after the device's original installation when required. The properties of the inputs in this module are the same as those of the inputs in the main processor module. The current consumption of the digital inputs is 2 mA when activated, while the range of the operating voltage is from 0...265 VAC/DC. The activation and release thresholds are set in the software and the resolution is 1 V. All digital inputs are scanned in 5 ms program cycles, and their pick-up and release delays as well as their NO/NC selection can be set with software.

For the naming convention of the digital inputs provided by this module please refer to the chapter titled "Construction and installation".

For technical details please refer to the chapter titled "Digital input module" in the "Technical data" section of this document.

Setting up the activation and release delays

The settings described in the table below can be found at *Control* → *Device I/O* → *Digital input settings* in the device settings.

Table. 7.4.1 - 216. Digital input settings of DI8 module.

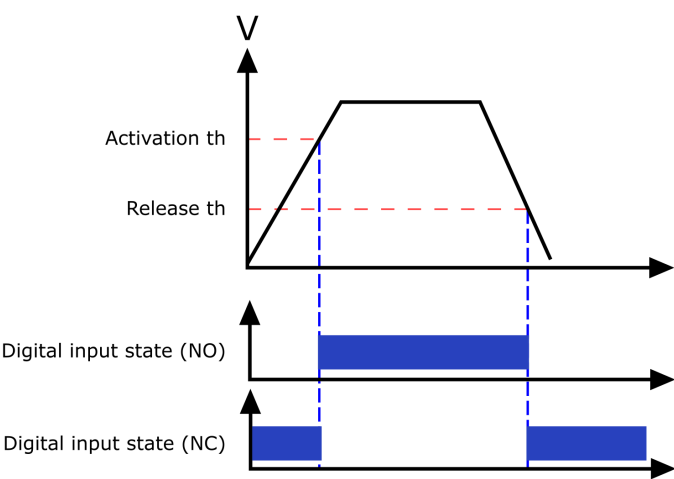
| Name | Range | Step | Default | Description |
|--------------------------|--|---------|----------|---|
| Dlx Polarity | <ul style="list-style-type: none"> NO (Normally open) NC (Normally closed) | - | NO | Selects whether the status of the digital input is 1 or 0 when the input is energized. |
| Dlx Activation threshold | 16.0...200.0 V | 0.1 V | 88 V | Defines the activation threshold for the digital input. When "NO" is the selected polarity, the measured voltage exceeding this setting activates the input. When "NC" is the selected polarity, the measured voltage exceeding this setting deactivates the input. |
| Dlx Release threshold | 10.0...200.0 V | 0.1 V | 60V | Defines the release threshold for the digital input. When "NO" is the selected polarity, the measured voltage below this setting deactivates the input. When "NC" is the selected polarity, the measured voltage below this setting activates the input. |
| Dlx Activation delay | 0.000...1800.000 s | 0.001 s | 0.000 s | Defines the delay when the status changes from 0 to 1. |
| Dlx Drop-off time | 0.000...1800.000 s | 0.001 s | 0.000 s | Defines the delay when the status changes from 1 to 0. |
| Dlx AC Mode | <ul style="list-style-type: none"> Disabled Enabled | - | Disabled | Selects whether or not a 30-ms deactivation delay is added to take the alternating current into account. The "Dlx Release threshold" parameter is hidden and forced to 10 % of the set "Dlx Activation threshold" parameter. |

| Name | Range | Step | Default | Description |
|-------------------|--|------|---------|--|
| Dlx Counter | $0 \dots 2^{32} - 1$ | 1 | 0 | Displays the number of times the digital input has changed its status from 0 to 1. |
| Dlx Clear counter | <ul style="list-style-type: none"> - Clear | - | - | Resets the Dlx counter value to zero. |

The user can set the activation threshold individually for each digital input. When the activation and release thresholds have been set properly, they will result in the digital input states to be activated and released reliably. The selection of the normal state between normally open (NO) and normally closed (NC) defines whether or not the digital input is considered activated when the digital input channel is energized.

The diagram below depicts the digital input states when the input channels are energized and de-energized.

Figure. 7.4.1 - 187. Digital input state when energizing and de-energizing the digital input channels.



Digital input descriptions

Option card inputs can be given a description. The user defined description are displayed in most of the menus:

- logic editor
- matrix
- block settings
-
-
- etc.

Table. 7.4.1 - 217. Digital input user description.

| Name | Range | Default | Description |
|-------------------------------|-------------------|---------|---|
| User editable description Dlx | 1...31 characters | Dlx | Description of the digital input. This description is used in several menu types for easier identification. |

Digital input voltage measurements

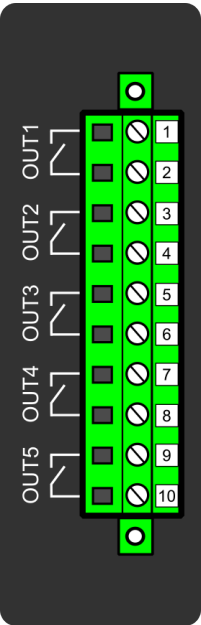
Digital input option card channels measure voltage on each channel. The measured voltage can be seen at *Control → Device IO → Digital inputs → Digital input voltages*.

Table. 7.4.1 - 218. Digital input channel voltage measurement.

| Name | Range | Step | Description |
|-----------------|-------------------|---------|---|
| Dlx Voltage now | 0.000...275.000 V | 0.001 V | Voltage measurement of a digital input channel. |

7.4.2 Digital output module (optional)

Figure. 7.4.2 - 188. Digital output module (DO5) with five add-on digital outputs.



| Connector | Description |
|-----------|--|
| X 1–2 | OUTx + 1 (1 st and 2 nd pole NO) |
| X 3–4 | OUTx + 2 (1 st and 2 nd pole NO) |
| X 5–6 | OUTx + 3 (1 st and 2 nd pole NO) |
| X 7–8 | OUTx + 4 (1 st and 2 nd pole NO) |
| X 9–10 | OUTx + 5 (1 st and 2 nd pole NO) |

The DO5 module is an add-on module with five (5) digital outputs. This module can be ordered directly to be installed into the device in the factory, or it can be upgraded in the field after the device's original installation when required. The properties of the outputs in this module are the same as those of the outputs in the main processor module. The user can set the digital output controls with software. All digital outputs are scanned in 5 ms program cycles, and their contacts are mechanical in type. The rated voltage of the NO/NC outputs is 250 VAC/DC.

For the naming convention of the digital inputs provided by this module please refer to the chapter titled "Construction and installation".

For technical details please refer to the chapter titled "Digital output module" in the "Technical data" section of this document.

Digital output descriptions

Option card outputs can be given a description. The user defined description are displayed in most of the menus:

- logic editor
- matrix
- block settings
-
-
- etc.

Table. 7.4.2 - 219. Digital output user description.

| Name | Range | Default | Description |
|--------------------------------|-------------------|---------|--|
| User editable description OUTx | 1...31 characters | OUTx | Description of the digital output. This description is used in several menu types for easier identification. |

7.4.3 Point sensor arc protection module (optional)

Figure. 7.4.3 - 189. Arc protection module.

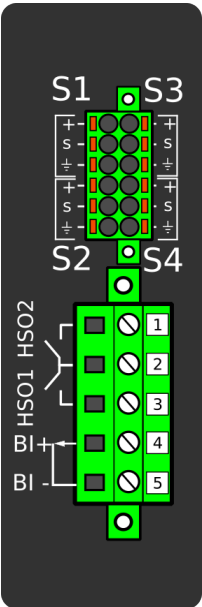


Table. 7.4.3 - 220. Module connections.

| Connector | Description |
|-----------|---|
| S1 | Light sensor channels 1...4 with positive ("+"), sensor ("S") and earth connectors. |
| S2 | |

| Connector | Description |
|-----------|--|
| S3 | |
| S4 | |
| X 1 | HSO2 (+, NO) |
| X 2 | Common battery positive terminal (+) for the HSOs. |
| X 3 | HSO1 (+, NO) |
| X 4 | Binary input 1 (+ pole) |
| X 5 | Binary input 1 (– pole) |

The arc protection module is an add-on module with four (4) light sensor channels, two (2) high-speed outputs and one (1) binary input. This module can be ordered directly to be installed into the device in the factory, or it can be upgraded in the field after the device's original installation when required. If even one of the sensor channels is connected incorrectly, the channel does not work. Each channel can have up to three (3) light sensors serially connected to it. The user can choose how many of the channels are in use.

The high-speed outputs (HSO1 and HSO2) operate only with a DC power supply. The battery's positive terminal (+) must be wired according to the drawing. The NO side of the outputs 1 or 2 must be wired through trip coil to the battery's negative terminal (–). The high-speed outputs can withstand voltages up to 250 VDC. The operation time of the high-speed outputs is less than 1 ms. For further information please refer to the chapter titled "Arc protection module" in the "Technical data" section of this manual.

The rated voltage of the binary input is 24 VDC. The threshold picks up at ≥ 16 VDC. The binary input can be used for external light information or for similar applications. It can also be used as a part of various ARC schemes. Please note that the binary input's delay is 5...10ms.

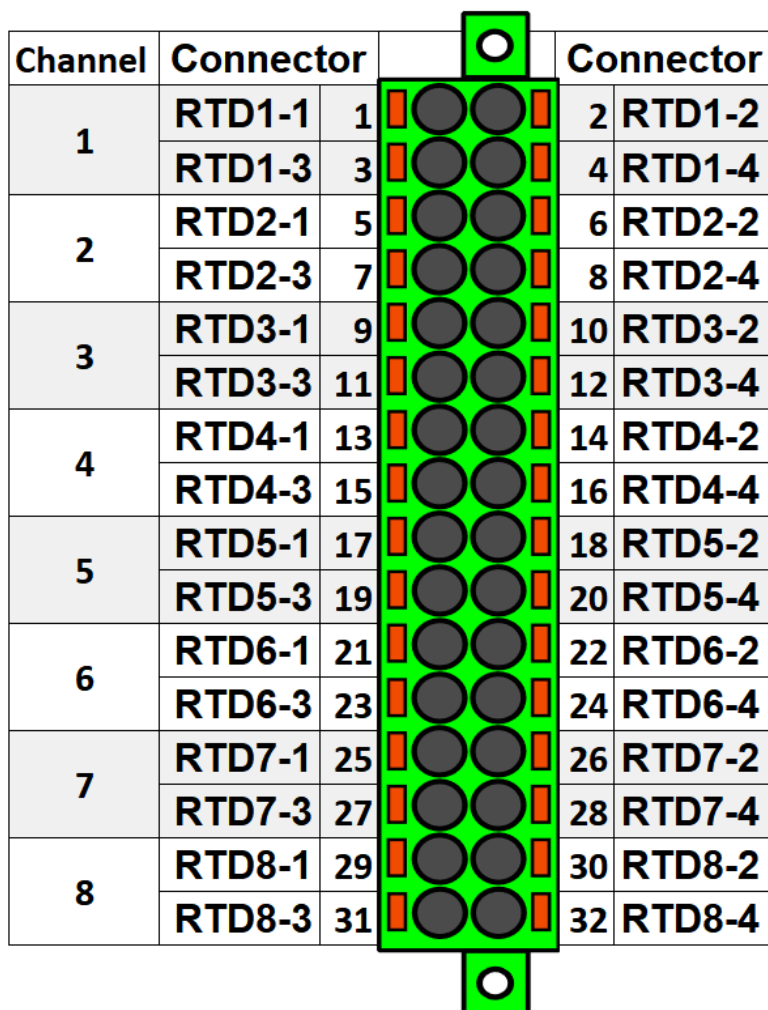


NOTICE!

BI1, HSO1 and HSO2 are not visible in the *Binary inputs* and *Binary outputs* menus (*Control* → *Device I/O*), they can only be programmed in the arc matrix menu (*Protection* → *Arc protection* → *I/O* → *Direct output control* and *HSO control*).

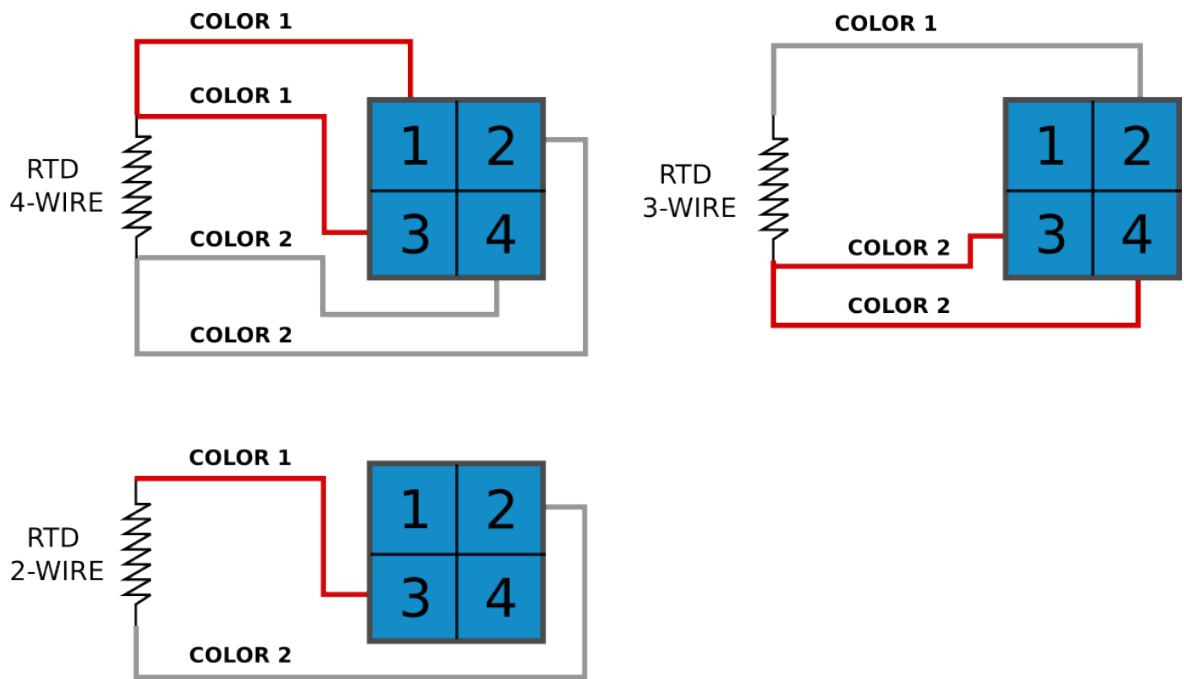
7.4.4 RTD input module (optional)

Figure. 7.4.4 - 190. RTD input module connectors.



The RTD input module is an add-on module with eight (8) RTD input channels. Each input supports 2-wire, 3-wire and 4-wire RTD sensors. The sensor type can be selected with software for two groups, four channels each. The card supports Pt100 and Pt1000 sensors

Figure. 7.4.4 - 191. RTD sensor connection types.



7.4.5 Serial RS-232 communication module (optional)

Figure. 7.4.5 - 192. Serial RS-232 module connectors.

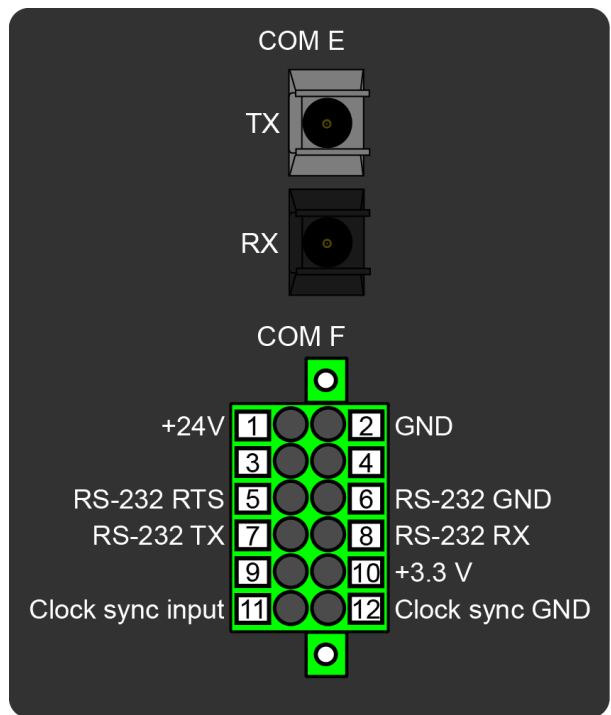


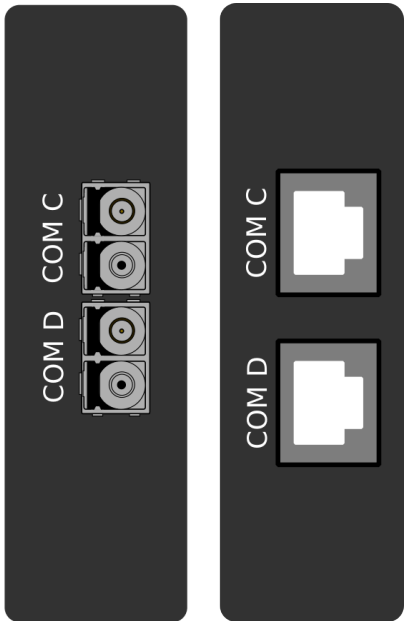
Table. 7.4.5 - 221. Module connections.

| Connector | Pin | Name | Description |
|-----------|-----|-----------------------|--|
| COM E | - | Serial fiber | <ul style="list-style-type: none"> Serial-based communications Port options: <ul style="list-style-type: none"> Glass/glass Plastic/plastic Glass/plastic Plastic/glass Wavelength 660 nm Compatible with 50/125 μm, 62.5/125 μm, 100/140 μm, and 200 μm Plastic-Clad Silica (PCS) fiber Compatible with ST connectors |
| COM F | 1 | +24 V input | Optional external auxiliary voltage for serial fiber. |
| | 2 | GND | |
| | 3 | - | Not in use. |
| | 4 | | |
| | 5 | RS-232 RTS | Serial based communications. |
| | 6 | RS-232 GND | |
| | 7 | RS-232 TX | |
| | 8 | RS-232 RX | |
| | 9 | - | Not in use. |
| | 10 | +3.3 V output (spare) | Spare power source for external equipment (45 mA). |
| | 11 | Clock sync input | Clock synchronization input (supports IRIG-B). |
| | 12 | Clock sync GND | |

The option card includes two serial communication interfaces: COM E is a serial fiber interface with glass/glass, plastic/plastic, glass/plastic and plastic/glass options, COM F is an RS-232 interface.

7.4.6 LC or RJ45 100 Mbps Ethernet communication module (optional)

Figure. 7.4.6 - 193. LC and RJ45 100 Mbps Ethernet module connectors.

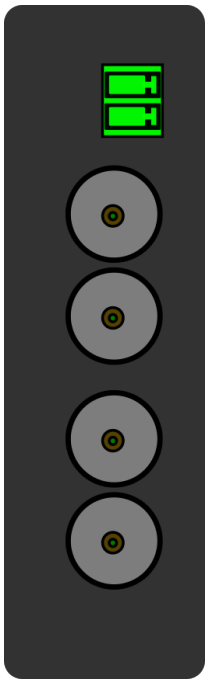


| Connector | Description (LC ports) | Description (RJ45) |
|-----------|--|--|
| COM C: | <ul style="list-style-type: none">• Communication port C, 100 MbpsLC fiber connector.• 62.5/125 μm or 50/125 μm multimode (glass).• Wavelength 1300 nm. | <ul style="list-style-type: none">• RJ-45 connectors• 10BASE-T and 100BASE-TX |
| COM D: | <ul style="list-style-type: none">• Communication port D, 100 Mbps LC fiber connector.• 62.5/125 μm or 50/125 μm multimode (glass).• Wavelength 1300 nm. | <ul style="list-style-type: none">• RJ-45 connectors• 10BASE-T and 100BASE-TX |

Both cards support both HSR and PRP protocols.

7.4.7 Double ST 100 Mbps Ethernet communication module (optional)

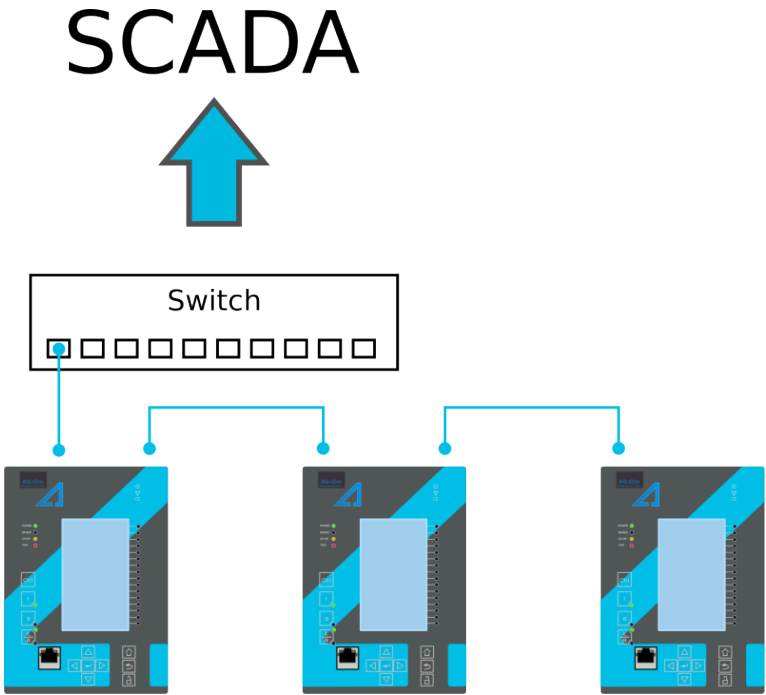
Figure. 7.4.7 - 194. Double ST 100 Mbps Ethernet communication module connectors.



| Connector | Description |
|-------------------|---|
| Two-pin connector | <ul style="list-style-type: none">• IRIG-B input |
| ST connectors | <ul style="list-style-type: none">• Duplex ST connectors• 62.5/125 μm or 50/125 μm multimode fiber• Transmitter wavelength: 1260...1360 nm (nominal: 1310 nm)• Receiver wavelength: 1100...1600 nm• 100BASE-FX• Up to 2 km |

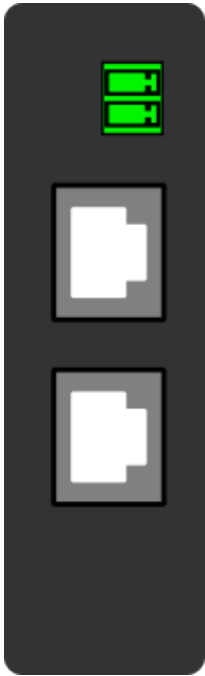
This option cards supports redundant ring configuration and multidrop configurations. Please note that each ring can only contain AQ-200 series devices, and any third party devices must be connected to a separate ring.

Figure. 7.4.7 - 195. Example of a multidrop configuration.



7.4.8 Double RJ45 10/100 Mbps Ethernet communication module (optional)

Figure. 7.4.8 - 196. Double RJ-45 10/100 Mbps Ethernet communication module.

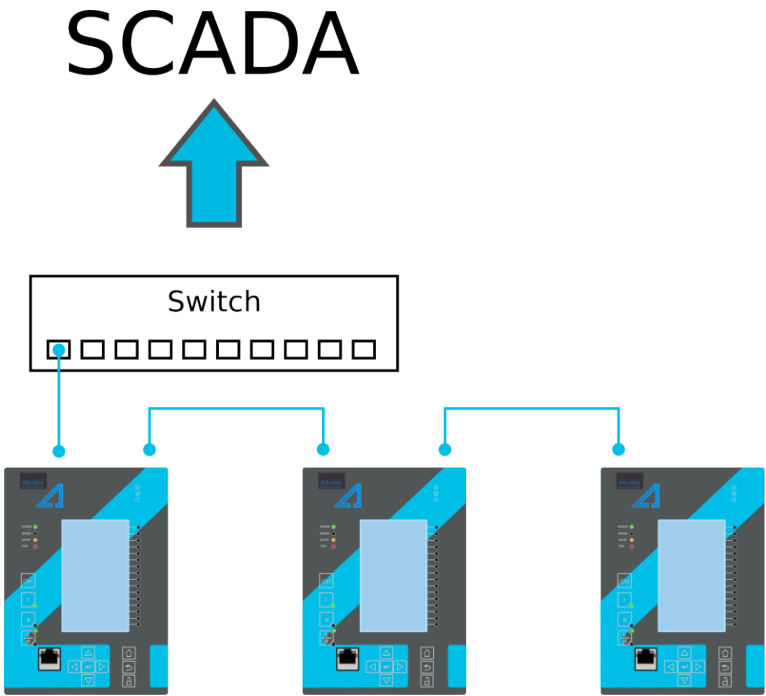


| Connector | Description |
|-------------------|--|
| Two-pin connector | <ul style="list-style-type: none">IRIG-B input |

| Connector | Description |
|------------------|---|
| RJ-45 connectors | <ul style="list-style-type: none">• Two Ethernet ports• RJ-45 connectors• 10BASE-T and 100BASE-TX |

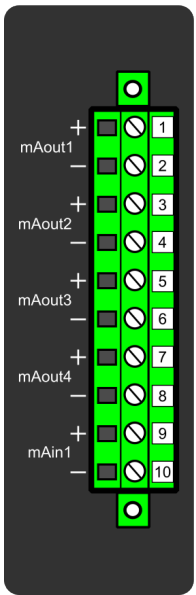
This option card supports multidrop configurations.

Figure. 7.4.8 - 197. Example of a multidrop configuration.



7.4.9 Milliampere output (mA) I/O module (optional)

Figure. 7.4.9 - 198. Milliampere output (mA) I/O module connections.



| Connector | Description |
|-----------|----------------------------------|
| Pin 1 | mA OUT 1 + connector (0...24 mA) |
| Pin 2 | mA OUT 1 – connector (0...24 mA) |
| Pin 3 | mA OUT 2 + connector (0...24 mA) |
| Pin 4 | mA OUT 2 – connector (0...24 mA) |
| Pin 5 | mA OUT 3 + connector (0...24 mA) |
| Pin 6 | mA OUT 3 – connector (0...24 mA) |
| Pin 7 | mA OUT 4 + connector (0...24 mA) |
| Pin 8 | mA OUT 4 – connector (0...24 mA) |
| Pin 9 | mA IN 1 + connector (0...33 mA) |
| Pin 10 | mA IN 1 – connector (0...33 mA) |

The milliampere (mA) I/O module is an add-on module with four (4) mA outputs and one (1) mA input. Both the outputs and the input are in two galvanically isolated groups, with one pin for the positive (+) connector and one pin for the negative (–) connector.

This module can be ordered directly to be installed into the device in the factory, or it can be upgraded in the field after the device's original installation when required.

The user sets the mA I/O with the mA outputs control function. This can be done at *Control* → *Device I/O* → *mA outputs* in the device configuration settings.

7.5 Dimensions and installation

The device can be installed either to a standard 19" rack or to a switchgear panel with cutouts. The desired installation type is defined in the order code. When installing to a rack, the device takes a quarter ($\frac{1}{4}$) of the rack's width, meaning that a total of four devices can be installed to the same rack next to one another.

The figures below describe the device dimensions (first figure), the device installation (second), and the panel cutout dimensions and device spacing (third).

Figure. 7.5 - 199. Device dimensions.

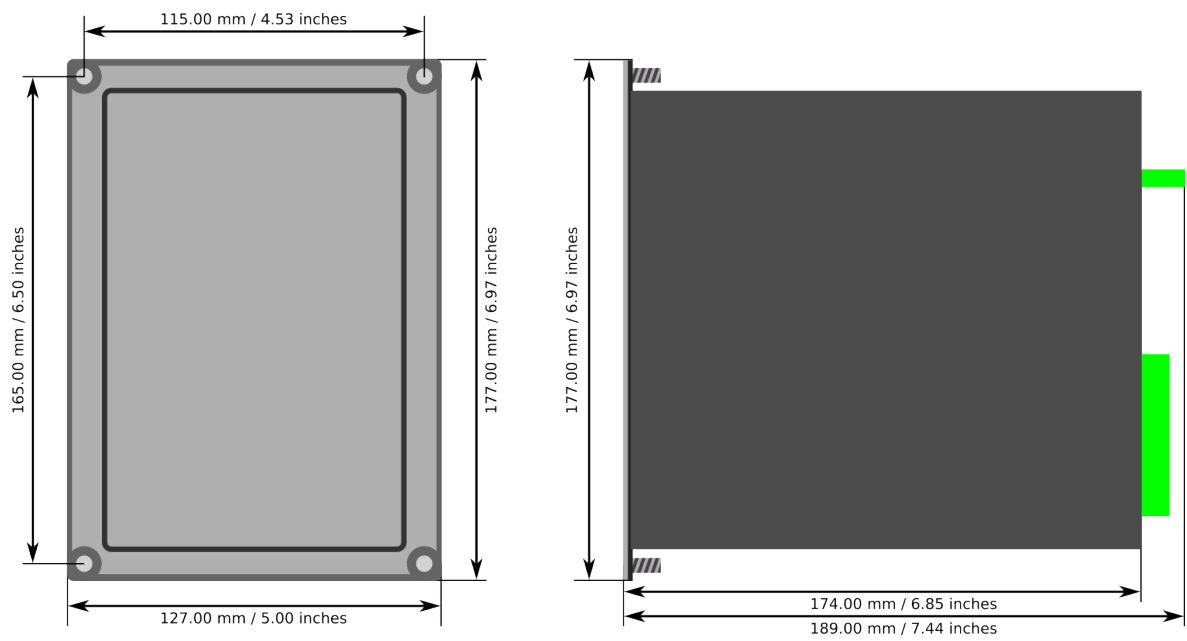


Figure. 7.5 - 200. Device installation.

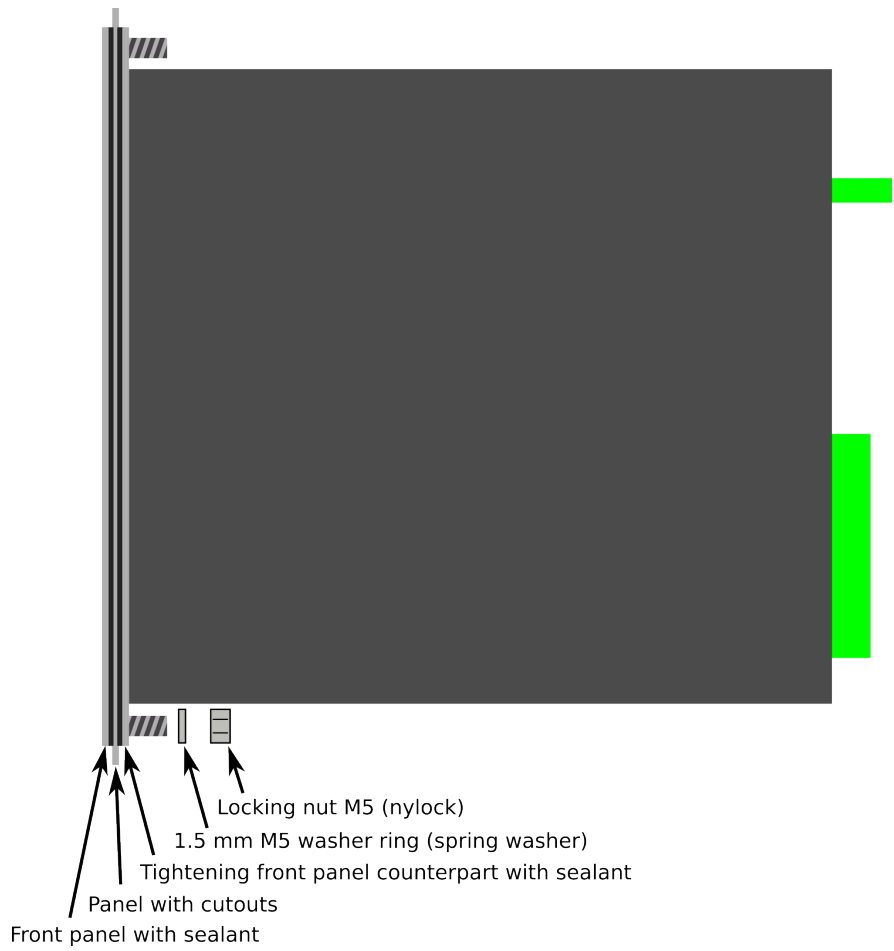
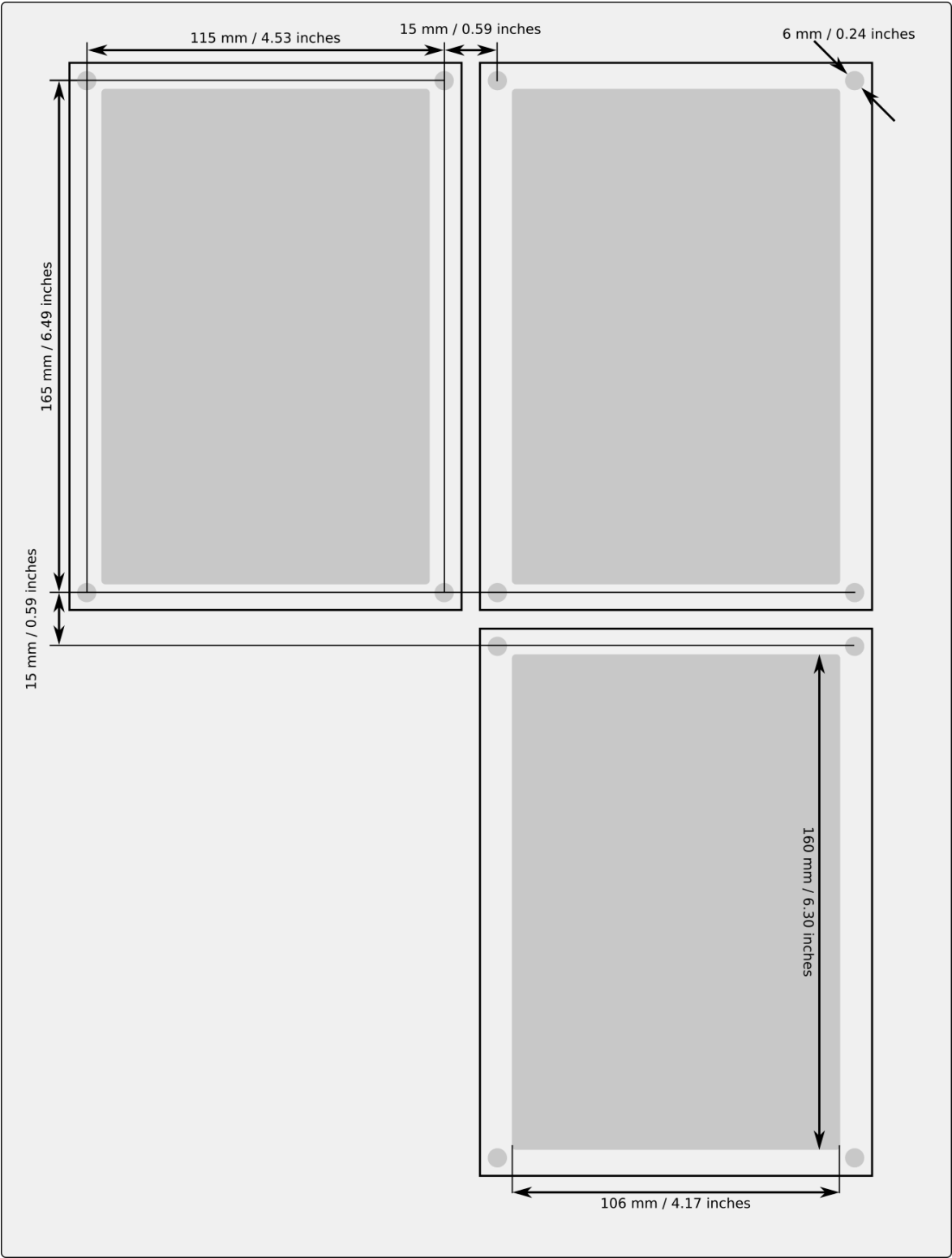


Figure. 7.5 - 201. Panel cutout dimensions and device spacing.



8 Technical data

8.1 Hardware

8.1.1 Measurements

8.1.1.1 Current measurement

Table. 8.1.1.1 - 222. Technical data for the current measurement module.

| General information | |
|-------------------------------------|--|
| Spare part code | #SP-2XX-CM |
| Compatibility | AQ-210 and AQ-250 series models |
| Connections | |
| Measurement channels/CT inputs | Three phase current inputs: IL1 (A), IL2 (B), IL3 (C) Two residual current inputs: Coarse residual current input I01, Fine residual current input I02 |
| Phase current inputs (A, B, C) | |
| Sample rate | 64 samples per cycle in frequency range 6...75Hz |
| Rated current I_N | 5 A (configurable 0.2...20 A) |
| Thermal withstand | 20 A (continuous) 100 A (for 10 s) 500 A (for 1 s) 1250 A (for 0.01 s) |
| Frequency measurement range | From 6...75Hz fundamental, up to the 31 st harmonic current |
| Current measurement range | 25 mA...250 A (RMS) |
| Current measurement inaccuracy | $0.005...4.000 \times I_N < \pm 0.5 \%$ or $< \pm 15 \text{ mA}$ $4...20 \times I_N < \pm 0.5 \%$ $20...50 \times I_N < \pm 1.0 \%$ |
| Angle measurement inaccuracy | $< \pm 0.2^\circ$ ($I > 0.1 \text{ A}$) $< \pm 1.0^\circ$ ($I \leq 0.1 \text{ A}$) |
| Burden (50/60 Hz) | $< 0.1 \text{ VA}$ |
| Transient overreach | $< 8 \%$ |
| Coarse residual current input (I01) | |
| Rated current I_N | 1 A (configurable 0.1...10 A) |

| | |
|---|--|
| Thermal withstand | 25 A (continuous) 100 A (for 10 s) 500 A (for 1 s) 1250 A (for 0.01 s) |
| Frequency measurement range | From 6...75 Hz fundamental, up to the 31 st harmonic current |
| Current measurement range | 5 mA...150 A (RMS) |
| Current measurement inaccuracy | $0.002...10.000 \times I_N < \pm 0.5 \%$ or $< \pm 3 \text{ mA}$ $10...150 \times I_N < \pm 0.5 \%$ |
| Angle measurement inaccuracy | $< \pm 0.2^\circ$ ($I > 0.05 \text{ A}$) $< \pm 1.0^\circ$ ($I \leq 0.05 \text{ A}$) |
| Burden (50/60Hz) | $< 0.1 \text{ VA}$ |
| Transient overreach | $< 5 \%$ |
| Fine residual current input (I02) | |
| Rated current I_N | 0.2 A (configurable 0.001...10 A) |
| Thermal withstand | 25 A (continuous) 100 A (for 10 s) 500 A (for 1 s) 1250 A (for 0.01 s) |
| Frequency measurement range | From 6...75 Hz fundamental, up to the 31 st harmonic current |
| Current measurement range | 1 mA...75 A (RMS) |
| Current measurement inaccuracy | $0.002...25.000 \times I_N < \pm 0.5 \%$ or $< \pm 0.6 \text{ mA}$ $25...375 \times I_N < \pm 1.0 \%$ |
| Angle measurement inaccuracy | $< \pm 0.2^\circ$ ($I > 0.01 \text{ A}$) $< \pm 1.0^\circ$ ($I \leq 0.01 \text{ A}$) |
| Burden (50/60Hz) | $< 0.1 \text{ VA}$ |
| Transient overreach | $< 5 \%$ |
| Screw connection terminal block (standard) | |
| Terminal block | Phoenix Contact FRONT 4-H-6,35 |
| Solid or stranded wire Nominal cross section | 4 mm ² |
| Ring lug terminal block connection (option) | |
| Ring terminal dimensions | Max 8mm diameter, with minimum 3,5mm screw hole |

**NOTICE!**

Current measurement accuracy has been verified with 50/60 Hz.

The amplitude difference is 0.2 % and the angle difference is 0.5 degrees higher at 16.67 Hz and other frequencies.

8.1.1.2 Frequency measurement

Table. 8.1.1.2 - 223. Frequency measurement accuracy.

| Frequency measurement performance | |
|-----------------------------------|---|
| Frequency measuring range | 6...75 Hz fundamental, up to the 31 st harmonic current or voltage |
| Inaccuracy | <1 mHz |

8.1.2 CPU & Power supply

Table. 8.1.2 - 224. General information for the CPU module.

| General information | |
|---|---------------------------------------|
| Spare part code | #SP-200-CPU |
| Compatibility | AQ-200 series models |
| Terminal block connection | |
| Screw connection terminal block (standard) | Phoenix Contact MSTB 2,5/5-ST-5,08 |
| Spring cage terminal block (option) | Phoenix Contact FKC 2,5/20-STF-5,08 |
| Solid or stranded wire Nominal cross section | 2.5 mm ² |
| RS-485 serial terminal block connection | |
| Screw connection terminal block (standard) | Phoenix Contact MC 1,5/ 5-ST-3,81 |
| Spring cage terminal block (option) | Phoenix Contact FK-MCP 1,5/ 5-ST-3,81 |
| Solid or stranded wire Nominal cross section | 1.5 mm ² |

8.1.2.1 Auxiliary voltage

Table. 8.1.2.1 - 225. Power supply model A

| Rated values | |
|----------------------------------|--|
| Rated auxiliary voltage | 80...265 V (AC/DC) |
| Power consumption | < 7 W (no option cards) < 15 W (maximum number of option cards) |
| Maximum permitted interrupt time | < 60 ms with 110 VDC |
| DC ripple | < 15 % |
| Other | |
| Minimum recommended fuse rating | MCB C2 |

Table. 8.1.2.1 - 226. Power supply model B

| Rated values | |
|----------------------------------|--|
| Rated auxiliary voltage | 18...72 VDC |
| Power consumption | < 7 W (no option cards) < 15 W (maximum number of option cards) |
| Maximum permitted interrupt time | < 90 ms with 24 VDC |
| DC ripple | < 15 % |
| Other | |
| Minimum recommended fuse rating | MCB C2 |

8.1.2.2 CPU communication ports

Table. 8.1.2.2 - 227. Front panel local communication port.

| Port | |
|--------------------|---|
| Port media | Copper Ethernet RJ-45 |
| Number of ports | 1 |
| Port protocols | PC-protocols FTP Telnet |
| Features | |
| Data transfer rate | 100 MB/s |
| System integration | Cannot be used for system protocols, only for local programming |

Table. 8.1.2.2 - 228. Rear panel system communication port A.

| Port | |
|--------------------|---|
| Port media | Copper Ethernet RJ-45 |
| Number of ports | 1 |
| Features | |
| Port protocols | IEC 61850 IEC 104 Modbus/TCP DNP3 FTP Telnet |
| Data transfer rate | 100 MB/s |
| System integration | Can be used for system protocols and for local programming |

Table. 8.1.2.2 - 229. Rear panel system communication port B.

| Port | |
|--------------------|---|
| Port media | Copper RS-485 |
| Number of ports | 1 |
| Features | |
| Port protocols | Modbus/RTU IEC 103 IEC 101 DNP3 SPA |
| Data transfer rate | 65 580 kB/s |
| System integration | Can be used for system protocols |

8.1.2.3 CPU digital inputs

Table. 8.1.2.3 - 230. CPU model-isolated digital inputs, with thresholds defined by order code.

| Rated values | |
|--|--|
| Rated auxiliary voltage | 265 V (AC/DC) |
| Nominal voltage | Order code defined: 24, 110, 220 V (AC/DC) |
| Pick-up threshold Release threshold | Order code defined: 19, 90, 170 V Order code defined: 14, 65, 132 V |
| Scanning rate | 5 ms |
| Settings | |
| Pick-up delay | Software settable: 0...1800 s |
| Polarity | Software settable: Normally On/Normally Off |
| Current drain | 2 mA |

8.1.2.4 CPU digital outputs

Table. 8.1.2.4 - 231. Digital outputs (Normally Open)

| Rated values | |
|--|---------------|
| Rated auxiliary voltage | 265 V (AC/DC) |
| Continuous carry | 5 A |
| Make and carry 0.5 s Make and carry 3 s | 30 A 15 A |

| | |
|--|--|
| Breaking capacity, DC (L/R = 40 ms) at 48 VDC at 110 VDC at 220 VDC | 1 A 0.4 A 0.2 A |
| Control rate | 5 ms |
| Settings | |
| Polarity | Software settable: Normally Open / Normally Closed |

Table. 8.1.2.4 - 232. Digital outputs (Change-Over)

| | |
|--|--|
| Rated values | |
| Rated auxiliary voltage | 265 V (AC/DC) |
| Continuous carry | 2.5 A |
| Make and carry 0.5 s Make and carry 3 s | 30 A 15 A |
| Breaking capacity, DC (L/R = 40 ms) at 48 VDC at 110 VDC at 220 VDC | 1 A 0.3 A 0.15 A |
| Control rate | 5 ms |
| Settings | |
| Polarity | Software settable: Normally Open / Normally Closed |

**CAUTION!**

Please note, that signaling relay 5 and system fault's signaling relay are designed only for signaling purposes, and are not to be used in trip coil control.

8.1.3 Option cards

8.1.3.1 Digital input module

Table. 8.1.3.1 - 233. Technical data for the digital input module.

| | |
|----------------------------|----------------------|
| General information | |
| Spare part code | #SP-200-DI8 |
| Compatibility | AQ-200 series models |
| Rated values | |
| Rated auxiliary voltage | 5...265 V (AC/DC) |
| Current drain | 2 mA |

| | |
|---|--|
| Scanning rate Activation/release delay | 5 ms 5...11 ms |
| Settings | |
| Pick-up threshold Release threshold | Software settable: 16...200 V, setting step 1 V Software settable: 10...200 V, setting step 1 V |
| Pick-up delay | Software settable: 0...1800 s |
| Drop-off delay | Software settable: 0...1800 s |
| Polarity | Software settable: Normally On/Normally Off |
| Terminal block connection | |
| Screw connection terminal block (standard) | Phoenix Contact MSTB 2,5/10-ST-5,08 |
| Spring cage terminals block (option) | Phoenix Contact FKC 2,5/10-STF-5,08 |
| Solid or stranded wire Nominal cross section | 2.5 mm ² |

8.1.3.2 Digital output module

Table. 8.1.3.2 - 234. Technical data for the digital output module.

| | |
|--|---|
| General information | |
| Spare part code | #SP-200-DO5 |
| Compatibility | AQ-200 series models |
| Rated values | |
| Rated auxiliary voltage | 265 V (AC/DC) |
| Continuous carry | 5 A |
| Make and carry 0.5 s Make and carry 3 s | 30 A 15 A |
| Breaking capacity, DC (L/R = 40 ms) at 48 VDC at 110 VDC at 220 VDC | 1 A 0.4 A 0.2 A |
| Control rate | 5 ms |
| Settings | |
| Polarity | Software settable: Normally On/Normally Off |
| Terminal block connection | |
| Screw connection terminal block (standard) | Phoenix Contact MSTB 2,5/10-ST-5,08 |
| Spring cage terminals block (option) | Phoenix Contact FKC 2,5/10-STF-5,08 |

| | |
|---|---------------------|
| Solid or stranded wire Nominal cross section | 2.5 mm ² |
|---|---------------------|

8.1.3.3 Point sensor arc protection module

Table. 8.1.3.3 - 235. Technical data for the point sensor arc protection module.

| General information | |
|---|--|
| Spare part code | #SP-2XX-ARC |
| Compatibility | AQ-200 series & AQ-250 series models |
| Connections | |
| Input arc point sensor channels | S1, S2, S3, S4 (pressure and light, or light only) |
| Sensors per channel | 3 |
| Maximum cable length | 200 m |
| Performance | |
| Pick-up light intensity | 8, 25 or 50 kLx (the sensor is selectable in the order code) |
| Point sensor detection radius | 180 degrees |
| Start and instant operating time (light only) | Typically <5 ms with dedicated semiconductor outputs (HSO) Typically <10 ms regular output relays |

Table. 8.1.3.3 - 236. High-Speed Outputs (HSO1...2)

| Rated values | |
|--|---------------|
| Rated auxiliary voltage | 250 VDC |
| Continuous carry | 2 A |
| Make and carry 0.5 s Make and carry 3 s | 15 A 6 A |
| Breaking capacity, DC (L/R = 40 ms) | 1 A/110 W |
| Control rate | 5 ms |
| Operation delay | <1 ms |
| Polarity | Normally Off |
| Contact material | Semiconductor |

Table. 8.1.3.3 - 237. Binary input channel

| Rated values | |
|-------------------|---------|
| Voltage withstand | 265 VDC |

| | |
|---|------------------------------|
| Nominal voltage Pick-up threshold Release threshold | 24 VDC ≥16 VDC ≤15 VDC |
| Scanning rate | 5 ms |
| Polarity | Normally Off |
| Current drain | 3 mA |

Table. 8.1.3.3 - 238. Terminal block connections

| Arc point sensor terminal block connections | |
|---|-------------------------------------|
| Spring cage terminal block | Phoenix Contact DFMC 1,5/ 6-STF-3,5 |
| Solid or stranded wire Nominal cross section | 1.5 mm ² |
| Binary input and HSO terminal block connections | |
| Screw connection terminal block (standard) | Phoenix Contact MSTB 2,5/5-ST-5,08 |
| Spring cage terminals block (option) | Phoenix Contact FKC 2,5/10-STF-5,08 |
| Solid or stranded wire Nominal cross section | 2.5 mm ² |

**NOTICE!**

The polarity must be correct!

8.1.3.4 Milliampere output module (mA out & mA in)

Table. 8.1.3.4 - 239. Technical data for the milliampere output module.

| General information | |
|--|---|
| Spare part code | #SP-2XX-MA |
| Compatibility | AQ-200 series & AQ-250 series models |
| Signals | |
| Output magnitudes Input magnitudes | 4 × mA output signal (DC) 1 × mA input signal (DC) |
| mA input | |
| Range (hardware) Range (measurement) Inaccuracy | 0...33 mA 0...24 mA ±0.1 mA |
| Update cycle Response time @ 5 ms cycle Update cycle time inaccuracy | 5...10 000 ms, setting step 5 ms ~ 15 ms (13...18 ms) Max. +20 ms above the set cycle |

| | |
|--|---|
| mA input scaling range | 0...4000 mA |
| Output scaling range | -1 000 000.0000...1 000 000.0000, setting step 0.0001 |
| mA output | |
| Inaccuracy @ 0...24 mA | ±0.01 mA |
| Response time @ 5 ms cycle [fixed] | < 5 ms |
| mA output scaling range | 0...24 mA, setting step 0.001 mA |
| Source signal scaling range | -1 000 000.000...1 000 000.0000, setting step 0.0001 |
| Terminal block connection | |
| Screw connection terminal block (standard) | Phoenix Contact MSTB 2,5/10-ST-5,08 |
| Spring cage terminals block (option) | Phoenix Contact FKC 2,5/10-STF-5,08 |
| Solid or stranded wire | 2.5 mm ² |
| Nominal cross section | |

8.1.3.5 RTD input module

Table. 8.1.3.5 - 240. Technical data for the RTD input module.

| | |
|----------------------------------|--------------------------------------|
| General information | |
| Spare part code | #SP-2xx-RTD |
| Compatibility | AQ-200 series & AQ-250 series models |
| Channels 1-8 | |
| 2/3/4-wire RTD | |
| Pt100 or Pt1000 | |
| Terminal block connection | |
| Spring cage terminals block | Phoenix Contact DFMC 1,5/ 16-STF-3,5 |
| Solid or stranded wire | 1.5 mm ² |
| Nominal cross section | |

8.1.3.6 RS-232 & serial fiber communication module

Table. 8.1.3.6 - 241. Technical data for the RS-232 & serial fiber communication module.

| | |
|----------------------------|---------------|
| General information | |
| PP Spare part code | #SP-2XX-232PP |
| PG Spare part code | #SP-2XX-232PG |
| GP Spare part code | #SP-2XX-232GP |
| GG Spare part code | #SP-2XX-232GG |

| | |
|---|--------------------------------------|
| Compatibility | AQ-200 series & AQ-250 series models |
| Ports | |
| RS-232 | |
| Serial fiber (GG/PP/GP/PG) | |
| Serial port wavelength | |
| 660 nm | |
| Cable type | |
| 1 mm plastic fiber | |
| Terminal block connections | |
| Spring cage terminals block | Phoenix Contact DFMC 1,5/ 6-STF-3,5 |
| Solid or stranded wire Nominal cross section | 1.5 mm ² |

8.1.3.7 Double LC 100 Mbps Ethernet communication module

Table. 8.1.3.7 - 242. Technical data for the double LC 100 Mbps Ethernet communication module.

| | |
|--------------------------|--|
| General information | |
| Spare part code | #SP-2XX-2XLC |
| Compatibility | AQ-200 series & AQ-250 series models |
| Protocols | |
| Protocols | HSR and PRP |
| Ports | |
| Quantity of fiber ports | 2 |
| Communication port C & D | LC fiber connector Wavelength 1300 nm |
| Fiber cable | 50/125 µm or 62.5/125 µm multimode (glass) |

8.1.3.8 Double ST 100 Mbps Ethernet communication module

Table. 8.1.3.8 - 243. Technical data for the double ST 100 Mbps Ethernet communication module.

| | |
|---------------------|--------------------------------------|
| General information | |
| Spare part code | #SP-2XX-2XST |
| Compatibility | AQ-200 series & AQ-250 series models |
| Dimensions | 74 mm X 179 mm |

| | |
|---|--|
| Ports | ST connectors (2) and IRIG-B connector (1) |
| Protocols | |
| Protocols | IEC61850, DNP/TCP, Modbus/TCP, IEC104 & FTP |
| ST connectors | |
| Connector type | Duplex ST connectors 62.5/125 µm or 50/125 µm multimode fiber 100BASE-FX |
| Transmitter wavelength | 1260...1360 nm (nominal: 1310 nm) |
| Receiver wavelength | 1100...1600 nm |
| Maximum distance | 2 km |
| IRIG-B Connector | |
| Screw connection terminal block | Phoenix Contact MC 1,5/ 2-ST-3,5 BD:1-2 |
| Solid or stranded wire Nominal cross section | 1.5 mm ² |

8.1.4 Display

Table. 8.1.4 - 244. Technical data for the HMI LCD display.

| | |
|----------------------------------|-----------------------------------|
| General information | |
| Spare part code | #SP-200-DISP |
| Compatibility | AQ-200 series models |
| Dimensions and resolution | |
| Number of dots/resolution | 320 x 160 |
| Size | 84.78 × 49.90 mm (3.34 × 1.96 in) |
| Display | |
| Type of display | LCD |
| Color | Monochrome |

8.2 Functions

8.2.1 Protection functions

8.2.1.1 Non-directional overcurrent protection ($I>$; 50/51)

Table. 8.2.1.1 - 245. Technical data for the non-directional overcurrent function.

| Measurement inputs | |
|---|--|
| Current inputs | Phase current inputs: I_{L1} (A), I_{L2} (B), I_{L3} (C) |
| Current input magnitudes | RMS phase currents TRMS phase currents Peak-to-peak phase currents |
| Pick-up | |
| Pick-up current setting | $0.10 \dots 50.00 \times I_n$, setting step $0.01 \times I_n$ |
| Inrush 2nd harmonic blocking | $0.10 \dots 50.00 \% I_{fund}$, setting step $0.01 \% I_{fund}$ |
| Inaccuracy: - Current - 2 nd harmonic blocking | $\pm 0.5 \% I_{set}$ or $\pm 15 \text{ mA}$ ($0.10 \dots 4.0 \times I_{set}$) $\pm 1.0 \%$ -unit of the 2 nd harmonic setting |
| Operation time | |
| Definite time function operating time setting | $0.00 \dots 1800.00 \text{ s}$, setting step 0.005 s |
| Inaccuracy: - Definite time: I_m/I_{set} ratio > 3 - Definite time: I_m/I_{set} ratio $= 1.05 \dots 3$ | $\pm 1.0 \%$ or $\pm 20 \text{ ms}$ $\pm 1.0 \%$ or $\pm 30 \text{ ms}$ |
| IDMT setting parameters: - k Time dial setting for IDMT - A IDMT constant - B IDMT constant - C IDMT constant | $0.01 \dots 25.00$, step 0.01 $0 \dots 250.0000$, step 0.0001 $0 \dots 5.0000$, step 0.0001 $0 \dots 250.0000$, step 0.0001 |
| Inaccuracy: - IDMT operating time - IDMT minimum operating time | $\pm 1.5 \%$ or $\pm 20 \text{ ms}$ $\pm 20 \text{ ms}$ |
| Retardation time (overshoot) | $< 30 \text{ ms}$ |
| Instant operation time | |
| Start time and instant operation time (trip): - I_m/I_{set} ratio > 3 - I_m/I_{set} ratio $= 1.05 \dots 3$ | $< 35 \text{ ms}$ (typically 25 ms) $< 50 \text{ ms}$ |
| Reset | |
| Reset ratio | 97 % of the pick-up current setting |
| Reset time setting Inaccuracy: Reset time | $0.010 \dots 10.000 \text{ s}$, step 0.005 s $\pm 1.0 \%$ or $\pm 50 \text{ ms}$ |

| | |
|---------------------------------------|--------|
| Instant reset time and start-up reset | <50 ms |
|---------------------------------------|--------|

**NOTICE!**

The release delay does not apply to phase-specific tripping!

8.2.1.2 Non-directional earth fault protection ($I_0 >$; 50N/51N)

Table. 8.2.1.2 - 246. Technical data for the non-directional earth fault function.

| Measurement inputs | |
|--|---|
| Current input (selectable) | Residual current channel I_{01} (Coarse) Residual current channel I_{02} (Fine) Calculated residual current: I_{L1} (A), I_{L2} (B), I_{L3} (C) |
| Current input magnitudes | RMS residual current (I_{01} , I_{02} or calculated I_0) TRMS residual current (I_{01} or I_{02}) Peak-to-peak residual current (I_{01} or I_{02}) |
| Pick-up | |
| Used magnitude | Measured residual current I_{01} (1 A) Measured residual current I_{02} (0.2 A) Calculated residual current I_{0Calc} (5 A) |
| Pick-up current setting | $0.0001 \dots 40.00 \times I_n$, setting step $0.0001 \times I_n$ |
| Inaccuracy: - Starting I_{01} (1 A) - Starting I_{02} (0.2 A) - Starting I_{0Calc} (5 A) | $\pm 0.5 \% I_{0set}$ or $\pm 3 \text{ mA}$ ($0.005 \dots 10.0 \times I_{set}$) $\pm 1.5 \% I_{0set}$ or $\pm 1.0 \text{ mA}$ ($0.005 \dots 25.0 \times I_{set}$) $\pm 1.0 \% I_{0set}$ or $\pm 15 \text{ mA}$ ($0.005 \dots 4.0 \times I_{set}$) |
| Operating time | |
| Definite time function operating time setting | $0.00 \dots 1800.00 \text{ s}$, setting step 0.005 s |
| Inaccuracy: - Definite time: I_m/I_{set} ratio > 3 - Definite time: I_m/I_{set} ratio = $1.05 \dots 3$ | $\pm 1.0 \%$ or $\pm 20 \text{ ms}$ $\pm 1.0 \%$ or $\pm 30 \text{ ms}$ |
| IDMT setting parameters: - k Time dial setting for IDMT - A IDMT constant - B IDMT constant - C IDMT constant | $0.01 \dots 25.00$, step 0.01 $0 \dots 250.0000$, step 0.0001 $0 \dots 5.0000$, step 0.0001 $0 \dots 250.0000$, step 0.0001 |
| Inaccuracy: - IDMT operating time - IDMT minimum operating time | $\pm 1.5 \%$ or $\pm 20 \text{ ms}$ $\pm 20 \text{ ms}$ |
| Retardation time (overshoot) | <30 ms |
| Instant operation time | |
| Start time and instant operation time (trip): - I_m/I_{set} ratio > 3.5 - I_m/I_{set} ratio = $1.05 \dots 3.5$ | <50 ms (typically 35 ms) <55 ms |

| Reset | |
|--|--|
| Reset ratio | 97 % of the pick-up current setting |
| Reset time setting Inaccuracy: Reset time | 0.010...10.000 s, step 0.005 s ± 1.0 % or ± 50 ms |
| Instant reset time and start-up reset | <50 ms |

**NOTICE!**

The operation and reset time accuracy does **not** apply when the measured secondary current in I02 is 1...20 mA. The pick-up is tuned to be more sensitive and the operation times vary because of this.

8.2.1.3 Negative sequence overcurrent/ phase current reversal/ current unbalance protection (I2>; 46/46R/46L)

Table. 8.2.1.3 - 247. Technical data for the current unbalance function.

| Measurement inputs | |
|---|--|
| Current inputs | Phase current inputs: I_{L1} (A), I_{L2} (B), I_{L3} (C) |
| Current input calculations | Positive sequence current (I1) Negative sequence current (I2) |
| Pick-up | |
| Used magnitude | Negative sequence component I2pu Relative unbalance I2/I1 |
| Pick-up setting | 0.01...40.00 $\times I_n$, setting step 0.01 $\times I_n$ (I2pu) 1.00...200.00 %, setting step 0.01 % (I2/I1) |
| Minimum phase current (at least one phase above) | 0.01...2.00 $\times I_n$, setting step 0.01 $\times I_n$ |
| Inaccuracy: - Starting I2pu - Starting I2/I1 | ± 1.0 %-unit or ± 100 mA (0.10...4.0 $\times I_n$) ± 1.0 %-unit or ± 100 mA (0.10...4.0 $\times I_n$) |
| Operating time | |
| Definite time function operating time setting | 0.00...1800.00 s, setting step 0.005 s |
| Inaccuracy: - Definite time (I_m/I_{set} ratio > 1.05) | ± 1.5 % or ± 60 ms |
| IDMT setting parameters: - k Time dial setting for IDMT - A IDMT Constant - B IDMT Constant - C IDMT Constant | 0.01...25.00, step 0.01 0...250.0000, step 0.0001 0...5.0000, step 0.0001 0...250.0000, step 0.0001 |
| Inaccuracy: - IDMT operating time - IDMT minimum operating time | ± 2.0 % or ± 30 ms ± 20 ms |
| Retardation time (overshoot) | <5 ms |

| Instant operation time | |
|---|--|
| Start time and instant operation time (trip): - I_M/I_{set} ratio > 1.05 | <70 ms |
| Reset | |
| Reset ratio | 97 % of the pick-up setting |
| Reset time setting Inaccuracy: Reset time | 0.010...10.000 s, step 0.005 s ± 1.5 % or ± 60 ms |
| Instant reset time and start-up reset | <55 ms |

8.2.1.4 Harmonic overcurrent protection (I_h >; 50H/51H/68H)

Table. 8.2.1.4 - 248. Technical data for the harmonic overcurrent function.

| Measurement inputs | |
|---|---|
| Current inputs | Phase current inputs: I_{L1} (A), I_{L2} (B), I_{L3} (C) Residual current channel I_{01} (Coarse) Residual current channel I_{02} (Fine) |
| Pick-up | |
| Harmonic selection | 2 nd , 3 rd , 4 th , 5 th , 6 th , 7 th , 9 th , 11 th , 13 th , 15 th , 17 th or 19 th |
| Used magnitude | Harmonic per unit ($\times I_N$) Harmonic relative (I_h/I_L) |
| Pick-up setting | 0.05...2.00 $\times I_N$, setting step 0.01 $\times I_N$ ($\times I_N$) 5.00...200.00 %, setting step 0.01 % (I_h/I_L) |
| Inaccuracy: - Starting $\times I_N$ - Starting $\times I_h/I_L$ | <0.03 $\times I_N$ (2 nd , 3 rd , 5 th) <0.03 $\times I_N$ tolerance to I_h (2 nd , 3 rd , 5 th) |
| Operation time | |
| Definite time function operating time setting | 0.00...1800.00 s, setting step 0.005 s |
| Inaccuracy: - Definite time (I_M/I_{SET} ratio >1.05) | ± 1.0 % or ± 35 ms |
| IDMT setting parameters: k Time dial setting for IDMT A IDMT constant B IDMT constant C IDMT constant | 0.01...25.00, step 0.01 0...250.0000, step 0.0001 0...5.0000, step 0.0001 0...250.0000, step 0.0001 |
| Inaccuracy: - IDMT operating time - IDMT minimum operating time | ± 1.5 % or ± 20 ms ± 20 ms |
| Instant operation time | |
| Start time and instant operation time (trip): I_M/I_{SET} ratio >1.05 | <50 ms |

| Reset | |
|--|--|
| Reset ratio | 95 % of the pick-up setting |
| Reset time setting Inaccuracy: Reset time | 0.010...10.000 s, step 0.005 s ±1.0 % or ±35 ms |
| Instant reset time and start-up reset | <50 ms |

NOTICE!

Harmonics generally: The amplitude of the harmonic content must be least $0.02 \times I_N$ when the relative mode (Ih/IL) is used!



Blocking: To achieve fast activation for blocking purposes with the harmonic overcurrent stage, note that the harmonic stage may be activated by a rapid load change or fault situation. An intentional activation lasts for approximately 20 ms if a harmonic component is not present. The harmonic stage stays active if the harmonic content is above the pick-up limit.

Tripping: When using the harmonic overcurrent stage for tripping, please ensure that the operation time is set to 20 ms (DT) or longer to avoid nuisance tripping caused by the above-mentioned reasons.

8.2.1.5 Circuit breaker failure protection (CBFP; 50BF/52BF)

Table. 8.2.1.5 - 249. Technical data for the circuit breaker failure protection function.

| Measurement inputs | |
|--|--|
| Current inputs | Phase current inputs: I_{L1} (A), I_{L2} (B), I_{L3} (C) Residual current channel I_{01} (Coarse) Residual current channel I_{02} (Fine) |
| Current input magnitudes | RMS phase currents RMS residual current (I_{01} , I_{02} or calculated I_0) |
| Pick-up | |
| Monitored signals | Digital input status, digital output status, logical signals |
| Pick-up current setting: - $I_{L1}...I_{L3}$ - I_{01} , I_{02} , I_{0Calc} | $0.10...40.00 \times I_N$, setting step $0.01 \times I_N$ $0.005...40.00 \times I_N$, setting step $0.005 \times I_N$ |
| Inaccuracy: - Starting phase current (5A) - Starting I_{01} (1 A) - Starting I_{02} (0.2 A) - Starting I_{0Calc} (5 A) | $\pm 0.5 \% I_{SET}$ or ± 15 mA ($0.10...4.0 \times I_{SET}$) $\pm 0.5 \% I_{0SET}$ or ± 3 mA ($0.005...10.0 \times I_{SET}$) $\pm 1.5 \% I_{0SET}$ or ± 1.0 mA ($0.005...25.0 \times I_{SET}$) $\pm 1.0 \% I_{0SET}$ or ± 15 mA ($0.005...4.0 \times I_{SET}$) |
| Operation time | |
| Definite time function operating time setting | 0.050...1800.000 s, setting step 0.005 s |
| Inaccuracy: - Current criteria (I_M/I_{SET} ratio 1.05→) - DO or DI only | ± 1.0 % or ± 55 ms ± 15 ms |
| Reset | |

| | |
|-------------|-------------------------------------|
| Reset ratio | 97 % of the pick-up current setting |
| Reset time | <50 ms |

8.2.1.6 Low-impedance or high-impedance restricted earth fault/ cable end differential protection ($I_{0d}>$; 87N)

Table. 8.2.1.6 - 250. Technical data for the restricted earth fault/cable end differential function.

| Measurement inputs | |
|---|---|
| Current inputs | Phase current inputs: I_{L1} (A), I_{L2} (B), I_{L3} (C) Residual current channel I_{01} (Coarse) Residual current channel I_{02} (Fine) |
| Current input calculations | Calculated bias and residual differential currents |
| Pick-up | |
| Operating modes | Restricted earth fault Cable end differential |
| Characteristics | Biased differential with 3 settable sections and 2 slopes |
| Pick-up current sensitivity setting Slope 1 Slope 2 Bias (Turnpoint 1 & 2) | 0.01...50.00 % (I_N), setting step 0.01 % 0.00...150.00 %, setting step 0.01 % 0.00...250.00 %, setting step 0.01 % 0.01...50.00 $\times I_N$, setting step 0.01 $\times I_N$ |
| Inaccuracy - Starting | $\pm 3\%$ of the set pick-up value $> 0.5 \times I_N$ setting. $\pm 5 \text{ mA} < 0.5 \times I_N$ setting |
| Operation time | |
| Instant operation time $1.05 \times I_{SET}$ | <30 ms |
| Reset | |
| Reset ratio | No hysteresis |
| Reset time | <40 ms |

8.2.1.7 Line thermal overload protection ($TF>$; 49F)

Table. 8.2.1.7 - 251. Technical data for the line thermal overload protection function.

| Measurement inputs | |
|--------------------------|--|
| Current inputs | Phase current inputs: I_{L1} (A), I_{L2} (B), I_{L3} (C) |
| Current input magnitudes | TRMS phase currents (up to the 31 st harmonic) |
| Settings | |
| Time constants τ | 1 |

| | |
|---|--|
| Time constant value | 0.0...500.00 min, step 0.1 min |
| Service factor (maximum overloading) | 0.01...5.00 × I _N , step 0.01 × I _N |
| Thermal model biasing | - Ambient temperature (Set -60.0...500.0 deg, step 0.1 deg and RTD) - Negative sequence current |
| Thermal replica temperature estimates | Selectable between °C and °F |
| Outputs | |
| - Alarm 1 - Alarm 2 - Thermal trip - Trip delay - Restart inhibit | 0...150 %, step 1 % 0...150 %, step 1 % 0...150 %, step 1 % 0.000...3600.000 s, step 0.005 s 0...150 %, step 1 % |
| Inaccuracy | |
| - Starting - Operating time | ±0.5 % of the set pick-up value ±5 % or ± 500 ms |

8.2.1.8 Resistance temperature detectors (RTD)

Table. 8.2.1.8 - 252. Technical data of the resistance temperature detectors.

| | |
|--|--|
| Inputs | |
| Resistance input magnitudes | Measured temperatures measured by RTD sensors |
| RTD channels | 12 individual RTD channels |
| Settable alarms | 24 alarms available (two per each RTD channel) |
| Pick-up | |
| Alarm setting range Inaccuracy Reset ratio | 101.00...2000.00 deg, setting step 0.1 deg (either < or > setting) ±3 % of the set pick-up value 97 % of the pick-up setting |
| Operation | |
| Operating time | Typically <500 ms |

8.2.1.9 Arc fault protection (IArc>/IOArc>; 50Arc/50NArc) (optional)

Table. 8.2.1.9 - 253. Technical data for the arc fault protection function.

| | |
|---------------------------|---|
| Measurement inputs | |
| Current inputs | Phase current inputs: I _{L1} (A), I _{L2} (B), I _{L3} (C) Residual current channel I ₀₁ (Coarse) Residual current channel I ₀₂ (Fine) |
| Current input magnitudes | Sample-based phase current measurement Sample-based residual current measurement |

| | |
|--|--|
| Arc point sensor inputs | Channels S1, S2, S3, S4 (pressure and light sensor, or light-only sensor) Up to four (4) sensors per channel |
| System frequency operating range | 6.00...75.00 Hz |
| Pick-up | |
| Pick-up current setting (phase current) Pick-up current setting (residual current) Pick-up light intensity | 0.50...40.00 × I _N , setting step 0.01 × I _N 0.10...40.00 × I _N , setting step 0.01 × I _N 8, 25 or 50 kLx (the sensor is selected in the order code) |
| Starting inaccuracy (I _{Arc} > and I _{0Arc} >) | ±3 % of the set pick-up value > 0.5 × I _N setting. 5 mA < 0.5 × I _N setting. |
| Point sensor detection radius | 180 degrees |
| Operation time | |
| Light only: - Semiconductor outputs HSO1 and HSO2 - Regular relay outputs | Typically 7 ms (3...12 ms) Typically 10 ms (6.5...15 ms) |
| Light + current criteria (zone 1...4): - Semiconductor outputs HSO1 and HSO2 - Regular relay outputs | Typically 10 ms (6.5...14 ms) Typically 14 ms (10...18 ms) |
| Arc BI only: - Semiconductor outputs HSO1 and HSO2 - Regular relay outputs | Typically 7 ms (2...12 ms) Typically 10 ms (6.5...15 ms) |

8.2.2 Control functions

8.2.2.1 Setting group selection

Table. 8.2.2.1 - 254. Technical data for the setting group selection function.

| | |
|-----------------------------------|--|
| Settings and control modes | |
| Setting groups | 8 independent, control-prioritized setting groups |
| Control scale | Common for all installed functions which support setting groups |
| Control mode | |
| Local | Any binary signal available in the device |
| Remote | Force change overrule of local controls either from the setting tool, HMI or SCADA |
| Operation time | |
| Reaction time | <5 ms from receiving the control signal |

8.2.2.2 Object control and monitoring

Table. 8.2.2.2 - 255. Technical data for the object control and monitoring function.

| General | |
|---|--|
| Number of objects | 5 |
| Supported object types | Circuit breaker Circuit breaker with withdrawable cart Disconnecter (MC) Disconnecter (GND) |
| Signals | |
| Input signals | Digital inputs Software signals |
| Output signals | Close command output Open command output |
| Operation time | |
| Breaker traverse time setting | 0.02...500.00 s, setting step 0.02 s |
| Max. close/open command pulse length | 0.02...500.00 s, setting step 0.02 s |
| Control termination time out setting | 0.02...500.00 s, setting step 0.02 s |
| Inaccuracy: - Definite time operating time | ±0.5 % or ±10 ms |
| Breaker control operation time | |
| External object control time | <75 ms |
| Object control during auto-reclosing | See the technical sheet for the auto-reclosing function. |

8.2.2.3 Indicator object monitoring

Table. 8.2.2.3 - 256. Technical data for the indicator object monitoring function.

| General | |
|------------------------|------------------------------------|
| Number of objects | 5 |
| Supported object types | Disconnecter (GND) |
| Signals | |
| Input signals | Digital inputs Software signals |

8.2.2.4 Auto-reclosing (0 → 1; 79)

Table. 8.2.2.4 - 257. Technical data for the auto-reclosing function.

| Input signals | |
|---|--|
| Input signals | Software signals (protection, logics, etc.) Binary inputs |
| Requests | |
| REQ1-5 | 5 priority request inputs; can be set parallel as signals to each request |
| Shots | |
| 1-5 shots | 5 independent or scheme-controlled shots in each AR request |
| Operation time | |
| Operating time settings: - Lockout after successful AR - Object close reclaim time - AR shot starting delay - AR shot dead time delay - AR shot action time - AR shot specific reclaim time | 0.000...1800.000 s, setting step 0.005 s 0.000...1800.000 s, setting step 0.005 s 0.000...1800.000 s, setting step 0.005 s 0.000...1800.000 s, setting step 0.005 s 0.000...1800.000 s, setting step 0.005 s 0.000...1800.000 s, setting step 0.005 s |
| Inaccuracy | |
| AR starting (from a protection stage's START signal) | ±1.0 % or ±30 ms (AR delay) |
| AR starting (from a protection stage's TRIP signal) | Trip delay inaccuracy +25 ms (Protection + AR delay) |
| Dead time | ±1.0 % or ±35 ms (AR delay) |
| Action time | ±1.0 % or ±30 ms (AR delay) |
| Instant starting time | |
| Instant operation time | Protection activation delay + 15 ms (Protection + AR delay) |

8.2.2.5 Cold load pick-up (CLPU)

Table. 8.2.2.5 - 258. Technical data for the cold load pick-up function.

| Measurement inputs | |
|--|--|
| Current inputs | Phase current inputs: I_{L1} (A), I_{L2} (B), I_{L3} (C) |
| Current input magnitudes | RMS phase currents |
| Pick-up | |
| Pick-up current setting - $I_{LOW}/I_{HIGH}/I_{OVER}$ | 0.01...40.00 × I_N , setting step 0.01 × I_N |

| | |
|--|--|
| Reset ratio | 97 % of the pick-up current setting |
| Inaccuracy: - Current | $\pm 0.5 \% I_{SET}$ or $\pm 15 \text{ mA}$ ($0.10 \dots 4.0 \times I_{SET}$) |
| Operation time | |
| Definite time function operating time settings: - t_{SET} - t_{MAX} - t_{MIN} | 0.000...1800.000 s, setting step 0.005 s 0.000...1800.000 s, setting step 0.005 s 0.000...1800.000 s, setting step 0.005 s |
| Inaccuracy: - Definite time (I_M/I_{SET} ratio = 1.05/0.95) | $\pm 1.0 \%$ or $\pm 45 \text{ ms}$ |
| Instant operation time | |
| CLPU activation and release | <45 ms (measured from the trip contact) |

**NOTICE!**

A single-phase current (IL1, IL2 or IL3) is enough to prolong or release the blocking during an overcurrent condition.

8.2.2.6 Switch-on-to-fault (SOTF)

Table. 8.2.2.6 - 259. Technical data for the switch-on-to-fault function.

| | |
|--------------------------------|--|
| Initialization signals | |
| SOTF activate input | Any blocking input signal (Object closed signal, etc.) |
| Pick-up | |
| SOTF function input | Any blocking input signal ($I >$ or similar) |
| SOTF activation time | |
| Activation time | <40 ms (measured from the trip contact) |
| SOTF release time | |
| Release time setting | 0.000...1800.000 s, setting step 0.005 s |
| Inaccuracy: - Definite time | $\pm 1.0 \%$ or $\pm 30 \text{ ms}$ |
| SOTF instant release time | <40 ms (measured from the trip contact) |

8.2.3 Monitoring functions

8.2.3.1 Current transformer supervision

Table. 8.2.3.1 - 260. Technical data for the current transformer supervision function.

| |
|---------------------------|
| Measurement inputs |
|---------------------------|

| | |
|---|--|
| Current inputs | Phase current inputs: IL1 (A), IL2 (B), IL3 (C) Residual current channel I ₀₁ (Coarse) (optional) Residual current channel I ₀₂ (Fine) (optional) |
| Current input magnitudes | RMS phase currents RMS residual current (I ₀₁ , I ₀₂) (optional) |
| Pick-up | |
| Pick-up current settings: - I _{SET} high limit - I _{SET} low limit - I _{SUM} difference - I _{SET} ratio - I ₂ /I ₁ ratio | 0.10...40.00 × I _N , setting step 0.01 × I _N 0.10...40.00 × I _N , setting step 0.01 × I _N 0.10...40.00 × I _N , setting step 0.01 × I _N 0.01...100.00 %, setting step 0.01 % 0.01...100.00 %, setting step 0.01 % |
| Inaccuracy: - Starting IL1, IL2, IL3 - Starting I ₂ /I ₁ - Starting I ₀₁ (1 A) - Starting I ₀₂ (0.2 A) | ±0.5 % I _{SET} or ±15 mA (0.10...4.0 × I _{SET}) ±1.0 % I _{2SET} / I _{1SET} or ±100 mA (0.10...4.0 × I _N) ±0.5 % I _{0SET} or ±3 mA (0.005...10.0 × I _{SET}) ±1.5 % I _{0SET} or ±1.0 mA (0.005...25.0 × I _{SET}) |
| Time delay for alarm | |
| Definite time function operating time setting | 0.00...1800.00 s, setting step 0.005 s |
| Inaccuracy_ - Definite time (I _M /I _{SET} ratio > 1.05) | ±2.0 % or ±80 ms |
| Instant operation time (alarm): - I _M /I _{SET} ratio > 1.05 | <80 ms (<50 ms in differential protection relays) |
| Reset | |
| Reset ratio | 97/103 % of the pick-up current setting |
| Instant reset time and start-up reset | <80 ms (<50 ms in differential protection relays) |

8.2.3.2 Circuit breaker wear monitoring

Table. 8.2.3.2 - 261. Technical data for the circuit breaker wear monitoring function.

| | |
|--|--|
| Pick-up | |
| Breaker characteristics settings: - Nominal breaking current - Maximum breaking current - Operations with nominal current - Operations with maximum breaking current | 0.00...100.00 kA, setting step 0.001 kA 0.00...100.00 kA, setting step 0.001 kA 0...200 000 operations, setting step 1 operation 0...200 000 operations, setting step 1 operation |
| Pick-up setting for Alarm 1 and Alarm 2 | 0...200 000 operations, setting step 1 operation |
| Inaccuracy | |
| Inaccuracy for current/operations counter: - Current measurement element - Operation counter | 0.1 × I _N > I < 2 × I _N ±0.2 % of the measured current, rest 0.5 % ±0.5 % of operations deducted |

8.2.3.3 Current total harmonic distortion

Table. 8.2.3.3 - 262. Technical data for the total harmonic distortion function.

| Input signals | |
|--|--|
| Current inputs | Phase current inputs: I_{L1} (A), I_{L2} (B), I_{L3} (C) Residual current channel I_{01} (Coarse) Residual current channel I_{02} (Fine) |
| Current input magnitudes | Current measurement channels (FFT result) up to the 31 st harmonic component. |
| Pick-up | |
| Operating modes | Power THD Amplitude THD |
| Pick-up setting for all comparators | 0.10...200.00 % , setting step 0.01 % |
| Inaccuracy | ± 3 % of the set pick-up value $> 0.5 \times I_N$ setting; $5 \text{ mA} < 0.5 \times I_N$ setting. |
| Time delay | |
| Definite time function operating time setting for all timers | 0.00...1800.00 s, setting step 0.005 s |
| Inaccuracy: - Definite time operating time - Instant operating time, when I_M/I_{SET} ratio > 3 - Instant operating time, when I_M/I_{SET} ratio $1.05 < I_M/I_{SET} < 3$ | ± 0.5 % or ± 10 ms Typically < 20 ms Typically < 25 ms |
| Reset | |
| Reset time | Typically < 10 ms |
| Reset ratio | 97 % |

8.2.3.4 Disturbance recorder

Table. 8.2.3.4 - 263. Technical data for the disturbance recorder function.

| Recorded values | |
|---------------------------|--|
| Recorder analog channels | 0...20 channels Freely selectable |
| Recorder digital channels | 0...95 channels Freely selectable analog and binary signals 5 ms sample rate (FFT) |
| Performance | |
| Sample rate | 8, 16, 32 or 64 samples/cycle |

| | |
|----------------------|--|
| Recording length | 0.000...1800.000 s, setting step 0.001 s The maximum length is determined by the chosen signals. |
| Number of recordings | 0...100, 60 MB of shared flash memory reserved The maximum number of recordings according to the chosen signals and operation time setting combined |

8.2.3.5 Event logger

Table. 8.2.3.5 - 264. Technical data for the event logger function.

| General information | |
|----------------------------|---------------|
| Event history capacity | 15 000 events |
| Event timestamp resolution | 1 ms |

8.3 Tests and environmental

Electrical environment compatibility

Table. 8.3 - 265. Disturbance tests.

| All tests | CE-approved and tested according to EN 60255-26 |
|--|--|
| Emissions | |
| Conducted emissions: EN 60255-26 Ch. 5.2, CISPR 22 | 150 kHz...30 MHz |
| Radiated emissions: EN 60255-26 Ch. 5.1, CISPR 11 | 30...1 000 MHz |
| Immunity | |
| Electrostatic discharge (ESD): EN 60255-26, IEC 61000-4-2 | Air discharge 15 kV Contact discharge 8 kV |
| Electrical fast transients (EFT): EN 60255-26, IEC 61000-4-4 | Power supply input 4 kV, 5/50 ns, 5 kHz Other inputs and outputs 4 kV, 5/50 ns, 5 kHz |
| Surge: EN 60255-26, IEC 61000-4-5 | Between wires 2 kV, 1.2/50 μ s Between wire and earth 4 kV, 1.2/50 μ s |
| Radiated RF electromagnetic field: EN 60255-26, IEC 61000-4-3 | f = 80....1 000 MHz, 10 V/m |
| Conducted RF field: EN 60255-26, IEC 61000-4-6 | f = 150 kHz....80 MHz, 10 V (RMS) |

Table. 8.3 - 266. Voltage tests.

| Dielectric voltage test |
|-------------------------|
|-------------------------|

| | |
|--------------------------------------|-----------------------------|
| EN 60255-27, IEC 60255-5, EN 60255-1 | 2 kV (AC), 50 Hz, 1 min |
| Impulse voltage test | |
| EN 60255-27, IEC 60255-5 | 5 kV, 1.2/50 μ s, 0.5 J |

Physical environment compatibility

Table. 8.3 - 267. Mechanical tests.

| | |
|---|---|
| Vibration test | |
| EN 60255-1, EN 60255-27, IEC 60255-21-1 Class 1 | 2...13.2 Hz, \pm 3.5 mm 13.2...100 Hz, \pm 1.0 g |
| Shock and bump test | |
| EN 60255-1, EN 60255-27, IEC 60255-21-2 Class 1 | 20 g, 1 000 bumps/direction. |

Table. 8.3 - 268. Environmental tests.

| | |
|----------------------------|--|
| Damp heat (cyclic) | |
| EN 60255-1, IEC 60068-2-30 | Operational: +25...+55 °C, 93...97 % (RH), 12+12h |
| Dry heat | |
| EN 60255-1, IEC 60068-2-2 | Storage: +70 °C, 16 h Operational: +55 °C, 16 h |
| Cold test | |
| EN 60255-1, IEC 60068-2-1 | Storage: -40 °C, 16 h Operational: -20 °C, 16 h |

Table. 8.3 - 269. Environmental conditions.

| | |
|---|-----------------------------|
| IP classes | |
| Casing protection class | IP54 (front) IP21 (rear) |
| Temperature ranges | |
| Ambient service temperature range | -35...+70 °C |
| Transport and storage temperature range | -40...+70 °C |
| Other | |
| Altitude | <2000 m |
| Overvoltage category | III |
| Pollution degree | 2 |

Casing and package

Table. 8.3 - 270. Dimensions and weight.

| Without packaging (net) | |
|-------------------------|--|
| Dimensions | Height: 117 mm (4U) Width: 127 mm (¼ rack) Depth: 174 mm (no cards & connectors) |
| Weight | 1.5 kg |
| With packaging (gross) | |
| Dimensions | Height: 170 mm Width: 242 mm Depth: 219 mm |
| Weight | 2 kg |

9 Ordering information

| | AQ - F 2 1 0 - P X 8 X A X A - X X X X |
|---|--|
| Model | |
| F Feeder protection | |
| Device size | |
| 1 1/4 of 19" rack | |
| Analog measurement | |
| 0 5 Current measurement channels | |
| Mounting | |
| P Panel mounting | |
| Auxiliary voltage | |
| H 80...265 VAC/DC | |
| L 18...72 VDC | |
| Measurement accuracy class | |
| 8 N/A | |
| Terminals | |
| A Standard | |
| B Ring lug terminals | |
| C Standard current terminals, spring cage I/O terminals | |
| D Ring-lug current terminals, spring cage I/O terminals | |
| Reserved for future use | |
| A N/A | |
| Digital inputs on power supply module | |
| A 3 Digital inputs, 24 V nominal threshold | |
| B 3 Digital inputs, 110 V nominal threshold | |
| C 3 Digital inputs, 220 V nominal threshold | |
| D 2 Digital inputs, 24 V nominal threshold | |
| E 2 Digital inputs, 110 V nominal threshold | |
| F 2 Digital inputs, 220 V nominal threshold | |
| Reserved for future use | |
| A N/A | |
| Slots A, C, E, F (4 pcs) | |
| A Empty | |
| B 8 Digital inputs | |
| C 5 Output relays (max. 2 pcs) | |
| D Arc protection with 4 point sensor channels, 2 x HSO, 1 x BI (max. 1 pcs) | |
| F 8 x RTD input (max. 2 pcs) | |
| G 2 x RJ-45 100Mb Ethernet & IRIG-B (max. 1 pcs) * | |
| H 2 x ST 100Mb Ethernet & IRIG-B (max. 1 pcs) * | |
| I 4 x mA outputs - 1 x mA input (max. 2 pcs) | |
| J Double LC 100Mb Ethernet (HSR, PRP redundant protocols) (max. 1 pcs) * / ** | |
| K Double RJ45 100Mb Ethernet (HSR, PRP redundant protocols) (max. 1 pcs) * | |
| L RS-232 - Serial fiber (Plastic-Plastic) (max. 1 pcs) * | |
| M RS-232 - Serial fiber (Plastic-Glass) (max. 1 pcs) * | |
| N RS-232 - Serial fiber (Glass-Plastic) (max. 1 pcs) * | |
| O RS-232 - Serial fiber (Glass-Glass) (max. 1 pcs) * | |

* Can only be applied to the last slot

** Can't be applied when type "L" (18...72 VDC) auxiliary voltage is selected

Accessories

| Order code | Description | Note |
|------------|--|-------------------------------------|
| AX007 | External 6-channel 2 or 3 wires RTD Input module, pre-configured | Requires an external 24 VDC supply. |

| | | |
|--------|---|-------------------------------------|
| AX008 | External 8-ch Thermocouple mA Input module, pre-configured | Requires an external 24 VDC supply. |
| AQX009 | Raising frame 87 mm | - |
| AX010 | Raising frame 40 mm | - |
| AQX011 | AQ-210 series combiflex frame | - |
| AQX012 | AQ-210 series wall mounting bracket | - |
| AQ-01A | Light point sensor unit (8,000 lux threshold) | Max. cable length 200 m |
| AQ-01B | Light point sensor unit (25,000 lux threshold) | Max. cable length 200 m |
| AQ-01C | Light point sensor unit (50,000 lux threshold) | Max. cable length 200 m |
| AQ-02A | Pressure and light point sensor unit (8,000 lux threshold) | Max. cable length 200 m |
| AQ-02B | Pressure and light point sensor unit (25,000 lux threshold) | Max. cable length 200 m |
| AQ-02C | Pressure and light point sensor unit (50,000 lux threshold) | Max. cable length 200 m |

10 Contact and reference information

Manufacturer

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Visiting and postal address

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Contacts

| | |
|--------------------|---|
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